

# MUDANÇA DE VARIÁVEIS · COORDENADAS: POLARES; CILÍNDRICAS; E ESFÉRICAS.

## (I) TEOREMA DE JACOBI (1804-1851) · [MUDANÇA DE VARIÁVEIS EM INTEGRAIS DUPLAS].

Seja  $x(u,v)$  e  $y(u,v)$  uma mudança de variáveis, invertível, com derivadas parciais de 1ª ordem  $\frac{\partial x}{\partial u}$ ,  $\frac{\partial x}{\partial v}$ ,  $\frac{\partial y}{\partial u}$  e  $\frac{\partial y}{\partial v}$ , contínuas, a qual transforme uma região  $S$ , no plano- $uv$ , numa região  $R$ , no plano- $xy$ ; então:  $\iint_R f(x,y) dy dx = \iint_S f(x(u,v), y(u,v)) \left| \frac{\partial(x,y)}{\partial(u,v)} \right| dv du$ , onde  $\frac{\partial(x,y)}{\partial(u,v)} = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{vmatrix} \neq 0$  e não muda de sinal em  $S$ ;

## (II) APLICAÇÃO · MUDANÇA DE COORDENADAS CARTESIANAS PARA COORDENADAS POLARES.

Temos:  $x(r,\theta) = r \cos \theta$  e  $y(r,\theta) = r \sin \theta$ ; Logo:  $\frac{\partial(x,y)}{\partial(r,\theta)} = \begin{vmatrix} \frac{\partial x}{\partial r} & \frac{\partial x}{\partial \theta} \\ \frac{\partial y}{\partial r} & \frac{\partial y}{\partial \theta} \end{vmatrix} = \begin{vmatrix} \cos \theta & -r \sin \theta \\ \sin \theta & r \cos \theta \end{vmatrix} = r \cos^2 \theta + r \sin^2 \theta = r$ ;

Logo:  $\iint_R f(x,y) dy dx = \iint_S f(x(r,\theta), y(r,\theta)) \left| \frac{\partial(x,y)}{\partial(r,\theta)} \right| dr d\theta = \iint_S f(r \cos \theta, r \sin \theta) |r| dr d\theta$ ;

EXEMPLOS. Em cada caso, faça a mudança de coordenadas cartesianas para polares e calcule a integral:

$$\textcircled{a} \int_{-a}^a \int_{-\sqrt{a^2-x^2}}^{\sqrt{a^2-x^2}} e^{-x^2-y^2} dy dx = \int_0^{2\pi} \int_0^a e^{-(r \cos \theta)^2 - (r \sin \theta)^2} |r| dr d\theta = \int_0^{2\pi} \int_0^a e^{-r^2} r dr d\theta = -\frac{1}{2} \int_0^{2\pi} \int_0^a e^{-r^2} (-2r dr) d\theta =$$

$$= -\frac{1}{2} \int_0^{2\pi} \left[ e^{-r^2} \right]_0^a d\theta = -\frac{1}{2} \int_0^{2\pi} (e^{-a^2} - e^0) d\theta = \frac{(1 - e^{-a^2})}{2} \int_0^{2\pi} d\theta = \frac{(1 - e^{-a^2})}{2} \theta \Big|_0^{2\pi} = (1 - e^{-a^2}) \pi;$$

$$\textcircled{b} \int_{-3}^3 \int_0^{\sqrt{9-x^2}} dy dx = \int_0^{\pi} \int_0^3 |r| dr d\theta = \int_0^{\pi} \left[ \frac{1}{2} r^2 \right]_0^3 d\theta = \int_0^{\pi} \frac{1}{2} (3^2 - 0^2) d\theta = \frac{9}{2} \int_0^{\pi} d\theta = \frac{9}{2} \theta \Big|_0^{\pi} = \frac{9\pi}{2};$$



Quando devemos mudar de coordenadas cartesianas para coordenadas polares? A resposta a esta pergunta é: (i) quando a região de integração for o interior, ou parte do interior, de uma circunferência; ou (ii) quando a expressão " $x^2+y^2$ " fizer parte da definição de  $f(x,y)$ ;

