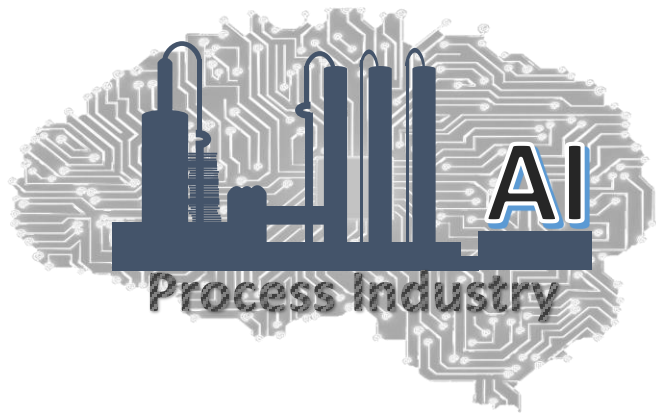


Statistical Techniques for Monitoring Industrial Processes

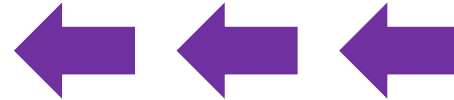


Lecture : Introduction to PLS

Module : PLS-based MSPM

Course TOC

- ❑ Introduction to Statistical Process Monitoring (SPM)
- ❑ Python Installation and basics (optional)
- ❑ Univariate SPM & Control Charts
 - Shewhart Charts
 - CUSUM Charts
 - EWMA Charts
- ❑ Multivariate SPM
 - Principal Component Analysis (PCA)-based MSPM
 - Partial Least Squares (PLS) regression-based MSPM
 - Fault detection & diagnosis (FDD) using PLS
 - Application to a LDPE reactor monitoring
 - Strategies for handling nonlinear, dynamic, multimode systems
- ❑ Deploying SPM solutions

