Definitions used in Cohn's Measure Theory (second edition)

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1 Measures

Definition 1.1 (Algebra). Let X be a set, an arbitrary collection of subsets \mathscr{A} of X is an algebra on X if

- (a) $X \in \mathcal{A}$,
- (b) if $A \in \mathcal{A}$ then $A^c \in \mathcal{A}$,
- (c) for each finite sequence $\{A_n\}_{n=1}^N$ of sets in \mathscr{A} , the set $\bigcup_{n=1}^N A_n$ belongs to \mathscr{A} , and
- (d) for each finite sequence $\{A_n\}_{n=1}^N$ of sets in \mathscr{A} , the set $\bigcap_{n=1}^N A_n$ belongs to \mathscr{A} .

Definition 1.2 (σ -Algebra). Let X be a set, an arbitrary collection of subsets \mathscr{A} of X is a σ -algebra on X if

- (a) $X \in \mathcal{A}$,
- (b) if $A \in \mathscr{A}$ then $A^c \in \mathscr{A}$,
- (c) for each infinite sequence $\{A_n\}_{n=1}^{\infty}$ of sets in \mathscr{A} , the set $\bigcup_{n=1}^{\infty} A_n$ belongs to \mathscr{A} , and
- (d) for each infinite sequence $\{A_n\}_{n=1}^{\infty}$ of sets in \mathscr{A} , the set $\bigcap_{n=1}^{\infty} A_n$ belongs to \mathscr{A} .

Definition 1.3 (Borel σ -algebra on \mathbb{R}^d). The Borel σ -algebra on \mathbb{R}^d , denoted $\mathscr{B}(\mathbb{R}^d)$, is generated by the collection of open subsets of \mathbb{R}^d . **Proposition 1.1.5** states that $\mathscr{B}(\mathbb{R}^d)$ is generated by each of the collections of sets

- (a) the collection of all closed subsets of \mathbb{R}^d ;
- (b) the collection of all closed half-spaces in \mathbb{R}^d that have the form $\{(x_1, \ldots, x_d) : x_i \leq b\}$ for some $b \in \mathbb{R}$;
- (c) the collection of all rectangles in \mathbb{R}^d that have the form

$$\{(x_1, \dots, x_d) : a_i < x_i \le b_i \text{ for } i = 1, \dots, d\}.$$

Definition 1.4 (Measure). Let \mathscr{A} be a σ -algebra. A function $\mu : \mathscr{A} \to [0, \infty]$ is called *countably additive* if

$$\mu\left(\bigcup_{n=1}^{\infty} A_n\right) = \sum_{n=1}^{\infty} \mu(A_n),$$

for each infinite sequence of disjoint sets $\{A_n\}_{n=1}^{\infty}$ in \mathscr{A} . If μ in addition to being countably additive also satisfies $\mu(\varnothing) = 0$, μ is said to be a *measure* on \mathscr{A} .

Definition 1.5 (Measure space). Let X be a set, \mathscr{A} a σ -algebra on X and μ a measure on \mathscr{A} . The triplet (X, \mathscr{A}, μ) is then called a *measure space*, the pair (X, \mathscr{A}) is often called a *measurable space*.

Definition 1.6 (Outer measure). Let X be a set, and let $\mathscr{P}(X)$ be the power set of X. An outer measure on X is a function $\mu^* : \mathscr{P}(X) \to [0, \infty]$ such that

- (a) $\mu^*(\emptyset) = 0$,
- (b) $A \subseteq B \subseteq X$ implies $\mu^*(A) \le \mu^*(B)$, and
- (c) if $\{A_n\}$ is an infinite sequence of sets in $\mathscr{P}(X)$, then $\mu^*(\bigcup A_n) \leq \sum \mu^*(A_n)$.

Definition 1.7 (Lebesgue outer measure). Lebesgue outer measure on \mathbb{R}^d which we denote by λ^* is defined as follows. For each set $A \subseteq \mathbb{R}^d$ define the set \mathscr{C}_A of all sequences $\{R_n\}$ of bounded and open d-cells R_n such that $A \subseteq \bigcup_{n=1}^{\infty} R_n$. Then

$$\lambda^*(A) = \inf \left\{ \sum_{n=1}^{\infty} \operatorname{vol}(R_n) : \{R_n\} \in \mathscr{C}_A \right\}.$$

Definition 1.8 (μ^* -measurable set). Let X be a set, and let μ^* be an outer measure on X. A subset B of X is μ^* -measurable if

$$\mu^*(A) = \mu^*(A \cap B) + \mu^*(A \cap B^c),$$

for all $A \subseteq X$.

Definition 1.9 (Complete measure). Let (X, \mathscr{A}, μ) be a measure space. The measure μ , or the measure space (X, \mathscr{A}, μ) , is called *complete* if $A \in \mathscr{A}$, $\mu(A) = 0$, and $B \subseteq A$ implies $B \in \mathscr{A}$.

