

CS 302.1 - Automata Theory

Lecture 09

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Quick Recap

Pumping Lemma for CFL: If L is Context Free, then there exists $p > 0$ (pumping length), such that, for any $w \in L$ of length $|w| \geq p$, w can be split into five parts, i.e. $w = uvxyz$ satisfying the following conditions:

- $|vy| \geq 1$
- $|vxy| \leq p$
- $uv^i xy^i z \in L, \forall i \geq 0$

Closure properties of CFLs

CFLs are closed under

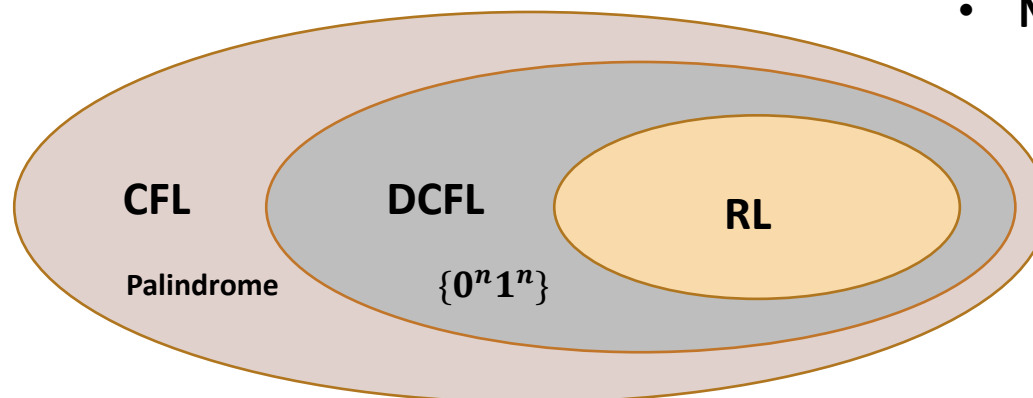
- **Union**
- **Star**
- **Concatenation**

CFLs are NOT closed under

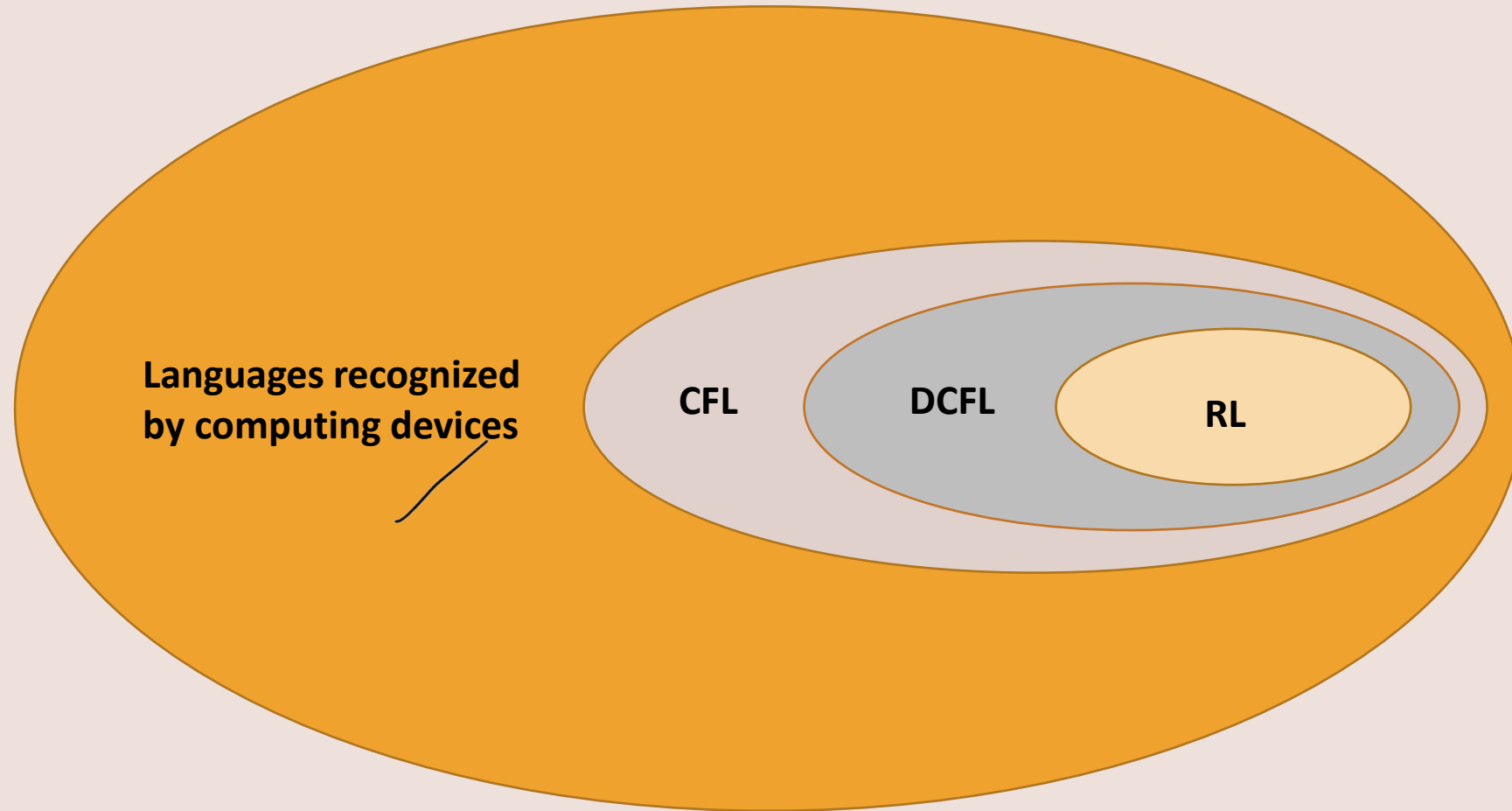
- **Complementation**
- **Intersection**

For DCFLs

- **NOT closed Union**
- **Closed under complementation**
- **NOT closed under intersection**



