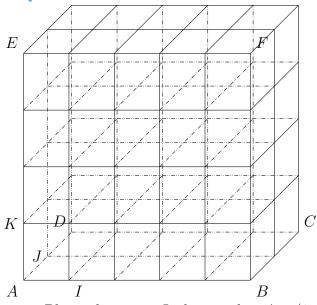


- 1. Placer le point L de coordonnées (3;0;0).
- **2.** Placer le point M de coordonnées (1; 2; 4).
- 3. Placer le point N de coordonnées (2;1;0).





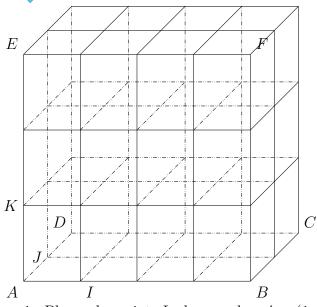


- 1. Placer le point L de coordonnées (3;0;0).
- **3.** Placer le point N de coordonnées (2;1;0).
- 2. Placer le point M de coordonnées (4;2;3).





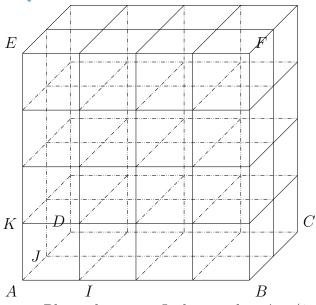




- 1. Placer le point L de coordonnées (1;0;0).
- **3.** Placer le point N de coordonnées (0;1;1).
- **2.** Placer le point M de coordonnées (4;2;3).



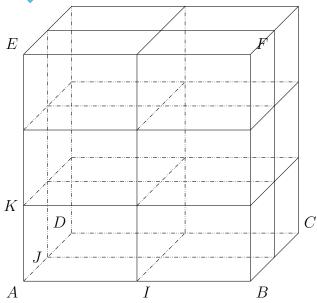




- 1. Placer le point L de coordonnées (0;1;2).
- **2.** Placer le point M de coordonnées (4; 2; 1).
- **3.** Placer le point N de coordonnées (0;0;2).



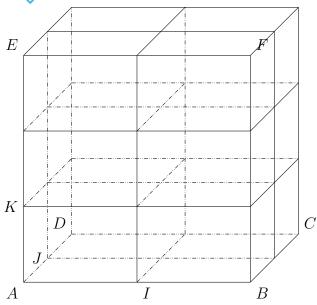




- 1. Placer le point L de coordonnées (0;0;1).
- **2.** Placer le point M de coordonnées (1;0;3).
- **3.** Placer le point N de coordonnées (2;1;2).





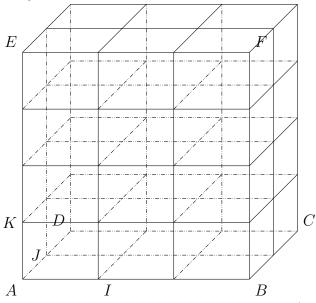


- 1. Placer le point L de coordonnées (1;0;2).
- **2.** Placer le point M de coordonnées (1;0;2).
- **3.** Placer le point N de coordonnées (0;2;0).





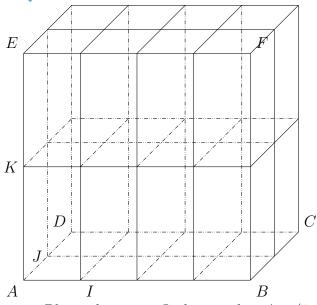




- 1. Placer le point L de coordonnées (0;0;4).
- **3.** Placer le point N de coordonnées (0;0;1).
- 2. Placer le point M de coordonnées (3;1;1).



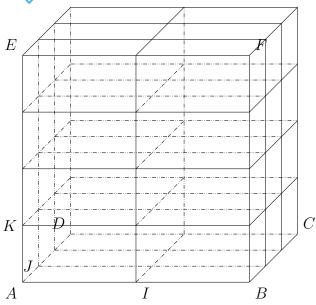




- 1. Placer le point L de coordonnées (3;1;2).
- **2.** Placer le point M de coordonnées (0;0;1).
- **3.** Placer le point N de coordonnées (0;1;2).





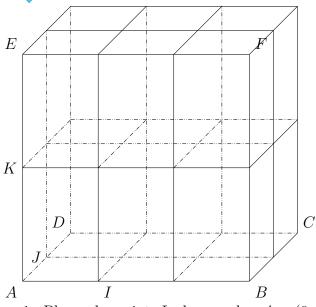


- 1. Placer le point L de coordonnées (0;0;4).
- **3.** Placer le point N de coordonnées (1;0;3).
- 2. Placer le point M de coordonnées (1;1;2).





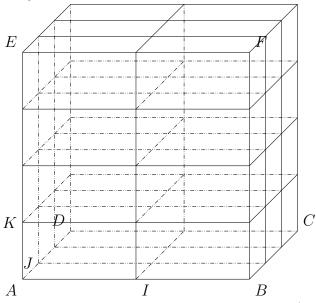




- 1. Placer le point L de coordonnées (0;2;1).
- **3.** Placer le point N de coordonnées (1;1;0).
- 2. Placer le point M de coordonnées (0;2;0).





