

Digital Logic Design: a rigorous approach ©

Chapter 17: Flip-Flops

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Book Homepage:

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Preliminary questions

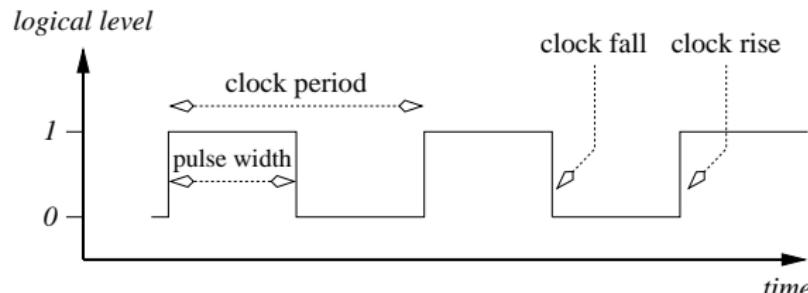
- ① How is time measured in a synchronous circuit?
- ② What is a “clock” in a microprocessor?
- ③ What is the frequency of a clock?
- ④ How are bits stored?
- ⑤ What is the functionality of a flip-flop?
- ⑥ What is a stable state? How many stable states does a flip-flop have?
- ⑦ How does a flip-flop move from one stable state to another?
- ⑧ How fast is this transition?

The clock

the clock is generated by rectifying and amplifying a signal generated by special non-digital devices (e.g., crystal oscillators).

Definition

A **clock** is a periodic logical signal that oscillates instantaneously between logical one and logical zero. There are two instantaneous transitions in every clock period: (i) in the beginning of the clock period, the clock transitions instantaneously from zero to one; and (ii) at some time in the interior of the clock period, the clock transitions instantaneously from one to zero.



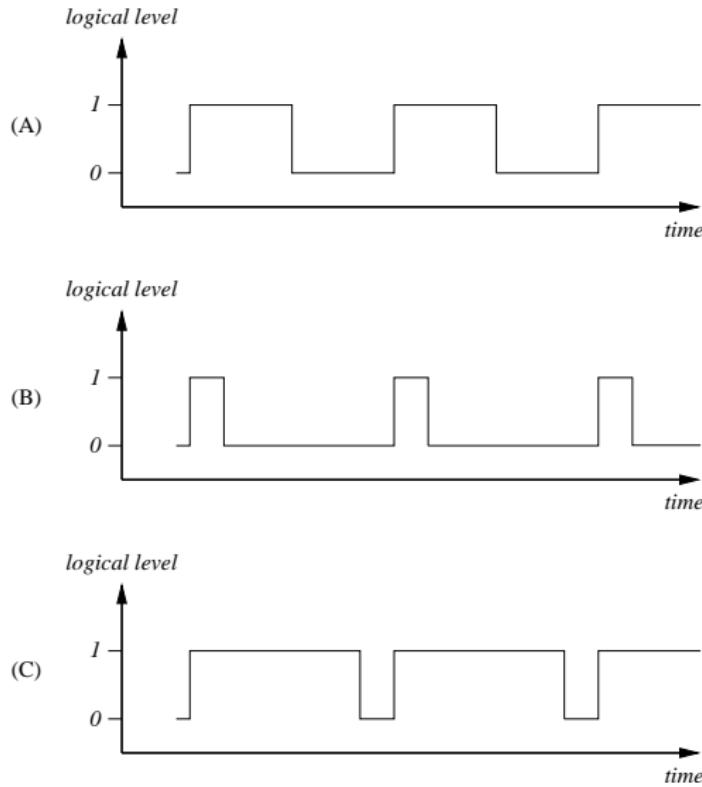


Figure: (A) A symmetric clock (B) narrow pulses (C) wide pulses.

Clock cycles

- A clock partitions time into discrete intervals.
- t_i - the starting time of the i th clock period.
- $[t_i, t_{i+1})$ -clock cycle i .

Definition (edge-triggered flip-flop)

Inputs: $D(t)$ and a clock CLK.

Output: $Q(t)$.

Parameters: Four parameters are used to specify the functionality of a flip-flop:

- **Setup-time** denoted by t_{su} ,
- **Hold-time** denoted by t_{hold} ,
- **Contamination-delay** denoted by t_{cont} , and
- **Propagation-delay** denoted by t_{pd} .

