

CENG 384 - Signals and Systems for Computer Engineers  
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Homework 2

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1. (a)  $\int x(t) - 5y(t) dt = y(t)$

(b) By getting the differential of the equation above, we get:

$$y'(t) + 5y(t) = x(t)$$

Solving the characteristic equation gives us:

$$r + 5 = 0$$

$$r = -5$$

The homogeneous solution is found as  $y_h = Ke^{-5t}$

We know that the system is linear. Therefore, we can find the particular solutions from:

$$x(t) = (e^{-t} + e^{-3t})u(t) = e^{-t}u(t) + e^{-3t}u(t)$$

$$x_1(t) = e^{-t}u(t) \text{ and } x_2(t) = e^{-3t}u(t)$$

We need to find  $x_1$  and  $x_2$ . After that, we need to add them.

For the first equation:

$$x_1(t) = e^{-t}u(t), \text{ so } x_1(t) = 0 \text{ for } t < 0 \text{ and } e^{-t} \text{ for } t > 0.$$

Transfer function for  $x_1(t)$  is  $H(\lambda) = \frac{1}{\lambda + 5}$ .  $\lambda = -1$  and  $H(-1) = \frac{1}{4}$ .

Hence, the particular solution for  $x_1(t) = \frac{1}{4}e^{-t}u(t)$ .

We can get the particular solution for  $x_2(t)$  following the same steps.

$$x_2(t) = e^{-3t}u(t) \text{ and } H(-3) = \frac{1}{2}$$

Therefore, particular solution for  $x_2(t)$  is  $\frac{1}{2}e^{-3t}u(t)$

$$y(t) = y_H(t) + y_P(t) = Ke^{-5t} + \frac{1}{4}e^{-t}u(t) + \frac{1}{2}e^{-3t}u(t)$$

Finally, we need to find K.

$$y(0) = K + \frac{1}{4} + \frac{1}{2} = 0$$

$$K = -\frac{3}{4}$$

Therefore,  $y(t) = -\frac{3}{4}e^{-5t} + \frac{1}{4}e^{-t}u(t) + \frac{1}{2}e^{-3t}u(t)$

2. (a)

$$\begin{aligned}
y[n] &= x[n] * h[n] \\
&= \sum_{k=-\infty}^{\infty} x[k] \cdot h[n-k] \\
&= \sum_{k=-\infty}^{\infty} (2\delta[k] \cdot \delta[n-k-1] + 2\delta[k+1] \cdot \delta[n-k-1] + \delta[k+1] \cdot 2\delta[n-k+1]) \\
&= 2 \sum_{k=-\infty}^{\infty} \delta[k] \cdot \delta[n-k-1] + 4 \sum_{k=-\infty}^{\infty} \delta[k] \cdot \delta[n-k+1] + \sum_{k=-\infty}^{\infty} \delta[k+1] \cdot \delta[n-k-1] + 2 \sum_{k=-\infty}^{\infty} \delta[k+1] \cdot \delta[n-k+1] \\
&= 2\delta[n-1] + 4\delta[n+1] + \delta[n] + 2\delta[n+2] \\
y[n] &= 2\delta[n-1] + \delta[n] + 4\delta[n+1] + 2\delta[n+2]
\end{aligned}$$

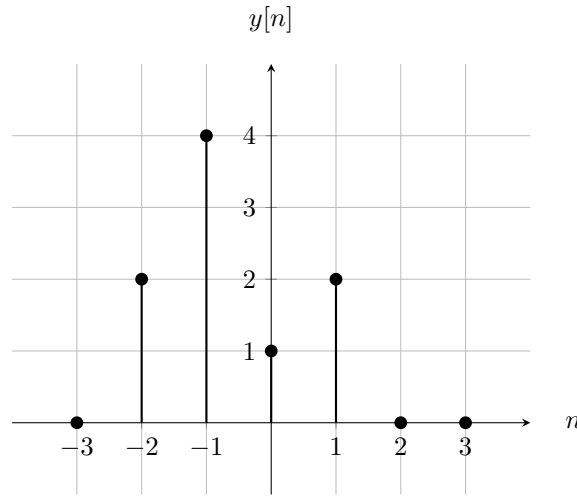


Figure 1:  $y[n] = x[n] * h[n]$ .