Vejam os mais um exemplo:

$$\begin{aligned} \textcircled{c} \int_0^{\sqrt{2}} \int_y^{\sqrt{4-y^2}} \frac{1}{1+\sqrt{x^2+y^2}} dx dy &= \int_0^{\pi/4} \int_0^2 \frac{1}{1+r} \cdot r dr d\theta = \int_0^{\pi/4} \int_0^2 \frac{r}{1+r} dr d\theta = \int_0^{\pi/4} \int_0^2 \left[ 1 - \frac{1}{1+r} \right] dr d\theta = \\ &= \int_0^{\pi/4} (r - \ln(1+r)) \Big|_0^2 d\theta = \int_0^{\pi/4} [(2 - \ln 3) - (0 - \ln 1)] d\theta = (2 - \ln 3) \int_0^{\pi/4} d\theta = \\ &= (2 - \ln 3) \theta \Big|_0^{\pi/4} = (2 - \ln 3) \left( \frac{\pi}{4} - 0 \right) = \frac{(2 - \ln 3)\pi}{4}; \end{aligned}$$

(III) TEOREMA DE JACOBI. [MUDANÇA DE VARIÁVEIS EM INTEGRAIS TRIPLAS].

Seja  $x(u,v,w)$ ;  $y(u,v,w)$ ; e  $z(u,v,w)$ ; uma mudança de variáveis, invertível, com derivadas parciais de 1ª ordem  $\frac{\partial x}{\partial u}$ ,  $\frac{\partial x}{\partial v}$ ,  $\frac{\partial x}{\partial w}$ ,  $\frac{\partial y}{\partial u}$ ,  $\frac{\partial y}{\partial v}$ ,  $\frac{\partial y}{\partial w}$ ,  $\frac{\partial z}{\partial u}$ ,  $\frac{\partial z}{\partial v}$  e  $\frac{\partial z}{\partial w}$ , contínuas, a qual transforme uma região

$G$ , no espaço- $uvw$ , numa região  $S$  no espaço- $xyz$ , então:

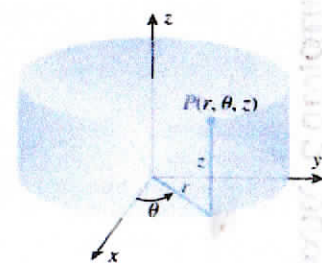
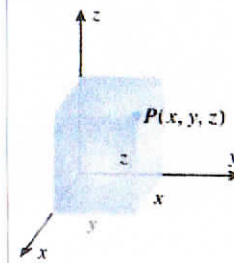
$$\iiint_S f(x,y,z) dz dy dx = \iiint_G f(x(u,v,w), y(u,v,w), z(u,v,w)) \cdot \left| \frac{\partial(x,y,z)}{\partial(u,v,w)} \right| du dv dw, \text{ onde: } \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} & \frac{\partial x}{\partial w} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} & \frac{\partial y}{\partial w} \\ \frac{\partial z}{\partial u} & \frac{\partial z}{\partial v} & \frac{\partial z}{\partial w} \end{vmatrix} \neq 0 \text{ e não muda de sinal em } G;$$

(IV) APLICAÇÃO. MUDANÇA DE COORDENADAS CARTESIANAS PARA COORDENADAS CILÍNDRICAS.

A Figura ao lado, esclarece bem as relações entre as coordenadas cartesianas  $x, y$  e  $z$  e as coordenadas cilíndricas  $r, \theta$  e  $z$ ; no plano- $xy$  as relações entre  $x$  e  $y$  e  $r$  e  $\theta$  são as mesmas das coordenadas polares, ou seja:

$x = r \cos \theta$  e  $y = r \sin \theta$ ; e como  $z = z$ , em coordenadas cilíndricas, temos:

$$x(r, \theta, z) = r \cos \theta; \quad y(r, \theta, z) = r \sin \theta; \quad \text{e} \quad z(r, \theta, z) = z;$$



$$\text{Logo: } \frac{\partial(x, y, z)}{\partial(r, \theta, z)} = \begin{vmatrix} \frac{\partial x}{\partial r} & \frac{\partial x}{\partial \theta} & \frac{\partial x}{\partial z} \\ \frac{\partial y}{\partial r} & \frac{\partial y}{\partial \theta} & \frac{\partial y}{\partial z} \\ \frac{\partial z}{\partial r} & \frac{\partial z}{\partial \theta} & \frac{\partial z}{\partial z} \end{vmatrix} = \begin{vmatrix} \cos \theta & -r \sin \theta & 0 \\ \sin \theta & r \cos \theta & 0 \\ 0 & 0 & 1 \end{vmatrix} = r \cos^2 \theta + r \sin^2 \theta = r;$$

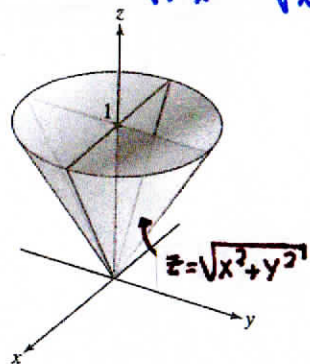
$$\text{Então, } \iiint_S F(x, y, z) dz dy dx = \iiint_G F(r \cos \theta, r \sin \theta, z) r dr dz d\theta;$$