Definition 1.10 (μ -negligible set). A subset B of X is called μ -negligible or μ -null if there exists $A \in \mathscr{A}$ such that $\mu(A) = 0$ and $B \subseteq A$. Thus (X, \mathscr{A}, μ) is complete if and only if every μ -negligible set belongs to \mathscr{A} .

Definition 1.11 (Completion of a σ -algebra under a measure). Let (X, \mathscr{A}) be a measurable space. The *completion* of \mathscr{A} under μ is the collection \mathscr{A}_{μ} of $A \subseteq X$ for which there exists $E, F \in \mathscr{A}$ such that

$$E \subseteq A \subseteq F$$
.

and

$$\mu(F \setminus E) = 0.$$

A set that belongs to \mathscr{A}_{μ} is sometimes said to be μ -measurable.

Definition 1.12 (Completion of a measure). Let (X, \mathcal{A}, μ) be a measure space. The *completion* of μ is defined as $\overline{\mu} : \mathcal{A}_{\mu} \to [0, \infty]$ by letting $\overline{\mu}(A)$ be the common value of E, F, defined in the above definition.

Definition 1.13 (Inner and outer measure). Let (X, \mathcal{A}, μ) be a measure space, and let A be an arbitrary subset of X. The *inner measure* μ_* of A is defined by

$$\mu_*(A) = \sup \{ \mu(B) : B \subseteq A \text{ and } B \in \mathscr{A} \}.$$

The outer measure μ^* of A meanwhile, is defined by

$$\mu^*(A) = \inf \{ \mu(B) : A \subseteq B \text{ and } B \in \mathscr{A} \}.$$

Remark. According to Proposition 1.5.4, the outer measure defined in **Definition 1.13** satisfies the conditions placed on an outer measure in **Definition 1.6**.

Definition 1.14 (Regular measure). Let \mathscr{A} be a σ -algebra on \mathbb{R}^d that includes $\mathscr{B}(\mathbb{R}^d)$. A measure μ on \mathscr{A} is regular if

- (a) each compact subset K of \mathbb{R}^d satisfies $\mu(K) < \infty$,
- (b) each set A in \mathcal{A} satisfies

$$\mu(A) = \inf \{ \mu(U) : U \text{ is open and } A \subseteq U \}, and$$

(c) each open subset U of \mathbb{R}^d satisfies

$$\mu(U) = \sup \{ \mu(K) : K \text{ is compact and } K \subseteq A \}.$$

Definition 1.15 (Dykin class). Let X be a set. A collection \mathscr{D} is a d-system, or Dykin class, on X if

- (a) $X \in \mathcal{D}$,
- (b) $A \setminus B \in \mathcal{D}$ whenever $A, B \in \mathcal{D}$ and $A \supseteq B$, and
- (c) $\bigcup A_n \in \mathcal{D}$ whenever $\{A_n\}$ is an increasing sequence of sets in \mathcal{D} .

Definition 1.16 (π -system). A collection of subsets of X is a π -system if it is closed under the formation of finite unions.

2 Functions and Integrals

Definition 2.1 (\mathscr{A} -measurable function). Let (X, \mathscr{A}) be a measurable space, and let $A \in \mathscr{A}$. A function $f: A \to [-\infty, \infty]$ is measurable with respect to \mathscr{A} if it satisfies any of the conditions, and thus all, of the conditions in **Proposition 2.1.1**. That is any of

- (a) $\forall t \in \mathbb{R} \quad \{x \in A : f(x) \le t\} \in \mathscr{A},$
- (b) $\forall t \in \mathbb{R} \quad \{x \in A : f(x) < t\} \in \mathcal{A},$
- (c) $\forall t \in \mathbb{R} \quad \{x \in A : f(x) \ge t\} \in \mathcal{A},$
- (d) $\forall t \in \mathbb{R} \quad \{x \in A : f(x) > t\} \in \mathscr{A}.$

A function that is measurable with respect to \mathscr{A} may be called \mathscr{A} -measurable or if what σ -algebra is meant is obvious from context, simply measurable. In the case $X = \mathbb{R}^d$ functions measurable with respect to $\mathscr{B}(\mathbb{R}^d)$ are called Borel measurable or Borel functions. A function measurable with respect to \mathscr{M}_{λ^*} is called Lebesgue measurable.

Definition 2.2 (Almost everywhere). Let (X, \mathcal{A}, μ) be a measure space. A property of points on X is said to hold μ -almost everywhere if the set of points in X where it fails to hold is μ -negligible. The expression μ -almost everywhere is often abbreviated μ -a.e. or to a.e. $[\mu]$. If the measure is clear from context one may simply say almost everywhere.

