

CarLexer
<div>- m_cmd : int</div> <div>- name : char[128]</div> <div>- num : int</div> <div>- role : char</div> <div>- m_errnumber : int</div> <div>- m_guided : bool</div> <div>- route : vector<unsigned int></div> <div>- m_id : int</div> <div>- from : unsigned int</div> <div>- to : unsigned int</div>
<div>+ yylex()</div> <div>+ get_name()</div> <div>+ get_num()</div> <div>+ get_errnumber()</div> <div>+ get_guided()</div> <div>+ get_cmd()</div> <div>+ get_id()</div> <div>+ get_route()</div> <div>+ get_from()</div> <div>+ get_to()</div>

SharedData
<div>+ m_alist : uint_vector</div> <div>+ m_salist : uint_vector</div> <div>+ m_palist : uint_vector</div> <div>+ lon : int</div> <div>+ lat : int</div>
<div>+ SharedData(void_alloc : const void_allocator&)</div>

SmartCity
<div># segment : managed_shared_memory*</div> <div># shm_map : offset_ptr<shm_map_Type></div> <div># m_delay : int</div> <div># m_run : bool</div> <div>- m_mutex : mutex</div> <div>- m_cv : condition_variable</div> <div>- m_thread : thread</div> <div>- m_waynode_locations : WaynodeLocations</div> <div>- m_busWayNodesMap : WayNodesMap</div> <div>- m_way2nodes : Way2Nodes</div> <div>- m_way2name : WayNames</div> <div>- m_remover : shm_remove*</div>
<div>+ SmartCity(osm_file : const char *, shm_segment : const char *, map_file : const char *, mode : int)</div> <div>+ SmartCity (osm_file : const char *, shm_segment : const char *)</div> <div>~ SmartCity()</div> <div>+ node2way(node : osmium : :unsigned_object_id_type)</div> <div>+ processes () + « (os : std : :ostream&, t : SmartCity&) : std : :ostream&</div> <div>+ city_run()</div> <div>+ busWayLength (verbose : bool) : double</div>