Devemos mudar de coordenadas cartesianas  $x, y$  e  $z$  para as coordenadas cilíndricas  $r, \theta$  e  $z$ , quando a região de integração  $S$  for um interior, ou parte, do interior de um cilindro, ou, quando a expressão " $x^2 + y^2$ " fizer parte da definição de  $F(x, y, z)$ ; vejamos exemplos:

(d)  $\int_{-1}^1 \int_{-\sqrt{1-x^2}}^{\sqrt{1-x^2}} \int_{\sqrt{x^2+y^2}}^1 (x^2+y^2)^{3/2} dz dy dx = \int_0^{2\pi} \int_0^1 \int_r^1 (r^2)^{3/2} r dr dz d\theta = \int_0^{2\pi} \int_0^1 r^3 \cdot r dz dr d\theta = \int_0^{2\pi} \int_0^1 r^4 dz dr d\theta =$

$$= \int_0^{2\pi} \int_0^1 r^4 z \Big|_r^1 dr d\theta = \int_0^{2\pi} \int_0^1 r^4 (1-r) dr d\theta = \int_0^{2\pi} \left( \frac{r^5}{5} - \frac{r^6}{6} \right) \Big|_0^1 d\theta =$$

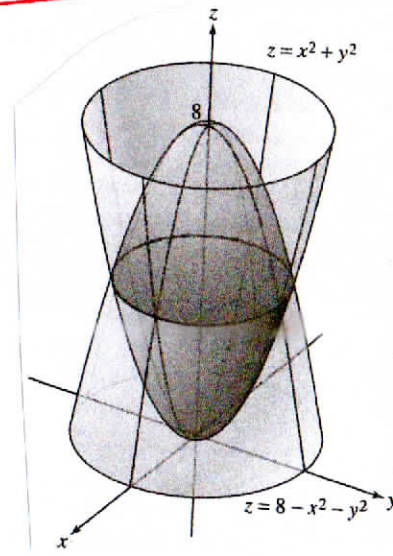
$$= \int_0^{2\pi} \left[ \left( \frac{1}{5} - \frac{1}{6} \right) - (0-0) \right] d\theta = \frac{(6-5)}{30} \int_0^{2\pi} d\theta = \frac{1}{30} \theta \Big|_0^{2\pi} = \frac{1}{30} (2\pi - 0) = \frac{\pi}{15};$$



(e)  $\int_{-2}^2 \int_{-\sqrt{4-x^2}}^{\sqrt{4-x^2}} \int_{x^2+y^2}^{8-x^2-y^2} dz dy dx = \int_0^{2\pi} \int_0^2 \int_{r^2}^{8-r^2} r dr dz d\theta = \int_0^{2\pi} \int_0^2 r \int_{r^2}^{8-r^2} dz dr d\theta =$

$$= \int_0^{2\pi} \int_0^2 r (8-r^2-r^2) dr d\theta = \int_0^{2\pi} \int_0^2 (8r-2r^3) dr d\theta = \int_0^{2\pi} \left( 4r^2 - \frac{r^4}{2} \right) \Big|_0^2 d\theta =$$

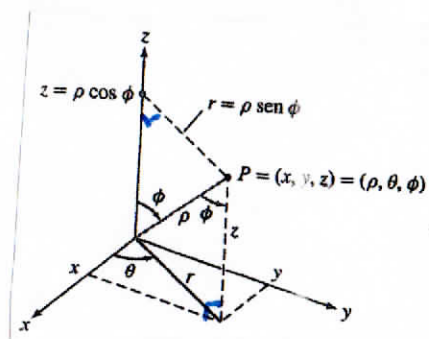
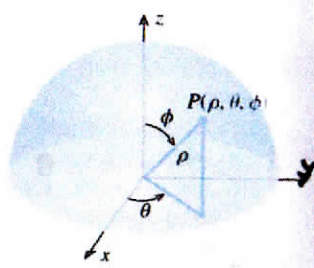
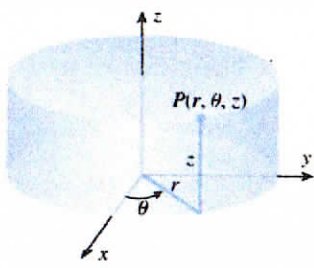
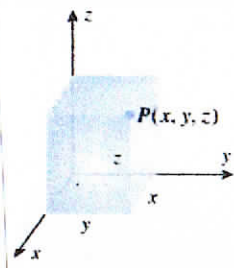
$$= \int_0^{2\pi} [(16-8) - (0-0)] d\theta = 8 \int_0^{2\pi} d\theta = 8 \theta \Big|_0^{2\pi} = 8(2\pi - 0) = 16\pi;$$