2.1 Construction of the integral

Definition 2.3 (Integral of a simple non-negative function). Let μ be a measure on (X, \mathscr{A}) . If f is a real-valued, simple, \mathscr{A} -measurable function given by $f = \sum_{i=1}^{m} a_i \chi_{A_i}$, where each $a_i \geq 0$ and $A_i \in \mathscr{A}$ are disjoint. Then the *integral of* f with respect to μ is then defined to be

$$\int f \, d\mu = \sum_{n=1}^{m} a_i \mu(A_i).$$

Definition 2.4 (Integral of arbitrary \mathscr{A} -measurable, non-negative function). Let f be an arbitrary \mathscr{A} -measurable function, with image in $[0,\infty]$. The integral of f is then defined as

$$\int f \, d\mu = \sup \left\{ \int g \, d\mu : g \in \mathscr{S}_+ \text{ and } g \le f \right\}.$$

Definition 2.5 (Integral of arbitrary measurable function). Let $f: X \to [-\infty, \infty]$ be a measurable function on (X, \mathcal{A}, μ) . If $\int f^+ d\mu$ and $\int f^- d\mu$ are both finite, then f is called *integrable* and its *integral* is defined by

$$\int f \, d\mu = \int f^+ \, d\mu - \int f^- \, d\mu.$$

The integral of f is said to exist if at least one of $\int f^+ d\mu$ and $\int f^- d\mu$ is finite, in this case the integral is defined $\int f d\mu = \int f^+ d\mu - \int f^- d\mu$.

Definition 2.6 (Integral over a subset). Let (X, \mathscr{A}, μ) be a measure space, and let $f: X \to [-\infty, \infty]$ be \mathscr{A} -measurable. The integral of f over a subset $A \subseteq X$ is said to exist if the integral of $f\chi_A$ exists. In that case the integral over A is defined to be

$$\int_A f \, d\mu = \int f \chi_A \, d\mu.$$

Likewise, if $A \in \mathscr{A}$ and $f: A \to [-\infty, \infty]$ is \mathscr{A} -measurable, then the integral of f over A is defined to be the integral of the function which agrees with f on A and vanishes on A^c .

Definition 2.7 (Lebesgue integral). The case $X = \mathbb{R}^d$ and $\mu = \lambda$ we simply talk about Lebesgue integrability and the Lebesgue integral. We may use any of the following notations for the Lebesgue integral over an interval [a, b]

$$\int_{a}^{b} f = \int_{a}^{b} f(x) dx = (L) \int_{a}^{b} f = (L) \int_{a}^{b} f(x) dx,$$

where the latter two are used to emphasise that we are talking about the Lebesgue integral.

Definition 2.8 (\mathscr{L}^1). We define $\mathscr{L}^1(X, \mathscr{A}, \mu, \mathbb{R})$, or sometimes simply \mathscr{L}^1 , as the set of all integrable functions $f: X \to \mathbb{R}$. (As opposed to $[-\infty, \infty]$ -valued functions.)

2.2 Measurable functions again

Definition 2.9 (Measurable function between sets). Let (X, \mathscr{A}) and (Y, \mathscr{B}) be measurable spaces. A function $f: X \to Y$ is measurable with respect to \mathscr{A} and \mathscr{B} if for each $B \in \mathscr{B}$ the set $f^{-1}(B)$ belongs to \mathscr{A} . In stead of saying measurable with respect to \mathscr{A} and \mathscr{B} , we may say that f is a measurable function from (X, \mathscr{A}) to (Y, \mathscr{B}) , or simply that $f: (X, \mathscr{A}) \to (Y, \mathscr{B})$ is measurable.

Definition 2.10 (Integral of complex-valued function). Let (X, \mathcal{A}, μ) be a measure space. A complex-valued function f on X is *integrable* if its real and imaginary parts $\Re(f)$ and $\Im(f)$ are integrable; if f is integrable then its *integral* is defined by

$$\int f d\mu = \int \Re(f) d\mu + i \int \Im(f) d\mu.$$

Definition 2.11 (μf^{-1}) . Let (X, \mathscr{A}, μ) be a measure space, let (Y, \mathscr{B}) be a measurable space, and let $f: (X, \mathscr{A}) \to (Y, \mathscr{B})$ be measurable. Define $\mu f^{-1}: \mathscr{B} \to [0, \infty]$ by $\mu f^{-1}(B) = \mu(f^{-1}(B))$. It is easy to show that μf^{-1} is a measure, this measure is sometimes called the image of μ under f.

3 Convergence

Definition 3.1 (Convergence in measure). Let (X, \mathcal{A}, μ) be a measure space, and let f and f_1, f_2, \ldots be real valued \mathcal{A} -measurable functions on X. The sequence $\{f_n\}$ converges to f in measure if

$$\lim_{n} \mu \left(\left\{ x \in X : |f_n(x) - f_n| > \varepsilon \right\} \right) = 0$$

for every $\varepsilon > 0$.

Definition 3.2 (Almost uniform convergence). Let (X, \mathcal{A}, μ) be a measure space, and let f and f_1, f_2, \ldots be real valued \mathcal{A} -measurable functions on X. Then $\{f_n\}$ converges to f almost uniformly if for all $\varepsilon > 0$ there is $B \in \mathcal{A}$ such that $\{f_n\}$ converges to f on B and $\mu(B^c) < \varepsilon$.