Terminology Require $-t_{su} < t_{hold} < t_{cont} < t_{pd}$.

- **critical segment**: $C_i \stackrel{\triangle}{=} [t_i - t_{su}, t_i + t_{hold}]$
- **instability segment**: $A_i \stackrel{\triangle}{=} [t_i + t_{cont}, t_i + t_{pd}]$

Functionality: If $D(t)$ is stable during the critical segment C_i , then $Q(t) = D(t_i)$ during the interval $(t_i + t_{pd}, t_{i+1} + t_{cont})$.

Critical and instability segments in a flip-flop

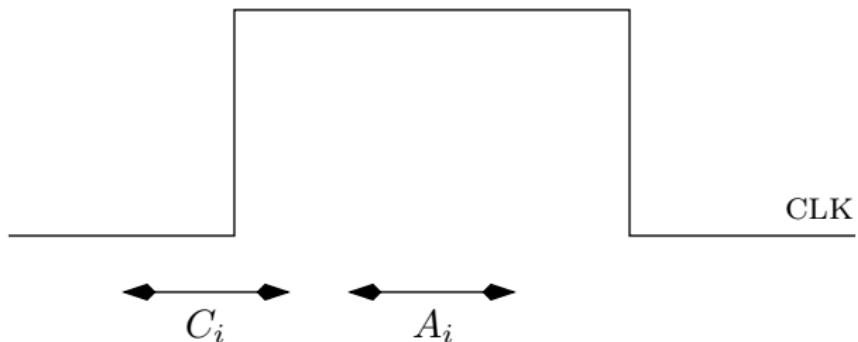
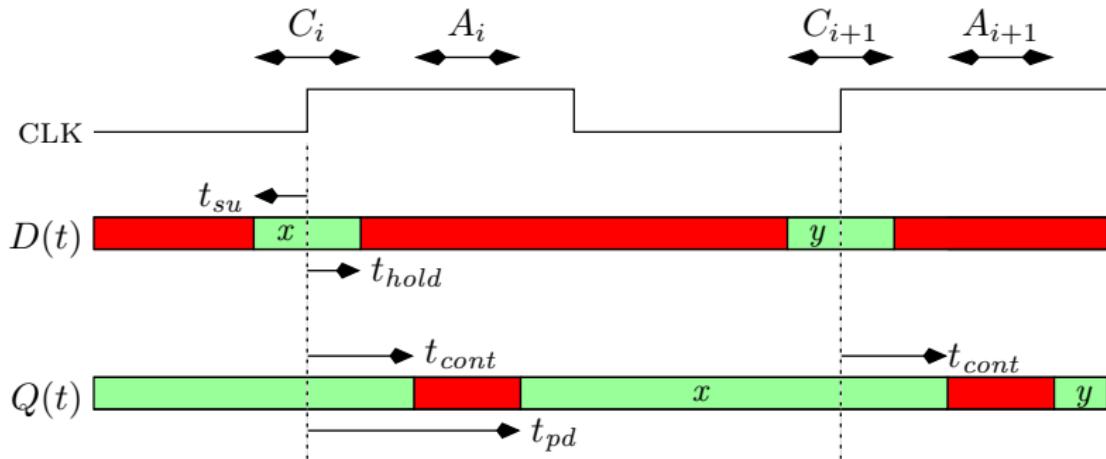


Figure: The critical segment $C_i = [t_i - t_{su}, t_i + t_{hold}]$ and instability segment $A_i = [t_i + t_{cont}, t_i + t_{pd}]$ corresponding the clock period starting at t_i .

Timing diagram of a Flip Flop

- The x-axis corresponds to time.
- A green interval means that the signal is stable during this interval.
- A red interval means that the signal may be unstable.

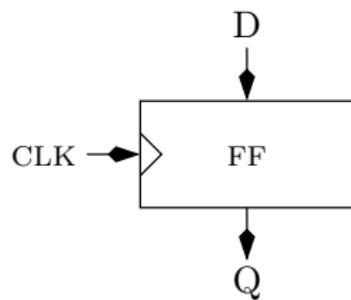


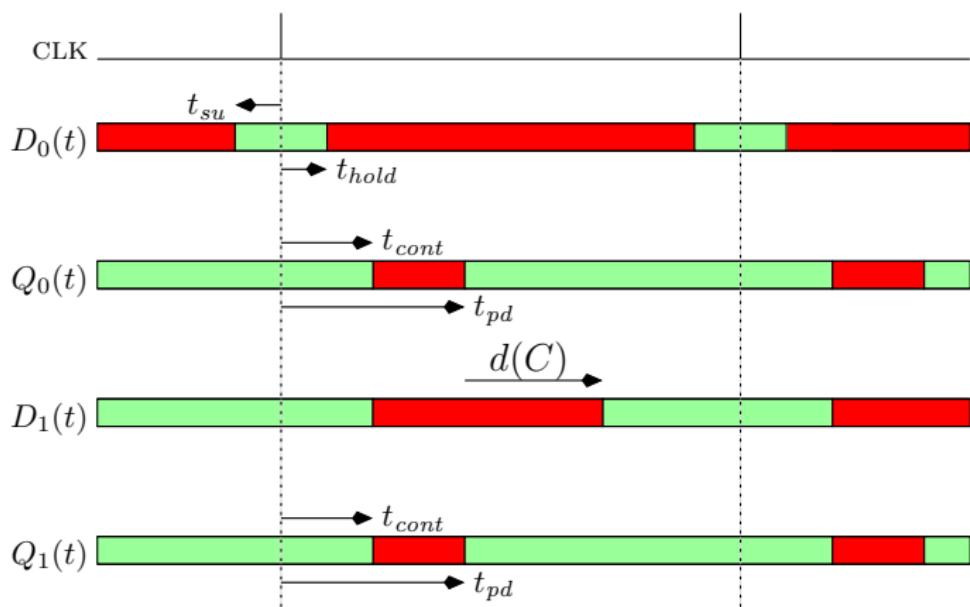
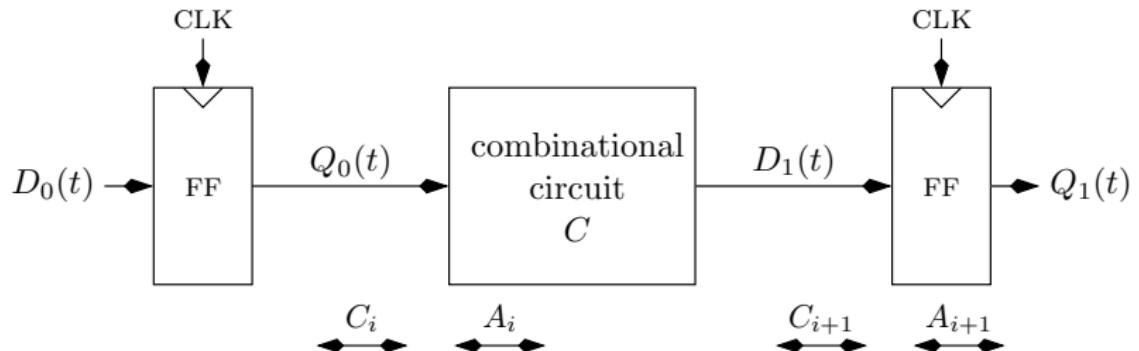
Remarks about flip-flops