## (V) APLICAÇÃO. MUDANÇA DE COORDENADAS CARTESIANAS PARA COORDENADAS ESFÉRICAS.

As Figuras ao lado, mostram um mesmo ponto no espaço, representado em: coordenadas cartesianas  $x, y$  e  $z$ ; coordenadas cilíndricas  $\rho, \theta$  e  $z$ ; e coordenadas esféricas  $\rho, \theta$  e  $\phi$ ;



Já a Figura ao lado, esclarece bem as relações entre as coordenadas cartesianas  $x, y$  e  $z$  e as coordenadas esféricas  $\rho, \theta$  e  $\phi$ ;  $\rho$  é a distância do ponto  $(x, y, z)$  à origem  $(0, 0, 0)$ ; ou seja:  $\rho = \sqrt{x^2 + y^2 + z^2}$ ; já  $\theta$  continua sendo o mesmo ângulo, no plano- $xy$ , tanto das coordenadas polares, quanto das cilíndricas;  $0 \leq \theta \leq 2\pi$ ; a novidade é o ângulo  $\phi$ ; que é medido partindo do eixo- $z$  positivo, ou seja  $\phi = 0$ , e vai até o eixo- $z$  negativo, quando  $\phi = \pi$ ; portanto:  $0 \leq \phi \leq \pi$ ; se por  $P$  tiramos uma perpendicular ao eixo- $z$ , formamos um triângulo retângulo, com hipotenusa  $\rho$  e catetos:  $z = \rho \cos \phi$  e  $\rho = \rho \sin \phi$ ; e este  $\rho$  é o mesmo  $\rho$  de coordenadas polares; portanto:  $x = \rho \sin \phi \cos \theta$  e  $y = \rho \sin \phi \sin \theta$ ; temos portanto:  $x(\rho, \theta, \phi) = \rho \sin \phi \cos \theta$ ;  $y(\rho, \theta, \phi) = \rho \sin \phi \sin \theta$ ; e  $z(\rho, \theta, \phi) = \rho \cos \phi$ ; **Encontremos, então, o Jacobiano:**

$$\frac{\partial(x, y, z)}{\partial(\rho, \theta, \phi)} = \begin{vmatrix} \frac{\partial x}{\partial \rho} & \frac{\partial x}{\partial \theta} & \frac{\partial x}{\partial \phi} \\ \frac{\partial y}{\partial \rho} & \frac{\partial y}{\partial \theta} & \frac{\partial y}{\partial \phi} \\ \frac{\partial z}{\partial \rho} & \frac{\partial z}{\partial \theta} & \frac{\partial z}{\partial \phi} \end{vmatrix} = \begin{vmatrix} \sin \phi \cos \theta & -\rho \sin \phi \sin \theta & \rho \cos \phi \cos \theta \\ \sin \phi \sin \theta & \rho \sin \phi \cos \theta & \rho \cos \phi \sin \theta \\ \cos \phi & 0 & -\rho \sin \phi \end{vmatrix}; \text{ Ou seja:}$$

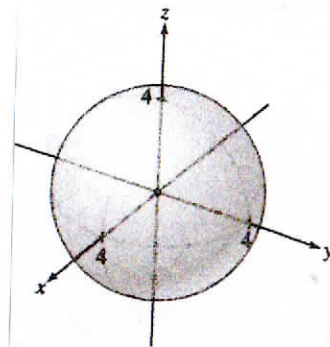
$$\frac{\partial(x, y, z)}{\partial(\rho, \theta, \phi)} = \cos \phi [(-\rho^2) \sin \phi \cos \phi (\sin^2 \theta + \cos^2 \theta)] + (-\rho \sin \phi) [\rho \sin^2 \phi (\cos^2 \theta + \sin^2 \theta)] = -\rho^2 \sin \phi (\cos^2 \phi + \sin^2 \phi) = -\rho^2 \sin \phi;$$

Logo,  $\left| \frac{\partial(x, y, z)}{\partial(\rho, \theta, \phi)} \right| = |-\rho^2 \sin \phi| = \rho^2 \sin \phi;$