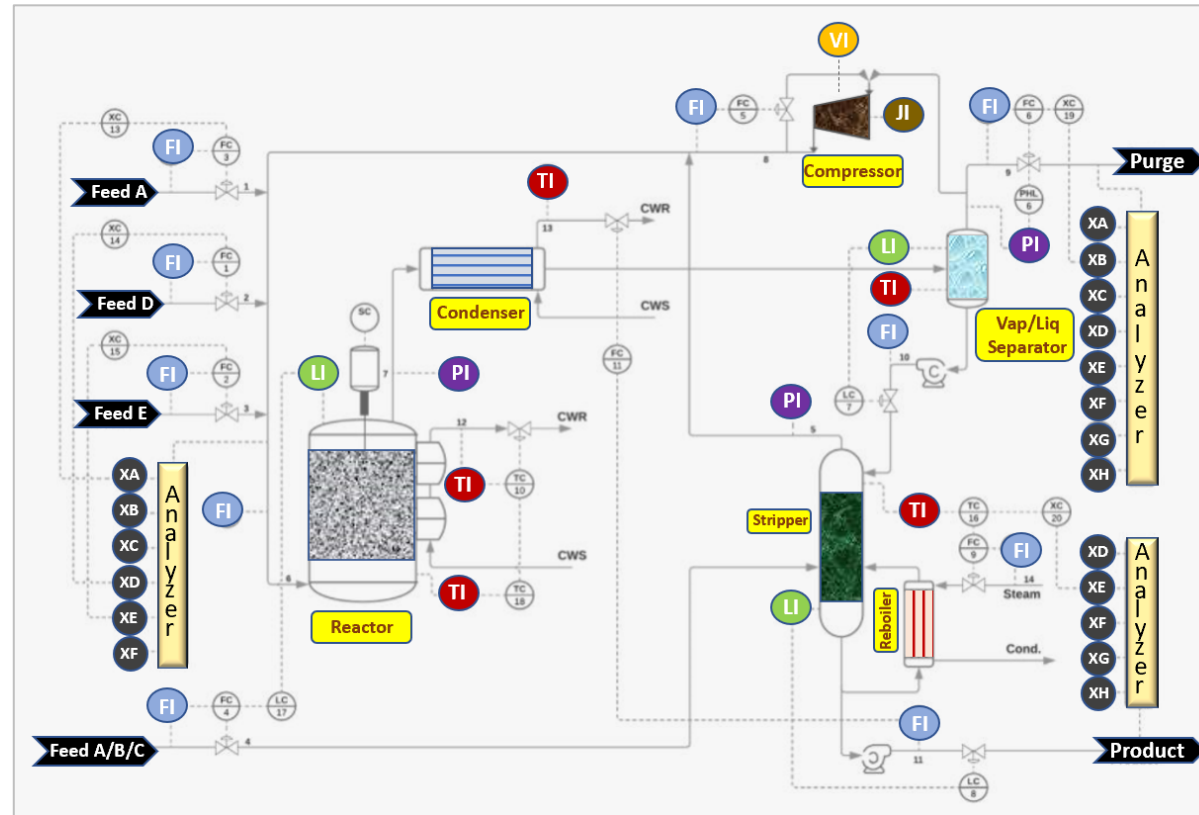


PLS (Partial Least Squares) : X and Y Blocks of Variables

Input or X variables

- Incoming feed flow
- Intermediate temperatures
- Intermediate pressures
- Intermediate flows

⋮



*Typical Chemical Plant (Tennessee Eastman Process)**

Output or Y variables

- Analyzer measurements
- Process efficiency
- Product flows

⋮

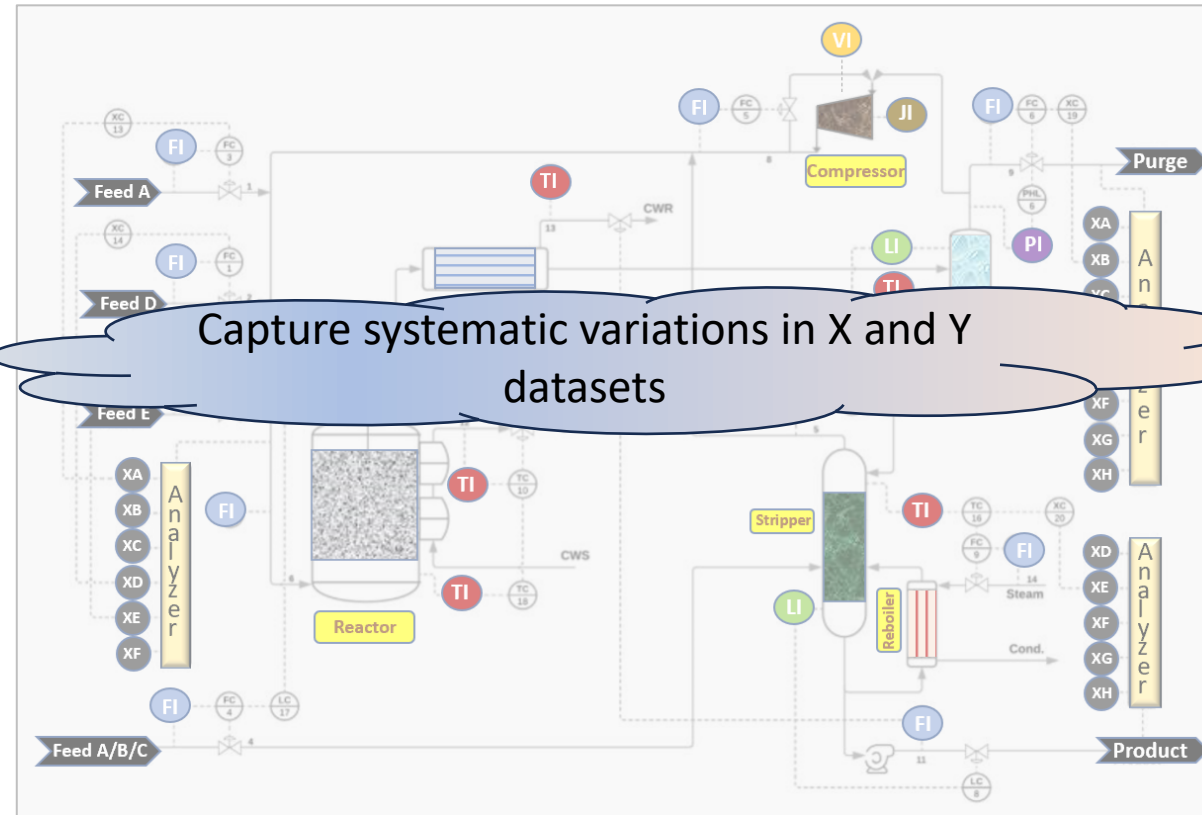
* Adapted from the original flowsheet by Gilberto Xavier (<https://github.com/gmxavier/TEP-meets-LSTM>) provided under Creative-Commons Attribution 4.0 International License (<https://creativecommons.org/licenses/by/4.0/>).

