



Conditional Random Field

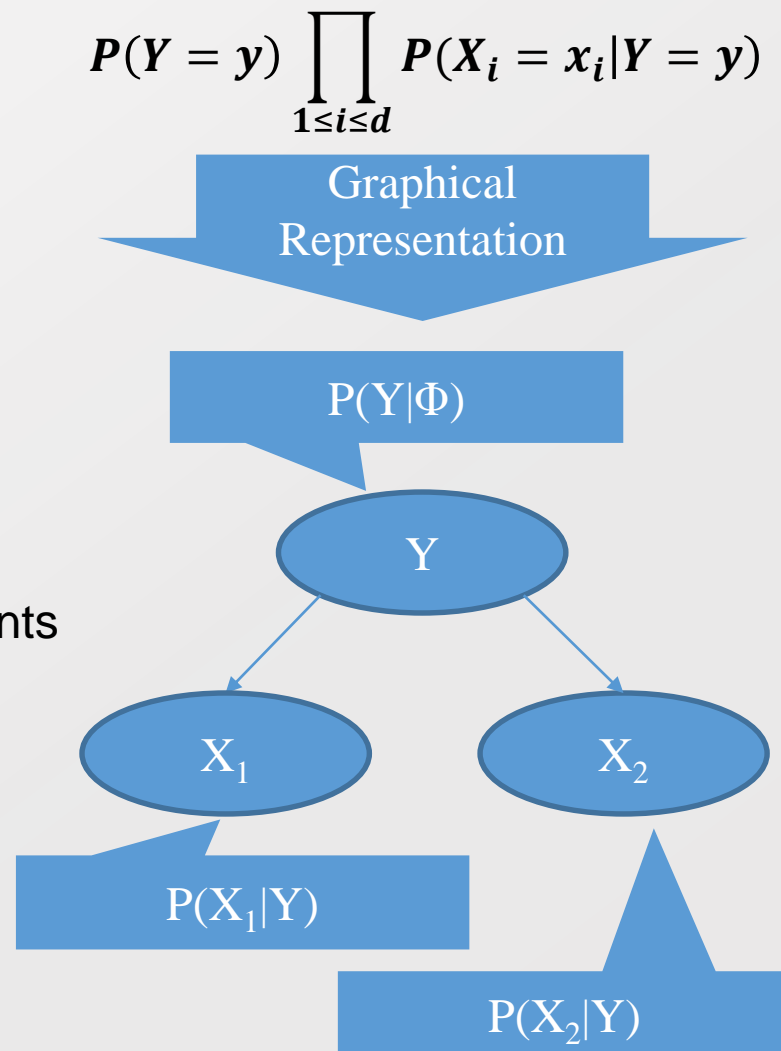
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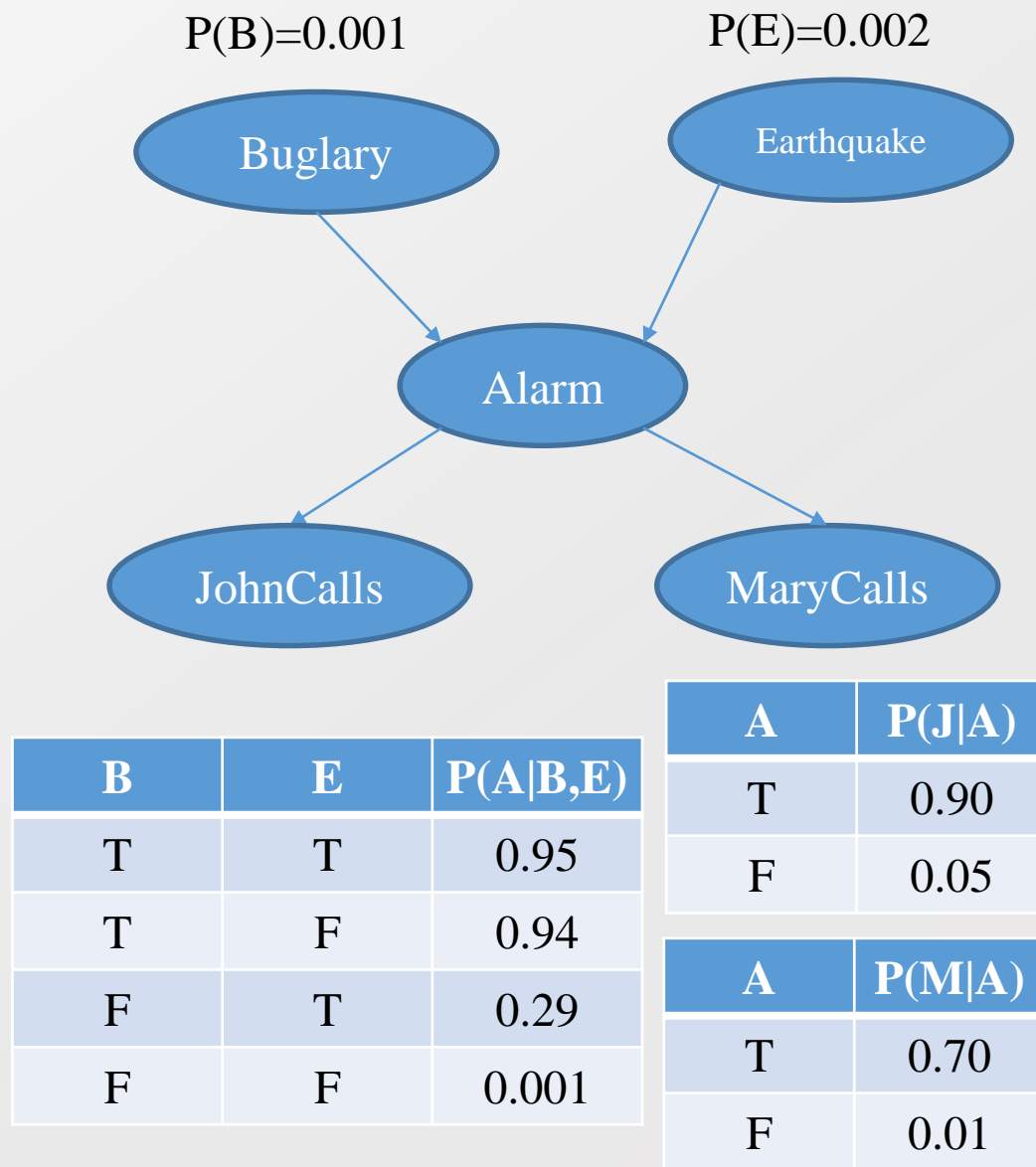
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- A graphical notation of
 - Random variables
 - Conditional independence
 - To obtain a compact representation of the full joint distributions
- Syntax
 - A acyclic and directed graph
 - A set of nodes
 - A random variable
 - A conditional distribution given its parents
 - $P(X_i | \text{Parents}(X_i))$
 - A set of links
 - Direct influence from the parent to the child

