



A Sensor is a particular operator that waits for a condition to be true. If the condition is true, the task is marked successful, and the next task runs. If the condition is false, the sensor waits for another interval until it times out and fails.

Implementing a Sensor is as simple as shown below:

```
from airflow import DAG
from airflow.sensors.python import PythonSensor
def condition():
    return False
with DAG(
    dag_id="sensor",
    start_date=datetime(2021, 1, 1),
    schedule="@daily",
    catchup=False,
):
    waiting_for_condition = PythonSensor(
        task_id="waiting_for_condition",
        python_callable=_condition,
        poke_interval=60,
        timeout=7 * 24 * 60 * 60
    )
```

In the example above, the Sensor checks $_$ condition to be true every 60 seconds by default (poke_interval). Since $_$ condition always returns False, the Sensor will continue checking every 60 seconds until it times out after 7 days (7 * 24 * 60 * 60 by default). When the Sensor times out, it is marked failed.

That's it.

Now that you know what Sensors are, let's discover how do they work and why they are so useful.

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