## Definitions used in Brezis' Functional Analysis, Sobolev Spaces and Partial Differential Equations (first edition)

Gustaf Bjurstam bjurstam@kth.se

## Preliminaries – not in the book

**Definition 0.1.** Let E be a vector space over  $\mathbb{R}$ . A functional is a function  $f: A \to \mathbb{R}$  where A is some subspace of E.

## 1 The Hahn-Banach Theorems. Introduction to Conjugate Convex Functions

**Definition 1.1.** Let E be a vector space over  $\mathbb{R}$ . A *Minkowski functional* is a function  $p: E \to \mathbb{R}$  satisfying

$$p(\lambda x) = \lambda p(x),$$
  $\forall x \in E \text{ and } \lambda > 0.$  (1)

$$p(x+y) \le p(x) + p(y), \qquad \forall x, y \in E.$$
 (2)

**Definition 1.2.** Let P be a set with a (partial) order relation  $\leq$ . A subset  $Q \subseteq P$  is *totally ordered* if for any pair (a, b) in Q at least one of  $a \leq b$  and  $b \leq a$  holds.

**Definition 1.3.** Let P be a set with a partial order relation  $\leq$ , and let  $Q \subset P$ . We say that  $c \in P$  is an *upper bound* for Q if  $a \leq c$  for all  $a \in Q$ . We say that  $m \in P$  is a maximal element of P if there is no element  $x \in P \setminus \{m\}$  such that  $m \leq x$ . If every totally ordered subset Q of P has an upper bound, we call P inductive.

**Definition 1.4.** Let E be a real normed vector space. We denote by  $E^*$  the dual space of E, that is, the set of all continuous linear functionals on E. The dual norm is defined by

$$||f||_{E^*} = \sup_{\substack{x \in E \\ ||x|| \le 1}} f(x).$$

Given  $f \in E^*$  and  $x \in E$  we may write  $\langle f, x \rangle$  instead of f(x); we say that  $\langle , \rangle$  is the scalar product for the duality  $E^*, E$ .

**Definition 1.5.** Let E be a normed vector space over  $\mathbb{R}$ . For every  $x_0 \in E$ , we set

$$F(x_0) = \left\{ f_0 \in E^* : ||f_0|| = ||x_0|| \text{ and } \langle f_0, x_0 \rangle = ||x_0||^2 \right\}.$$

The map  $x_0 \mapsto F(x_0)$  is called the duality map of E into  $E^*$ .

**Definition 1.6.** Let E be a real vector space. An *affine hyperplane* is a subset H of E of the form  $H = \{x \in E : f(x) = \alpha\}$  where f is a linear functional not necessarily in  $E^*$ , and  $\alpha \in \mathbb{R}$  is a given constant. We write  $H = [f = \alpha]$  and say that  $f = \alpha$  is the equation of H.