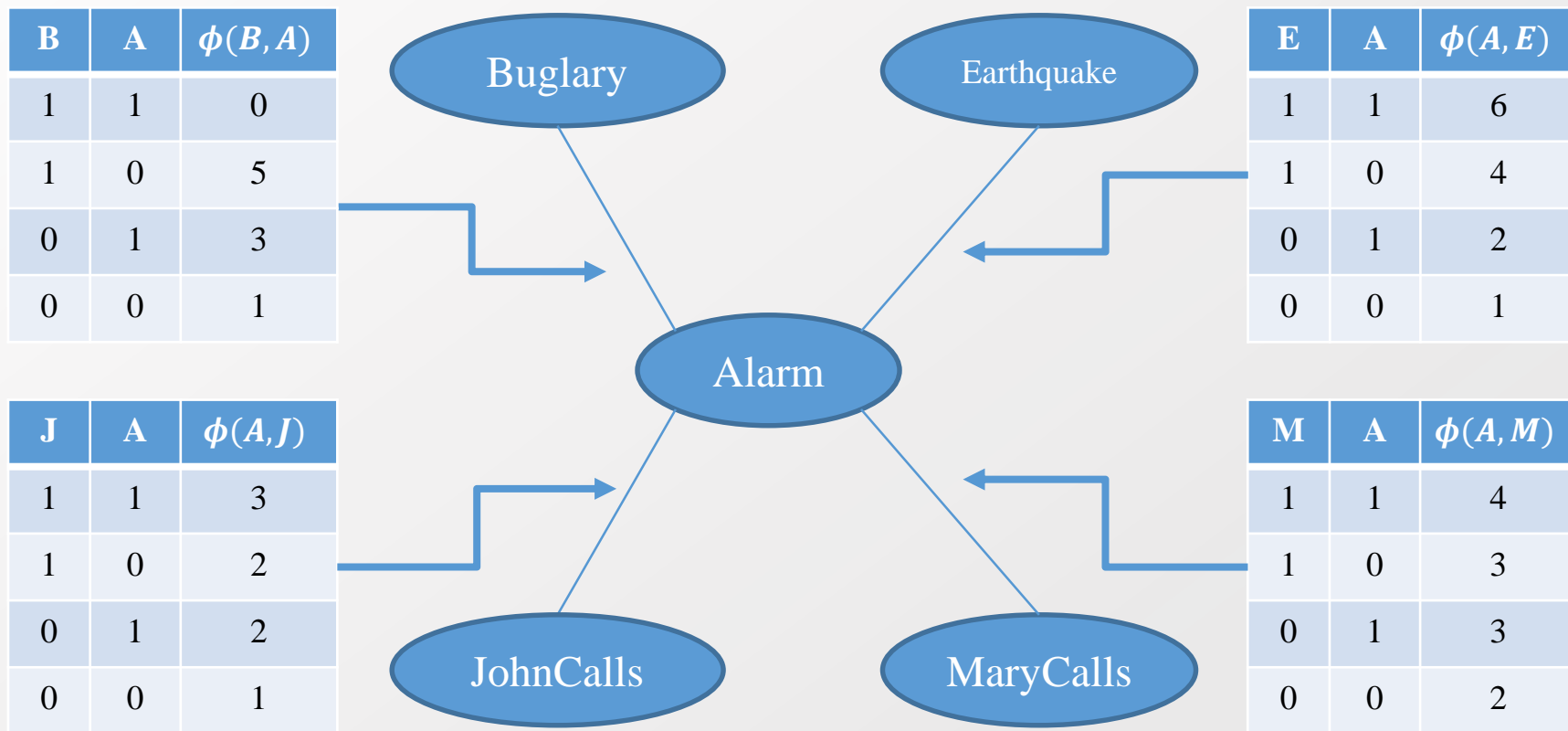


Detour: Components of Bayesian Network

- Qualitative components
 - Prior knowledge of causal relations
 - Learning from data
 - Frequently used structures
 - Structural aspects
- Quantitative components
 - Conditional probability tables
 - Probability distribution assigned to nodes
- Probability computing is related to both
 - Quantitative and Qualitative



Undirected Graphical Model



- Full joint distribution

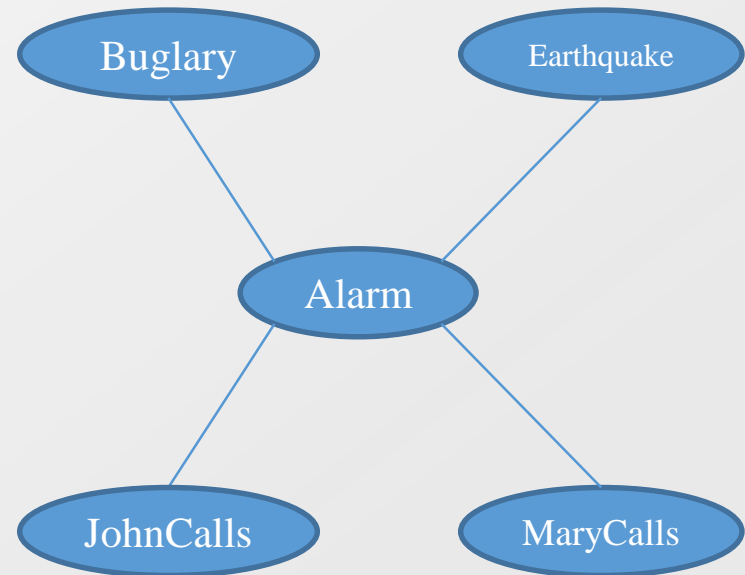
- $$P(B, E, A, J, M) = \frac{\phi(A, B)\phi(A, E)\phi(A, J)\phi(A, M)}{\sum_{A, B, E, J, M} \phi(A, B)\phi(A, E)\phi(A, J)\phi(A, M)} = \frac{\phi(A, B)\phi(A, E)\phi(A, J)\phi(A, M)}{Z}$$