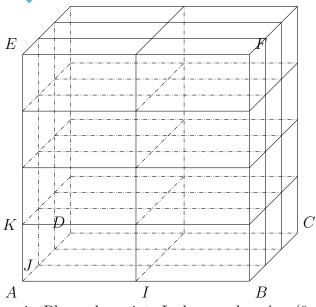


- 1. Placer le point L de coordonnées (1;3;0).
- **2.** Placer le point M de coordonnées (1;0;3).
- **3.** Placer le point N de coordonnées (2;2;4).





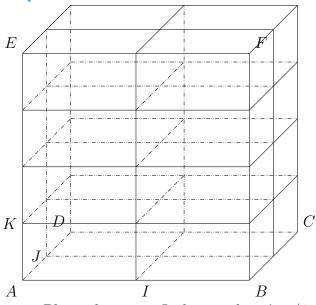




- 1. Placer le point L de coordonnées (0;1;1).
- **3.** Placer le point N de coordonnées (1;1;4).
- 2. Placer le point M de coordonnées (2;1;2).





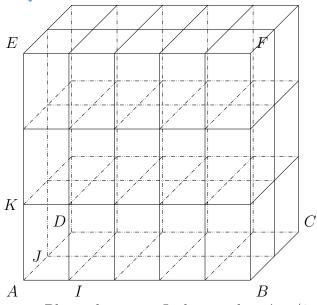


- 1. Placer le point L de coordonnées (0;1;1).
- **3.** Placer le point N de coordonnées (0;0;3).
- **2.** Placer le point M de coordonnées (1;1;2).







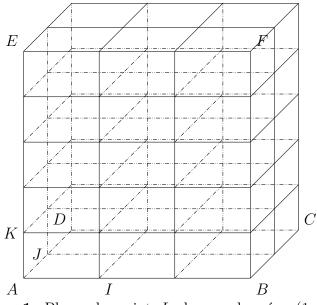


- 1. Placer le point L de coordonnées (2;0;0).
- **2.** Placer le point M de coordonnées (5;0;2).
- **3.** Placer le point N de coordonnées (0;1;0).







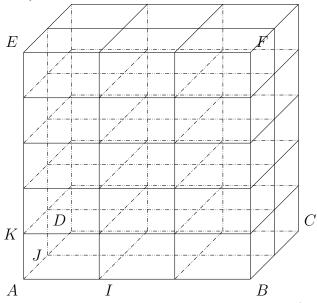


- 1. Placer le point L de coordonnées (1;0;2).
- **2.** Placer le point M de coordonnées (2;0;3).
- **3.** Placer le point N de coordonnées (0;1;3).







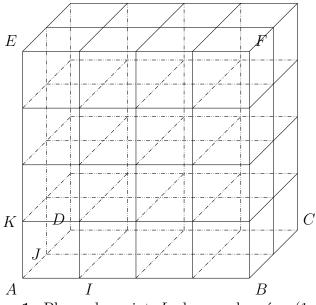


- 1. Placer le point L de coordonnées (2;1;2).
- es (2;1;2). 3. Placer le point N de coordonnées (3;1;3).
- **2.** Placer le point M de coordonnées (3;0;4).







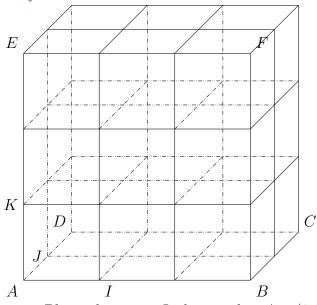


- 1. Placer le point L de coordonnées (1;0;1).
- **3.** Placer le point N de coordonnées (1;1;0).
- **2.** Placer le point M de coordonnées (2;2;1).







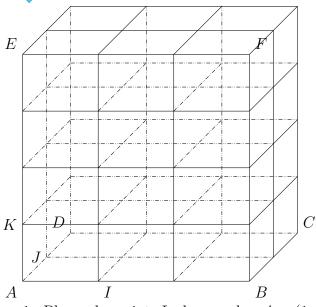


- 1. Placer le point L de coordonnées (2;0;2).
- **2.** Placer le point M de coordonnées (0;0;3).
- **3.** Placer le point N de coordonnées (0;1;2).







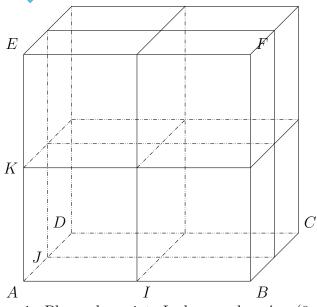


- 1. Placer le point L de coordonnées (1;2;2).
- **3.** Placer le point N de coordonnées (3;1;1).
- 2. Placer le point M de coordonnées (0;2;2).





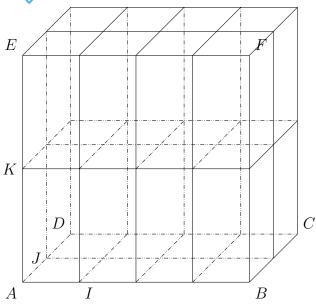




- 1. Placer le point L de coordonnées (0;1;0).
- **3.** Placer le point N de coordonnées (0;1;0).
- **2.** Placer le point M de coordonnées (0; 2; 2).