(b)  $\frac{dx(t)}{dt} = \delta(t-1) + \delta(t+1)$

Since the Convolution is distributive,

$$\begin{aligned}
y(t) &= \frac{dx(t)}{dt} * h(t) \\
&= h(t) * (\delta(t-1) + \delta(t+1)) \\
&= (h(t) * \delta(t-1)) + (h(t) * \delta(t+1)) \\
&= h(t-1) + h(t+1) \\
y(t) &= e^{-(t-1)} \sin(t-1) \cdot u(t-1) + e^{-(t+1)} \sin(t+1) \cdot u(t+1)
\end{aligned}$$

3. (a)  $y(t) = x(t)h(t) = \int_{-\infty}^{\infty} e^{-\tau} u(\tau) e^{-2(t-\tau)} u(t-\tau) d\tau$

Since  $u(\tau)$  and  $u(t-\tau)$  does not overlap when  $t < 0$ , we do not need to consider that interval.

But, we need to consider when  $t > 0$ , because they overlap in that interval.

So, we need to change the limits of the integral in the interval 0 to t.

$$\begin{aligned}
y(t) &= \int_0^t e^{-\tau} e^{-2(t-\tau)} d\tau \\
&= e^{-2t} \int_0^t e^{\tau} d\tau \\
&= e^{-2t} (e^t - 1) \\
&= (e^{-t} - e^{-2t}) u(t)
\end{aligned}$$

$$(b) \quad x(t) = u(t) - u(t-1)$$

$$= \delta(t-1)$$

$$y(t) = x(t) * h(t)$$

$$= \delta(t-1) * h(t)$$

$$= h(t-1)$$

$$y(t) = e^{3(t-1)} \cdot u(t-1)$$

$$4. \quad (a) \quad y[n] - y[n-1] - y[n-2] = 0, y[0] = 1 \text{ and } y[1] = 1$$

$$r^2 - r - 1 = 0$$

$$r_1 = \frac{1 + \sqrt{5}}{2}$$

$$r_2 = \frac{1 - \sqrt{5}}{2}$$

$$y[n] = A\left(\frac{1 + \sqrt{5}}{2}\right)^n + B\left(\frac{1 - \sqrt{5}}{2}\right)^n$$

$$y[0] = A + B = 1$$

$$y[1] = A\frac{1 + \sqrt{5}}{2} + B\frac{1 - \sqrt{5}}{2} = 1$$

$$y[1] - \frac{y[0]}{2} = \frac{\sqrt{5}}{2}(A - B) = \frac{1}{2}$$

$$A - B = \frac{1}{\sqrt{5}}$$

$$A + B = 1$$

$$A = \frac{1 + \frac{1}{\sqrt{5}}}{2} = \frac{\sqrt{5} + 1}{2\sqrt{5}}$$

$$B = \frac{1 - \frac{1}{\sqrt{5}}}{2} = \frac{\sqrt{5} - 1}{2\sqrt{5}}$$

Therefore:

$$y[n] = \frac{\sqrt{5} + 1}{2\sqrt{5}} \left(\frac{1 + \sqrt{5}}{2}\right)^n + \frac{\sqrt{5} - 1}{2\sqrt{5}} \left(\frac{1 - \sqrt{5}}{2}\right)^n$$

$$(b) \quad y^{(3)}(t) - 6y''(t) + 13y'(t) - 10y(t) = 0, y''(0) = 3, y'(0) = \frac{3}{2} \text{ and } y(0) = 1.$$