Definition 3.3 (Convergence in mean). Let (X, \mathscr{A}, μ) be a measure space, and let f and f_1, f_2, \ldots be real valued \mathscr{A} -measurable functions on X. Then $\{f_n\}$ converges to f in mean if

$$\lim_{n} \int |f_n - f| \, d\mu = 0.$$

3.1 Normed spaces

Definition 3.4 (Norm & seminorm). Let V be a vector space over \mathbb{C} . A *norm* on V is a function $\|\cdot\|:V\to\mathbb{R}$ that satisfies

- (a) $||v|| \ge 0$,
- (b) $||v|| = 0 \iff v = 0$,
- (c) $\|\alpha v\| = |\alpha| \|v\|$,
- (d) $||u + v|| \le ||u|| + ||v||$

for each $u, v \in V$ and $\alpha \in \mathbb{C}$. If condition (b) was replaced by " $||v|| = 0 \iff v = 0$ " $||\cdot||$ is a seminorm.

Definition 3.5 (Metric & semimetric). A *metric* on a set S is a function $d: S \times S \to \mathbb{R}$ that satisfies

- (a) $d(s,t) \ge 0$,
- (b) $d(s,t) = 0 \iff s = t$,
- (c) d(s,t) = d(t,s),
- (d) $d(r,t) \le d(r,s) + d(s,t)$

for all $r, s, t \in S$. If condition (b) is replaced by " $d(s, t) = 0 \iff s = t$ " d is a semimetric. A metric space is a set S together with a metric d on S. This may, if there is no risk for confusion with a measurable space, be written as (S, d).

Definition 3.6 (Converging sequence). Let (S, d) be a metric (or semimetric) space, a sequence $\{s_n\}$ in S is said to *converge* to $s \in S$ if for all $\varepsilon > 0$ there exists N such that $\forall n \geq N \ d(s_n, s) \leq \varepsilon$. The point s is then said to be the *limit point* of $\{s_n\}$. In particular,

if V is a normed linear space, $v \in V$ and $\{v_n\}$ is a sequence in V, then $\{v_n\}$ converges to v (with respect to the metric induced by the norm on V) if and only if $\lim_n \|v_n - v\| = 0$. Note that if d is a semimetric $\{s_n\}$ may have several limit points.

Definition 3.7 (Dense subset). Let (S, d) be a metric (or semimetric) space, a subset $A \subseteq S$ is said to be *dense* in S if for all $s \in S$ and $\varepsilon > 0$ there exists $a \in A$ such that $d(s, a) < \varepsilon$.

Definition 3.8 (Separable space). Let (S, d) be a metric (or semimetric) space, if S has a countable dense subset, S is *separable*.

Definition 3.9 (Cauchy sequences and completeness). Let (S, d) be a metric space, a *Cauchy sequence* is a sequence $\{s_n\}$ in S such that for all $\varepsilon > 0$ there exists N such that for all $n, m \geq N, d(s_n, s_m) < \varepsilon$. A metric space (S, d) is said to be *complete* if all Cauchy sequences in (S, d) converge.

Definition 3.10 (Banach space). If a normed linear space is complete, with respect to the metric induced by the norm on the space, then it is called a *Banach space*.

Definition 3.11 (Inner product). Let V be a vector space over \mathbb{C} . A function $(\cdot, \cdot) : V \times V \to \mathbb{C}$ is an *inner product* on V if

- (a) $(x, x) \ge 0$,
- (b) $(x, x) = 0 \iff x = 0$,
- (c) $(x,y) = \overline{(y,x)}$, and
- (d) $(\alpha x + \beta y, z) = \alpha(x, z) + \beta(y, z)$

hold for all $x, y, z \in V$ and $\alpha, \beta \in \mathbb{C}$. An *inner product space* is a vector space, together with an inner product. The *norm* $\|\cdot\|$ associated to the inner product (\cdot, \cdot) is defined by $\|x\| = \sqrt{(x, x)}$.

Definition 3.12 (Hilbert space). An inner product space that is complete under the norm associated with the inner product is called a *Hilbert space*.

3.2 \mathscr{L}^p and L^p

Definition 3.13 (\mathscr{L}^p) . Let (X, \mathscr{A}, μ) be a measure space, and let $p \in [1, \infty)$. Then $\mathscr{L}^p(X, \mathscr{A}, \mu, \mathbb{R})$ is the set of all \mathscr{A} -measurable functions $f: X \to \mathbb{R}$ such that $|f|^p$ is integrable, and $\mathscr{L}^p(X, \mathscr{A}, \mu, \mathbb{C})$ is the set of \mathscr{A} -measurable functions $f: X \to \mathbb{C}$ such that $|f|^p$ is integrable.

