

# Silverback CPU

## User Manual

Emiliano Gutierrez

### 1. Name of the CPU

For this project, I designed and built a small single-cycle CPU that I ended up calling the **Silverback CPU**. The name doesn't have any deep meaning behind it—I just wanted something simple and cool, lol.

### 2. Partner

I didn't choose to have a partner due to the grades of the first project.

### 3. Job Description

Since I worked alone, all parts of the project were my responsibility. This included:

- designing the overall datapath,
- choosing the instruction format and encodings,
- wiring everything in Logisim-Evolution,
- writing the Python assembler,
- testing instructions and writing the demo program,
- putting together this user manual.

### 4. How to Use the Assembler

#### 4.1 Running the Assembler

The assembler file is called `Silverback.py`. It reads a text file with my custom assembly language and outputs a hex file that Logisim understands.

Run it like this:

```
python3 Silverback.py demo.s demo.hex
```

The script doesn't use any special libraries and doesn't check for syntax errors, so the assembly program needs to be written correctly.

## 4.2 Loading the Machine Code Into Logisim

Once the hex file is created, you can load it:

1. Open `Silverback.circ`.
2. Click on the ROM component.
3. Choose "Load Image".
4. Select the hex file (e.g., `demo.hex`).

If your program uses loads, make sure RAM has the right initial values. You can click on RAM, go to "Edit Contents," and type in values before running the CPU.

## 5. CPU Architecture Description

### 5.1 Register File

Silverback has **four general-purpose registers**: R0, R1, R2, and R3. They each store an 8-bit value. The assembly language refers to them directly as **R0–R3**.

The datapath can read two registers in a single cycle and write to one, which is enough for the ADD and SUB formats I chose.

### 5.2 ALU

The ALU is simple but does what it needs to:

- **ADD**:  $R_n + R_m$
- **SUB**:  $R_n - R_m$

A single control bit decides which operation happens. I chose ADD and SUB because they're straightforward to wire and easy to test, but also because the project required at least two arithmetic operations.

## 5.3 Memory

There are two memory blocks:

- **ROM** (256x8) for instructions.
- **RAM** (256x8) for load/store instructions.

## 5.4 Load/Store Addressing

Loads and stores use a base register plus a small offset. The effective address is:

$$Address = BaseRegister + Offset$$

The offset is only 2 bits, but that's enough for testing memory behavior without making the instruction too big.

# 6. Instruction Format and Encodings

All instructions are **8 bits long**. I split them into four equal 2-bit fields:

$$Opcode(2) \mid Field1(2) \mid Field2(2) \mid Field3(2).$$

This made decoding much easier in Logisim since everything stays the same width.

## 6.1 Why 2 Bits for Everything?

- There are only four instructions, so the opcode only needs 2 bits.
- I have four registers, so each register field needs 2 bits.
- Offsets for load/store only need to be small (0–3), so 2 bits works fine.

## 6.2 Register Encodings

Register	Bits
R0	00
R1	01
R2	10
R3	11

### 6.3 Opcode Table

Instruction	Meaning	Opcode
ADD	Add two registers	00
SUB	Subtract two registers	01
LDR	Load from memory	10
STR	Store to memory	11

### 6.4 Instruction Formats

**ADD Rd, Rn, Rm**

$$00 \mid Rd \mid Rn \mid Rm$$

$$Rd \leftarrow Rn + Rm$$

**SUB Rd, Rn, Rm**

$$01 \mid Rd \mid Rn \mid Rm$$

$$Rd \leftarrow Rn - Rm$$

**LDR Rt, offset(Rs)**

$$10 \mid Rt \mid Rs \mid offset$$

$$Rt \leftarrow RAM[Rs + offset]$$

**STR Rt, offset(Rs)**

$$11 \mid Rt \mid Rs \mid offset$$

$$RAM[Rs + offset] \leftarrow Rt$$

## 7. Summary

Overall, the Silverback CPU is...

- four 8-bit general-purpose registers,
- ADD and SUB instructions on the ALU,
- load/store instructions with offset addressing,
- an 8-bit uniform instruction encoding,
- a working assembler and demo program,
- and a complete single-cycle datapath.

Even though the design is small, building it helped me understand how instructions actually move through the datapath and how control signals are generated.