$$r^3 - 6r^2 + 13r - 10 = 0$$

$$= (r-2)(r-(2+j))(r-(2-j))$$

$$y(t) = Ae^{2t} + Be^{(2+j)t} + Ce^{(2-j)t}$$

$$y(0) = A + B + C = 1$$

$$y'(0) = 2A + (2+j)B + (2-j)C = \frac{3}{2}$$

$$= 2(A + B + C) + j(B - C)$$

$$j(B - C) = \frac{-1}{2}$$

$$y''(0) = 4A + (2+j)^2B + (2-j)^2C = 3$$

$$= 4A + 3B + 3C + 4j(B - C)$$

$$A + 4j(B - C) = 0$$

$$A = 2$$

$$B + C = -1$$

$$B - C = \frac{j}{2}$$

$$B = \frac{j-2}{4}C = \frac{-j-2}{4}$$

$$y(t) = 2e^{2t} + \frac{j-2}{4}e^{(2+j)t} + \frac{-j-2}{4}e^{(2-j)t}$$

$$= e^{2t}(2 + \frac{j-2}{4}(\cos(t) + j\sin(t)) + \frac{-j-2}{4}(\cos(t) - j\sin(t)))$$

$$y(t) = e^{2t}[2 - \frac{1}{2}(\sin(t) + 2\cos(t))]$$

5. (a)  $y_p(t) = Kx(t) = K\cos(5t)$

$$K = H(\lambda) = \frac{\sum_{k=0}^M b_k \lambda^k}{\sum_{k=0}^N a_k \lambda^k}$$

According to the Euler's formula :

$$\cos(5t) = \frac{(e^{j5t} + e^{-j5t})}{2}$$

$$y_p(t) = K\cos(5t) = \frac{K.e^{j5t} + K.e^{-j5t}}{2}$$

For  $x_1(t) = e^{j5t}$ ,  $\lambda$  is  $(j5t)$ , so using the formula of the Transfer function:

$$\text{We have } H(j5) = \frac{j5}{(j5)^2 + 5(j5) + 6}$$

For  $x_1(t)$ , the particular solution is  $H(j5)e^{j5t}$

For  $x_2(t)$ , the particular solution is  $H(-j5)e^{-j5t}$

For  $x(t) = \frac{x_1(t) + x_2(t)}{2}$ , the particular solution is:

$$y_p(t) = \frac{H(j5)e^{j5t} + H(-j5)e^{-j5t}}{2}$$

(b) Assume  $y_h(t) = Ce^{st} \Rightarrow Cs^2e^{st} + 5Cse^{st} + 6Ce^{st} = 0$

$$y_h(t) = C(s^2 + 5s + 6)e^{st}$$

So,  $(S = -3)$  or  $(S = -2)$

$$y_h(t) = C_1e^{-3t} + C_2e^{-2t}$$

(c)  $y(t) = y_h(t) + y_p(t)$

Use initially at rest condition is  $y(0) = 0$  and  $y'(0) = 0$

$$y(0) = y_h(0) + y_p(0) = 0$$

$$y(0) = C_1e^{-3.0} + C_2e^{-2.0} + \frac{H(j.5)e^{j.5.0} + H(-j.5)e^{-j.5.0}}{2} = 0$$

$$C_1 + C_2 + \frac{H(5j)}{2} + \frac{H(-5j)}{2} = 0$$

$$H(5j) = \frac{5j}{25j - 19} \quad \text{and} \quad H(-5j) = \frac{-5j}{-25j - 19}$$

$$C_1 + C_2 = \frac{5j \cdot (25j + 19) + 5j(25j - 19)}{-(25^2 + 19^2) \cdot 2}$$

$$C_1 + C_2 = \frac{-250}{-986.2} = \frac{125}{986}$$

$$y'(0) = -3C_1 e^{-3 \cdot 0} - 2C_2 e^{-2 \cdot 0} + \frac{(5j)H(j \cdot 5)e^{j \cdot 5 \cdot 0} + (-5j)H(-j \cdot 5)e^{-j \cdot 5 \cdot 0}}{2} = 0$$

