

view\_frames Result

Recorded at time: 1548216004.091

robot\_1/map

Broadcaster: /robot\_1/slam\_gmapping  
Average rate: 20.204 Hz  
Most recent transform: 1548216004.123 ( -0.033 sec old)  
Buffer length: 4.900 sec

robot\_1/odom

Broadcaster: /robot\_1/mobile\_base\_nodelet\_manager  
Average rate: 20.690 Hz  
Most recent transform: 1548216004.075 ( 0.016 sec old)  
Buffer length: 4.930 sec

robot\_1/base\_footprint

Broadcaster: /robot\_1/robot\_state\_publisher  
Average rate: 10000.000 Hz  
Most recent transform: 0.000 ( 1548216004.091 sec old)  
Buffer length: 0.000 sec

robot\_1/base\_link

Broadcaster: /robot\_1/robot\_state\_publisher  
Average rate: 10000.000 Hz  
Most recent transform: 0.000 ( 1548216004.091 sec old)  
Buffer length: 0.000 sec

robot\_1/caster\_back\_link

Broadcaster: /robot\_1/robot\_state\_publisher  
Average rate: 10000.000 Hz  
Most recent transform: 0.000 ( 1548216004.091 sec old)  
Buffer length: 0.000 sec

robot\_1/caster\_front\_link

Broadcaster: /robot\_1/robot\_state\_publisher  
Average rate: 10000.000 Hz  
Most recent transform: 0.000 ( 1548216004.091 sec old)  
Buffer length: 0.000 sec

robot\_1/cliff\_sensor\_front\_link

Broadcaster: /robot\_1/robot\_state\_publisher  
Average rate: 10000.000 Hz  
Most recent transform: 0.000 ( 1548216004.091 sec old)  
Buffer length: 0.000 sec

robot\_1/cliff\_sensor\_left\_link

Broadcaster: /robot\_1/robot\_state\_publisher  
Average rate: 10000.000 Hz  
Most recent transform: 0.000 ( 1548216004.091 sec old)  
Buffer length: 0.000 sec

robot\_1/cliff\_sensor\_right\_link

Broadcaster: /robot\_1/robot\_state\_publisher  
Average rate: 10000.000 Hz  
Most recent transform: 0.000 ( 1548216004.091 sec old)  
Buffer length: 0.000 sec

robot\_1/gyro\_link

Broadcaster: /robot\_1/robot\_state\_publisher  
Average rate: 10000.000 Hz  
Most recent transform: 0.000 ( 1548216004.091 sec old)  
Buffer length: 0.000 sec

robot\_1/base\_scan

Broadcaster: /robot\_1/base\_scan  
Average rate: 10000.000 Hz  
Most recent transform: 0.000 ( 1548216004.091 sec old)  
Buffer length: 0.000 sec

robot\_1/wheel\_left\_link

Broadcaster: /robot\_1/robot\_state\_publisher  
Average rate: 16.024 Hz  
Most recent transform: 1548216004.075 ( 0.016 sec old)  
Buffer length: 4.930 sec

robot\_1/wheel\_right\_link

Broadcaster: /robot\_1/robot\_state\_publisher  
Average rate: 16.024 Hz  
Most recent transform: 1548216004.075 ( 0.016 sec old)  
Buffer length: 4.930 sec