PLS (Partial Least Squares) : X and Y Blocks of Variables

Input or X variables

- Incoming feed flow
- Intermediate temperatures
- Intermediate pressures
- Intermediate flows

Quantify noise
in input
variables



Typical Chemical Plant (Tennessee Eastman Process)*

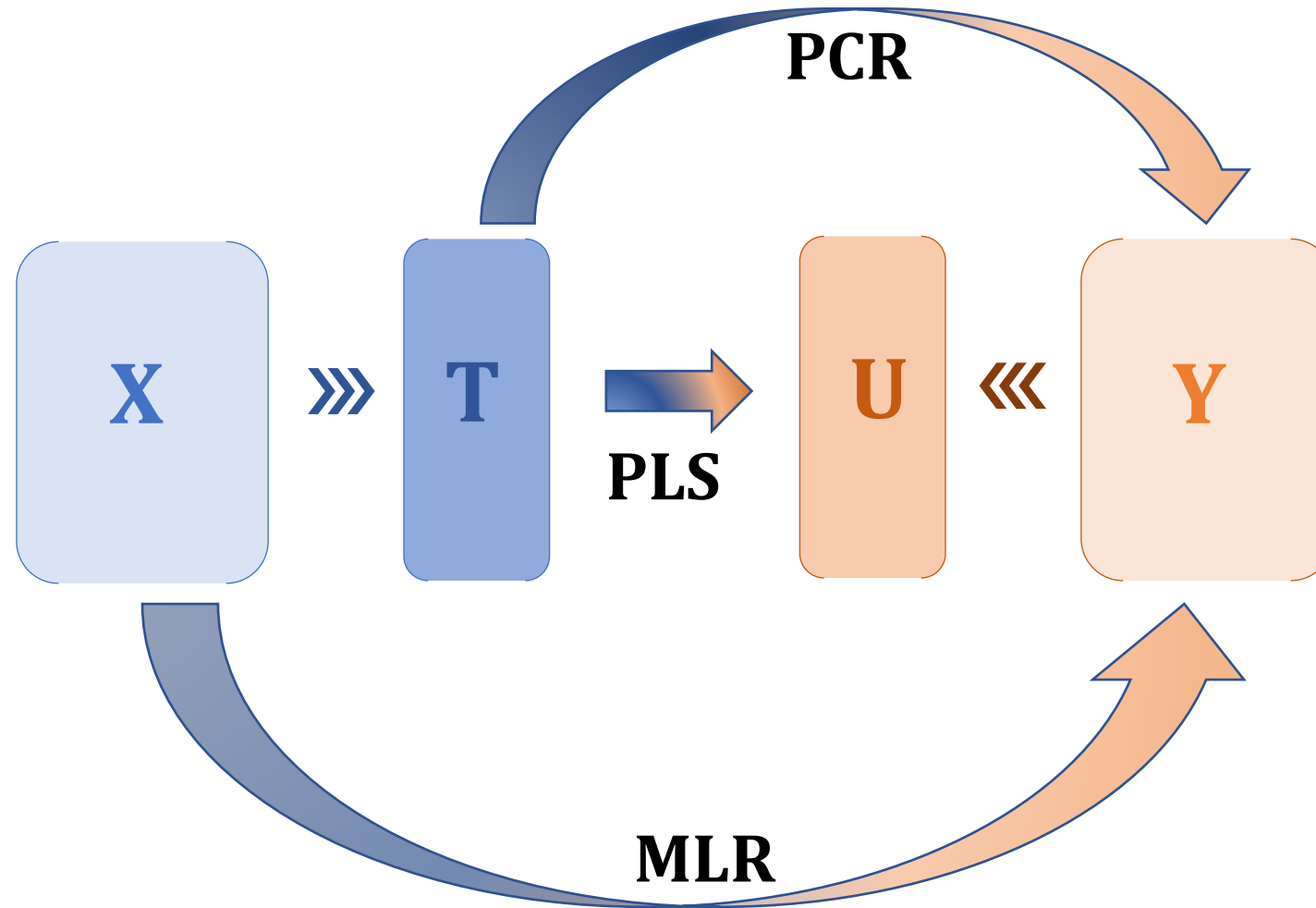
Output or Y variables

- Analyzer measurements