The set of all languages



**Languages recognized
by computing devices**

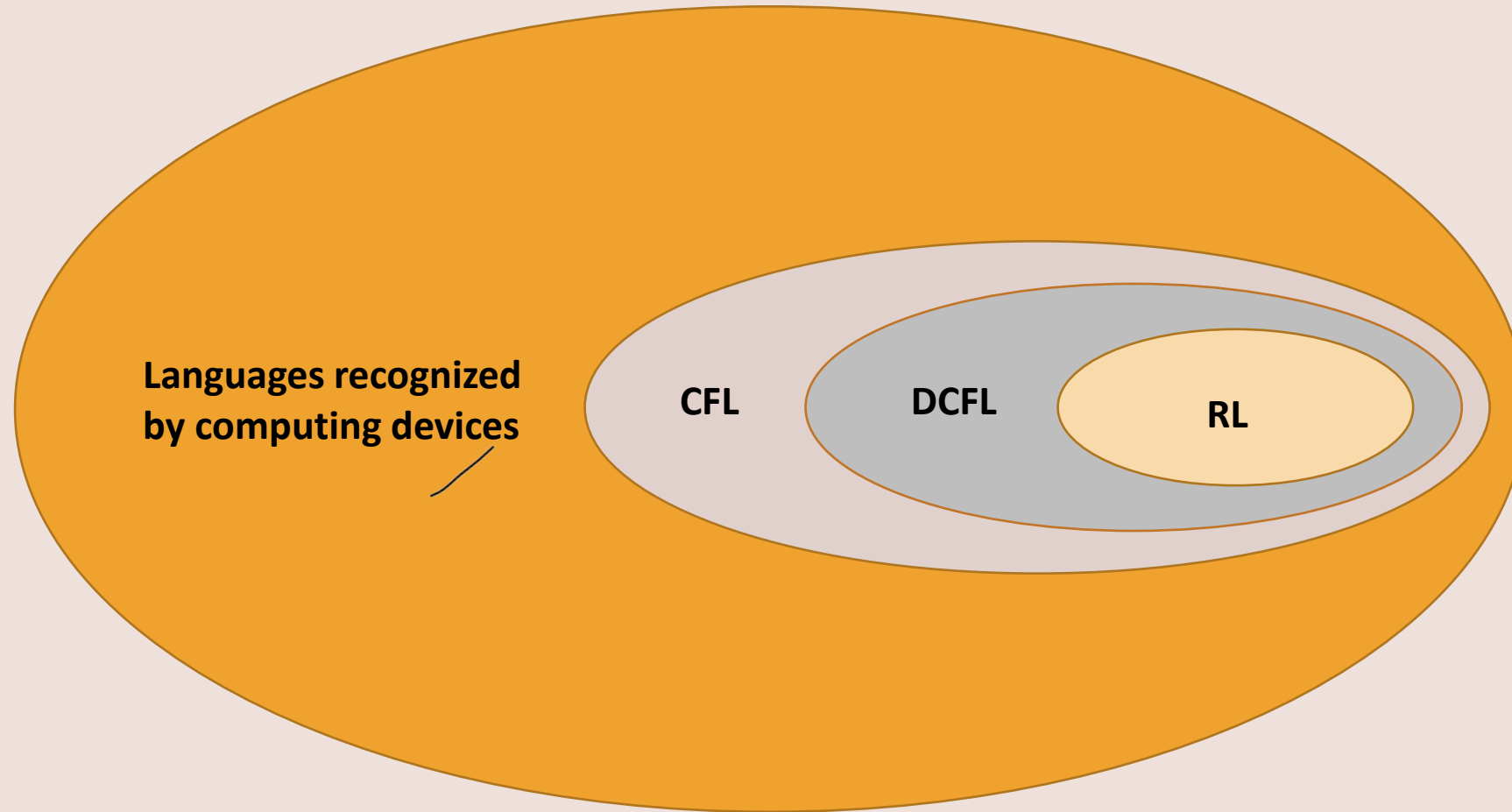
CFL

DCFL

RL

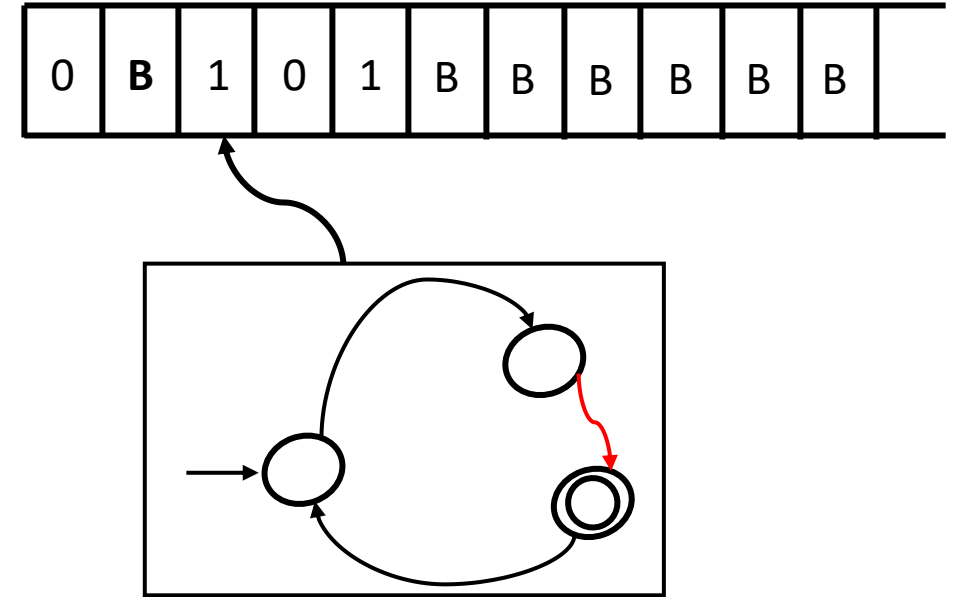
Which languages lie here?

The set of all languages



Turing Machines

- A Turing machine is an FSM that has access to a infinite tape as its memory.
- The infinite tape contains in it, the input string followed by Blanks (indicated by B)
- The Turing machine can both read from the tape and write in it – one cell at a time, using a Read/Write head.
- The Read/Write head can move to the Left or to the Right – again one cell at a time.

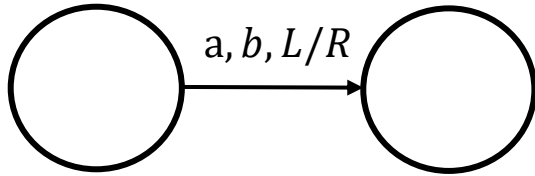


At each step, the TM:

- Replaces the symbol of the current cell in the tape with a new one
 - Transitions from one state to another (or remains where it was)
 - The Read/Write head moves either to the Left or to the Right
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- Whenever the computation reaches an accept/reject state – the TM accepts or rejects the input string (halts)

- In a way these “added features” give TMs their power. (eg: ability to write on the tape)
- Notice: acceptance/rejection of a run is not tied to the input.
- Auxiliary computation can be performed – as much as needed, even when the input string has been scanned

Turing Machines



Transition $a, b, L/R$: Read a from the tape, replace with b and move L/R

So, given a TM M and an input ω ,

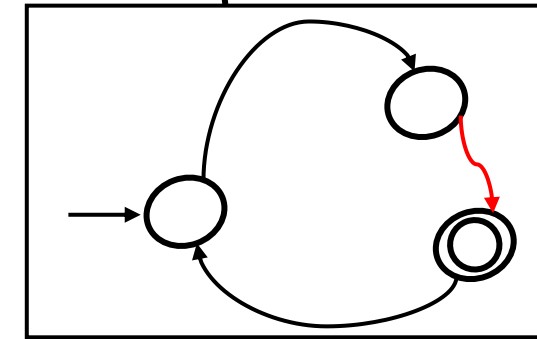
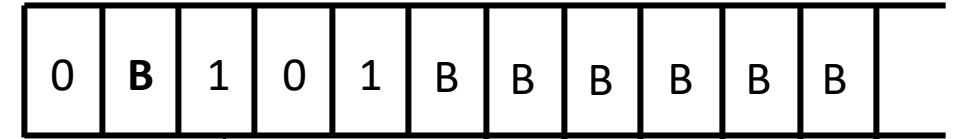
$M(\omega)$ **accepts** if $\omega \in L(M)$

$M(\omega)$ **rejects** if $\omega \notin L(M)$

$M(\omega)$ **runs infinitely** if $\omega \notin L(M)$



TM halts and **accepts/rejects** on reaching these states



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Turing Machines

Turing machines are named after **Alan Turing**. In 1936, he gave a negative answer to Hilbert's *Entscheidungsproblem* (Decision problem) – *Are all decision problems decidable?*

ON COMPUTABLE NUMBERS, WITH AN APPLICATION TO
THE ENTSCHEIDUNGSPROBLEM

By A. M. TURING.

[Received 28 May, 1936.—Read 12 November, 1936.]

The “computable” numbers may be described briefly as the real numbers whose expressions as a decimal are calculable by finite means.



Turing claimed that anything “humanly computable” can be simulated by his machines

- Turing assumed that the human brain to be a finite state machine with a finite number of states
- Consider such a human being working on a problem with a notebook, pencil and an eraser.
- The pages of the notebook are laid out on the tape – each cell consists of one page, with a finite amount of information.
- Whatever the human being does with the notebook, can be simulated on the TM: reading, writing, erasing (writing a blank), moving left or right to a new page etc.

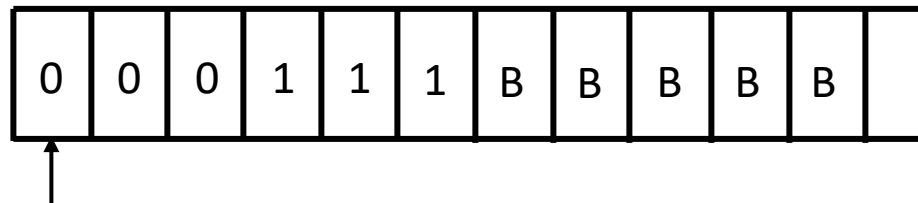
Turing Machines

Example: Let $L = \{0^n 1^n | n \geq 1\}$

We will try to develop the basic idea in designing the Turing Machine for this language. Note that $L = CFL$.