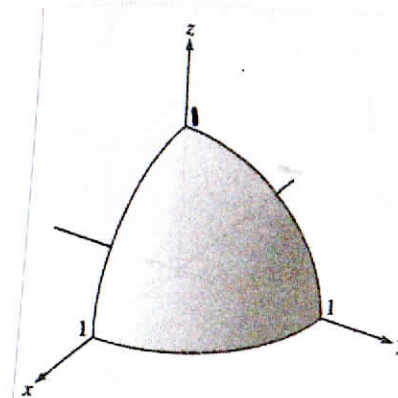
Então,  $\iiint_S F(x,y,z) dz dy dx = \iiint_G F(\rho \sin \phi \cos \theta, \rho \sin \phi \sin \theta, \rho \cos \phi) \rho^2 \sin \phi d\rho d\phi d\theta;$

Vejaamos exemplos:

$$\begin{aligned} (f) \int_{-4}^4 \int_{-\sqrt{16-x^2}}^{\sqrt{16-x^2}} \int_{-\sqrt{16-x^2-y^2}}^{\sqrt{16-x^2-y^2}} dz dy dx &= \int_0^{2\pi} \int_0^{\pi} \int_0^4 \rho^2 \sin \phi d\rho d\phi d\theta = \int_0^{2\pi} \int_0^{\pi} \sin \phi \int_0^4 \rho^2 d\rho d\phi d\theta = \int_0^{2\pi} \int_0^{\pi} \sin \phi \frac{\rho^3}{3} \Big|_0^4 d\phi d\theta = \\ &= \frac{64}{3} \int_0^{2\pi} \int_0^{\pi} \sin \phi d\phi d\theta = \frac{64}{3} \int_0^{2\pi} [-\cos \phi]_0^{\pi} d\theta = \frac{64}{3} (1 - (-1)) \int_0^{2\pi} d\theta = \frac{128}{3} \theta \Big|_0^{2\pi} = \frac{256\pi}{3}; \end{aligned}$$



$$\begin{aligned} (g) \int_0^1 \int_0^{\sqrt{1-x^2}} \int_0^{\sqrt{1-x^2-y^2}} \frac{1}{(1+x^2+y^2+z^2)} dz dy dx &= \int_0^{\pi/2} \int_0^{\pi/2} \int_0^1 \frac{1}{1+\rho^2} \cdot \rho^2 \sin \phi d\rho d\phi d\theta = \int_0^{\pi/2} \int_0^{\pi/2} \sin \phi \int_0^1 \frac{\rho^2}{1+\rho^2} d\rho d\phi d\theta = \\ &= \int_0^{\pi/2} \int_0^{\pi/2} \sin \phi \left( 1 - \frac{1}{1+\rho^2} \right) d\rho d\phi d\theta = \int_0^{\pi/2} \int_0^{\pi/2} \sin \phi (1 - \sec \phi) d\phi d\theta = \\ &= \int_0^{\pi/2} \int_0^{\pi/2} \sin \phi [(1 - \sec \phi) - (0 - \sec \phi \cdot 0)] d\phi d\theta = \\ &= \int_0^{\pi/2} \int_0^{\pi/2} \sin \phi (1 - \frac{\pi}{4}) d\phi d\theta = (1 - \frac{\pi}{4}) \int_0^{\pi/2} [-\cos \phi]_0^{\pi/2} d\theta = (1 - \frac{\pi}{4}) (0 - (-1)) \int_0^{\pi/2} d\theta = (1 - \frac{\pi}{4}) (\frac{\pi}{2}) = \frac{\pi}{2} - \frac{\pi^2}{8}; \end{aligned}$$



$$\begin{aligned} (h) \int_{-2}^2 \int_{-\sqrt{4-y^2}}^{\sqrt{4-y^2}} \int_0^{\sqrt{4-x^2-y^2}} \frac{1}{\sqrt{x^2+y^2+z^2}} dz dx dy &= \int_0^{2\pi} \int_0^{\pi/2} \int_0^2 \rho \sin \phi d\rho d\phi d\theta = \int_0^{2\pi} \int_0^{\pi/2} \sin \phi \int_0^2 \rho^2 d\rho d\phi d\theta = \\ &= \int_0^{2\pi} \int_0^{\pi/2} \sin \phi \frac{\rho^3}{3} \Big|_0^2 d\phi d\theta = \frac{8}{3} \int_0^{2\pi} [-\cos \phi]_0^{\pi/2} d\theta = \frac{8}{3} (0 - (-1)) \int_0^{2\pi} d\theta = \frac{16}{3} \theta \Big|_0^{2\pi} = \frac{32\pi}{3}; \end{aligned}$$