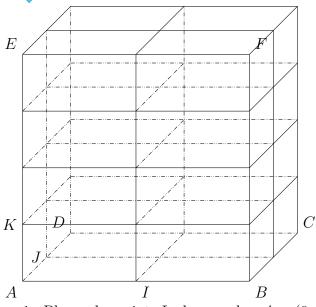


- 1. Placer le point L de coordonnées (2;0;1).
- **2.** Placer le point M de coordonnées (0; 2; 0).
- **3.** Placer le point N de coordonnées (4;1;2).







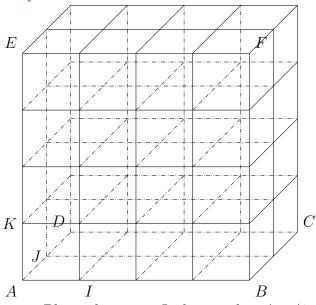


- 1. Placer le point L de coordonnées (0;1;3).
- **3.** Placer le point N de coordonnées (2;0;4).
- 2. Placer le point M de coordonnées (0;0;1).







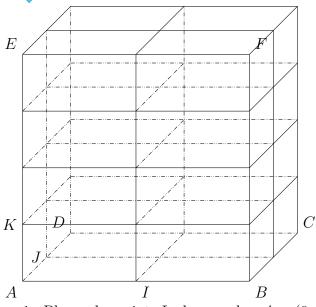


- 1. Placer le point L de coordonnées (2;0;4).
- **3.** Placer le point N de coordonnées (2;2;0).
- 2. Placer le point M de coordonnées (0;0;3).







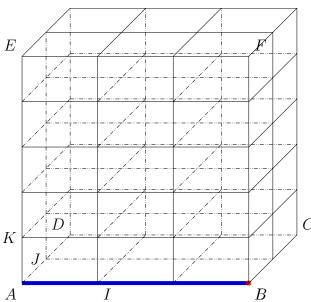


- 1. Placer le point L de coordonnées (0;2;3).
- **3.** Placer le point N de coordonnées (0;0;3).
- 2. Placer le point M de coordonnées (2;2;3).

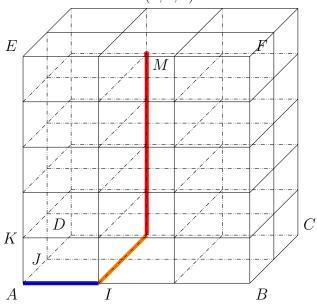




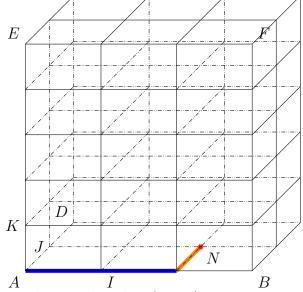
2.



**1.** L de coordonnées (3; 0; 0).



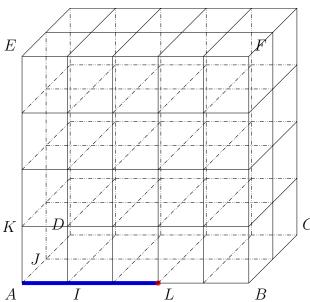
M de coordonnées (1; 2; 4).



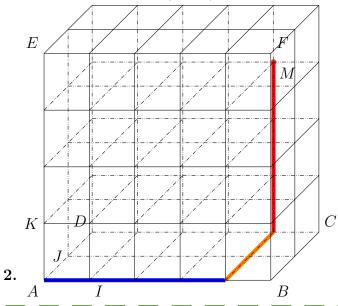
3.  $\begin{array}{ccc}
A & I \\
N & \text{de coordonnées } (\mathbf{2}; \mathbf{1}; \mathbf{0}).
\end{array}$ 



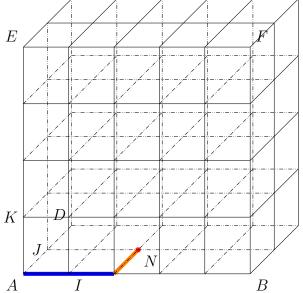




**1.** L de coordonnées (3; 0; 0).



M de coordonnées (4; 2; 3).



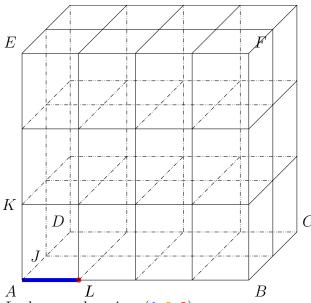
 $\begin{array}{ccc}
A & I \\
N & \text{de coordonnées } (2;1;0).
\end{array}$ 

3.

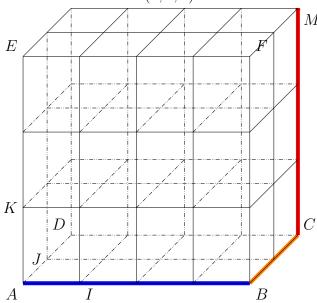




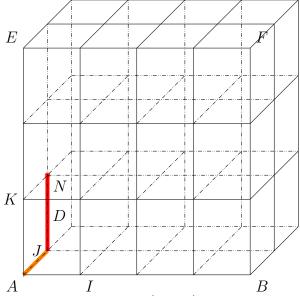
2.



**1.** L de coordonnées (1; 0; 0).



M de coordonnées (4; 2; 3).



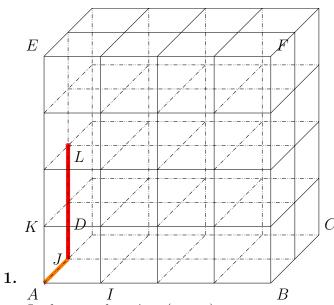
 $\begin{array}{ccc}
A & I \\
N & \text{de coordonnées } (\mathbf{0}; \mathbf{1}; \mathbf{1}).
\end{array}$ 

3.

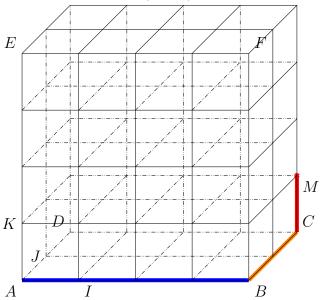




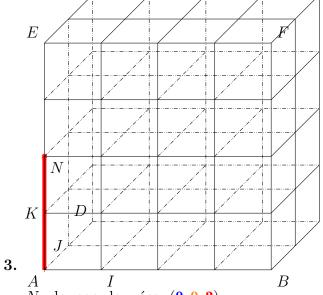
2.



A = I L de coordonnées (0; 1; 2).



M de coordonnées (4; 2; 1).

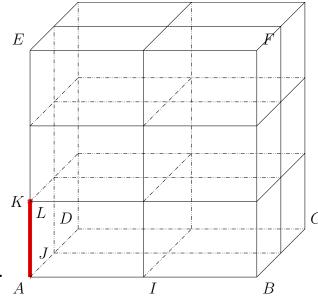


 $\begin{array}{ccc}
A & I \\
N & \text{de coordonnées } (0; 0; 2).
\end{array}$ 

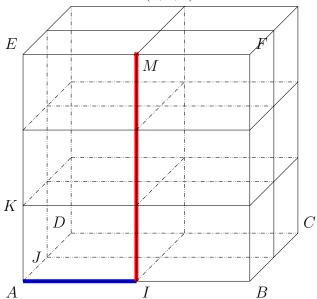




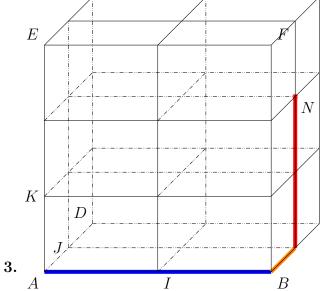
2.



1.  $\begin{array}{ccc} A & & I \\ L & {\rm de} & {\rm coordonn\acute{e}es} & \textbf{(0;0;1)}. \end{array}$ 



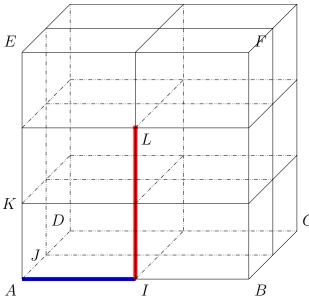
M de coordonnées (1; 0; 3).



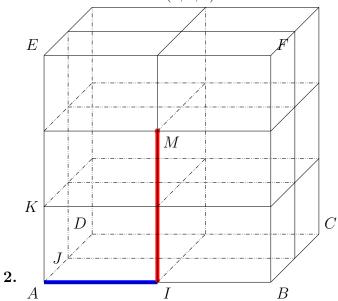
 $\stackrel{A}{N}$  de coordonnées (2; 1; 2).



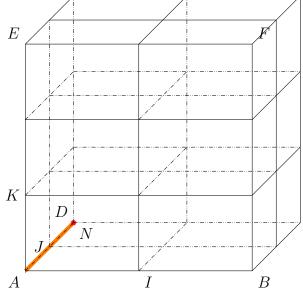




**1.** L de coordonnées (1; 0; 2).



M de coordonnées (1; 0; 2).

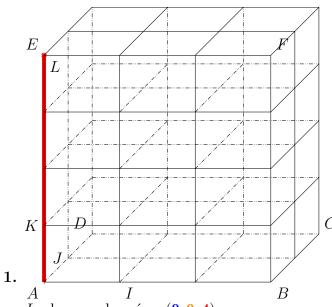


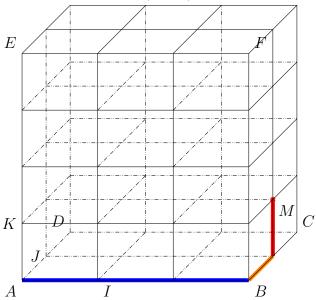
3.  $\stackrel{A}{N}$  de coordonnées (0; 2; 0).



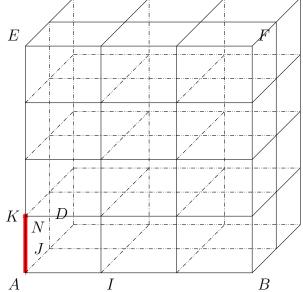


2.





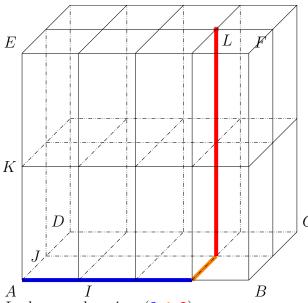
M de coordonnées (3;1;1).



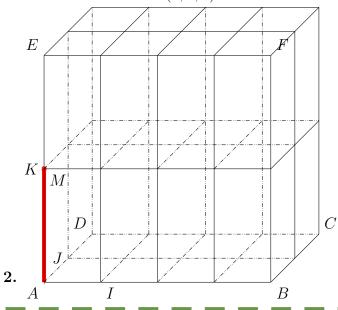
3.  $\begin{array}{ccc}
A & I \\
N & \text{de coordonnées } (\mathbf{0}; \mathbf{0}; \mathbf{1}).
\end{array}$ 



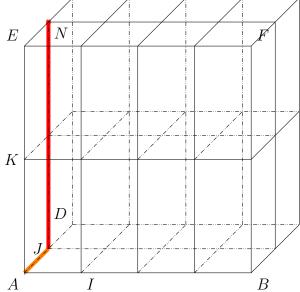




**1.** L de coordonnées (3;1;2).



M de coordonnées (0; 0; 1).



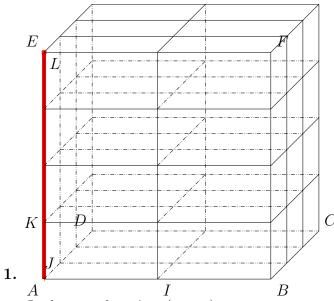
 $\begin{array}{ccc}
A & I \\
N & \text{de coordonnées } (\mathbf{0}; \mathbf{1}; \mathbf{2}).
\end{array}$ 

3.

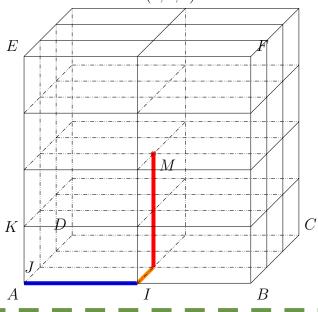




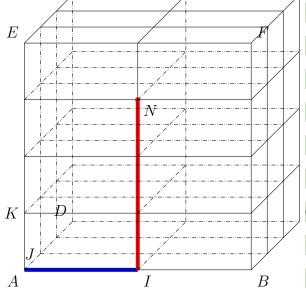
2.



 $\begin{array}{ccc} A & I \\ L & \text{de coordonn\'ees} & (\mathbf{0}; \mathbf{0}; \mathbf{4}). \end{array}$ 



M de coordonnées (1; 1; 2).

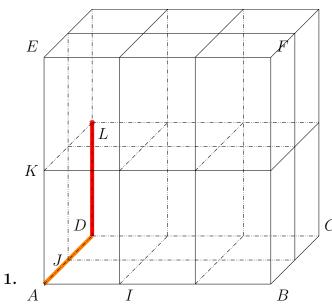


 $\stackrel{A}{N}$  de coordonnées (1; 0; 3).

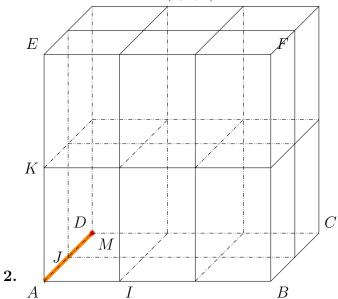
3.



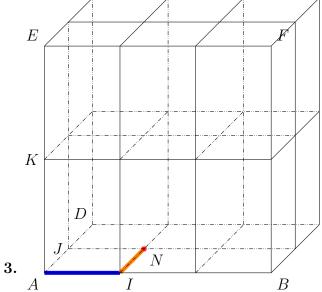




A I L de coordonnées  $(\mathbf{0}; \mathbf{2}; \mathbf{1})$ .



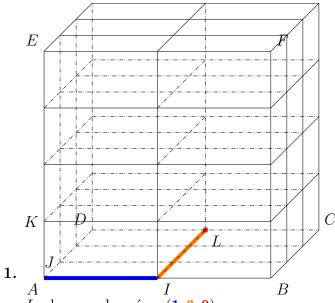
M de coordonnées (0; 2; 0).



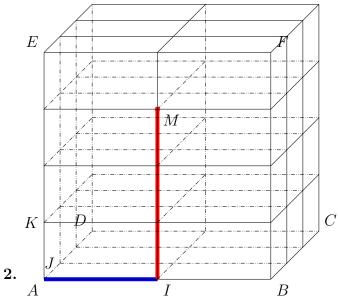
 $\begin{array}{ccc}
A & I \\
N & \text{de coordonnées } (\mathbf{1}; \mathbf{1}; \mathbf{0}).
\end{array}$ 



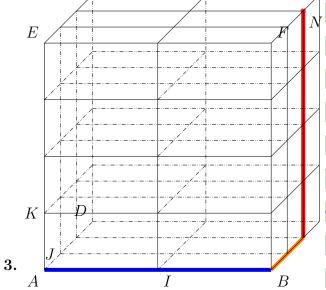




L de coordonnées (1;3;0).



M de coordonnées (1; 0; 3).

