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In [22]: #importing required libraries
import cv2
import numpy as np
import matplotlib.pyplot as plt
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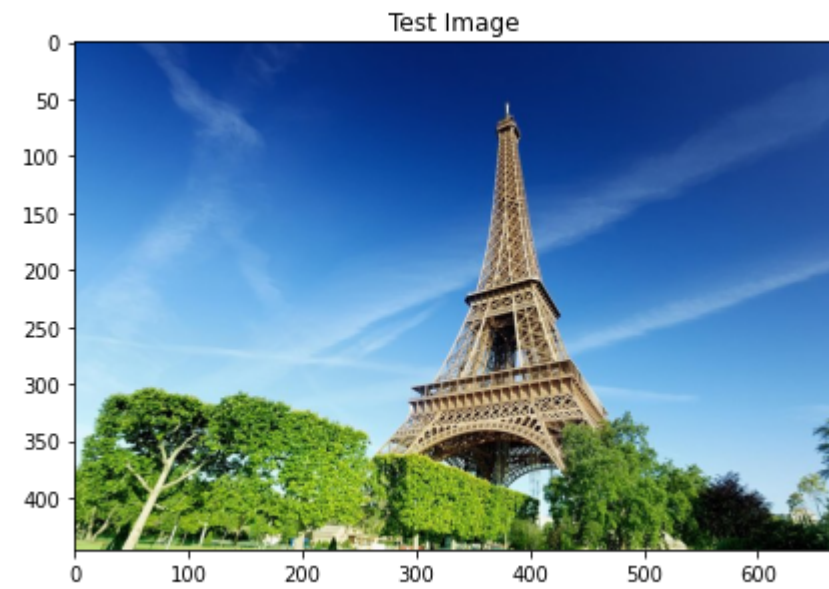
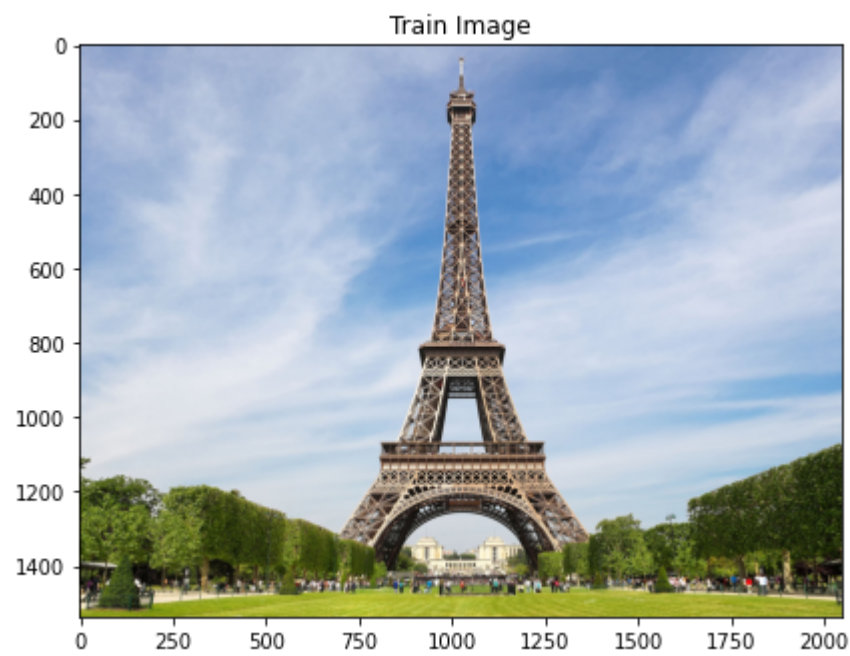
```
In [23]: #reading test image
train_img = cv2.imread('./train.jpg')

#reading train image
test_img = cv2.imread('./test.jpg')
```

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In [32]: #function to plot signed 32bit signed matrix images side by side
def plot_32bs_images(img1, img2, title1="", title2=""):
    fig = plt.figure(figsize=[15, 15])
    axis1 = fig.add_subplot(121)
    axis1.imshow(cv2.cvtColor(img1, cv2.CV_32S))
    axis1.set(title=title1)
    axis2 = fig.add_subplot(122)
    axis2.imshow(cv2.cvtColor(img2, cv2.CV_32S))
    axis2.set(title=title2)