- Process efficiency
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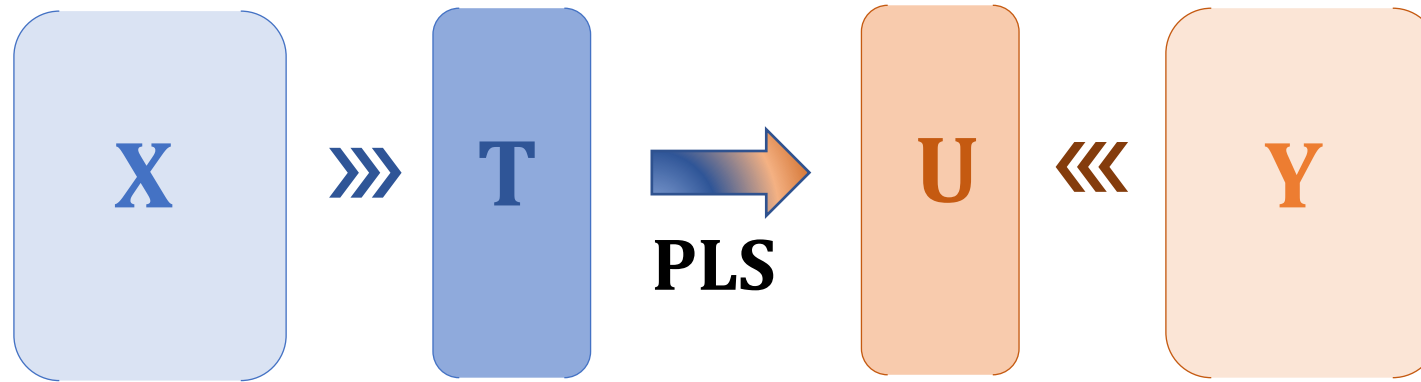
Quantify noise
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PLS: Data Transformation



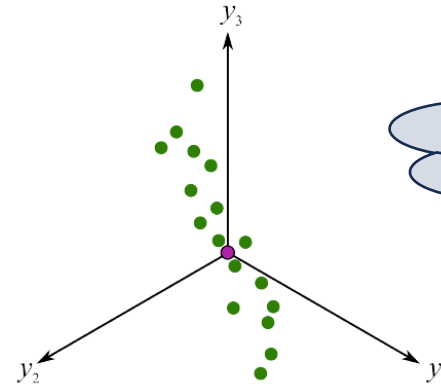
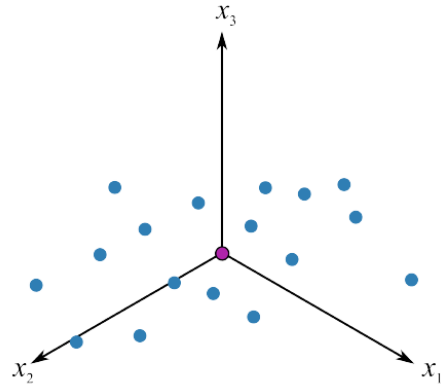
PLS: Data Transformation



PLS finds T and U matrices such that:

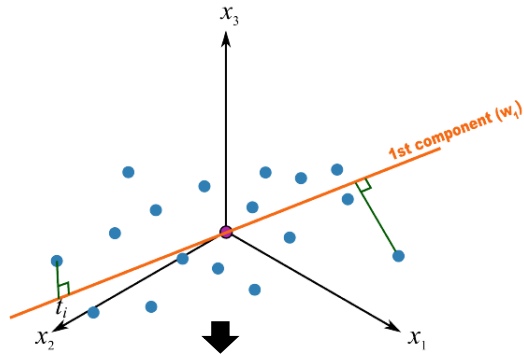
- explain as much variance as possible in X dataset
- explain as much variance as possible in Y dataset
- relationship between X and Y datasets is maximally captured

PLS: Geometric Interpretation*

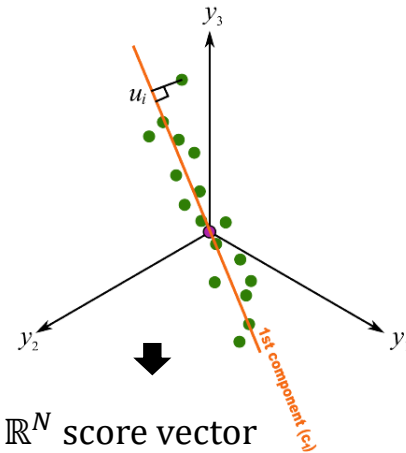


Here, # of input variables (m) = # of output variables (p) just for convenience. Usually, $p < m$

First component



$t_1 \in \mathbb{R}^N$ score vector

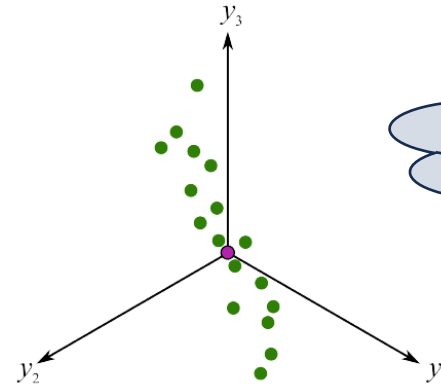
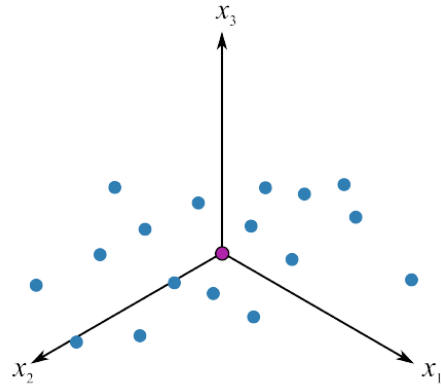


$u_1 \in \mathbb{R}^N$ score vector

PLS finds w_1 and c_1 such that $\text{Cov}(t_1, u_1)$ is maximal!

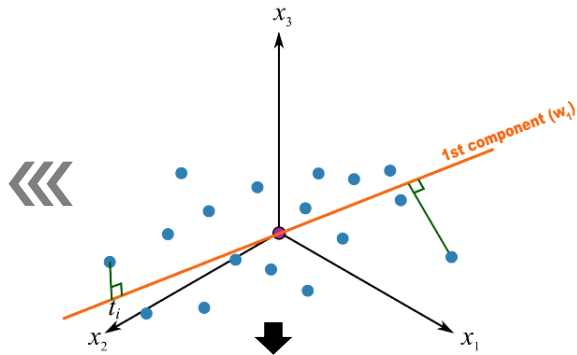
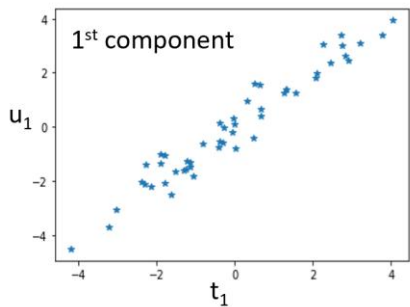
* Visualizations are copyrighted work of Kevin Dunn (<https://learnche.org/pid/>) and shared under CC BY-SA 4.0 license