- Markov random field
 - A probability distribution p over variables $x_1 \dots x_n$ defined by an undirected graph G in which nodes correspond to variable x_i .

$$p(x_1 \dots x_n) = \frac{1}{Z} \prod_{c \in C} \phi_c(x_c)$$

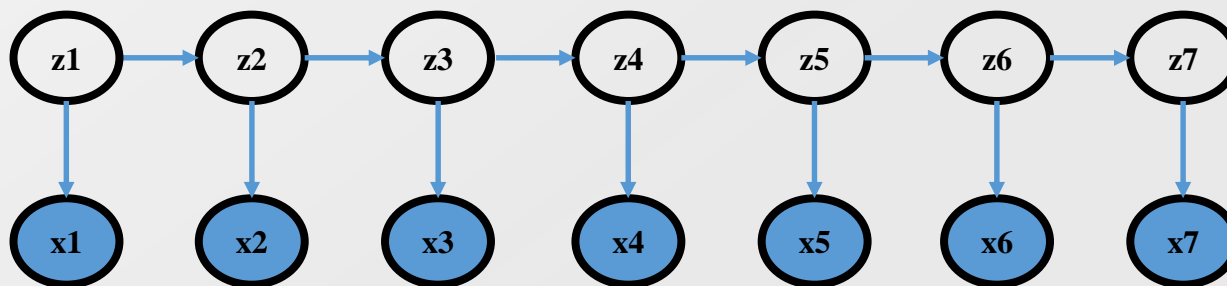
- Here, C is the set of cliques of G .
 - Edge is a minimum form of clique with two nodes
- ϕ_c is a nonnegative function over the variables in a clique.
- Z is the partition function to normalize.

$$Z = \sum_{x_1 \dots x_n} \prod_{c \in C} \phi_c(x_c)$$



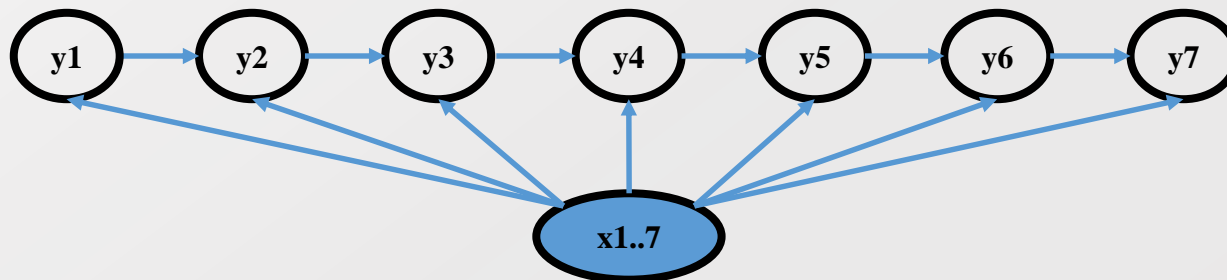
$$\begin{aligned} P(B, E, A, J, M) &= \frac{\phi(A, B)\phi(A, E)\phi(A, J)\phi(A, M)}{\sum_{A, B, E, J, M} \phi(A, B)\phi(A, E)\phi(A, J)\phi(A, M)} \\ &= \frac{\phi(A, B)\phi(A, E)\phi(A, J)\phi(A, M)}{Z} \end{aligned}$$

- Hidden Markov model captures limited dependencies
 - State at the current time to Observation at the current time
 - State at the previous time to State at the current time
 - Only forward dependencies in the state
- Hidden Markov model is a generative model that could be used for a classification task
 - HMM maximizes the likelihood of $P(X, Z)$
 - Classification task optimizes $P(Z|X)$ instead of $P(X, Z)$