Idea: An accepting run of a TM for L could look something like this:

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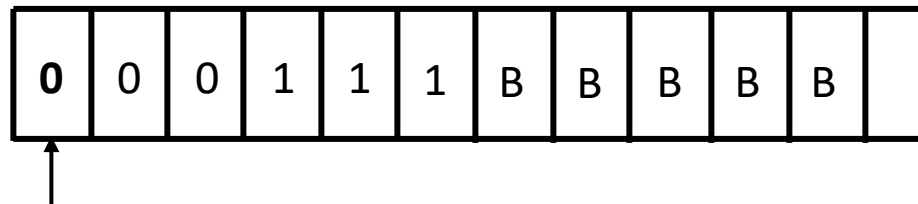
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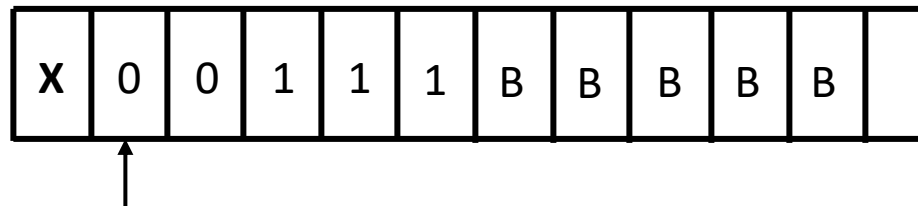
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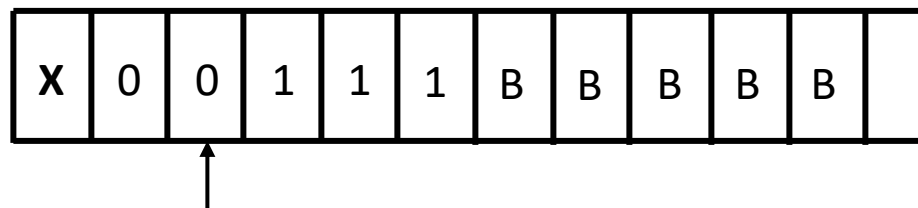
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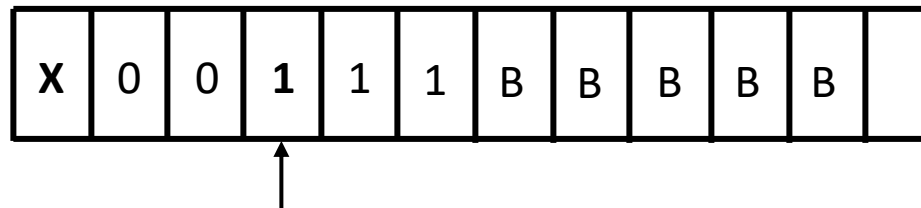
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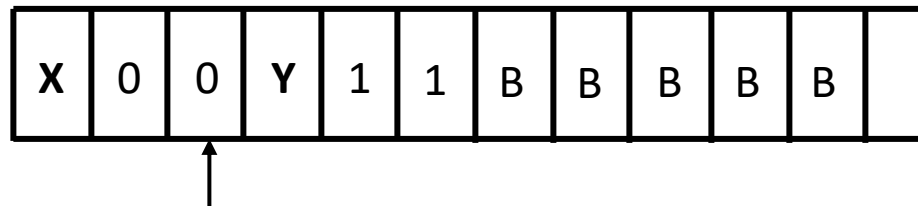
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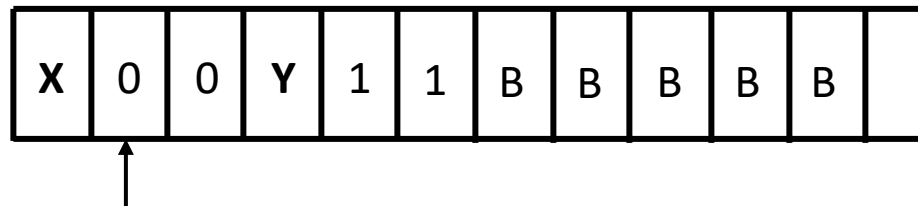
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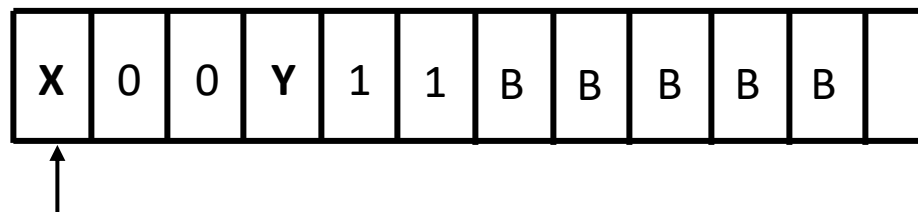
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While moving left, when an X is encountered, the head should move right until the next 0 to be marked is encountered \Rightarrow **We need rules like (X, X, R)**

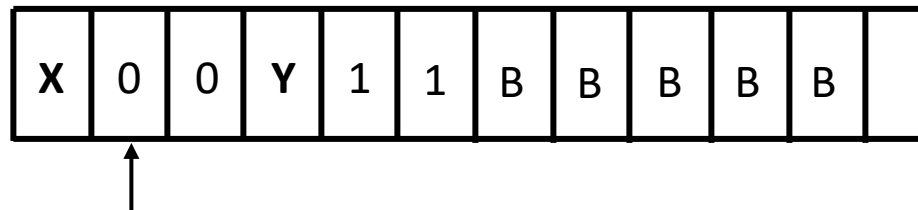
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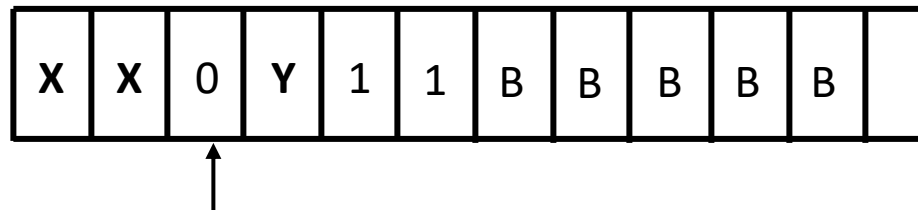
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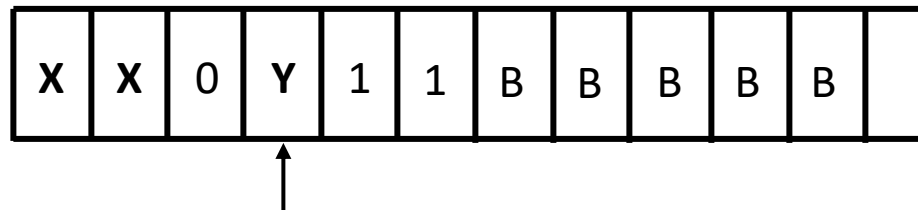
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While moving right, when a Y is encountered, the head should move right as that's where the next 1 to be marked is
 \Rightarrow **We need rules like (Y, Y, R)**

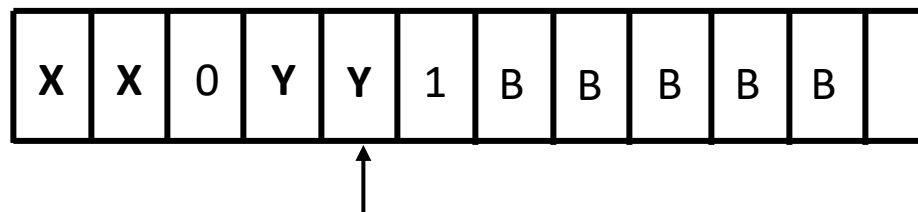
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While moving left, when a Y is encountered, the head should keep moving left as those 1's have been marked already \Rightarrow **We need rules like (Y, Y, L)**

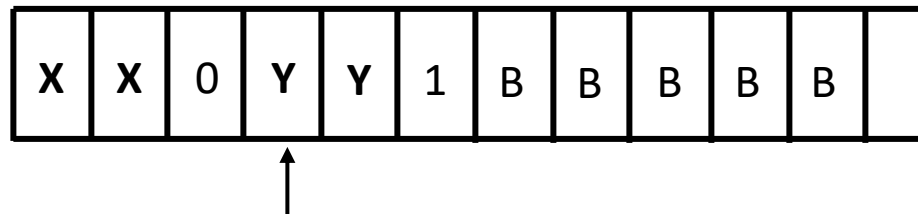
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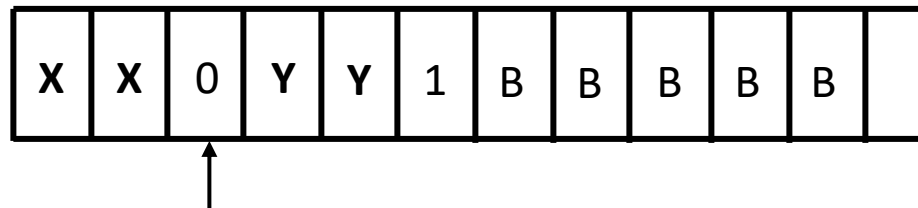
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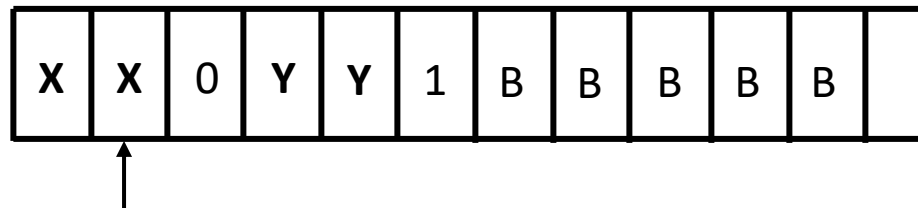
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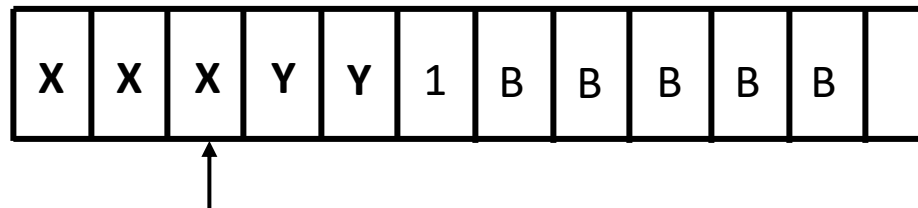
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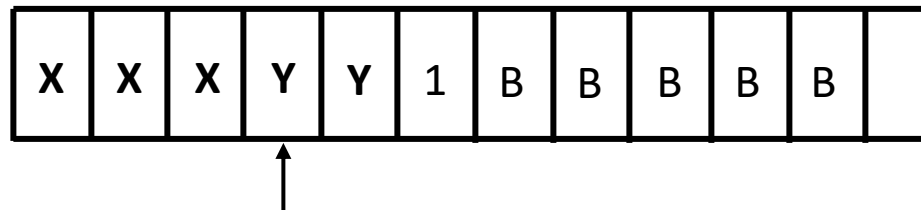
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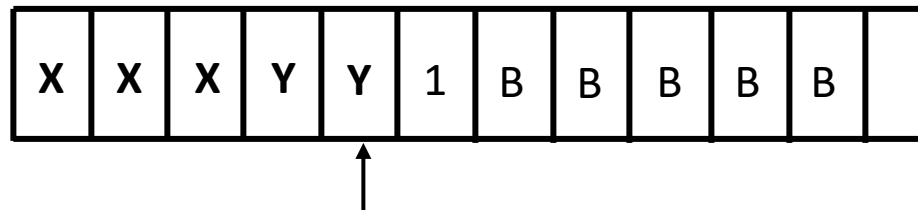
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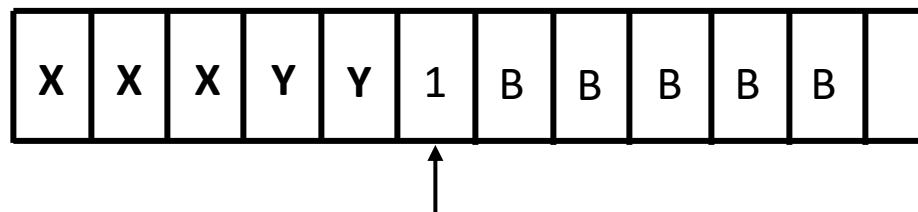
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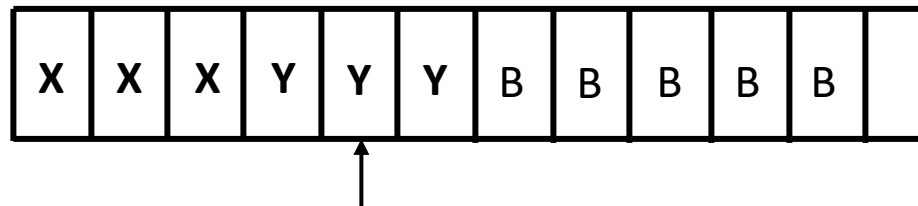
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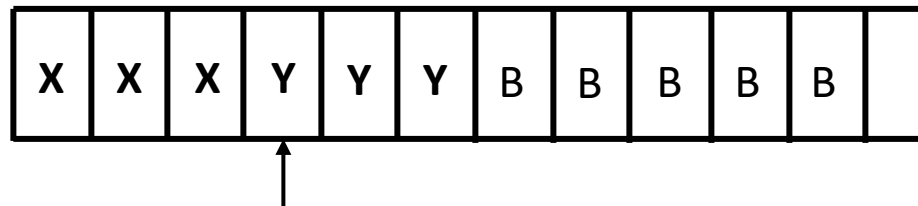
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- Continue to move left until you encounter the second 0 (its to the right of the X you had marked before)
- Continue to move right until you encounter a second 1 (its to the right of the Y you had marked before)
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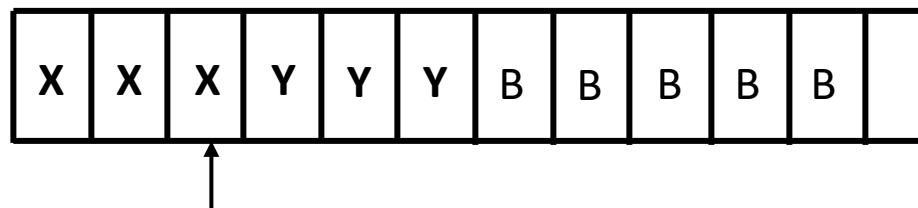
Turing Machines

Example: Let $L = \{0^n 1^n | n \geq 1\}$

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At this stage the head should move right to look for the next 0 to mark, but finds Y

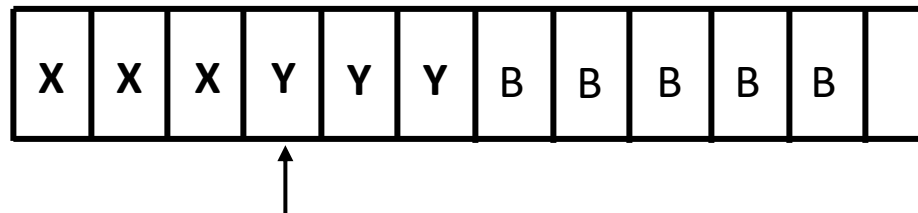
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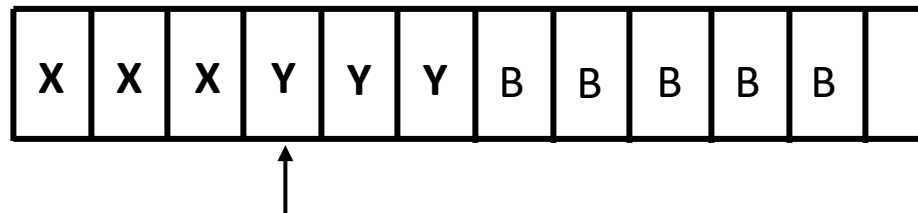
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The head keeps moving right until it finds a B

