## (if you are interested in "Deep Graph Anomaly Detection with Contrastive Learning" project):

- 1. Classify the quark/gluon data with a model that learns data representation with a contrastive loss.
- 2. Evaluate the classification performance on a test dataset.

def \_\_init\_\_(self, base\_transforms, n\_views=2):
 self.base transforms = base transforms

self.n\_views = n\_views

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In [ ]: import torch
        from torch.utils.data import Dataset, DataLoader, random_split
        from torch import nn, optim
        import torch.functional as F
        import torchvision
        import h5py
        import os
        import multiprocessing as mp
        from torchvision import transforms
        import pytorch_lightning as pl
        import numpy as np
        import torchmetrics as tm
        from pytorch_lightning.callbacks import LearningRateMonitor, ModelCheckpoint
        %load_ext tensorboard
        device = "cuda"
       def subset_dataset(raw_path, processed_path, subset_len = 6000):
            with h5py.File(raw_path, 'r') as f, h5py.File(processed_path, 'w') as p:
                 keys = list(f.keys())
                total_events = f[keys[1]].shape[0]
                for key in keys:
                    shape = (subset_len,)
                    if len(f[key].shape) > 1:
                         shape = (subset_len, 125, 125, 3)
                    p.create dataset(key, shape=shape)
                quark count = 0
                gluon count = 0
                idx = 0
                 for i in range(total_events):
                    if quark_count < subset_len // 2:</pre>
                         for key in keys:
                             p[key][idx] = f[key][idx]
                         quark_count += 1
                         idx += 1
                    elif gluon_count < subset_len // 2:</pre>
                         for key in keys:
                             p[key][idx] = f[key][idx]
                         gluon count += 1
                        idx += 1
                    elif idx >= subset_len:
                         break
In [ ]: |uncompressed_data_path = "../Data/hdf5/processed/quark-gluon-dataset.hdf5"
        subset_data_path = "../Data/hdf5/processed/processed.hdf5"
        CHECKPOINT_PATH = "saved_models/"
In [ ]: if not os.path.exists(subset data path):
            subset_dataset(uncompressed_data_path, subset_data_path, subset_len=30000)
In [ ]: class QuarkGluonDataset(Dataset):
            def __init__(self, path, transform = None) -> None:
                super().__init__()
                self.path = path
                self.transform = transform
                with h5py.File(self.path, 'r') as f:
                    self.keys = list(f.keys())
                __len__(self):
                with h5py.File(self.path, 'r') as f:
                    return len(f[self.keys[1]])
            def __getitem__(self, index):
                with h5py.File(self.path, 'r') as f:
                    x = f[self.keys[0]][index]
                    y = np.array(f['y'][index])
                    y = torch.from numpy(y)
                    # y = torch.nn.functional.one hot(y.long(), 2)
                    x = torch.from numpy(x)
                    x = torch.permute(x, (2, 0, 1)) # convert(n, n, 3) -> (3, n, n)
                    if self.transform is not None:
                        x = self.transform(x)
                         return x, y
                    return x, y
In [ ]: class ContrastiveTransformations(object):
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def __call__(self, x):
                return [self.base_transforms(x) for i in range(self.n views)]
        contrast_transforms = transforms.Compose([
                                                   transforms.ToPILImage(),
                                                   transforms.RandomResizedCrop(size=96),
                                                   transforms.RandomApply([
                                                       transforms.ColorJitter(brightness=0.5,
                                                                              contrast=0.5,
                                                                              saturation=0.5,
                                                                              hue=0.1
                                                   ], p=0.8),
                                                   transforms.ToTensor(),
                                                   transforms.Normalize((0.5,),(0.5,)),
                                                  ])
In [ ]: | def train_val_test_split(dataset, train = 0.6, val = 0.2, test = 0.2):
            train_data, val_data, test_data = random_split(dataset, [train, val, test])
            datasets = {}
            datasets['train'] = train_data
            datasets['val'] = val_data
            datasets['test'] = test_data
            return datasets
        cpu_count = mp.cpu_count()
        class QuarkGluonDataModule(pl.LightningDataModule):
            def __init__(self,dataset, batch_size = 64) -> None:
                super().__init__()
                self.batch_size = batch_size
                self.dataset = dataset
            def setup(self, stage:str):
                self.train_data = self.dataset['train']
                self.val_data = self.dataset['val']
                self.test_data = self.dataset['test']
            def get_train(self, idx):
                return self.train_data[idx][0]
            def train_dataloader(self):
                return DataLoader(self.train_data, batch_size=self.batch_size, shuffle=True,
                                   num_workers=cpu_count, prefetch_factor=2* cpu_count)
            def val dataloader(self):
                return DataLoader(self.val_data, batch_size=self.batch_size, shuffle=False,
                                   num_workers=cpu_count, prefetch_factor=2* cpu_count)
            def test_dataloader(self):
                return DataLoader(self.test_data, batch_size=self.batch_size, shuffle=False,
                                  num_workers=cpu_count, prefetch_factor=2* cpu_count)
In [ ]: class Model(pl.LightningModule):
            def __init__(self, hidden_dim, lr, temperature, weight_decay, max_epochs=500):
                super().__init__()
                self.save_hyperparameters()
                assert self.hparams.temperature > 0.0, 'The temperature must be a positive float!'
                # Base model f(.)
