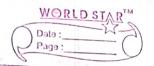
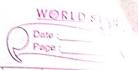


software agent has encoded bit strings are its programs land actions Agent istructure can be viewedical a combination of Agent Architecture and Agent Program. Agent Architecture reters to the machinery that an agent executus on whereas Agent Program 16 and implementation of an agent tonctions. Fig 2 schows four important types of agent architecture. Agent > (STOSOPS) How is the world like now? actions Curat actions. condition, what actions 1 hred to do? 7 Heed todo? Rule Millectors Iffectors/ Model Board Peller (a) simple Reflex Agent Sensors! blow is the 1 world like How isthe world like now cvolves what happen fluhal m what happens 11 I do action & action 14. I do actionA How happy 7 Inred todo floors are by doing while action n. what actions i Effectors tettectors) (c) Goal Based Agent (d) Utility, Based Agent Fig 2(a): Agent, Architecture Type



Ac Seen in Pig 2(a), simple Reflex agente choose actions only based on the corrent percept only they are rational only of a correct decision is made only on the basis of corrent precept. Agent coveronment ton such agents is tully observable. Hodel Based Rellex Agente use a model of the world to choose their actions. They maintain an internal state as a persustent information. Here the model megas Enouledge about how the things happens in the world that is representation of unabserved aspects of current state depending on percept bictory. Agent take into account, how ite actions affect the world. Goal board agents show in Fig choose the action in order to achieve goals. Goal based approach is more flexible than reflex agent since the thowledge supporting a diccision is explicitly modeled, thereby allowing for modifications goals are madequate where there are conflicting goals, out of come uncertainty of being achieved. and you need to weigh likelihood of success against the important of a goal. on the other hand utility function particular state is desirable.



An AI agent is referred to as Rational Agent - A rational agent always pertor right action, where the right action means the action that covers the agent to be most successfull in the given percept sequence. The problem the agent solve is characterized by Performance Measure, En Wronment, Actuators, and sensors (PEAS). These ar Collectively referred to as PEAS descripton for the agent task environment PEAS descriptors provide emportant ensight into agent and the task environment it operate in This congrete are very uschol in agent disign. Another important piece of intermation is tast environment properties. while analyzing task entironment the agent architect nord to orderanside following properties.

1. Diccretz or continuous: It there are a limited no of distinct clearly defined, states of the environment, the environment is discrete, otherwise it is continuous.

2- observable or Particular philapide.

2- Observable or Partially observable.

If it is possible to determine the

complete state of the environment

at each time point from the percept

jt is observable.

does not change while an agent It re dynamic. 4- Deterministre or Non-deterministre If the next state of the environment 1s completely determined by the corrent clate and the actions of the agent, then the environment is deterministre ; otherwise it is boo-deterministic Episodic on sequential. In an episodic environment, each ispisodic of events considered the acting of the action the acting of the quality of the extron depends just ion the episodic i heeff. Single agent or Multiple agents:
The covironment may contain single
agent or other agents which may
be of the same or different kind as that of the agent.

Decessible or Inaccessible: The agent's sencory apparatus can have access to the complete state of the environment, then the environment is accessible to that agent

Working: Scarch internet for AI based application & In following scenarios and identity who is agent for that application Further list out PEAS descriptors for agent environment in each of the Autonomous Conar Rover 2. Deep Blue Checs playing computer system 3. Eliza the natural language processing computer program created from 1964 to 1966 at the MIT Artifical Intelligence laboratory by Joseph Weizenbaum. 4. Automotic Portfolio management. 5. sophia is a social humanoid vabot dereloped by Hong kong based company Honson Robotics. Alphaba 15 a computer program that plays the board game Go. It was. developed by Alphabet lab on london. 3 Apple virtual assistance siri 2. Endurance: A componion for Dementia 9. Casper: Helping Incomnace yet through the
16- Marvel: yearding the Galaxing with Night Comic Book Crossovers II Automated cross word solver. Resources: The above dragrams are taken from ontroe tutorial available at tutorials

points on topic AI- Agents and Environment