Definition 3.14 (\mathscr{L}^{∞}) . Let (X, \mathscr{A}, μ) be a measure space. We define $\mathscr{L}^{\infty}(X, \mathscr{A}, \mu, \mathbb{R})$ to be the set of all¹ bounded real-valued \mathscr{A} -measurable functions, and $\mathscr{L}^p(X, \mathscr{A}, \mu, \mathbb{C})$ as the set of all bounded complex-valued \mathscr{A} -measurable functions.

¹I think it's supposed to be almost everywhere bounded functions, otherwise exercise 3.3.7 fails with this definition (however not with the alternative definition).

Remark. Some authors² define $\mathscr{L}^{\infty}(X,\mathscr{A},\mu)$ as the set of all essentially bounded \mathscr{A} -measurable functions on X. A function $f:X\to\mathbb{C}$ is essentially bounded if there exists M>0 such that $\{x\in X:|f(x)|>M\}$ is locally μ -null. For most purposes, it does not matter which definition of \mathscr{L}^{∞} one uses. However the study of liftings is convenient with **Definition 3.14**.

Definition 3.15 (Locally μ -null). Let (X, \mathscr{A}, μ) be a measure space. A subset $N \subseteq X$ is said to be *locally* μ -null if for each $A \in \mathscr{A}$ that satisfies $\mu(A) < \infty$ the set $A \cap N$ is μ -null. A property is said to hold *locally almost everywhere* if the set on which the property doesn't hold is locally μ -null.

Definition 3.16 (Seminorm on \mathcal{L}^p). In the case of $p \in [1, \infty)$ we define a seminorm $\|\cdot\|_p : \mathcal{L}^p(X, \mathcal{A}, \mu) \to \mathbb{R}$ by

$$||f||_p = \left(\int |f|^p d\mu\right)^{1/p}.$$

In the case $p=\infty$ we define a seminorm $\|\cdot\|_{\infty}: \mathscr{L}^{\infty}(X,\mathscr{A},\mu) \to \mathbb{R}$ by

$$||f||_{\infty} = \inf \{ M : \{ x \in X : |f(x)| > M \} \text{ is locally } \mu\text{-null} \}.$$

Definition 3.17 (\mathcal{N}^p) . Let (X, \mathcal{A}, μ) be a measure space, and let $\mathcal{N}^p(X, \mathcal{A}, \mu)$ be the subset of $\mathcal{L}^p(X, \mathcal{A}, \mu)$ which consists of the functions $f \in \mathcal{L}^p(X, \mathcal{A}, \mu)$ such that $\|f\|_p = 0$. That is, if $p \in [1, \infty)$, then $\mathcal{N}^p(X, \mathcal{A}, \mu)$ is the set of functions in $\mathcal{L}^p(X, \mathcal{A}, \mu)$ which vanish almost everywhere, and if $p = \infty$ then $\mathcal{N}^\infty(X, \mathcal{A}, \mu)$ is the set of functions in $\mathcal{L}^\infty(X, \mathcal{A}, \mu)$ which vanish locally almost everywhere.

²Notably, the first edition of Cohn's *Measure Theory* uses this definition.

Definition 3.18 (L^p) . Let (X, \mathscr{A}, μ) be a measure space. We define $L^p(X, \mathscr{A}, \mu)$ to be the quotient group $\mathscr{L}^p(X, \mathscr{A}, \mu)/\mathscr{N}^p(X, \mathscr{A}, \mu)$. That is $L^p(X, \mathscr{A}, \mu)$ is the collection of cosets of $\mathscr{N}^p(X, \mathscr{A}, \mu)$ in $\mathscr{L}^p(X, \mathscr{A}, \mu)$; these cosets are by definition the equivalence classes induced by the equivalence relation \sim , where $f \sim g$ holds if and only if $f - g \in \mathscr{N}^p(X, \mathscr{A}, \mu)$. Then if $p \in [1, \infty)$, $f \sim g \iff f = g$ almost everywhere.

Definition 3.19 (Norm on L^p). Let (X, \mathscr{A}, μ) be a measure space. For each $f \in \mathscr{L}^p(X, \mathscr{A}, \mu)$ let $\langle f \rangle$ be the coset of $\mathscr{N}^p(X, \mathscr{A}, \mu)$ in $\mathscr{L}^p(X, \mathscr{A}, \mu)$ to which f belongs. Then $L^p(X, \mathscr{A}, \mu)$ is a vector space and we can define a norm $\|\cdot\|_p : L^p(X, \mathscr{A}, \mu) \to \mathbb{R}$ by $\|\langle f \rangle\|_p = \|f\|_p$, where on the right hand side $\|\cdot\|_p : \mathscr{L}^p(X, \mathscr{A}, \mu) \to \mathbb{R}$ is given in **Definition 3.16**.

Definition 3.20 (Convergence in pth mean). Let (X, \mathcal{A}, μ) be a measure space, let $p \in [1, \infty)$, and let $f, f_1, f_2, \dots \in \mathcal{L}^p(X, \mathcal{A}, \mu)$. Then $\{f_n\}$ converges to f in pth mean, or in L^p norm, if $\lim_n \|f_n - f\|_p = 0$.

3.3 Dual Spaces

Definition 3.21 (Linear operator). Let V_1, V_2 be normed vector spaces over \mathbb{C} (or over \mathbb{R}), then a function $T: V_1 \to V_2$ is a linear operator or linear transformation if $T(\alpha v) = \alpha T(v)$ and T(u+v) = T(u) + T(v) hold for all $\alpha \in \mathbb{C}$ (or \mathbb{R}) and all $u, v \in V_1$.

Definition 3.22 (Bounded linear operator). Let V_1, V_2 be normed vector spaces, and let $T: V_1 \to V_2$ be linear. Then a nonnegative number A such that $||T(v)|| \le A ||v||$ holds for every $v \in V_1$ is called a *bound* for T, and the operator T is called *bounded* if there is a bound for it.

Definition 3.23 (Norm of linear operator). Let $T: V_1 \to V_2$ be a bounded linear operator, we define the *norm* of T by

$$||T|| = \inf\{A : A \text{ is a bound for } T\}.$$

Then $\|\cdot\|$ is a norm on the vector space of bounded linear operators from V_1 to V_2 .

Definition 3.24 (Isometry). Let $T: V_1 \to V_2$ be a linear operator between normed linear spaces. Then T is called and *isometry* if ||T(v)|| = ||v|| for every $v \in V_1$.

Definition 3.25 (Isometric isomorphism). Let $T: V_1 \to V_2$ be a linear operator between normed linear spaces. Then T is an isometric isomorphism if T is an isometry and is surjective. Because all isometries are injective, T is then bijective.

Definition 3.26 (Linear functional). Let V be a normed linear space. A linear functional on V is a linear operator on V whose values lie in \mathbb{C} , if V is a vector space over \mathbb{C} , or in \mathbb{R} , if V is a vector space over \mathbb{R} .

Definition 3.27 (Dual space). Let V be a normed linear space. The set of all bounded, and hence continuous, linear functionals on V then form a vector space. This vector space is called the *dual space* (or *conjugate space*) of V, and is denoted by V^* . Note that the function $\|\cdot\| V^* \to \mathbb{R}$ which assigns to each functional in V^* its norm, is in fact a norm on the vector space V^* .

4 Signed and Complex measures

Definition 4.1 (Signed measure). Let (X, \mathscr{A}) be a measurable space. A function $\mu : \mathscr{A} \to [-\infty, \infty]$ is called a *signed measure* if it is countably additive and satisfies $\mu(\varnothing) = 0$.

Definition 4.2 (Positive & negative sets). Let μ be a signed measure on a measurable space (X, \mathscr{A}) . A set $A \in \mathscr{A}$ is a positive set if every $B \in \mathscr{A}$ such that $B \subseteq A$ satisfies $\mu(B) \geq 0$. Likewise, a set $A \in \mathscr{A}$ is a negative set if every $B \in \mathscr{A}$ such that $B \subseteq A$ satisfies $\mu(B) \leq 0$.

Definition 4.3 (Hahn decomposition). A *Hahn decomposition* of a signed measure μ on the measurable space (X, \mathscr{A}) is a pair (P, N) of disjoint subsets in \mathscr{A} such that $X = P \cup N$, and P is a positive set and N is a negative set. Note that there may be several Hahn decomposition of the signed measure μ .

Definition 4.4 (Complex measure). Let (X, \mathscr{A}) be a measurable space. A *complex measure* is a function $\mu : \mathscr{A} \to \mathbb{C}$ that satisfies $\mu(\varnothing) = 0$ and is countably additive. A complex measure μ can be written as $\mu = \mu' + i\mu''$ where μ' and μ'' are finite signed measures.

Definition 4.5 (Jordan decomposition). Let μ be a signed measure on the measurable space (X, \mathscr{A}) , and let (P, N) be a Hahn decomposition of μ . Let $\mu^+(A) = \mu(A \cap P)$ and $\mu^-(A) = -\mu(A \cap N)$, then μ^+, μ^- are measures on (X, \mathscr{A}) and $\mu = \mu^+ - \mu^-$. The measures μ^+ and μ^- are called the *positive part* and *negative part* of μ , respectively. The representation $\mu = \mu^+ - \mu^-$ is called the *Jordan decomposition* of the signed measure μ . If μ is a complex measure on (X, \mathscr{A}) then the representation $\mu = \mu_1 - \mu_2 + i(\mu_3 - \mu_4)$ is called the *Jordan decomposition* of μ , if $\mu' = \mu_1 - \mu_2$ and $\mu'' = \mu_3 - \mu_4$ are the Jordan decompositions of the real and imaginary parts of μ .

