

$$\begin{array}{l} \text{??} \\ \text{???} \\ \text{?} \\ \text{?} \\ \text{?} \\ \text{?} \end{array} \quad \begin{array}{l} \text{?} \\ \text{?} \\ \text{?} \\ \text{?} \\ \text{?} \\ \text{?} \end{array} \quad \begin{array}{l} \text{?} \\ \text{?} \\ \text{?} \\ \text{?} \\ \text{?} \\ \text{?} \end{array}$$

$$\mathcal{L}_{SL} = -\frac{1}{m} \sum_{i=1}^m \log \frac{e^{w_{y_i}^T x_i}}{\sum_{k \in D} e^{w_k^T x_i}}$$

$$(1) \quad \begin{array}{l} D = \\ 1, \dots, n(\cdot)^T x_i \in \\ R^d y_i \in \\ Dw_k \in \\ R^d W = \\ [w_1, w_2, \dots, w_n] \in \\ R^{d \times n} nm \\ kw_k w_k k A_{kl} kl A_{kl} \end{array}$$

$$\cos(A_{kl}) = \frac{w_k^T}{\|w_k\|} \frac{w_l}{\|w_l\|} = \hat{w}_k^T \hat{w}_l$$

$$(2) \quad \begin{array}{l} \hat{w}_k \hat{w}_l w_k w_l ||| \cos(A_{kl}) A_{kl} \\ \text{??} \end{array}$$

$$\mathcal{L}_{Angle} = \sum_{k \in \mathcal{D}} \sum_{l \in \mathcal{D}, l \neq k} \hat{w}_k^T \hat{w}_l$$

$$(3) \quad \begin{array}{l} \mathcal{L}_{Angle} \mathcal{L}_{Angle} \\ d \geq \\ n- \\ 1 \hat{w}_k^T \hat{w}_l = \\ 1/(1- \\ n) \mathcal{L}_{Angle} - n \mathcal{L}_{Angle} = \\ -n A_{kl} = \\ \arccos(1/(1- \\ n)) \mathcal{L}_{Angle} \\ A_{kl} = \\ \arccos(1/(1- \\ n)) \mathcal{L}_{Angle} = \\ -n \mathcal{L}_{Angle} A_{kl} A_{kl} = \\ \arccos(1/(1- \\ n)) A_{kl} = \\ \arccos(1/(1- \\ n)) \text{??} \end{array}$$

$$\mathcal{L}_{ASL} = -\frac{1}{m} \sum_{i=1}^m \log \frac{e^{w_{y_i}^T x_i}}{\sum_{k \in D} e^{w_k^T x_i}}$$

$$(4) \quad s.t. \|w_k\| = 1 and w_k^T w_l = \frac{1}{1-n} \cdot (k, l \in \mathcal{D})$$

$$\begin{array}{l} \text{????} w_k ? \\ \text{???} \end{array}$$

$$\mathcal{L}_{CL} = \frac{1}{2m} \sum_{i=1}^m \|x_i - c_{y_i}\|^2$$

$$(5) \quad c_{y_i} y_i$$

$$(6) \quad \begin{array}{l} \mathcal{L} = \mathcal{L}_{SL} + \lambda \mathcal{L}_{CL} \\ \lambda \lambda = \\ 0 \lambda \\ w_k \Upsilon_k w_k \Upsilon_k ?? \end{array}$$

$$\mathcal{L}_C = \frac{1}{2m} \sum_{i=1}^m \|x_i - \Upsilon_{y_i} w_{y_i}\|^2$$

$$(7) \quad \begin{array}{l} \Upsilon_{y_i} w_{y_i} x_i y_i x_i \Upsilon_{y_i} w_{y_i} \mathcal{L}_C \\ \text{??} \end{array}$$