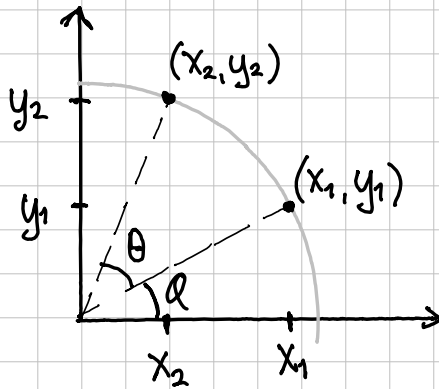


CORDIC Algorithm



$$x_1 = \cos Q$$

$$y_1 = \sin Q$$

$$x_2 = \cos(Q + \theta)$$

$$y_2 = \sin(Q + \theta)$$

$$\Delta x = \cos Q - \cos(Q + \theta)$$

$$= \cos Q - \cos Q \cos \theta + \sin Q \sin \theta$$

$$= x_1(1 - \cos \theta) + y_1 \sin \theta$$

$$\Delta y = \sin(Q + \theta) - \sin Q$$

$$= \cos Q \sin \theta + \cos \theta \sin Q - \sin Q$$

$$= x_1 \sin \theta + y_1(\cos \theta - 1)$$

$$x_2 = x_1 - \Delta x$$

$$x_2 = x_1 - (x_1(1 - \cos \theta) + y_1 \sin \theta)$$

$$x_2 = x_1 \cos \theta - y_1 \sin \theta$$

$$y_2 = y_1 + x_1 \sin \theta + y_1(\cos \theta - 1)$$

$$y_2 = x_1 \sin \theta + y_1 \cos \theta$$

$$x_2 = x_1 \cos \theta - y_1 \sin \theta$$

$$y_2 = x_1 \sin \theta + y_1 \cos \theta$$

$$\cos \theta = \frac{1}{\sqrt{1+\tan^2 \theta}}$$

$$\sin \theta = \frac{\tan \theta}{\sqrt{1+\tan^2 \theta}}$$

$$\tan \theta = \pm 2^{-i}$$

$$x_2 = x_1 \cdot \frac{1}{\sqrt{1+\tan^2 \theta}} - y_1 \frac{\tan \theta}{\sqrt{1+\tan^2 \theta}}$$

$$y_2 = x_1 \frac{\tan \theta}{\sqrt{1+\tan^2 \theta}} + y_1 \frac{1}{\sqrt{1+\tan^2 \theta}}$$

$$x_2 = \frac{1}{\sqrt{1+\tan^2 \theta}} (x_1 - y_1 \tan \theta)$$

$$y_2 = \frac{1}{\sqrt{1+\tan^2 \theta}} (x_1 \tan \theta + y_1)$$

$$x_{i+1} = \frac{1}{\sqrt{1+\tan^2 \theta}} (x_i - y_i \tan \theta)$$

$$y_{i+1} = \frac{1}{\sqrt{1+\tan^2 \theta}} (x_i \tan \theta + y_i)$$

$$x_{i+1} = \frac{1}{\sqrt{1+2^{-2i}}} (x_i \pm 2^{-i} y_i)$$

$$y_{i+1} = \frac{1}{\sqrt{1+2^{-2i}}} (y_i \pm 2^{-i} x_i)$$

We can scale x and y after n iterations:

$$K(n) = \prod_{i=0}^{n-1} K_i = \prod_{i=0}^{n-1} \frac{1}{\sqrt{1+2^{-2i}}}$$

$$x_{i+1} = x_i \pm 2^{-i} y_i$$

$$y_{i+1} = y_i \pm 2^{-i} x_i$$

$$\cos \theta \approx x = K(n) x_n$$

$$\sin \theta \approx y = K(n) y_n$$

To decide rotation direction we keep track of rotated angle at each iteration

$$\theta_0 = \theta$$

$$\theta_{i+1} < 0 \Rightarrow \sigma_{i+1} = -1$$

$$\theta_{i+1} = \theta_i - \sigma_i \gamma_i$$

$$\theta_{i+1} > 0 \Rightarrow \sigma_{i+1} = 1$$

γ_i is rotated angle at iteration i

$$x_{i+1} = x_i - \sigma_i \gamma_i 2^{-i}$$

$$x_0 = 1$$

$$y_{i+1} = y_i + \sigma_i x_i 2^{-i}$$

$$y_0 = 0$$

$$\theta_{i+1} = \theta_i - \sigma_i \gamma_i$$

$$\theta_0 = \theta$$

$$\sigma_i = \begin{cases} 1 & \theta_{i+1} \geq 0 \\ -1 & \theta_{i+1} < 0 \end{cases}$$

$$\sigma_0 = \begin{cases} 1 & \theta_0 \geq 0 \\ -1 & \theta_0 < 0 \end{cases}$$

$$K(n) = \prod_{i=0}^{n-1} \frac{1}{\sqrt{1+2^{-2i}}}$$

$$\cos \theta \approx K(n) x_n$$

$$\sin \theta \approx K(n) y_n$$