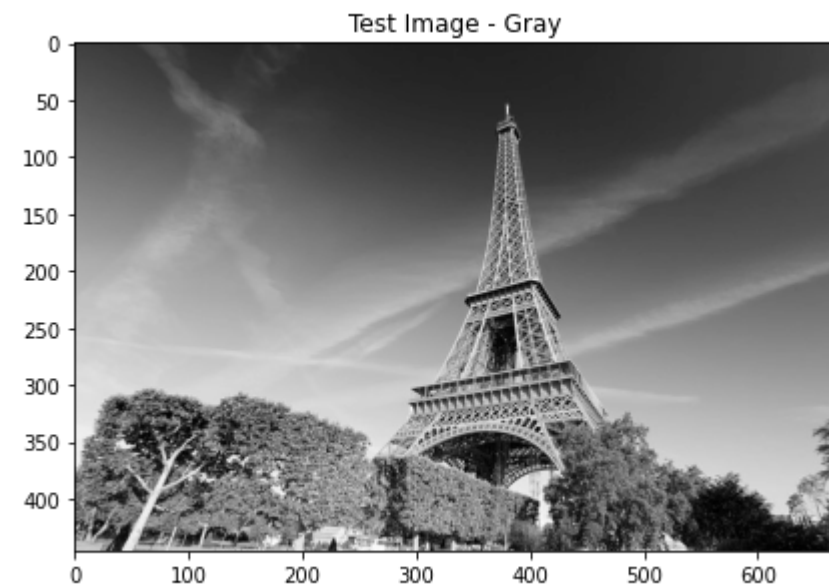
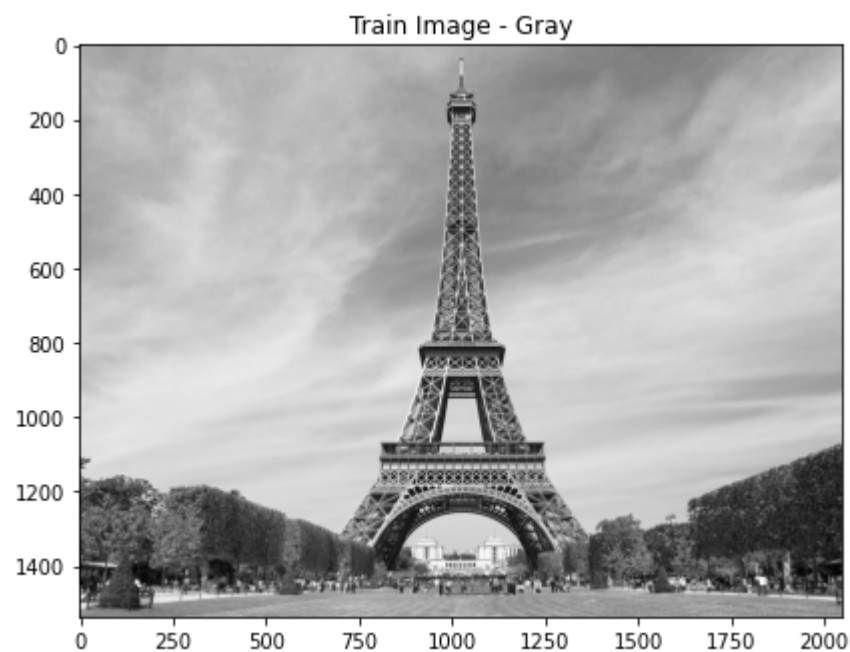
#function to plot gray images side by side
def plot_images(img1, img2, title1="", title2=""):
    fig = plt.figure(figsize=[15, 15])
    axis1 = fig.add_subplot(121)
    axis1.imshow(img1, cmap="gray")
    axis1.set(title=title1)
    axis2 = fig.add_subplot(122)
    axis2.imshow(img2, cmap="gray")
    axis2.set(title=title2)
```

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In [33]: # Show Original Images
plot_32bs_images(train_img, test_img, "Train Image", "Test Image")
```



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In [34]: # changing Images to grayscale
train_gray_img = cv2.cvtColor(train_img, cv2.COLOR_BGR2GRAY)
test_gray_img = cv2.cvtColor(test_img, cv2.COLOR_BGR2GRAY)
```

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In [36]: #plot grayscale images
plot_images(train_gray_img, test_gray_img, 'Train Image - Gray', 'Test Image - Gray')
```