Definition 4.6 (Variation). If μ is a signed measure on the measurable space (X, \mathscr{A}) , then the *variation* of μ is defined to be $|\mu| = \mu^+ + \mu^-$, and the *total variation* of μ is defined to be $|\mu| = |\mu|(X)$. If μ is a complex measure on (X, \mathscr{A}) , then the *variation* of μ is defined by

$$|\mu|(A) = \sup \left\{ \sum_{j=1}^n |\mu(A_j)| : \{A_j\}_{j=1}^n \text{ are finite disjoint sequences in } \mathscr{A} \text{ such that } A = \bigcup_{j=1}^n A_j \right\}.$$

The total variation of μ is defined to be $\|\mu\| = |\mu|(X)$.

Definition 4.7. Let (X, \mathscr{A}) be a measurable space. Define $M(X, \mathscr{A}, \mathbb{R})$ as the set of all finite signed measures on (X, \mathscr{A}) , and $M(X, \mathscr{A}, \mathbb{C})$ as the set of all complex measures on (X, \mathscr{A}) . It is easy to see that $M(X, \mathscr{A}, \mathbb{R})$ and $M(X, \mathscr{A}, \mathbb{C})$ are vector spaces over \mathbb{R} and \mathbb{C} respectively, and that the total variation gives a norm on each of them.

Definition 4.8 (Integration with signed measure). Let X, \mathscr{A}) be a measurable space. Denote by $B(X, \mathscr{A}, \mathbb{R})$ the vector space of bounded real-valued \mathscr{A} -measurable functions on X. If μ is a finite signed measure on (X, \mathscr{A}) , and $\mu = \mu^+ - \mu^-$ is the Jordan decomposition of μ , and if $f \in B(X, \mathscr{A}, \mathbb{R})$, then the *integral of f with respect to* μ is defined as

$$\int f \, d\mu = \int f \, d\mu^+ - \int f \, d\mu^-.$$

Definition 4.9 (Integration with complex measure). Let (X, \mathscr{A}) be a measurable space. Denote by $B(X, \mathscr{A}, \mathbb{C})$ the vector space of bounded complex-valued \mathscr{A} -measurable functions on X. If μ is a complex measure on (X, \mathscr{A}) , and μ_1, μ_2 are the real and imaginary parts of μ , and if $f \in B(X, \mathscr{A}, \mathbb{C})$, then the *integral of* f *with respect to* μ is defined by

$$\int f \, d\mu = \int f \, d\mu_1 + i \int f \, d\mu_2.$$

Remark. The formula $f \mapsto \int f d\mu$ and $\mu \mapsto \int f d\mu$ define a linear functionals on $B(X, \mathscr{A})$ and $M(X, \mathscr{A})$ respectively.

Definition 4.10 (Absolute continuity). Let (X, \mathscr{A}) be a measureable space, and let μ and ν be measures on (X, \mathscr{A}) . We say that ν is absolutely continuous with respect to μ if every $A \in \mathscr{A}$ such that $\mu(A) = 0$ also satisfies $\nu(A) = 0$. This is sometimes indicated as $\nu \ll \mu$. A measure ν on $(\mathbb{R}^d, \mathscr{B}(\mathbb{R}^d))$ is called absolutely continuous if $\nu \ll \lambda$.

Definition 4.11 (Absolute continuity of signed or complex measure). Let (X, \mathcal{A}, μ) be a measure space. A signed or complex measure ν on (X, \mathcal{A}) is absolutely continuous with respect to μ , written $\nu \ll \mu$, if the variation $|\nu|$ is absolutely continuous with respect to μ .

Definition 4.12 (Radon-Nikodym derivative). Let (X, \mathscr{A}) be a measurable space, let μ be a σ -finite measure on (X, \mathscr{A}) and let ν be a, finite signed, complex, or σ -finite, measure on (X, \mathscr{A}) such that $\nu \ll \mu$. A function g such that $\nu(A) = \int_A g \, d\mu$ hold for every $A \in \mathscr{A}$ is called a Radon-Nikodym derivative of ν with respect to μ , or in light of the μ -almost uniqueness of such g, the Radon-Nikodym derivative of ν with respect to μ . The Radon-Nikodym derivative of ν is sometimes denoted $\frac{d\nu}{d\mu}$.

Definition 4.13 (Concentrated measure). Let (X, \mathscr{A}) be a measurable space, a measure μ is concentrated on $E \in \mathscr{A}$ if $\mu(E^c) = 0$. A signed or complex measure μ is said to be concentrated on E if $|\mu|(E^c) = 0$.

Definition 4.14 (Singularity). Let (X, \mathscr{A}) be a measurable space, let μ and ν be positive, signed, or complex measures on (X, \mathscr{A}) . Then μ and ν are called mutually singular if there exists $E \in \mathscr{A}$ such that μ is concentrated on E and ν is concentrated on E^c . That two measures are mutually singular is sometimes denoted $\mu \perp \nu$. Sometimes the statement μ and ν are mutually singular is said, μ and ν are singular, μ is singular with respect to ν , or that ν is singular with respect to μ . A positive, signed, or complex measure on $(\mathbb{R}^d, \mathscr{B}(\mathbb{R}^d))$ is simply said to be singular if it is singular with respect to the d-dimensional Lebesgue measure on $(\mathbb{R}^d, \mathscr{B}(\mathbb{R}^d))$.