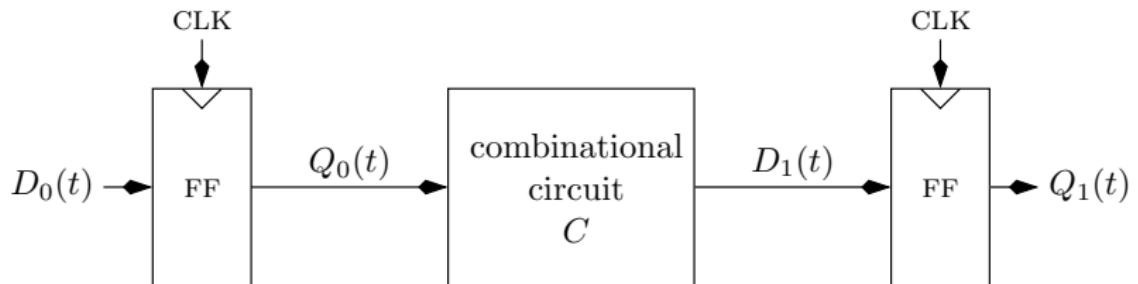
- ① The assumption $-t_{su} < t_{hold} < t_{cont} < t_{pd}$ implies that the critical segment C_i and the instability segment A_i are disjoint.
- ② If $D(t)$ is stable during the critical segment C_i , then the value of $D(t)$ during the critical segment C_i is well defined and equals $D(t_i)$.
- ③ The flip-flop **samples** the input signal $D(t)$ during the critical segment C_i . Sampling is successful only if $D(t)$ is stable while it is sampled.
- ④ If the input $D(t)$ is stable during the critical segments $\{C_i\}_i$, then the output $Q(t)$ is stable in between the instability segments $\{A_i\}_i$.
- ⑤ The stability of the input $D(t)$ during the critical segments depends on the clock period. We will later see that slowing down the clock (i.e., increasing the clock period) helps in achieving a stable signal $D(t)$ during the critical segments.

Flip-flop schematic

The special “arrow” that marks the clock input port.