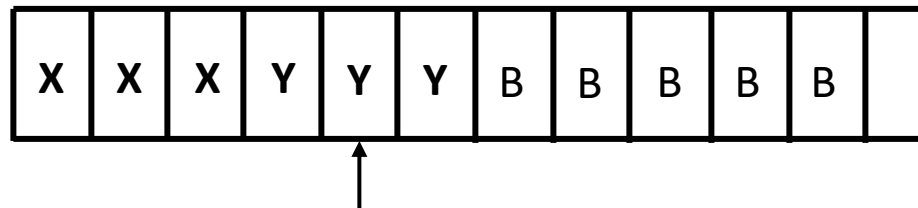
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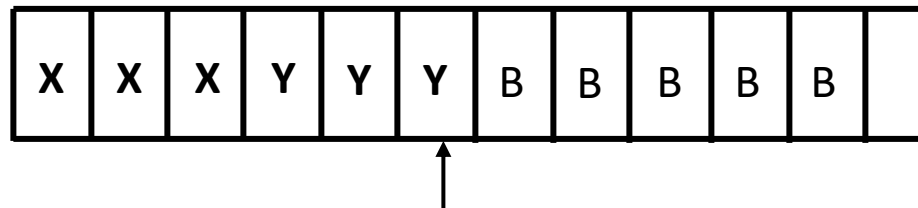
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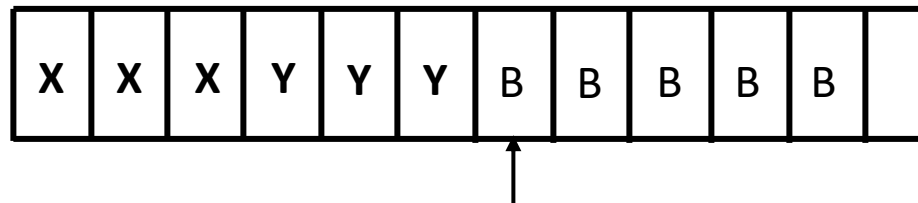
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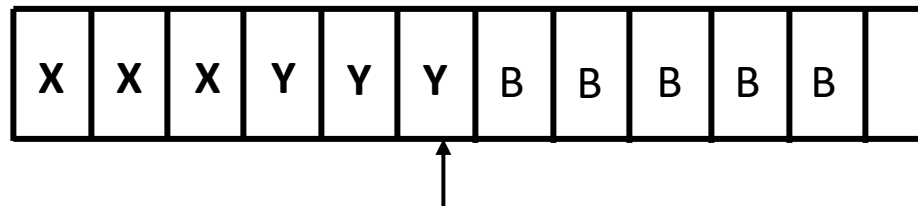
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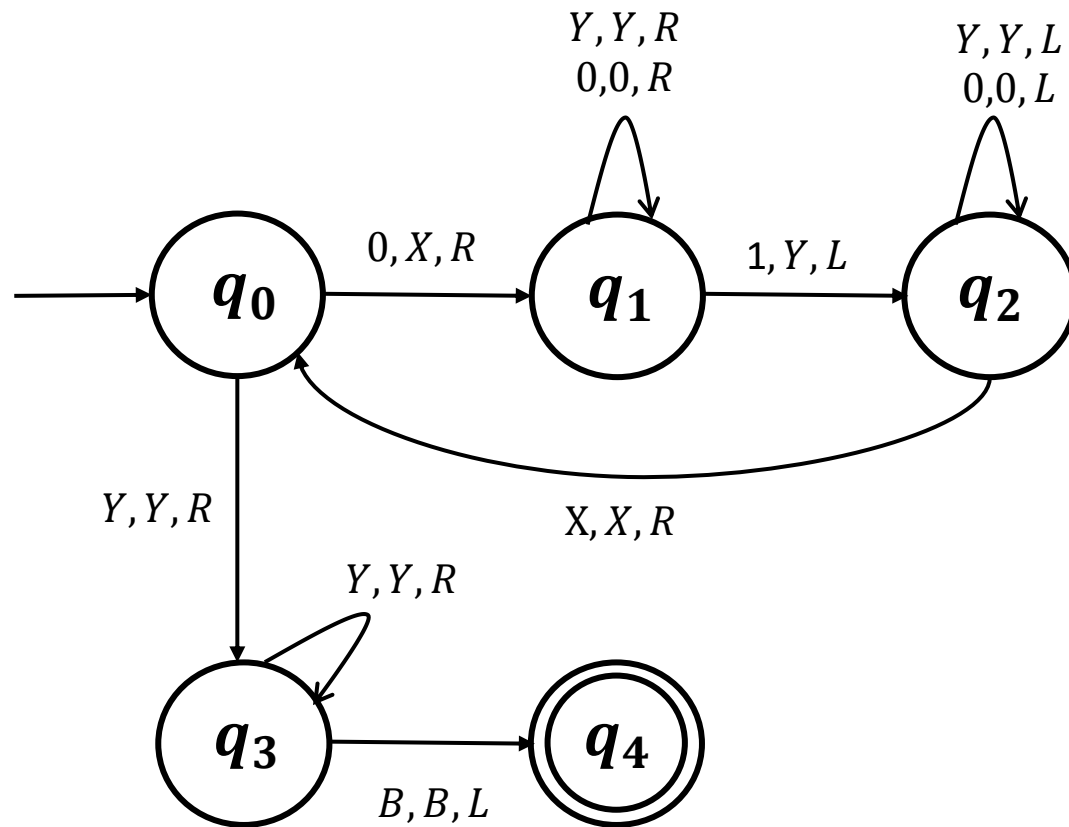
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This is when the TM decides to accept the input string.

Turing Machines

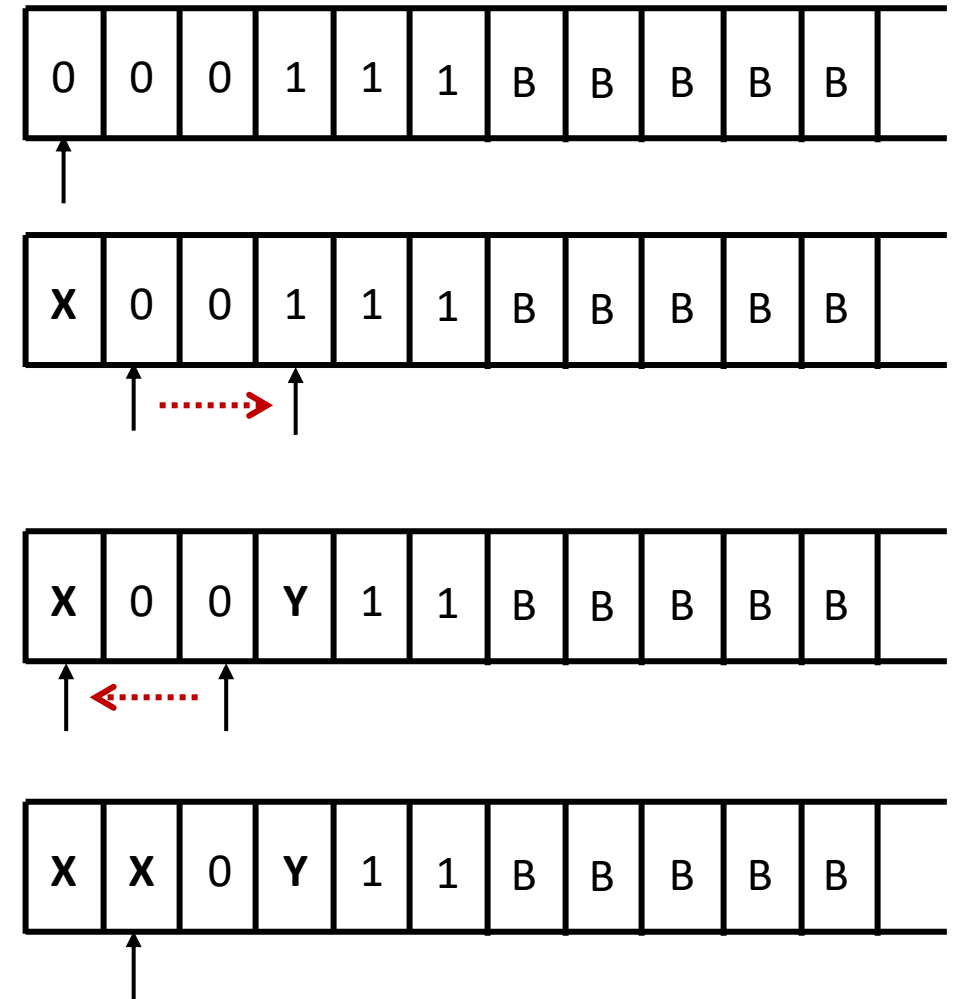
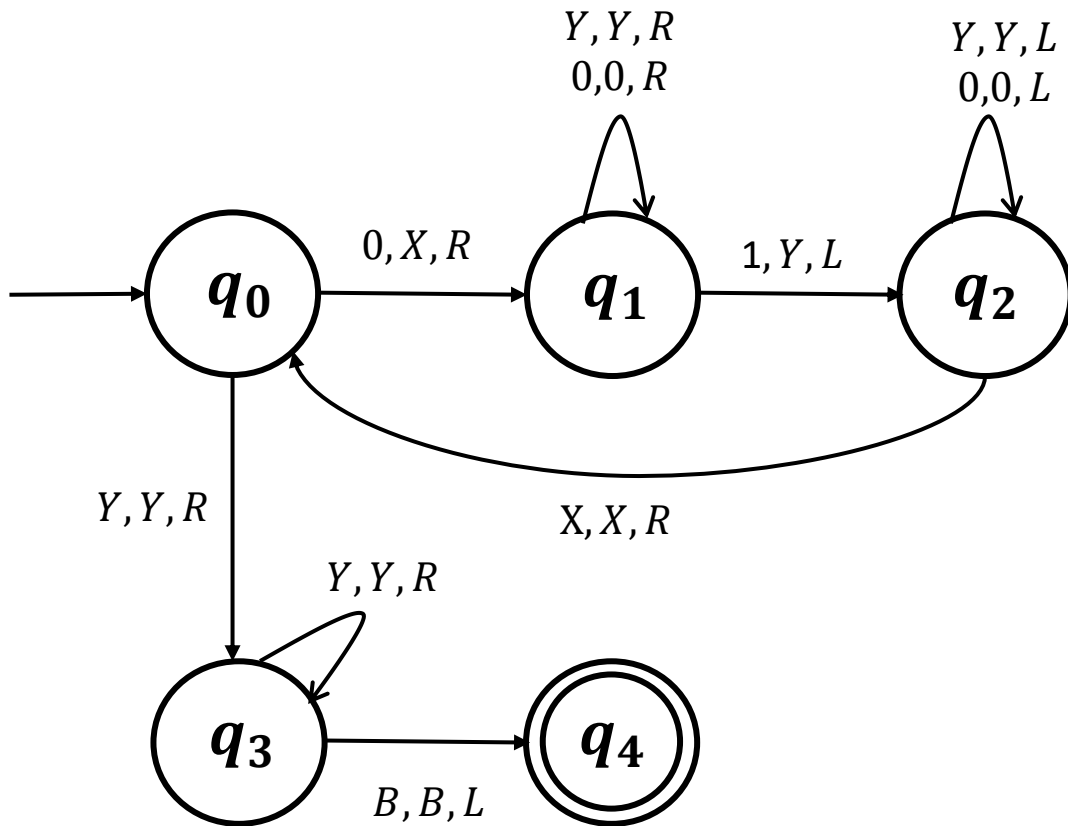
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All missing transitions lead to the reject state and the input is rejected when this state is reached.