Definition 4.15 (Lebesgue decomposition). Let (X, \mathcal{A}, μ) be a measure space, and let ν be a finite signed, complex, or σ -finite positive measure on (X, \mathcal{A}) . There are unique finite signed, complex, or σ -finite measures ν_a and ν_s on (X, \mathcal{A}) that satisfy

- (a) $\nu_a \ll \mu$,
- (b) $\nu_s \perp \mu$, and
- (c) $\nu = \nu_a + \nu_s$.

The decomposition $\nu = \nu_a + \nu_s$ is called the Lebesgue decomposition of ν .

5 Product Measures

Definition 5.1 (Product of σ -algebras). Let (X, \mathscr{A}) and (Y, \mathscr{B}) be measurable spaces. A subset of $X \times Y$ is called a *rectangle with measurable sides* if it has the form $A \times B$ for some $A \in \mathscr{A}$ and $B \in \mathscr{B}$. The σ -algebra on $X \times Y$ generated by collection of rectangles with measurable sides is called the *product* of \mathscr{A} and \mathscr{B} , and is denoted by $\mathscr{A} \times \mathscr{B}$.

Definition 5.2 (Product measure). Let (X, \mathcal{A}, μ) and (Y, \mathcal{B}, ν) be σ -finite measure spaces. The unique measure $\mu \times \nu$ on $\mathcal{A} \times \mathcal{B}$ which satisfies $(\mu \times \nu)(A \times B) = \mu(A)\nu(B)$, for every $A \in \mathcal{A}, B \in \mathcal{B}$, is called the *product* of μ and ν .

10 Probability

Definition 10.1 (Probability space). A probability space is a measure space (Ω, \mathcal{A}, P) such that $P(\Omega) = 1$. The elements of Ω are called the elementary outcomes or the sample points of our experiment, and the members of \mathcal{A} are called events. If $A \in \mathcal{A}$, then P(A) is the probability of the event A.

Definition 10.2 (Random variable). A real-valued random variable on a probability space (Ω, \mathcal{A}, P) is an \mathcal{A} -measurable function from Ω to \mathbb{R} . Such a variable represents a numerical observation or measurement whose value depends on the outcome of the random experiment represented by (Ω, \mathcal{A}, P) . More generally, a random variable with values in a measurable space (S, \mathcal{B}) is a measurable function from (Ω, \mathcal{A}, P) to (S, \mathcal{B}) .

Definition 10.3 (Distribution). Let X be a random variable with values in (S, \mathcal{B}) . The the distribution of X is the measure PX^{-1} (see **Definition 2.11**) defined on (S, \mathcal{B}) by $(PX^{-1})(A) = P(X^{-1}(A))$. We will often write P_X for the distribution of a random variable X. If X_1, \ldots, X_d are (S, \mathcal{B}) -valued random variables on (Ω, \mathcal{A}, P) , then the formula $X(\omega) = (X_1(\omega, \ldots, X_d(\omega)))$ defines an S^d -valued random variable X; the distribution of X is called the joint distribution of X_1, \ldots, X_d .

Definition 10.4 (Expected value). If a real-valued random variable on the probability space (Ω, \mathcal{A}, P) is integrable, then the *expected value* of X is defined $E(X) = \int X dP$. The expected value of X is often denoted μ_X .

Definition 10.5 (Variance). If X is a real-valued random variable, then the *variance* of X is the expected value of the random variable $(X - E(X))^2$, often denoted Var(X) or σ_X^2 . The numerical value $\sqrt{\sigma_X^2} = \sigma_X$ is called the *standard deviation* of X.

Definition 10.6. If X is \mathbb{R}^d valued and $P_X \ll \lambda$, then the Radon-Nikodym derivative of P_X f_X , is called the *density function* of X.

Definition 10.7 (Independence). Let (Ω, \mathscr{A}, P) be a probability space, and led $\{A_i\}_{i\in I}$ be an indexed family of events in \mathscr{A} . The events A_i are called *independent* if for each finite subset I_0 of I we have $P(\cap_{i\in I_0}A_i)=\prod_{i\in I_0}P(A_i)$. Let $\{X_i\}_{i\in I}$ be an indexed family of random variables defined on (Ω, \mathscr{A}, P) and with values in the measurable space (S, \mathscr{B}) . The random variables X_i are aclled *independent* if for each choice of sets $A_i \in \mathscr{B}$, $i \in I$, the events $X_i^{-1}(A_i)$ are independent. Finally if $\{\mathscr{A}\}_{i\in I}$ is an indexed family of sub- σ -algebras of \mathscr{A} , then the σ -algebras \mathscr{A}_i are independent if for each choice $A_i \in \mathscr{A}_i$ the events A_i are independent.