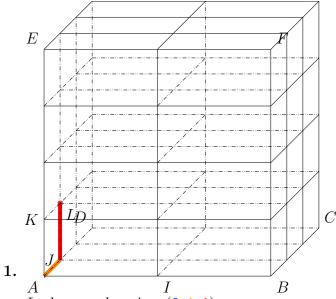


 $\begin{array}{ccc}
A & I \\
N & \text{de coordonnées} & (\mathbf{2}; \mathbf{2}; \mathbf{4}).
\end{array}$ 

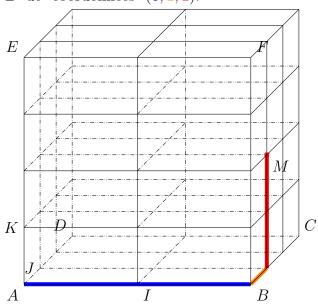




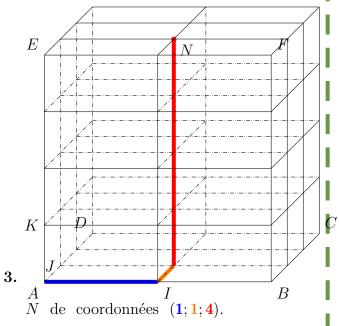
2.



L de coordonnées (0;1;1).



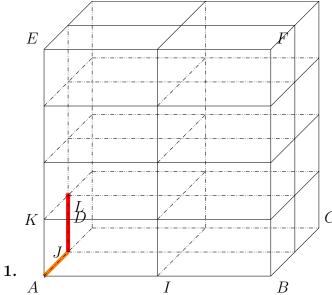
M de coordonnées (2;1;2).



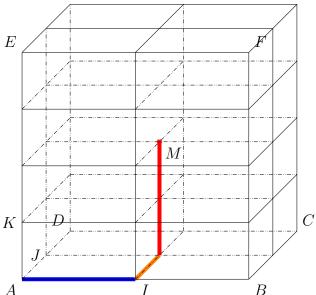




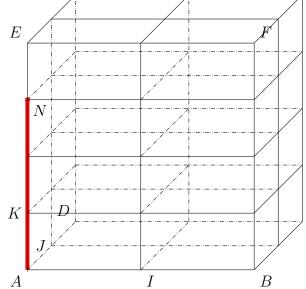
2.



L de coordonnées (0;1;1).



M de coordonnées (1;1;2).

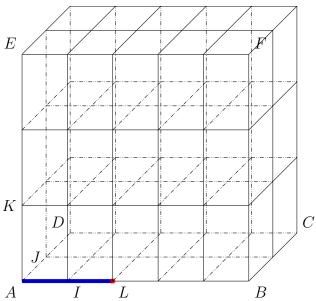


3.  $\stackrel{A}{N}$  de coordonnées (0; 0; 3).

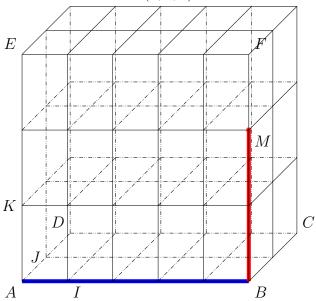




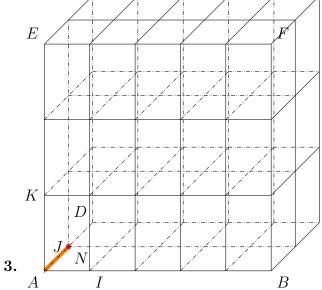
2.



**1.** L de coordonnées (2; 0; 0).



M de coordonnées  $(\mathbf{5}; \mathbf{0}; \mathbf{2})$ .

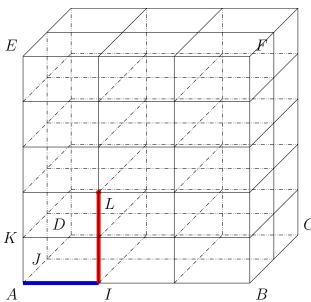


 $\begin{array}{ccc}
A & I \\
N & \text{de coordonnées } (\mathbf{0}; \mathbf{1}; \mathbf{0}).
\end{array}$ 

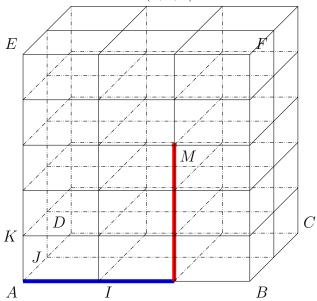




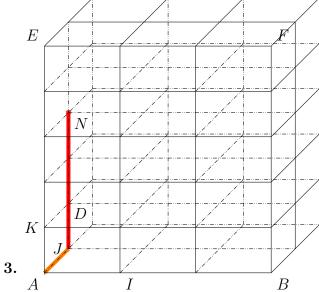
2.



**1.** L de coordonnées (1; 0; 2).



M de coordonnées (2; 0; 3).