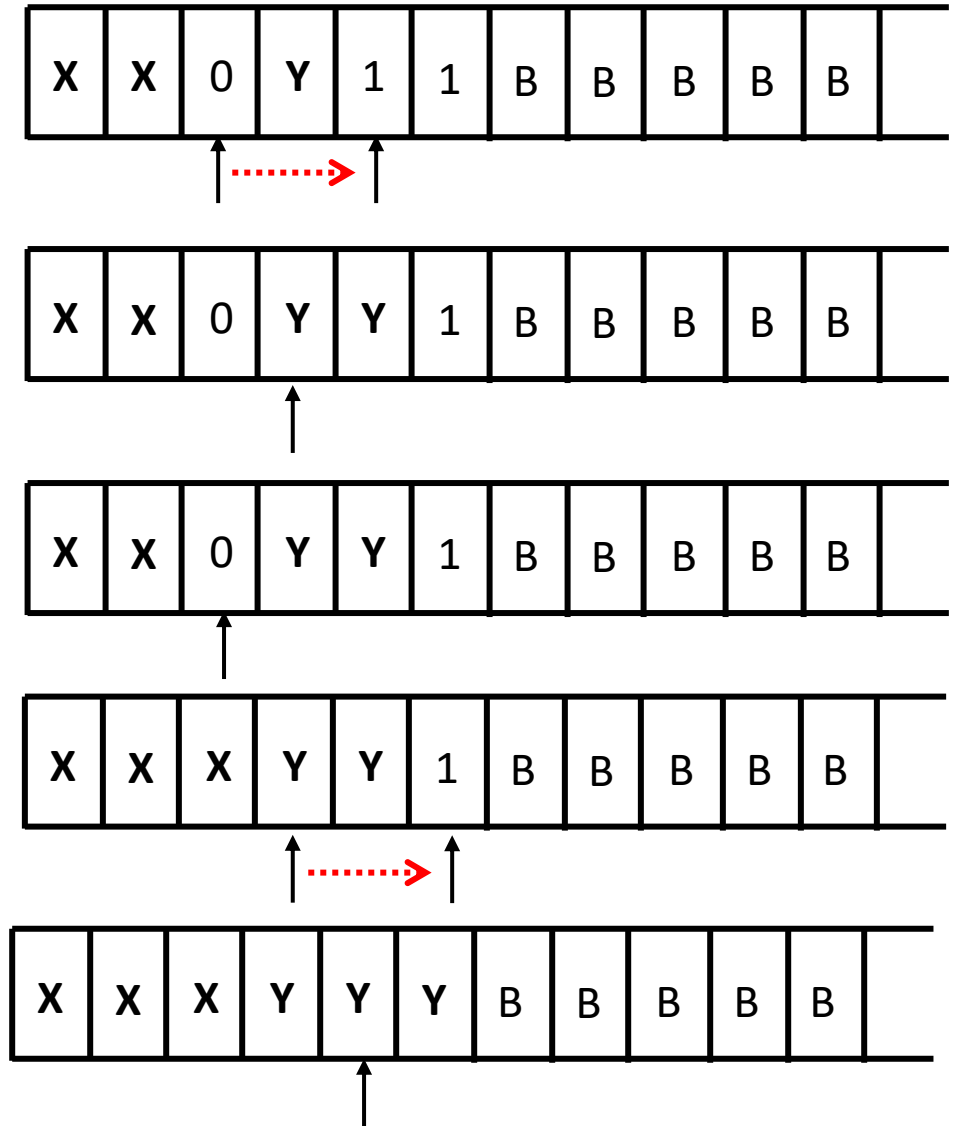
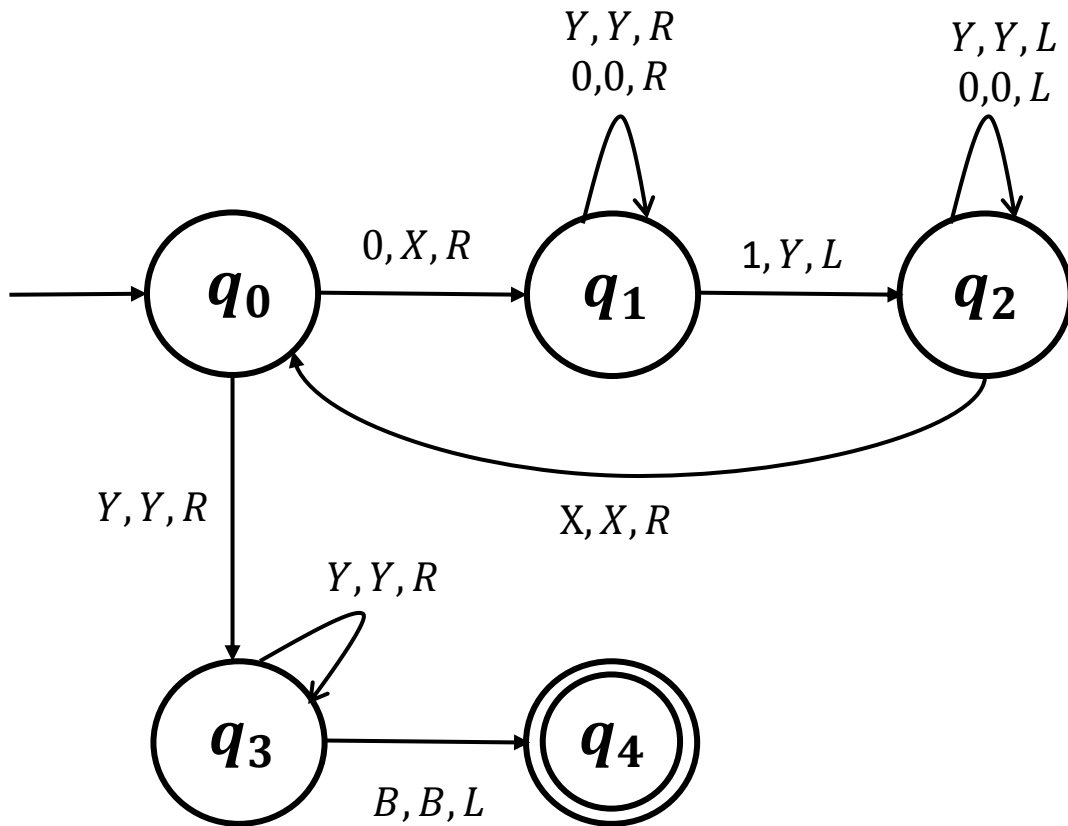
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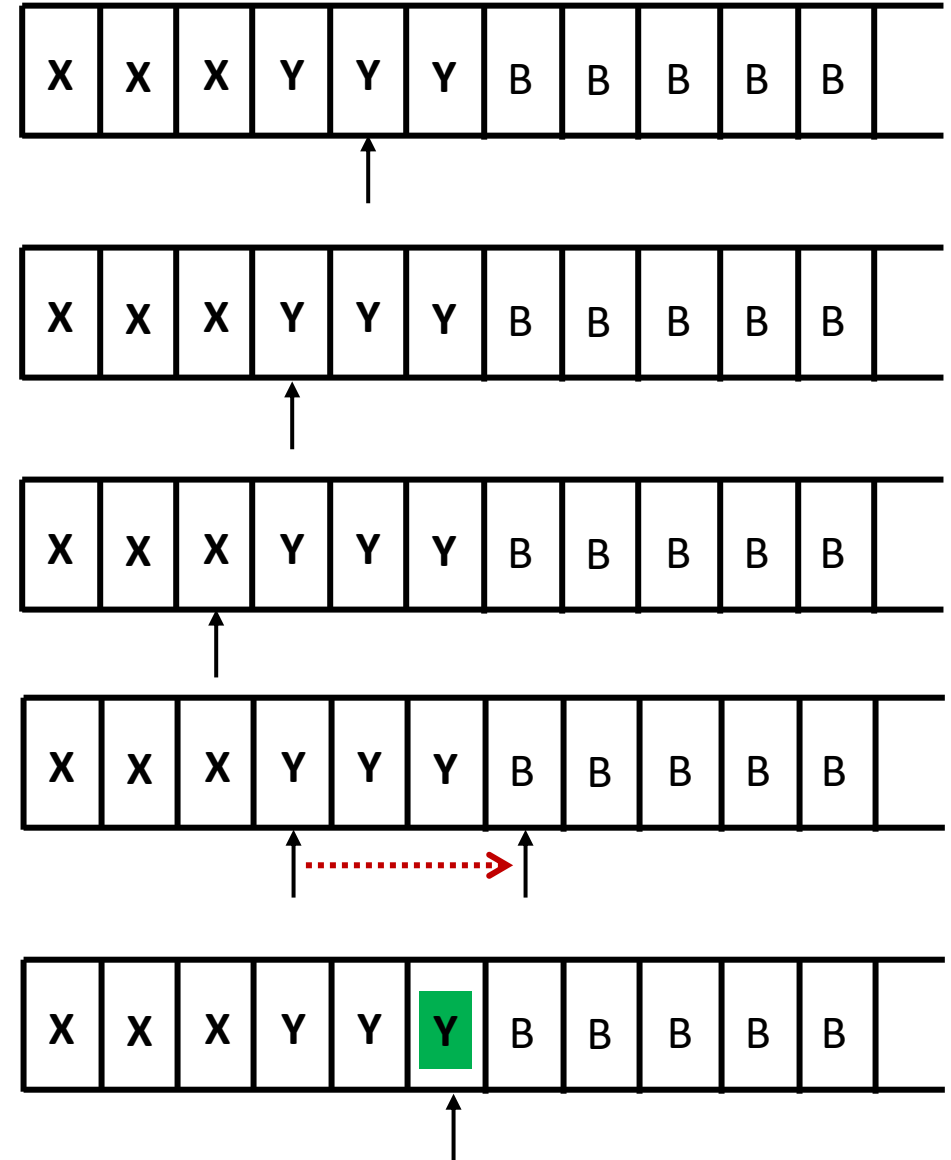
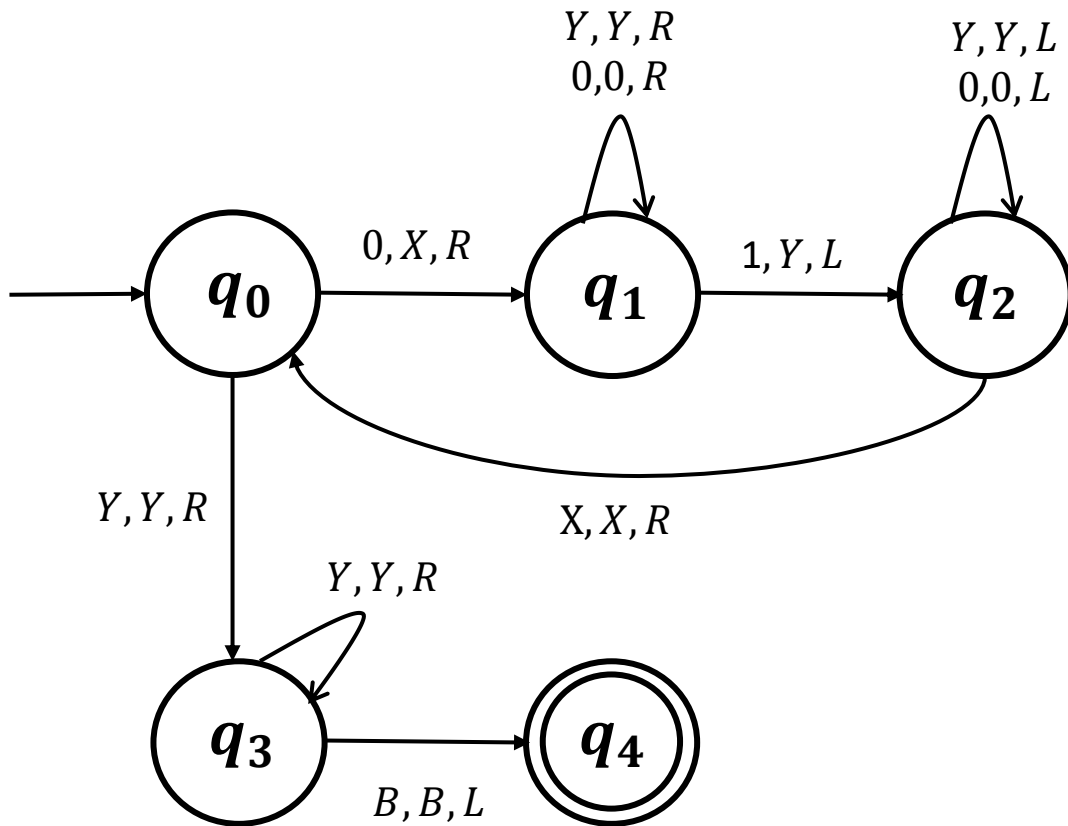
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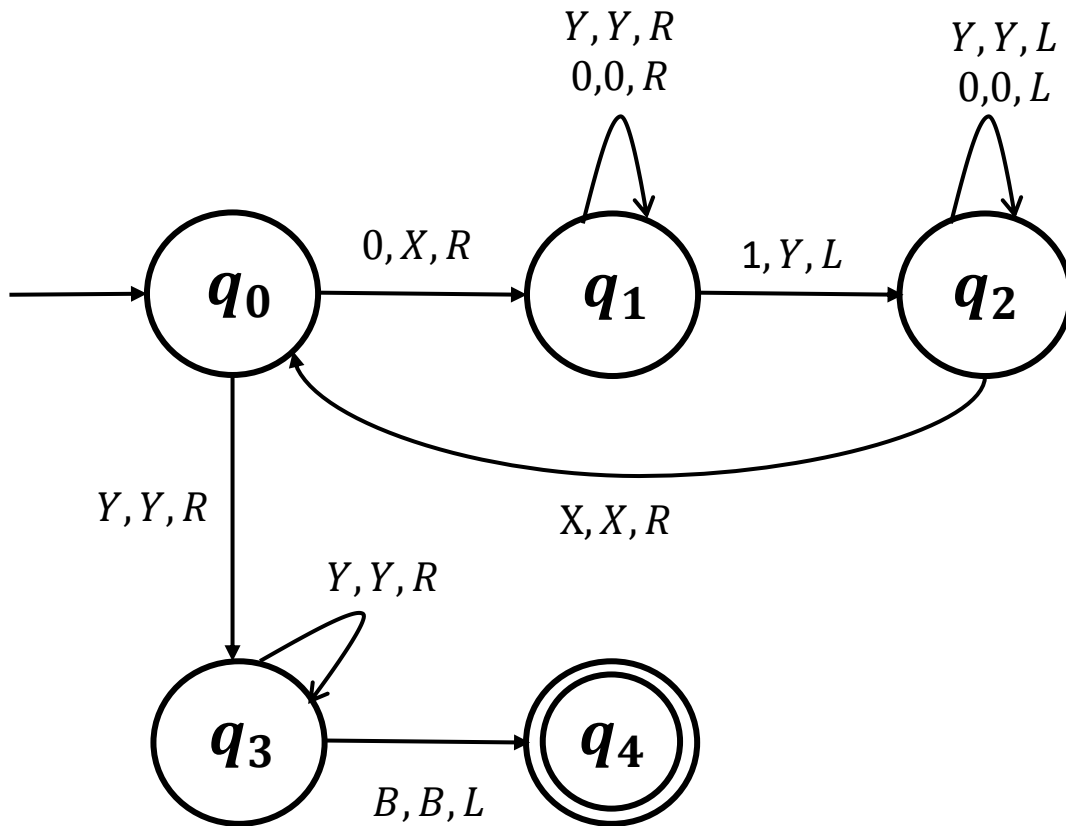
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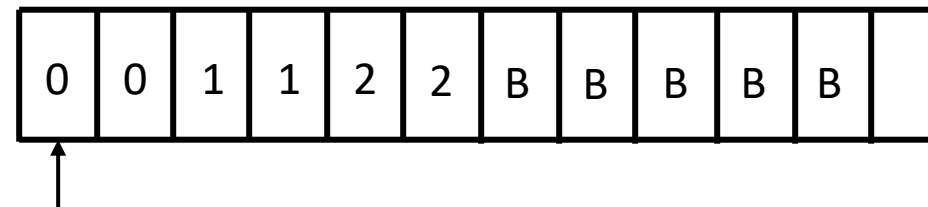