PLS: Geometric Interpretation*

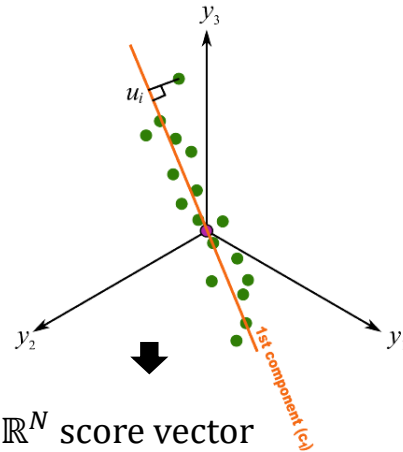


Here, # of input variables (m) = # of output variables (p) just for convenience. Usually, $p < m$

First component



$\mathbf{t}_1 \in \mathbb{R}^N$ score vector



$\mathbf{u}_1 \in \mathbb{R}^N$ score vector

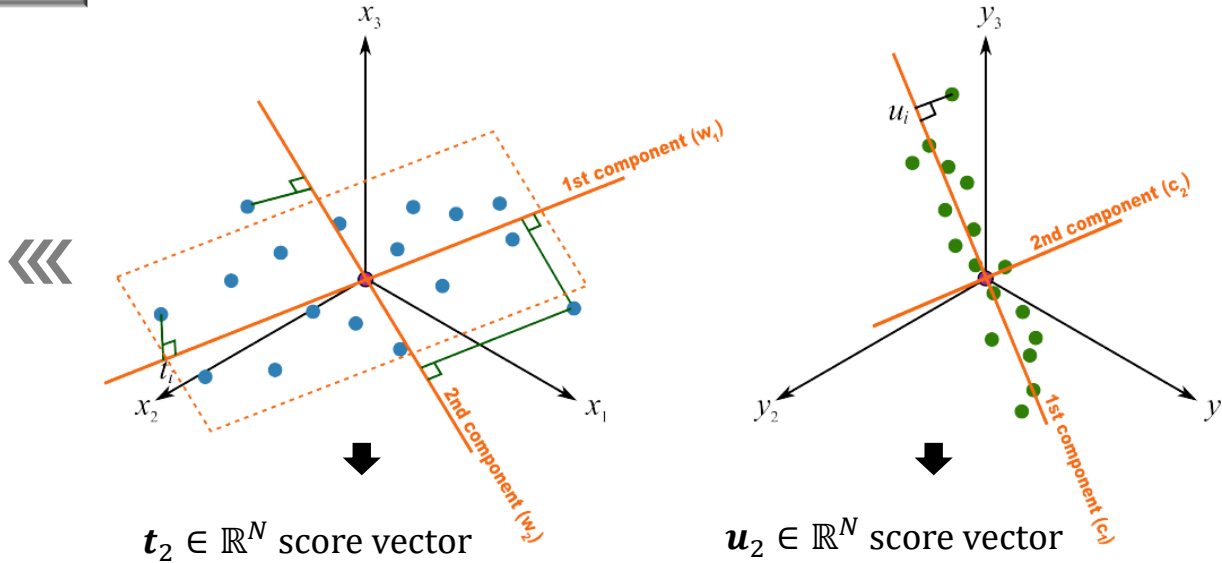
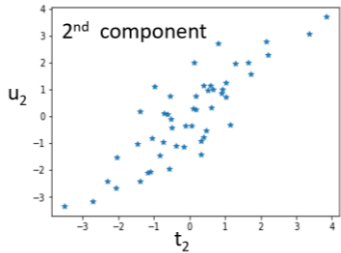
PLS finds \mathbf{w}_1 and \mathbf{c}_1 such that $\text{Cov}(\mathbf{t}_1, \mathbf{u}_1)$ is maximal!

$$\text{Cov}(\mathbf{t}_1, \mathbf{u}_1) = \text{Correlation}(\mathbf{t}_1, \mathbf{u}_1) * \sqrt{\text{Var}(\mathbf{t}_1)} * \sqrt{\text{Var}(\mathbf{u}_1)}$$

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PLS: Geometric Interpretation*

Second component



PLS finds \mathbf{w}_2 and \mathbf{c}_2 such that $\text{Cov}(\mathbf{t}_2, \mathbf{u}_2)$ is maximal!