$$-3C_1 + -2C_2 + \frac{(5j)H(5j)}{2} + \frac{(-5j)H(-5j)}{2} = 0$$

$$(5j) \cdot H(5j) = \frac{-25}{25j - 19} \quad \text{and} \quad (-5j) \cdot H(-5j) = \frac{25}{-25j - 19}$$

$$3C_1 + 2C_2 = \frac{-950}{-986.2} = \frac{475}{986}$$

$$C_1 = \frac{225}{986} \quad \text{and} \quad C_2 = \frac{-100}{986}$$

$$y(t) = \left(\frac{225}{986}\right)e^{-3t} + \left(\frac{-100}{986}\right)e^{-2t} + \frac{H(j \cdot 5)e^{j \cdot 5 \cdot t} + H(-j \cdot 5)e^{-j \cdot 5 \cdot t}}{2}$$

6. (a)  $h_0[n] - \frac{1}{2}h_0[n-1] = \delta[n] \rightarrow h_0[n] = \frac{1}{2}h_0[n-1] + \delta[n]$

If the system is initially at rest:

$$h_0[n] = 0 \text{ for all } n < 0.$$

$$h_0[n] = \frac{1}{2}h_0[n-1] + \delta[0] = 0 + 1 = 1$$

$\delta[n] = 0$  for all  $n > 0$ . Thus for  $n > 0$ ,

$$h_0[n] = \frac{1}{2^n} \cdot u[n]$$

(b)  $h[n] = h_0[n] \cdot h_0[n] = \sum_{k=-\infty}^{\infty} \frac{1}{2^k} \cdot u[k] \cdot \frac{1}{2^{n-k} \cdot u[n-k]}$

If  $n < 0$  and  $u[n-k]$  do not overlap, then  $h[n] = 0$ .

If  $n \geq 0$  and  $0 \geq u[n-k] \geq n$ , then Limits of the Sum can be changed.

$$h[n] = \sum_{k=0}^n \frac{1}{2^k} \cdot \frac{1}{2^{n-k}} = \sum_{k=0}^n \frac{1}{2^n} = \frac{n}{2^n}$$

As a result,  $h[n] = \frac{n}{2^n} \cdot u[n]$

(c)  $w[n] = y[n] - \frac{y[n-1]}{2}$

Since the System is the LTI system:

$$\frac{y[n-1]}{2} - \frac{y[n-2]}{4} = \frac{w[n-1]}{2}$$

We have two equations now. When we subtract them from each other,

$$x[n] = y[n] - y[n-1] + \frac{y[n-2]}{4} = w[n] - \frac{w[n-1]}{2}$$

$$x[n] = y[n] - y[n-1] + \frac{y[n-2]}{4}$$

```

7.      import matplotlib.pyplot as plt
      import numpy as np

      def convolution(signal1, start1, signal2, start2):
          len_x = len(signal1)
          len_h = len(signal2)
          len_y = len_x+len_h+1
          y = np.zeros(len_y)
          for n in range(len_y):
              for k in range(len_x):
                  if n - k >= 0 and n - k < len_h:
                      y[n] += signal1[k] * signal2[n - k]

          return y

      filename = "hw2_signal.csv"
      data = np.loadtxt(filename, delimiter=",")
      startIndex = int(data[0])
      signalList = data[1:]
      N = 20 # will change
      h = []
      len_x = len(signalList)
      for i in range(0, len_x):
          if (0 <= i+startIndex and i+startIndex <= N-1):
              h.append(1/N)
          else:
              h.append(0)
      lst = convolution(signalList, startIndex, h, startIndex)
      n = np.arange(startIndex, startIndex+len(signalList)*2+1)

      plt.stem(n, lst, linefmt='b-', markerfmt='bo', label="y[n]")
      plt.legend()
      plt.show()

```

a) The effect of convolution with  $\delta[n - 5]$  is shifting the signal to the right by 5.