CLK

$D_0(t)$

X

$Q_0(t)$

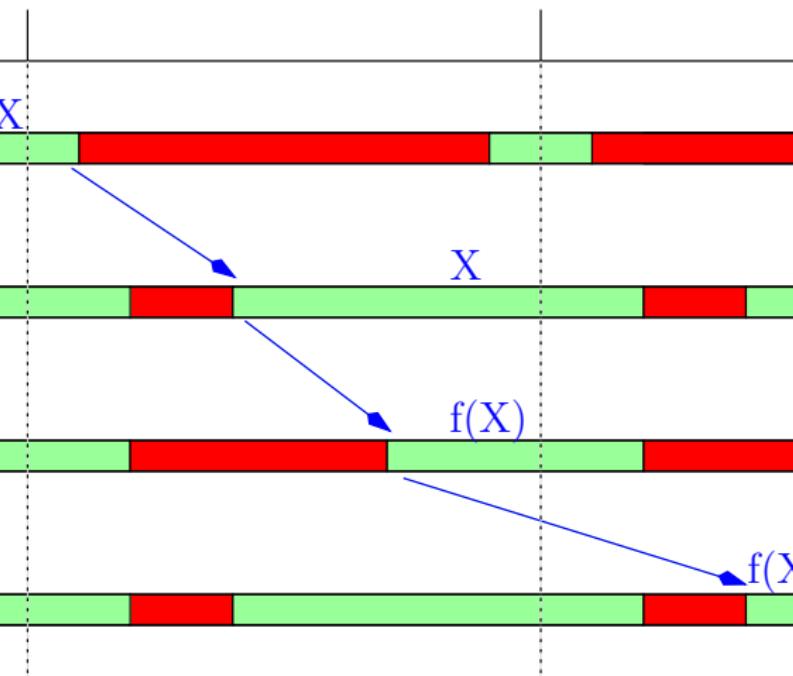
X

$D_1(t)$

$f(X)$

$Q_1(t)$

$f(X)$



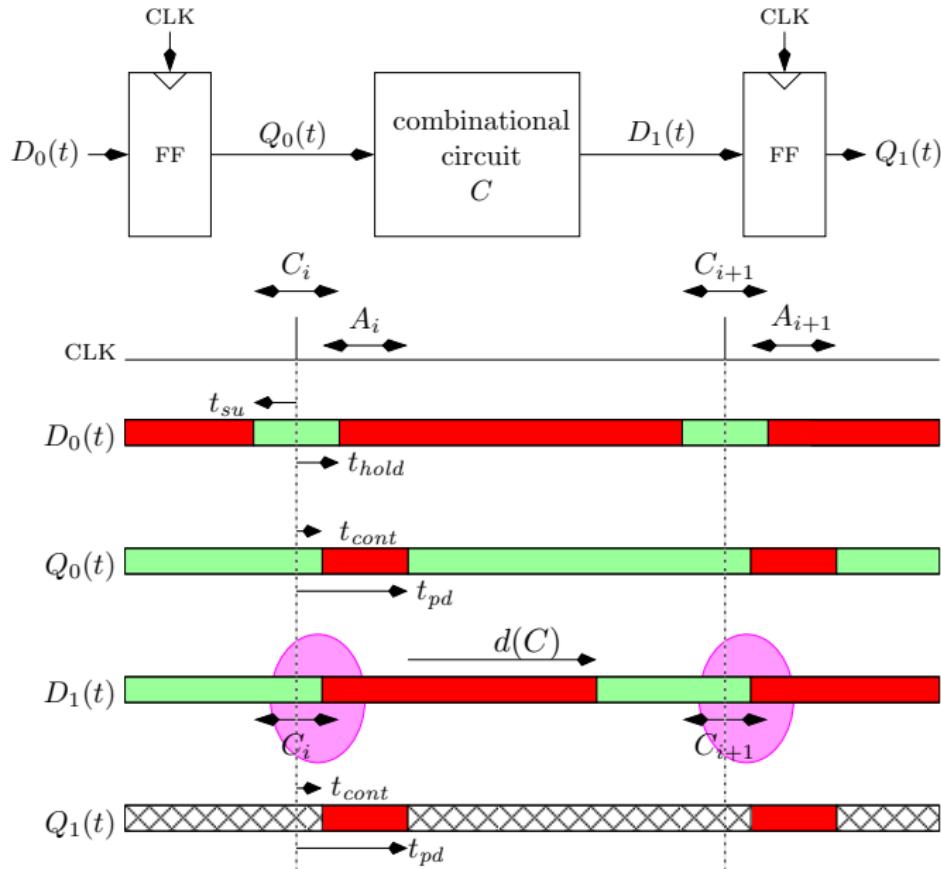
Non-empty intersection of C_i and A_i

The timing analysis fails if

$$C_i \cap A_i \neq \emptyset.$$

This could happen, if $t_{hold} > t_{cont}$ (in contradiction to the definition of a flip-flop).

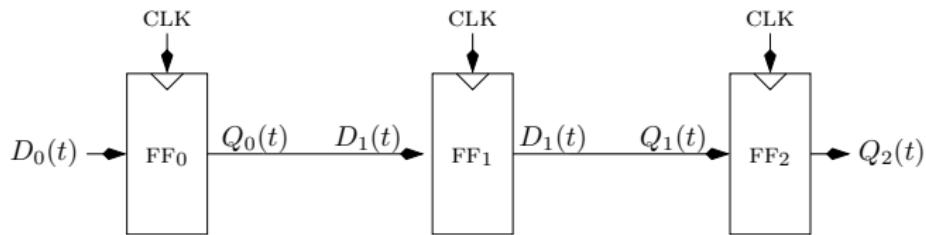
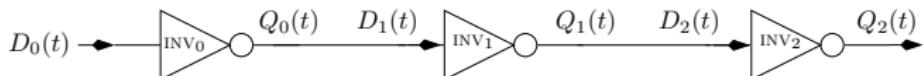
$$t_{hold} > t_{cont}$$