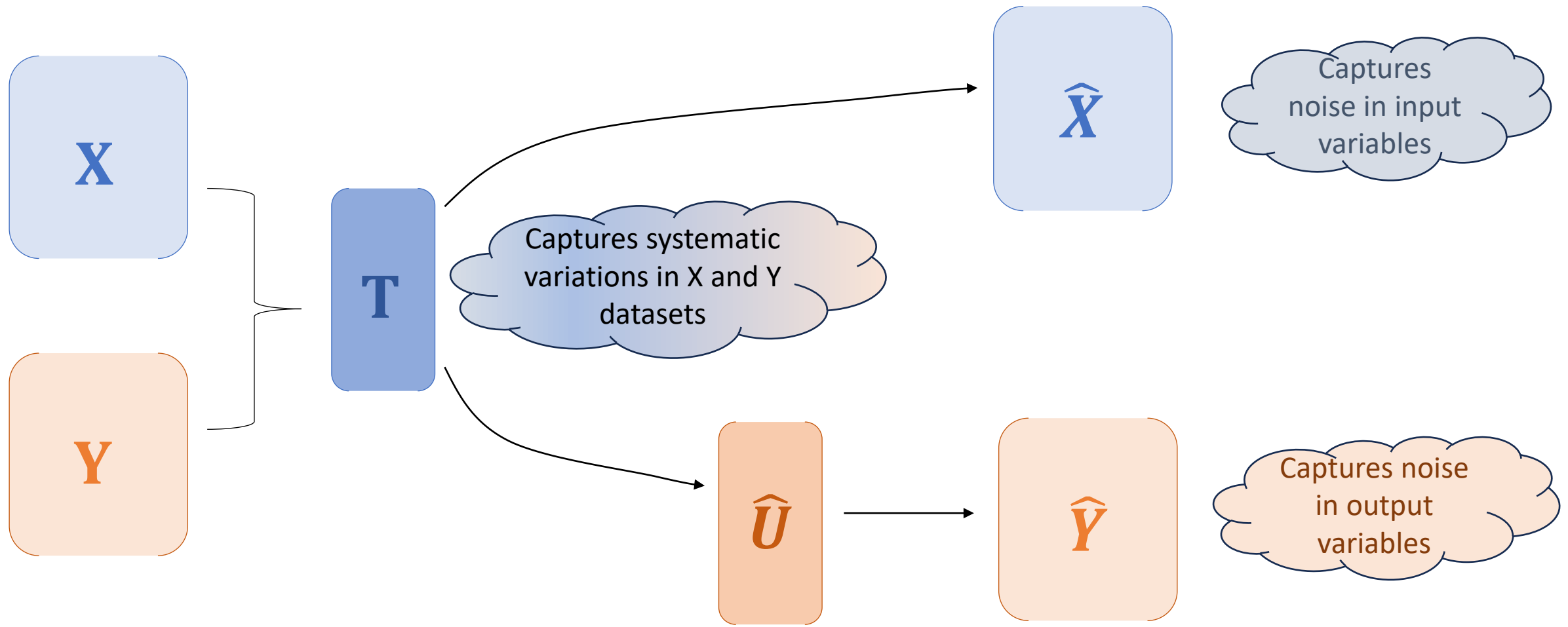
□ \mathbf{w}_2 is orthogonal to \mathbf{w}_1

Note: \mathbf{t}_2 (or \mathbf{u}_2) is not direct projection of \mathbf{X} (or \mathbf{Y}) onto \mathbf{w}_2 (or \mathbf{c}_2)

Maximum number of components extractable equals the number of input variables (m)

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PLS: Data Transformation



Statistical Techniques for Monitoring Industrial Processes



Next Lecture : PLS – Under the Hood

Module : PLS-based MSPM