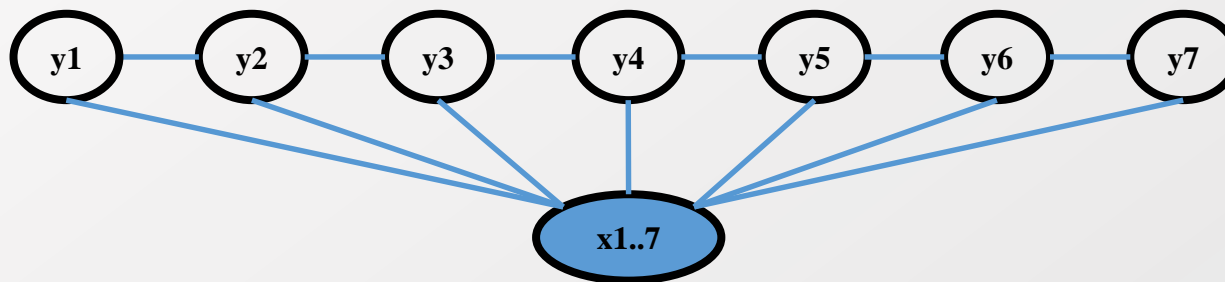


- MEMM captures dependencies
 - Observation from all time to State at the current time
 - Only forward dependencies in the state
- MEMM is a discriminative model for a classification task
 - MEMM optimizes $P(Z|X)$
- However, the formulation includes a new function of $f(y_i, y_{i-1}, X_{1:n})$
 - Potential function!

$$P(Y_{1:n}|X_{1:n}) = \prod_{i=1}^n P(y_i|y_{i-1}, X_{1:n}) = \prod_{i=1}^n \frac{\exp(w^T f(y_i, y_{i-1}, X_{1:n}))}{\sum_{y_j} \exp(w^T f(y_j, y_{i-1}, X_{1:n}))} = \prod_{i=1}^n \frac{\exp(w^T f(y_i, y_{i-1}, X_{1:n}))}{Z(y_{i-1}, X_{1:n})}$$



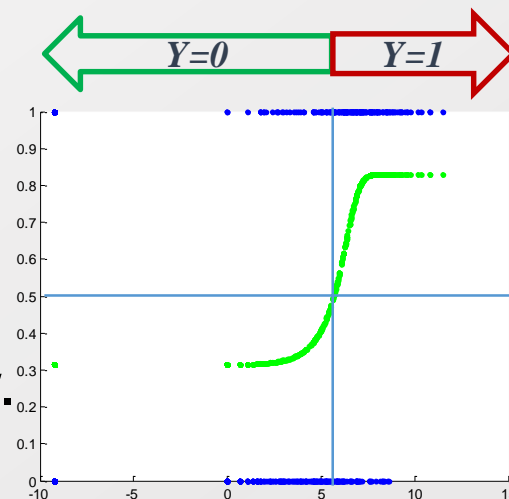
- Conditional random field defines
 - The potential function between state transitions
 - The potential function between the state and the observations



$$\begin{aligned} P(Y_{1:n}|X_{1:n}) &= \frac{1}{Z(\lambda, \mu, X_{1:n})} \prod_{i=1}^n \phi(y_i, y_{i-1}, X_{1:n}) \\ &= \frac{1}{Z(\lambda, \mu, X_{1:n})} \exp\left(\sum_{i=1}^n \left(\sum_k \lambda_k f_k(y_i, y_{i-1}, X_{1:n}) + \sum_l \mu_l g_l(y_i, X_{1:n})\right)\right) \\ Z(\lambda, \mu, X_{1:n}) &= \sum_{Y_{1:n}} \exp\left(\sum_{i=1}^n \left(\sum_k \lambda_k f_k(y_i, y_{i-1}, X_{1:n}) + \sum_l \mu_l g_l(y_i, X_{1:n})\right)\right) \end{aligned}$$

Detour: Logistic Regression

- Logistic regression is a probabilistic classifier to predict the binomial or the multinomial outcome
 - by fitting the conditional probability to the logistic function.
- You can see the problem from the different view.
 - This way is actually closer to the formal definition.
- Given the Bernoulli experiment
 - $P(y|x) = \mu(x)^y (1 - \mu(x))^{1-y}$
 - $\mu(x) = \frac{1}{1+e^{-\theta^T x}} = P(y = 1|x)$
 - Here, $\mu(x)$ is the logistic function
- From the previous slide,
 - $X\theta = \log\left(\frac{P(Y|X)}{1-P(Y|X)}\right) \rightarrow P(Y|X) = \frac{e^{X\theta}}{1+e^{X\theta}}$