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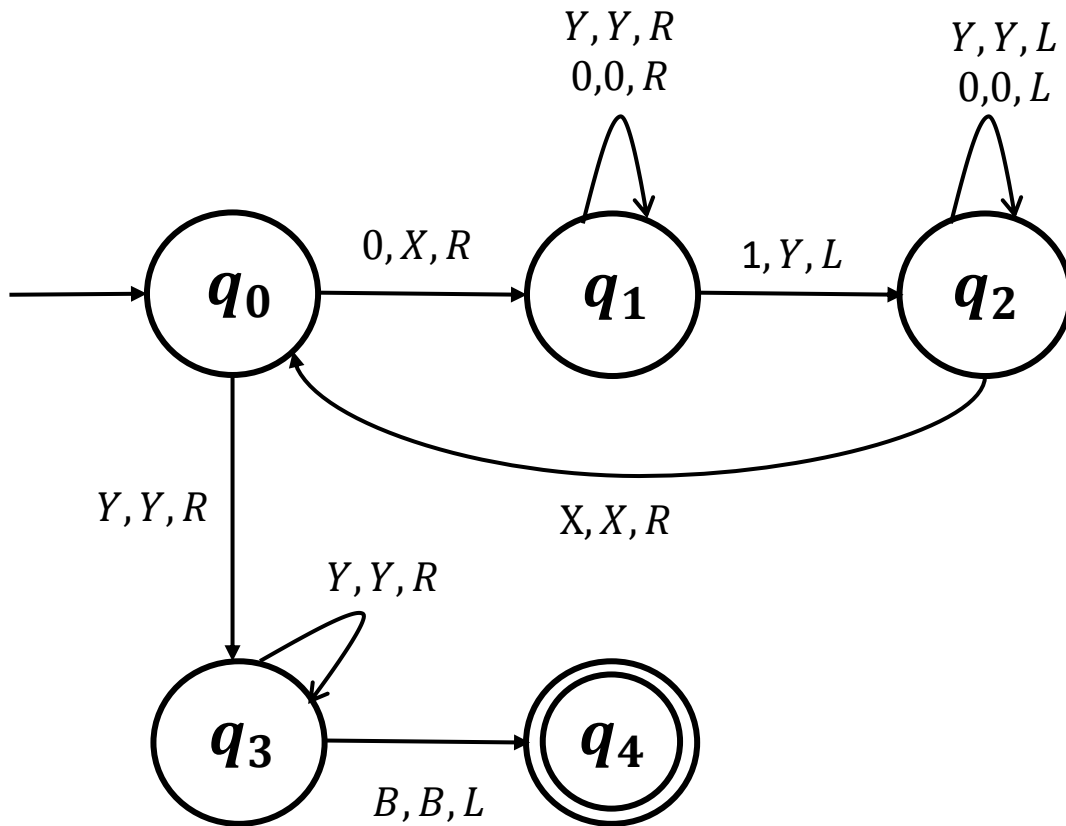