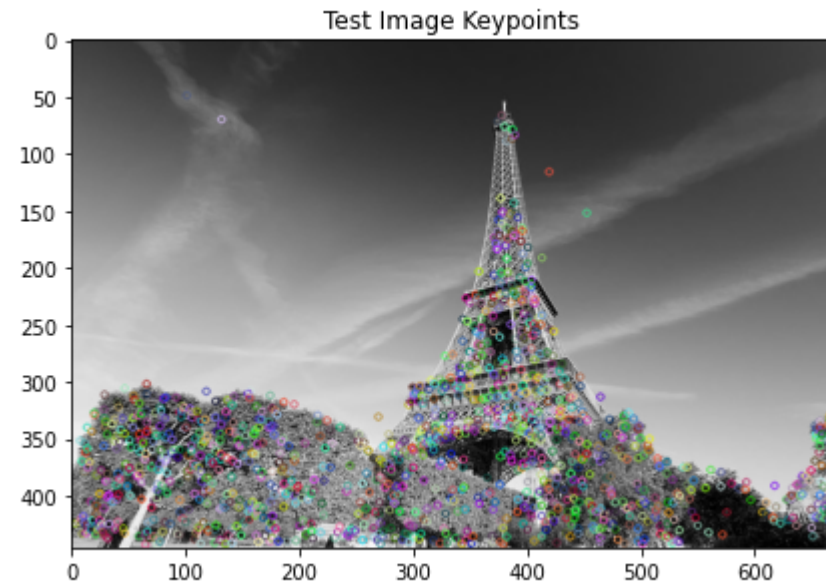
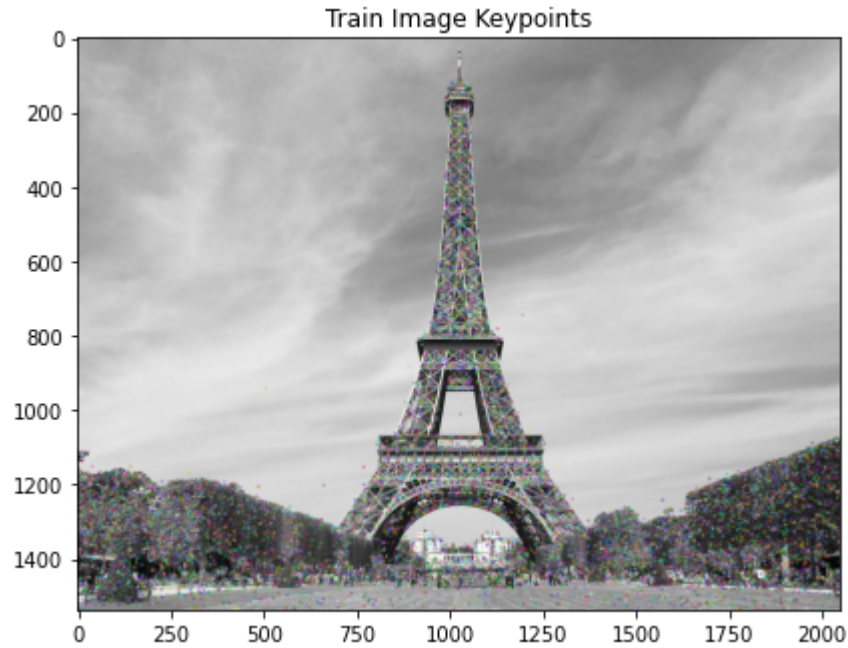
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In [37]: # Initialise Open CV SIFT detector
sift = cv2.SIFT_create()
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In [38]: #function to get keypoints and descriptors
def get_KP_DESC(img):
    return sift.detectAndCompute(img, None)
```

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In [41]: # Generate SIFT keypoints and descriptors
train_kp, train_desc = get_KP_DESC(train_gray_img)
test_kp, test_desc = get_KP_DESC(test_gray_img)
```

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In [44]: #function to draw keypoints on image
def draw_KP(gray_img_1, kp1, orig_img_1, title1, gray_img_2, kp2, orig_img_2, title2):
    img1 = cv2.drawKeypoints(gray_img_1, kp1, orig_img_1.copy())
    img2 = cv2.drawKeypoints(gray_img_2, kp2, orig_img_2.copy())
    fig = plt.figure(figsize=[15, 15])
    axis1 = fig.add_subplot(121)
    axis1.imshow(img1)
    axis1.set(title=title1)
    axis2 = fig.add_subplot(122)
    axis2.imshow(img2)
    axis2.set(title=title2)
```

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In [45]: #draw detected keypoints on images
draw_KP(train_gray_img, train_kp, train_img, 'Train Image Keypoints', test_gray_img, test_kp, test_img, 'Test Image Keypoints')
```



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In [49]: # create a Brute Force Matcher object which will match the SIFT features
brute_force = cv2.BFMatcher(cv2.NORM_L2, crossCheck=True)

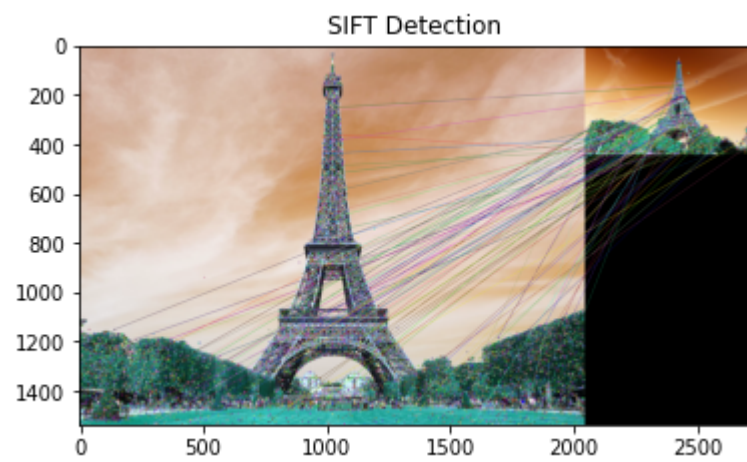
matches = brute_force.match(train_desc, test_desc)
```

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In [50]: # Sort the matches in the order of their distance in ascending order.
matches = sorted(matches, key = lambda x:x.distance)
```

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In [51]: # draw the top N matches
N_MATCHES = 100

matched_img = cv2.drawMatches(train_img, train_kp, test_img, test_kp, matches[:N_MATCHES], test_img.copy(), flags=0)
```

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In [53]: #Plotting matched image
plt.figure()
plt.imshow(matched_img)
plt.title('SIFT Detection')
plt.show()
```



In []:

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