Logistic Function

$$f(x) = \frac{1}{1 + e^{-x}}$$

The goal, finally, becomes finding out θ , again

- $$P(Y_{1:n}|X_{1:n}) = \frac{1}{Z(\lambda, \mu, X_{1:n})} \prod_{i=1}^n \phi(y_i, y_{i-1}, X_{1:n})$$

$$= \frac{1}{Z(\lambda, \mu, X_{1:n})} \exp\left(\sum_{i=1}^n \left(\sum_k \lambda_k f_k(y_i, y_{i-1}, X_{1:n}) + \sum_l \mu_l g_l(y_i, X_{1:n})\right)\right)$$

- Assume that

- y is a single dimension
 - $X_{1:n}$ has a binary value for each X_i
 - f_k is an indicator feature function as $f_k = \mathbf{1}_{X_i=1, y=1}$

- Then, the conditional random field becomes

- $$P(Y = 1|X_{1:n}) = \frac{1}{Z(\lambda, \mu, X_{1:n})} \exp\left(\sum_{i=1}^n \lambda_k \mathbf{1}_{X_i=1, y=1}\right)$$

$$= \frac{\exp\left(\sum_{i=1}^n \lambda_k \mathbf{1}_{X_i=1, y=1}\right)}{\exp\left(\sum_{i=1}^n \lambda_k \mathbf{1}_{X_i=1, y=0}\right) + \exp\left(\sum_{i=1}^n \lambda_k \mathbf{1}_{X_i=1, y=1}\right)}$$

$$= \frac{\exp(\sum_{i=1}^n \lambda_k X_i)}{\exp(0) + \exp(\sum_{i=1}^n \lambda_k X_i)} = \frac{\exp(\sum_{i=1}^n \lambda_k X_i)}{1 + \exp(\sum_{i=1}^n \lambda_k X_i)} = \frac{1}{1 + \exp(\sum_{i=1}^n -\lambda_k X_i)}$$

- Exponential Family

$$\text{Conditional Random Field : } P(Y_{1:n}|X_{1:n}) = \frac{1}{Z(\lambda, \mu, X_{1:n})} \exp(\sum_{i=1}^n (\sum_k \lambda_k f_k(y_i, y_{i-1}, X_{1:n}) + \sum_l \mu_l g_l(y_i, X_{1:n})))$$

- $P(x|\theta) = h(x) \exp(\eta(\theta) \cdot T(x) - A(\theta))$

- Sufficient statistics : $T(x)$, Natural parameter : $\eta(\theta)$

- Underlying measure : $h(x)$, Log normalizer : $A(\theta)$

- Normal Distribution : $P(x|\mu, \sigma) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp(-\frac{(x-\mu)^2}{2\sigma^2})$

- Sufficient statistics : $(x, x^2)^T$, Natural parameter : $(\frac{\mu}{\sigma^2}, -\frac{1}{2\sigma^2})^T$

- Underlying measure : $\frac{1}{\sqrt{2\pi}}$, Log normalizer : $\frac{\mu^2}{2\sigma^2} + \log |\sigma|$

- Dirichlet Distribution : $P(x_1, \dots, x_K | \alpha_1, \dots, \alpha_K) = \frac{\Gamma(\sum_{i=1}^K \alpha_i)}{\prod_{i=1}^K \Gamma(\alpha_i)} x_i^{\alpha_i - 1}$

- Sufficient statistics : $(\log x_1, \dots, \log x_K)^T$, Natural parameter : $(\alpha_1 - 1, \dots, \alpha_K - 1)^T$

- Underlying measure : 1, Log normalizer : $-\log \Gamma(\sum_{i=1}^K \alpha_i) + \log \prod_{i=1}^K \Gamma(\alpha_i)$