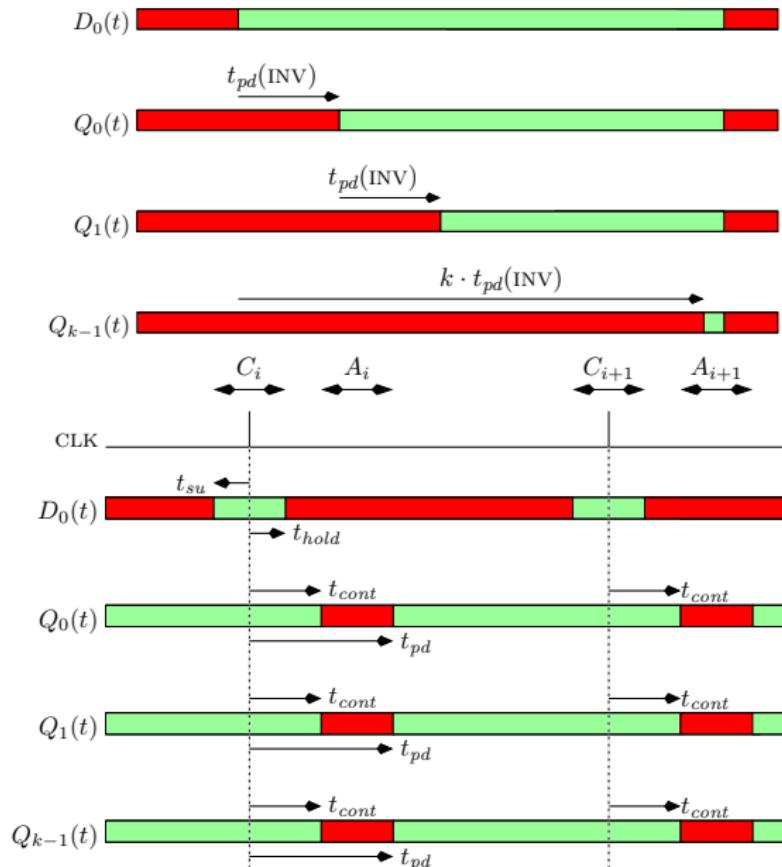
Bounding Instability

Flip-flops play a crucial role in bounding the segments of time during which signals may be unstable. Informally, uncertainty increases as the segments of stability become shorter. Flip-flops help bounding instability.

A chain of k inverters and a chain of k flip-flops



timing: chain of inverters vs. chain of FFs



Clock enabled flip-flops

Definition

A clock enabled flip-flop is defined as follows.

Inputs: Digital signals $D(t)$, $\text{CE}(t)$ and a clock CLK.

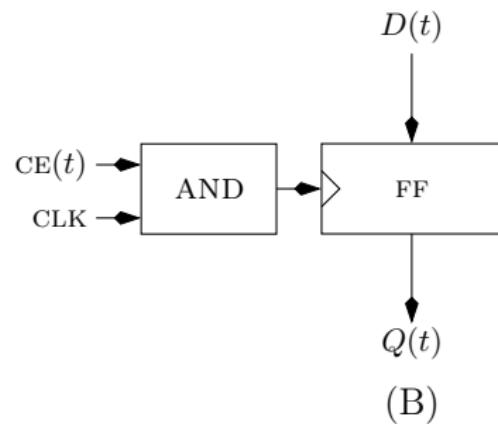
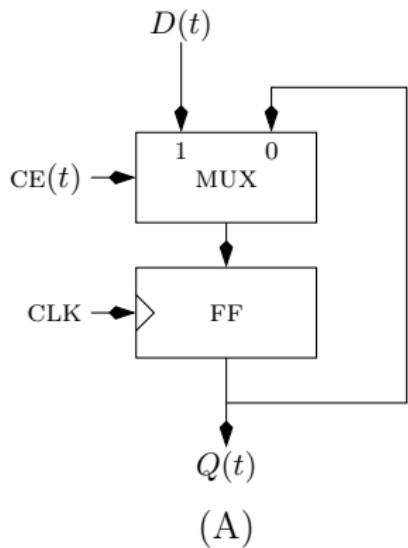
Output: A digital signal $Q(t)$.

Functionality: If $D(t)$ and $\text{CE}(t)$ are stable during the critical segment C_i , then for every $t \in (t_i + t_{pd}, t_{i+1} + t_{cont})$

$$Q(t) = \begin{cases} D(t_i) & \text{if } \text{CE}(t_i) = 1 \\ Q(t_i) & \text{if } \text{CE}(t_i) = 0. \end{cases}$$

We refer to the input signal $\text{CE}(t)$ as the clock-enable signal. Note that the input $\text{CE}(t)$ indicates whether the flip-flop samples the input $D(t)$ or maintains its previous value.

Which design is a correct clock enabled FF?



Summary

- memory devices: **flip-flops** and the **clock signal**.
- The flip-flop samples the value of the input at the “end” of a clock cycle and outputs the sampled value during the “next” clock cycle.
- Flip-flops play a crucial role in bounding the segments of time during which signals may be instable.
- Flip-flops and combinational circuits have opposite roles.
 - Combinational circuits compute interesting Boolean functions but increase uncertainty.
 - Flip-flops, on the other hand, output the same value that is fed as input but they provide certainty.