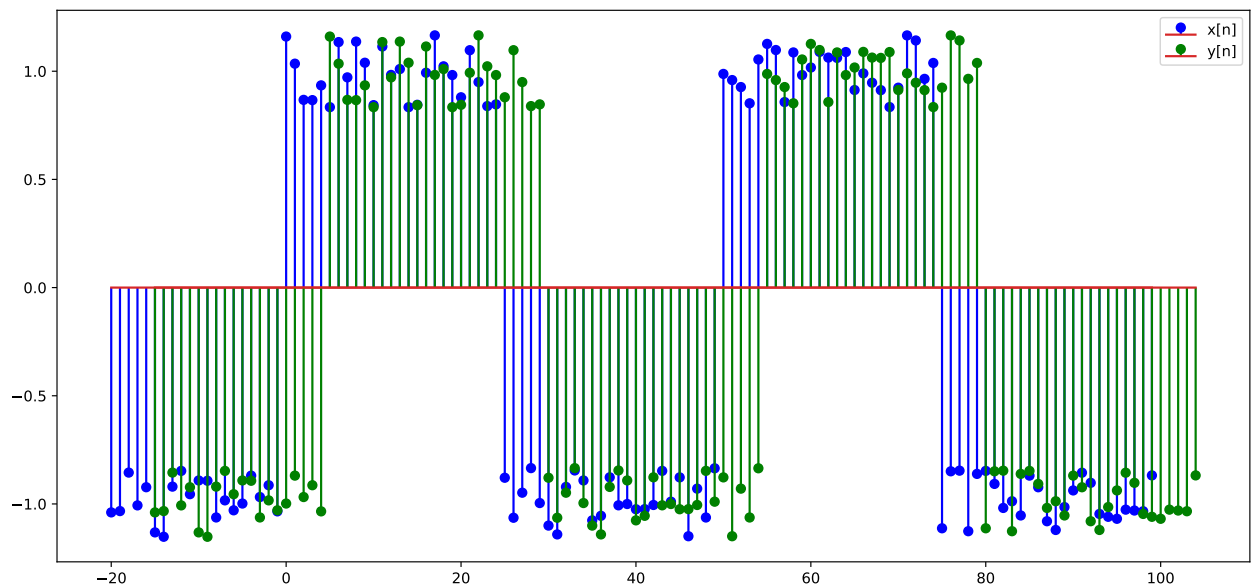


Figure 2:  $y[n]$

b) The effect of  $m[n]$  is that it produces a smoothed version of the input signal by averaging adjacent samples. The smoothing effect is more prominent as the length of the filter  $N$  increases. The differences between different  $N$  values are that a larger  $N$  will result in a smoother output signal with more attenuation of high-frequency components.