                self.convnet = torchvision.models.resnet18(num_classes=4*hidden_dim) # Output of last linear layer
                # The MLP for g(.) consists of Linear->ReLU->Linear
                self.convnet.fc = nn.Sequential(
                    self.convnet.fc, # Linear(ResNet output, 4*hidden dim)
                    nn.ReLU(inplace=True),
                    nn.Linear(4*hidden_dim, hidden_dim),
                    nn.Softmax()
            def configure_optimizers(self):
                optimizer = optim.AdamW(self.parameters(),
                                        lr=self.hparams.lr,
                                        weight decay=self.hparams.weight decay)
                lr_scheduler = optim.lr_scheduler.CosineAnnealingLR(optimizer,
                                                                     T max=self.hparams.max epochs,
                                                                     eta_min=self.hparams.lr/50)
                return [optimizer], [lr_scheduler]
            def info nce loss(self, batch, mode='train'):
                # print(batch.shape)
                imgs, _ = batch
                # Encode all images
                feats = self.convnet(imgs)
                # Calculate cosine similarity
                cos sim = torch.nn.functional.cosine similarity(feats[:,None,:], feats[None,:,:], dim=-1)
                # Mask out cosine similarity to itself
                self_mask = torch.eye(cos_sim.shape[0], dtype=torch.bool, device=cos_sim.device)
                cos_sim.masked_fill_(self_mask, -9e15)
                # Find positive example -> batch_size//2 away from the original example
                pos_mask = self_mask.roll(shifts=cos_sim.shape[0]//2, dims=0)
                # InfoNCE loss
                cos sim = cos sim / self.hparams.temperature
                nll = -cos_sim[pos_mask] + torch.logsumexp(cos sim, dim=-1)
                nll = nll.mean()
                # Logging loss
                self.log(mode+'_loss', nll)
                # Get ranking position of positive example
                comb_sim = torch.cat([cos_sim[pos_mask][:,None], # First position positive example
                                       cos_sim.masked_fill(pos_mask, -9e15)],
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sim_argsort = comb_sim.argsort(dim=-1, descending=True).argmin(dim=-1)
                # Logging ranking metrics
                self.log(mode+'_acc_top1', (sim_argsort == 0).float().mean())
                self.log(mode+'_acc_top5', (sim_argsort < 5).float().mean())</pre>
                self.log(mode+' acc mean pos', 1+sim argsort.float().mean())
                return nll
            def training step(self, batch, batch idx):
                return self.info_nce_loss(batch, mode='train')
            def validation_step(self, batch, batch_idx):
                self.info nce loss(batch, mode='val')
In [ ]: def train_model(batch_size, max_epochs=500, **kwargs):
            trainer = pl.Trainer(default_root_dir=os.path.join(CHECKPOINT_PATH, 'CLossCNN'),
                                 accelerator="gpu",
                                 devices=1,
                                 max epochs=max epochs,
                                 callbacks=[ModelCheckpoint(save_weights_only=True, mode='max', monitor='val_acc_top5'),
                                            LearningRateMonitor('epoch')],
                                enable progress bar=False)
            trainer.logger._default_hp_metric = None # Optional logging argument that we don't need
            # Check whether pretrained model exists. If yes, load it and skip training
            pretrained_filename = os.path.join(CHECKPOINT_PATH, 'CLossCNN.ckpt')
            if os.path.isfile(pretrained_filename):
                print(f'Found pretrained model at {pretrained_filename}, loading...')
                model = Model.load_from_checkpoint(pretrained_filename) # Automatically loads the model
                # with the saved hyperparameters
            else:
                pl.seed_everything(42) # To be reproducable
                dataset = QuarkGluonDataset(subset_data_path, transform=contrast_transforms)
                dataset = train_val_test_split(dataset)
                dataset = QuarkGluonDataModule(dataset, batch_size=batch_size)
                model = Model(max_epochs=max_epochs, **kwargs)
                trainer.fit(model, datamodule=dataset)
                # Load best checkpoint after training
                model = model.load_from_checkpoint(trainer.checkpoint_callback.best_model_path)
            return model
In [ ]: CLossCNN = train_model(batch_size=64,
                                 hidden dim = 2,
                                 lr=5e-4,
                                 temperature=0.07,
                                 weight decay=1e-4,
                                 max epochs=500)
        GPU available: True (cuda), used: True
        TPU available: False, using: 0 TPU cores
        IPU available: False, using: 0 IPUs
        HPU available: False, using: 0 HPUs
        Global seed set to 42
        LOCAL_RANK: 0 - CUDA_VISIBLE_DEVICES: [0]
          | Name | Type | Params
        0 | convnet | ResNet | 11.2 M
        11.2 M Trainable params
                  Non-trainable params
                  Total params
        11.2 M
                  Total estimated model params size (MB)
        /home/guru/miniconda3/envs/gnn/lib/python3.9/site-packages/torch/nn/modules/container.py:204: UserWarning: Implicit dimension c
        hoice for softmax has been deprecated. Change the call to include dim=X as an argument.
          input = module(input)
        `Trainer.fit` stopped: `max_epochs=500` reached.
        dataset = QuarkGluonDataset(subset_data_path, transform=contrast_transforms)
        dataset = train val test split(dataset)
        test_loader = DataLoader(dataset['test'], batch_size=64, shuffle=False)
In [ ]: with torch.no_grad():
            all_labels = []
            all preds = []
            for batch in test loader:
                pred = CLossCNN.convnet(batch[0])
                all preds.append(pred)
                all labels.append(batch[1])
In [ ]: all_labels = torch.cat(all_labels)
        all_preds = torch.cat(all_preds)
In [ ]:
        # %tensorboard --logdir ./saved_models/CLossCNN
        accuracy = tm.Accuracy(task="binary", num_classes=2)
In [ ]:
        accuracy(all_preds.argmax(dim=1), all_labels)
        tensor(0.5192)
Out[]:
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dim=-1

References:

model Architecture

In [ ]: