Guide of Use for the Feature Cube framework

This is a guide for using the whole-slide image (WSI) classifier, based on the feature cube framework, located in the /vast/update_wsi_classifier/3class/, accessed by the Ubunturunning servers 219.252.39.225 and 219.252.39.226.

The framework has 2 main modes: training and production. The training mode consists of training and testing the WSI classifier, while the production mode consists of applying the framework to a list of whole slides and saving the results in a database.

Requirements

```
numpy==1.21.4
tqdm==4.62.3
scikit-image==0.19.1
torch==1.10.1+cu113
torchvision==0.11.2+cu113
pymysql==1.0.2
pandas==1.3.5
pillow==7.0.0
```

Training

To train the WSI classifier simply run python train_wsi_classifier.py in the command line.

- The configuration file is located at src/training/train config.py.
- The list of slides should be stored as a .csv file as follows:

file	label	mode	path
name of the file	N, D, or M	train, val, or test	path of the slide
2019S003993001	D	test	slides/stomach/original/D/2019S003993001.mrxs

- Samples codes demonstrating how to store the paths as shown are located at save_stomach_slide_distribution.py and save_colon_slide_distribution.py.
- The patch-level classifier is located at lossdiff/merged_{x}_lossdif_balanced.pkl, where {x} is either colon or stomach. These models are based on torchvision.models.densenet201().

The file train wsi classifier.py runs 4 key functions:

- **extract_patches** (located in src/extract_patches) saves the patches extracted from slide distribution path to tile dir.
 - o **slide_distribution_path:** (str) path to the slide distribution file (.csv).
 - o **tile_dir:** (str) directory in which the patches are saved.
 - o **tile_size:** (int) size of the patches. The patches are meant to be squared (e.g., 256x256), therefore only one number is required.
 - o **overlap**: (int) number of pixels to be overlapped.
 - o **resolution_factor:** (int) zoom level in which the patches are going to be extracted.
 - o **tile_ext:** (str) extension for the patches (e.g., jpg or png).
 - o **limit_bounds:** (bool) True to render only the non-empty slide region.
 - o workers: (int) number of workers for the multi-processed tiler.
- **generate_feature_cubes** (located in src/generate_feature_cubes) converts the slides (being patched) to feature cubes. The feature cubes are saved into three folders:

```
{feature_cube_path}/train, {feature_cube_path}/val, and
{feature cube path}/test.
```

- o **slide_distribution_path:** (str) path to the slide distribution file (.csv).
- patch_classifier_path: (str) path to the patch classifier. By default the classifier is located at lossdiff/merged_{x}_lossdif_balanced.pkl, where {x} is either colon or stomach. These models are based on torchvision.models.densenet201()
- o **tile dir:** (str) path to the patches.
- o **feature_cube_path**: (str) path where the feature cubes are saved.
- o **lsize:** (int) length of the feature cube.
- o **csize**: (int) channels (depth) of the feature cube.
- o **batch_size**: (int) number of instances in a training batch.
- o **tile_size:** (int) dimension of the patch.
- o **resolution_factor:** (int) zoom level in which the patches are going to be extracted.
- o **overlap**: (int) number of pixels to be overlapped.
- o **already_patched:** (bool) True if you wish to extract patches again. False by default.
- **train_classifier** (located in src/training/train_slide_classifier) ****trains a model using the feature cube approach. **This function returns**

```
torchvision.models.densenet201().
```

- o **diagnosis:** (list) List of classes. E.g., D, M, and N.
- o **model_path:** (str) path where the model is saved.

- o data_path: (str) path where the feature cubes are located.
- o **batch_size:** (int) number of instances in a training batch.
- o **num_epochs**: (int) number of epochs.
- o **lr:** (float) learning rate.
- o **dropout**: (bool) True if you wish to apply dropout.
- **test_classifier** (located in src.training/train_slide_classifier) tests the model once it is trained.
 - o **model:** (torchvision.models.densenet201()) the model that was returned from train_classifier.
 - o **diagnosis**: (list) list of classes. By default: [D, M, N].
 - o **data_patch**: (str) path where the feature cubes are located.
 - o **batch_size:** (int) number of instances in a test batch.

Production

To use the feature cube framework and save the results in a database simply run python main.py in the command line.

- The configuration file is located at project config.py
- By default, the slides should be stored under a directory named /test/, this can be changed in project_config.py

```
EXAMPLE:
test/
|-- 2019S003993001
|-- 2019S003993002
|-- 2019S003993003
```

• The configuration of the database is located in project config.py:

```
mariadb = {
    "host": "219.252.39.14",
    "user": "root",
    "password": "seegeneai2020",
    "db": "digital_pathology",
}
```

• The patch-level classifier is located at lossdiff/merged_{x}_lossdif_balanced.pkl, where {x} is either colon or stomach. Keep in mind that this model is based on

```
torchvision.models.densenet201()
```

• The slide-level classifier is located at models/{x}/slide_classifier/{version}/slide_classifier.pt, where {x} is either color or stomach, and {version} is the version of the model. The models are based on torchvision.models.densenet201().

The file main.py consists of two main steps: step 2 and step 3. Step 1, binary classifier, has been discontinued.

- In step 2 the feature cubes are generated for a single whole slide using the patch classifier. The source code is located in src/production/step2_patch_level_3class_classifier.
- In step 3 the slide-level prediction is done by the slide classifier and saved in the database. The source code is located in src/production/step3_slide_level_3class_classifier.
- Step 2 and step 3 are run in a loop until all the slides in the dataset are assessed.

The following is a simplified pseudo-code of main.py