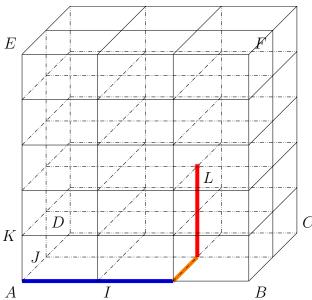


 $\begin{array}{ccc}
A & I \\
N & \text{de coordonnées } (0; 1; 3).
\end{array}$ 

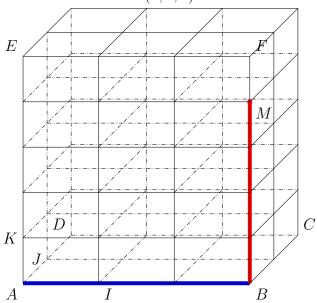




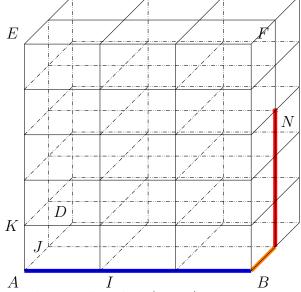
2.



**1.** L de coordonnées (2;1;2).



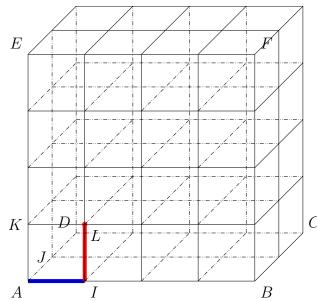
M de coordonnées (3; 0; 4).



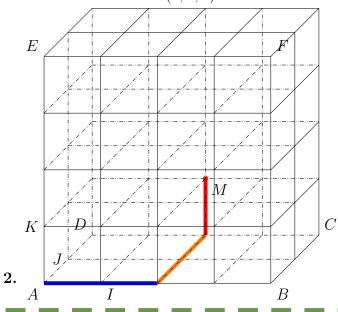
3.  $\begin{array}{ccc}
A & I \\
N & \text{de coordonnées } (\mathbf{3}; \mathbf{1}; \mathbf{3}).
\end{array}$ 



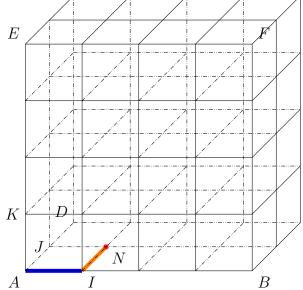




**1.** L de coordonnées (1; 0; 1).



M de coordonnées (2; 2; 1).

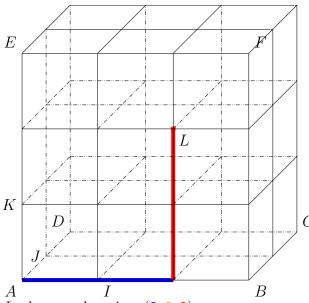


3.  $\begin{array}{ccc}
A & I \\
N & \text{de coordonnées } (1;1;0).
\end{array}$ 

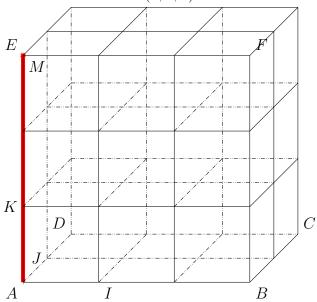




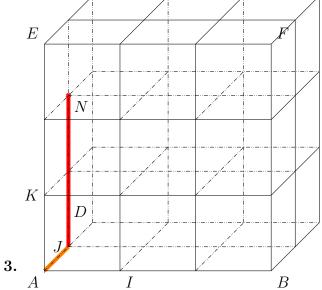
2.



**1.** L de coordonnées (2; 0; 2).



M de coordonnées (0; 0; 3).

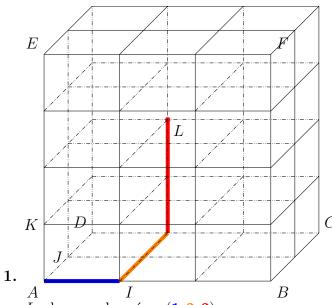


A = I N de coordonnées (0;1;2).

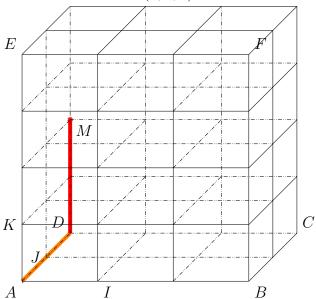




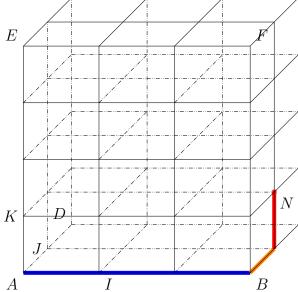
2.



L de coordonnées (1; 2; 2).



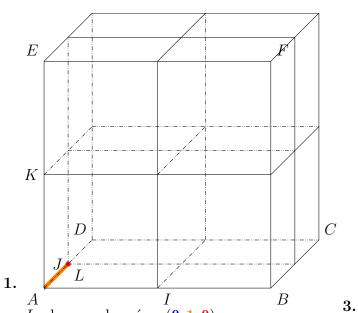
M de coordonnées  $(\mathbf{0}; \mathbf{2}; \mathbf{2})$ .



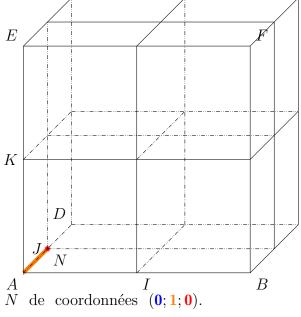
3.  $\begin{array}{ccc}
A & I \\
N & \text{de coordonnées } (\mathbf{3}; \mathbf{1}; \mathbf{1}).
\end{array}$ 







M de coordonnées  $(\mathbf{0}; \mathbf{2}; \mathbf{2})$ .