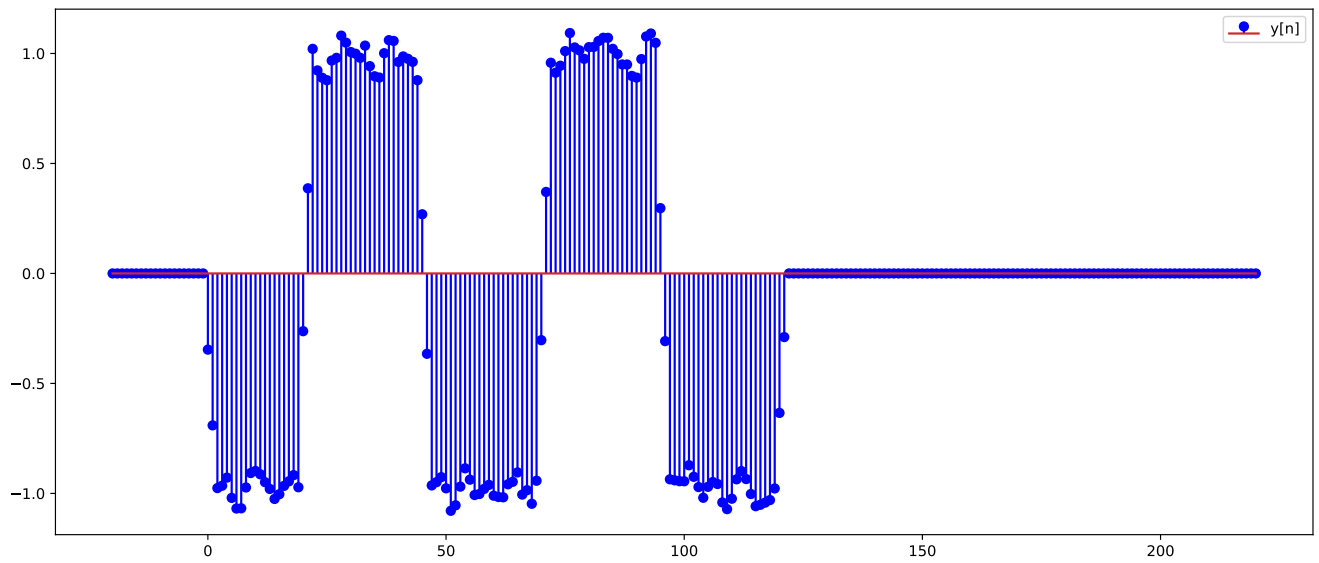


Figure 3:  $N=3$

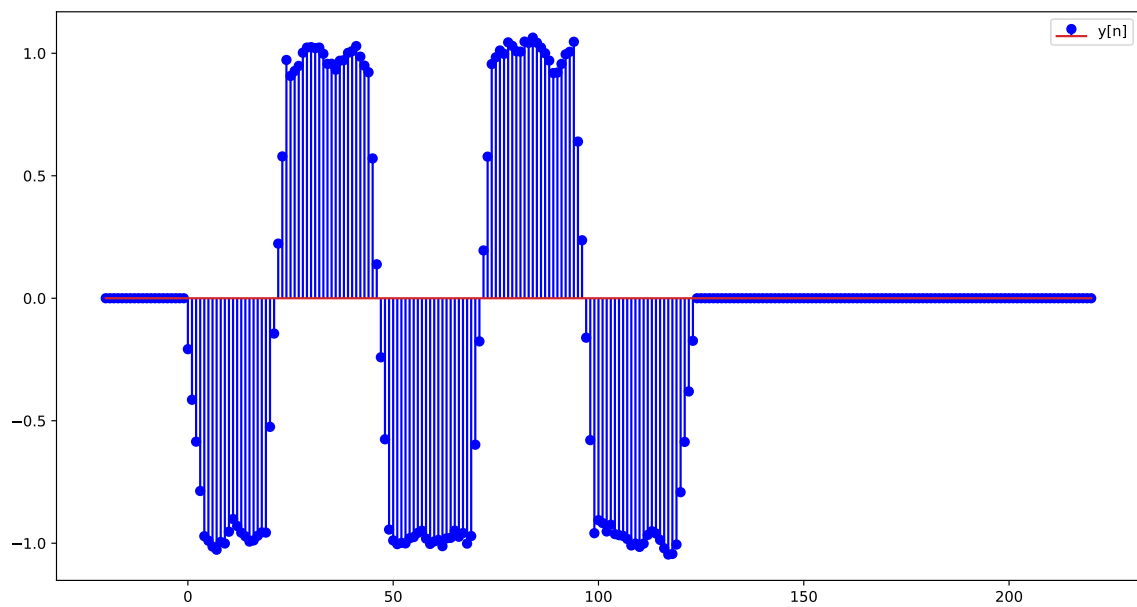


Figure 4:  $N=5$