- Derivative of log normalizer \rightarrow Moments of sufficient statistics

- $$\begin{aligned} \frac{d}{d\eta} a(\eta) &= \frac{d}{d\eta} \log \int h(x) \exp\{\eta^T T(x)\} dx = \frac{\int T(x) h(x) \exp\{\eta^T T(x)\} dx}{\int h(x) \exp\{\eta^T T(x)\} dx} \\ &= \frac{\int T(x) h(x) \exp\{\eta^T T(x)\} dx}{\exp(a(\eta))} = \int T(x) h(x) \exp\{\eta^T T(x) - a(\eta)\} dx \end{aligned}$$

- In supervised learning, the pair of $X_{1:n}$ and $Y_{1:n}$ are provided
 - Need to maximize $P(Y_{1:n}|X_{1:n})$ by adjusting CRF parameters

$$\begin{aligned} P(x|\theta) \\ &= h(x) \exp(\eta(\theta) \cdot T(x) - A(\theta)) \end{aligned}$$

- $\lambda^*, \mu^* = \operatorname{argmax}_{\lambda, \mu} L(\lambda, \mu) = \operatorname{argmax}_{\lambda, \mu} \prod_{d \in D} P(Y_{d,1:n} | X_{d,1:n}; \lambda, \mu)$

$$\begin{aligned} &= \operatorname{argmax}_{\lambda, \mu} \prod_{d \in D} \frac{1}{Z(\lambda, \mu, X_{d,1:n})} \exp\left(\sum_{i=1}^n \left(\sum_k \lambda_k f_k(y_{d,i}, y_{d,i-1}, X_{d,1:n}) + \sum_l \mu_l g_l(y_{d,i}, X_{d,1:n})\right)\right) \\ &= \operatorname{argmax}_{\lambda, \mu} \sum_{d \in D} \left[\sum_{i=1}^n \left(\sum_k \lambda_k f_k(y_{d,i}, y_{d,i-1}, X_{d,1:n}) + \sum_l \mu_l g_l(y_{d,i}, X_{d,1:n}) \right) - \log Z(\lambda, \mu, X_{d,1:n}) \right] \end{aligned}$$

- Simple gradient method can be applied to the objective function

- $\nabla_{\lambda_k} L(\lambda, \mu) = \sum_{d \in D} \left[\sum_{i=1}^n \lambda_k f_k(y_{d,i}, y_{d,i-1}, X_{d,1:n}) - \frac{d}{d\lambda_k} \log Z(\lambda, \mu, X_{d,1:n}) \right]$

- $\frac{d}{d\lambda_k} \log Z(\lambda, \mu, X_{d,1:n}) = E_{P(Y_{d,1:n} | X_{d,1:n}; \lambda, \mu)} \left[\sum_{i=1}^n \sum_k f_k(y_i, y_{i-1}, X_{1:n}) \right]$

- $\because \frac{d}{d\eta} a(\eta) = E_P[T(x)]$

- $\nabla_{\lambda_k} L(\lambda, \mu) = \sum_{d \in D} \left[\sum_{i=1}^n \lambda_k f_k(y_{d,i}, y_{d,i-1}, X_{d,1:n}) - \sum_{Y_{d,1:n}} P(Y_{d,1:n} | X_{d,1:n}; \lambda, \mu) \sum_{i=1}^n \sum_k f_k(y_i, y_{i-1}, X_{1:n}) \right]$
- $= \sum_{d \in D} \left[\sum_{i=1}^n \lambda_k f_k(y_{d,i}, y_{d,i-1}, X_{d,1:n}) - \sum_{Y_{d,1:n}} P(Y_{d,1:n} | X_{d,1:n}; \lambda, \mu) \sum_{i=1}^n \sum_k f_k(y_i, y_{i-1}, X_{1:n}) \right]$
- $= \sum_{d \in D} \left[\sum_{i=1}^n \lambda_k f_k(y_{d,i}, y_{d,i-1}, X_{d,1:n}) - \sum_{i=1}^n \sum_{y_{d,i}, y_{d,i-1}} \sum_k P(Y_{d,1:n} | X_{d,1:n}; \lambda, \mu) f_k(y_i, y_{i-1}, X_{1:n}) \right]$

- Similarity on model structure
 - Neuron with logistic activation function == Logistic regression
 - CRF with assumptions == Logistic regression
- Similarity on model inference
 - Neuron with gradient descent
 - CRF with gradient descent
- Two models are easily interoperable and inferred together