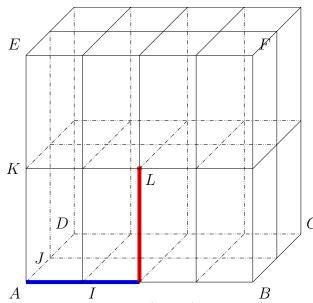


L de coordonnées (0;1;0).

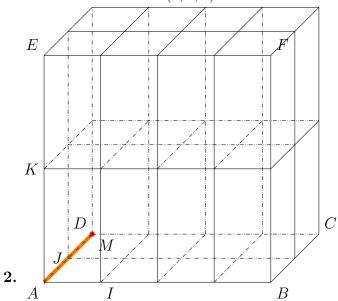
EKC2.



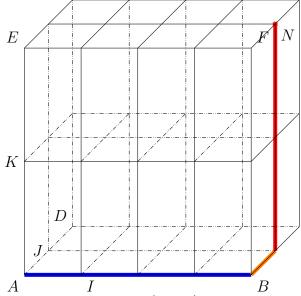




**1.** L de coordonnées (2; 0; 1).



M de coordonnées (0; 2; 0).

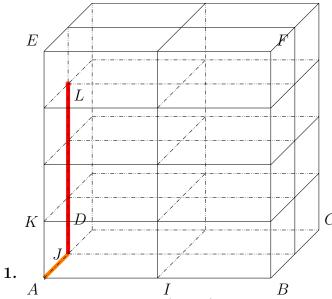


 $\stackrel{A}{N}$  de coordonnées (4; 1; 2).

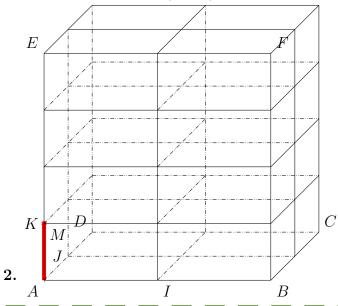
3.



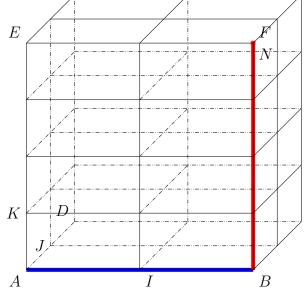




L de coordonnées (0;1;3).



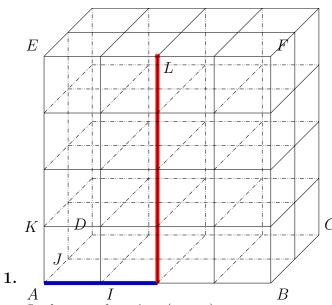
M de coordonnées  $(\mathbf{0}; \mathbf{0}; \mathbf{1})$ .



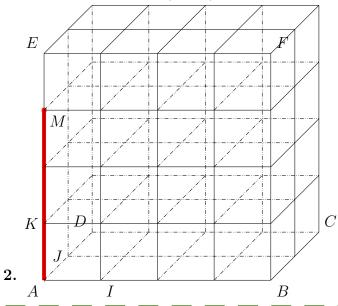
3.  $\stackrel{A}{N}$  de coordonnées (2; 0; 4).



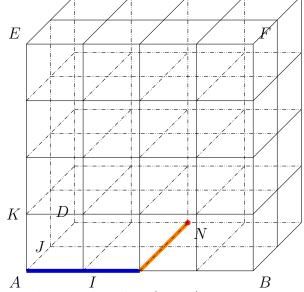




L de coordonnées (2; 0; 4).



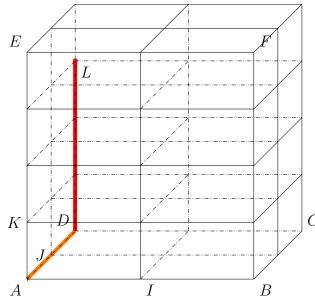
M de coordonnées  $(\mathbf{0}; \mathbf{0}; \mathbf{3})$ .



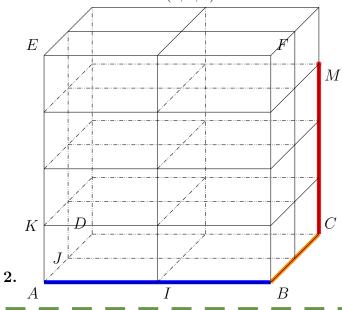
3.  $\begin{array}{ccc}
A & I \\
N & \text{de coordonnées } (\mathbf{2}; \mathbf{2}; \mathbf{0}).
\end{array}$ 



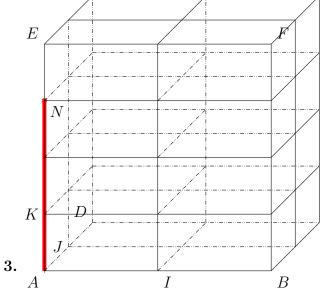




1. L de coordonnées (0; 2; 3).



M de coordonnées (2; 2; 3).



 $\stackrel{A}{N}$  de coordonnées (0; 0; 3).