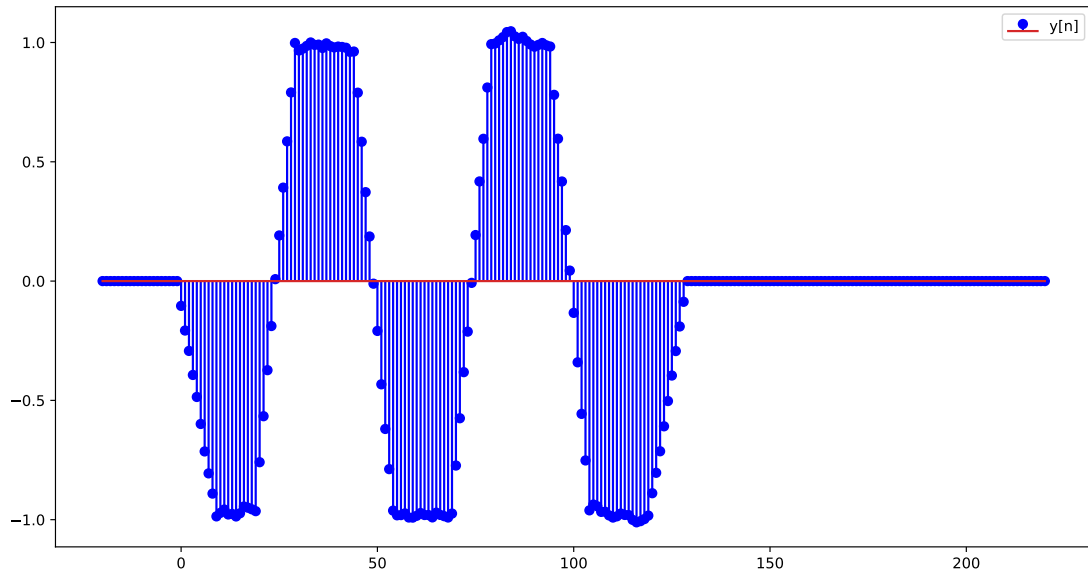


Figure 5:  $N=10$

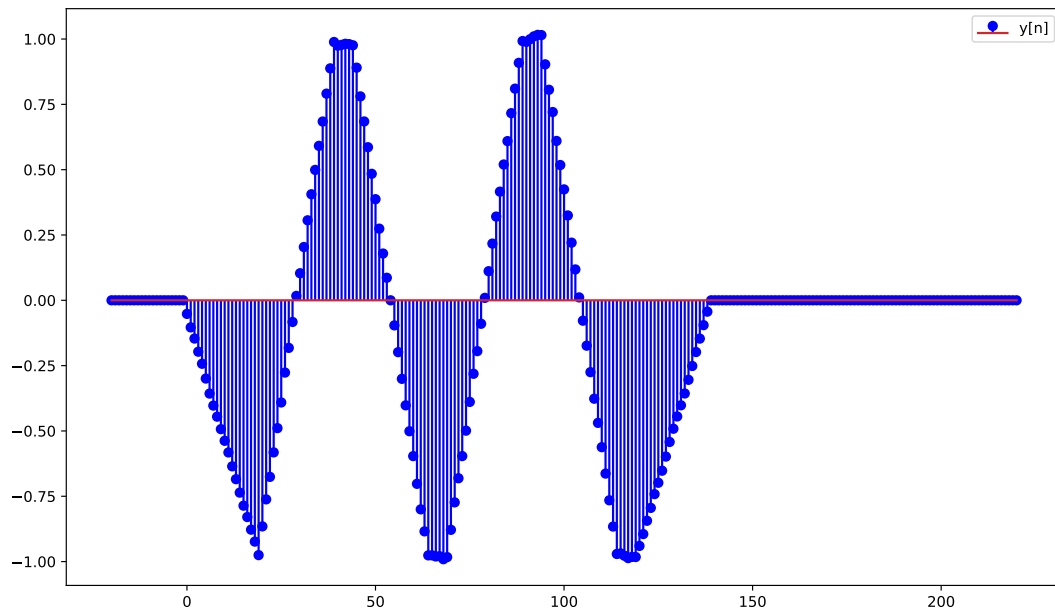


Figure 6:  $N=20$