

# RECAP

- ▶ We looked at  $n$ -length random vectors  $\mathbf{X}$  which are essentially multivariate random variables.
- ▶ Its CDF/pdf is simply joint CDF/pdf of components
- ▶  $E[\mathbf{X}] = [E[X_1], \dots, E[X_n]]$ .  $C_{\mathbf{X}}$  is the covariance matrix.

Let  $\mathbf{Y} = G(\mathbf{X})$  where  $G : \mathbb{R}^n \rightarrow \mathbb{R}^n$ , continuous invertible with continuous partial derivatives. Let  $H$  denote its inverse. Then  $f_{\mathbf{Y}}(\mathbf{y}) = f_{\mathbf{X}}(H(\mathbf{y}))|J|$  where  $J$  is the determinant of the Jacobian matrix.

- ▶ If  $\mathbf{Y} = \mathbf{A}\mathbf{X} + \mathbf{b}$ , then  $C_{\mathbf{Y}} = \mathbf{A}C_{\mathbf{X}}\mathbf{A}^T$  and

$$f_{\mathbf{Y}}(\mathbf{y}) = \frac{1}{|\det(\mathbf{A})|} f_{\mathbf{X}}(\mathbf{A}^{-1}(\mathbf{y} - \mathbf{b}))$$

# Standard Normal Vector

- ▶ An  $n$  length random vector  $\mathbf{Z}$  is called as a standard normal vector if its components  $Z_i$  are independent and standard normal.
- ▶ What is  $E[\mathbf{Z}]$  and  $C_{\mathbf{Z}}$  ?
- ▶ Show that the pdf is given by

$$f_{\mathbf{Z}}(\mathbf{z}) = \frac{1}{(2\pi)^{n/2}} e^{\{-\frac{1}{2}\mathbf{z}^T \mathbf{z}\}}$$

# Standard Normal Vector

- ▶ Now suppose  $\mathbf{X} = A\mathbf{Z} + \boldsymbol{\mu}$ . What is  $E[\mathbf{X}]$  and  $C_{\mathbf{X}}$ ?
- ▶  $E[\mathbf{X}] = \boldsymbol{\mu}$  and  $C_{\mathbf{X}} = AA^T$ .
- ▶ Note that  $A$  can have dimension  $n \times l$  in which case  $\mathbf{Z}$  is an  $l$  length standard normal.
- ▶ What is  $f_{\mathbf{X}}(\mathbf{x})$ ?

# Multivariate Gaussian Vector

- ▶ What is  $f_{\mathbf{X}}(\mathbf{x})$ ?

$$\begin{aligned} f_{\mathbf{X}}(\mathbf{x}) &= \frac{1}{|\det(A)|} f_{\mathbf{Z}}(A^{-1}(\mathbf{x} - \boldsymbol{\mu})) \\ &= \frac{1}{(2\pi)^{n/2} \sqrt{\det(C_{\mathbf{X}})}} e^{\{-\frac{1}{2}(\mathbf{x} - \boldsymbol{\mu})^T C_{\mathbf{X}}^{-1}(\mathbf{x} - \boldsymbol{\mu})\}} \end{aligned}$$

- ▶ Henceforth we will use the notation  $\Sigma$  to represent  $C_{\mathbf{X}}$ .

Definition 1:  $\mathbf{X}$  is multivariate Gaussian with mean vector  $\boldsymbol{\mu}$  and covariance matrix  $\Sigma$  (denoted by  $\mathbf{X} \sim \mathcal{N}(\boldsymbol{\mu}, \Sigma)$ ) if for some  $A$  and  $\boldsymbol{\mu}$ , it can be written as  $\mathbf{X} = A\mathbf{Z} + \boldsymbol{\mu}$  where  $\mathbf{Z}$  is a standard normal vector and  $\Sigma = AA^T$ .

# Equivalent definitions of a Gaussian vector

The following are equivalent definitions (without proof)

$\mathbf{X} \sim \mathcal{N}(\mu, \Sigma)$  if for some  $A$  and  $\mu$ , it can be written as  
 $\mathbf{X} = A\mathbf{Z} + \mu$

$\mathbf{X} \sim \mathcal{N}(\mu, \Sigma)$  if it has the pdf

$$f_{\mathbf{X}}(\mathbf{x}) = \frac{1}{(2\pi)^{n/2} \sqrt{\det(\Sigma)}} e^{\{-\frac{1}{2}(\mathbf{x}-\mu)^T \Sigma^{-1}(\mathbf{x}-\mu)\}}$$

$\mathbf{X} \sim \mathcal{N}(\mu, \Sigma)$  iff for all vectors  $\mathbf{a} \in \mathbb{R}^n$ , it turns out that  $\mathbf{a}^T \mathbf{X}$  is univariate Gaussian  $\mathcal{N}(\mathbf{a}^T \mu, \mathbf{a}^T \Sigma \mathbf{a})$ .

For equivalent definitions see [https://en.wikipedia.org/wiki/Multivariate\\_normal\\_distribution](https://en.wikipedia.org/wiki/Multivariate_normal_distribution)

# Affine transformations preserve Gaussianity

- ▶ Suppose  $\mathbf{X} \sim \mathcal{N}(\boldsymbol{\mu}, \Sigma)$ , then what can we say about  $\mathbf{Y} = \mathbf{A}\mathbf{X} + \mathbf{b}$ ? Is it a Gaussian vector ?
- ▶ Easy to see that  $E[\mathbf{Y}] = AE[\mathbf{X}] + b$  and  $C_{\mathbf{Y}} = A\Sigma A^T$ .
- ▶ Like in the univariate case, we can use MGF (for multivariate MGF see Bertsekas) to show the following

Suppose  $\mathbf{X} \sim \mathcal{N}(\boldsymbol{\mu}, \Sigma)$ . Now consider  $\mathbf{Y} = \mathbf{A}\mathbf{X} + \mathbf{b}$ . Then we have  $\mathbf{Y} \sim \mathcal{N}(AE[\mathbf{X}] + b, A\Sigma A^T)$ .