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- **Very similar to the TM for $\{0^n 1^n\}$** , except now the FSM would count the number of 2's as well. So it marks the 2's with another symbol (say Z)

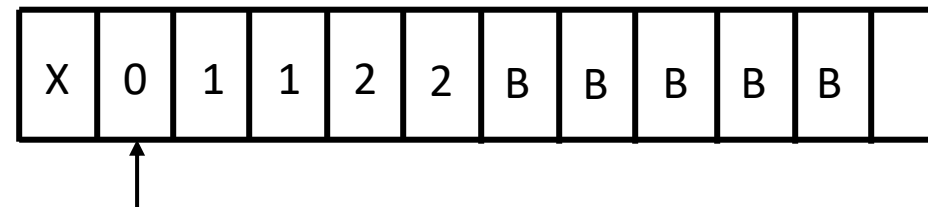


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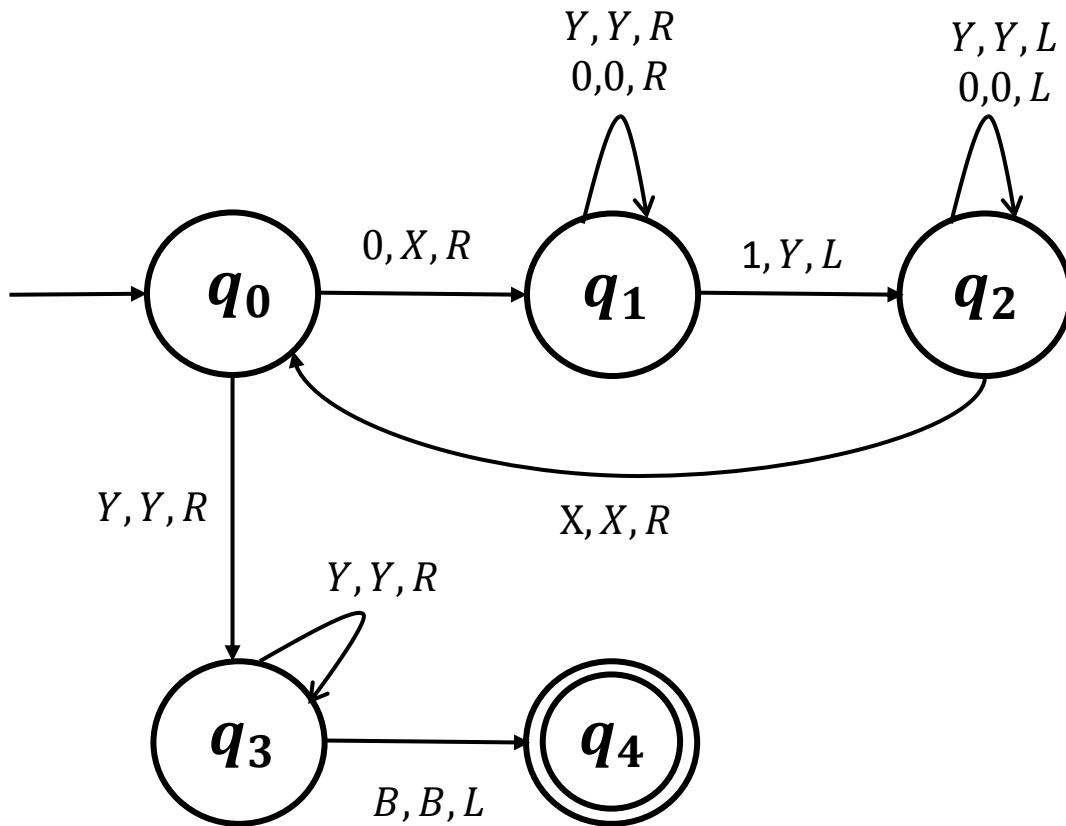


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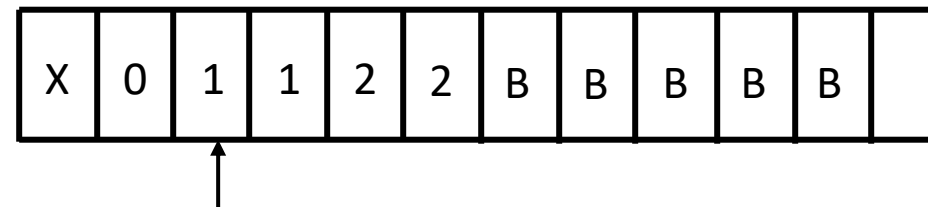


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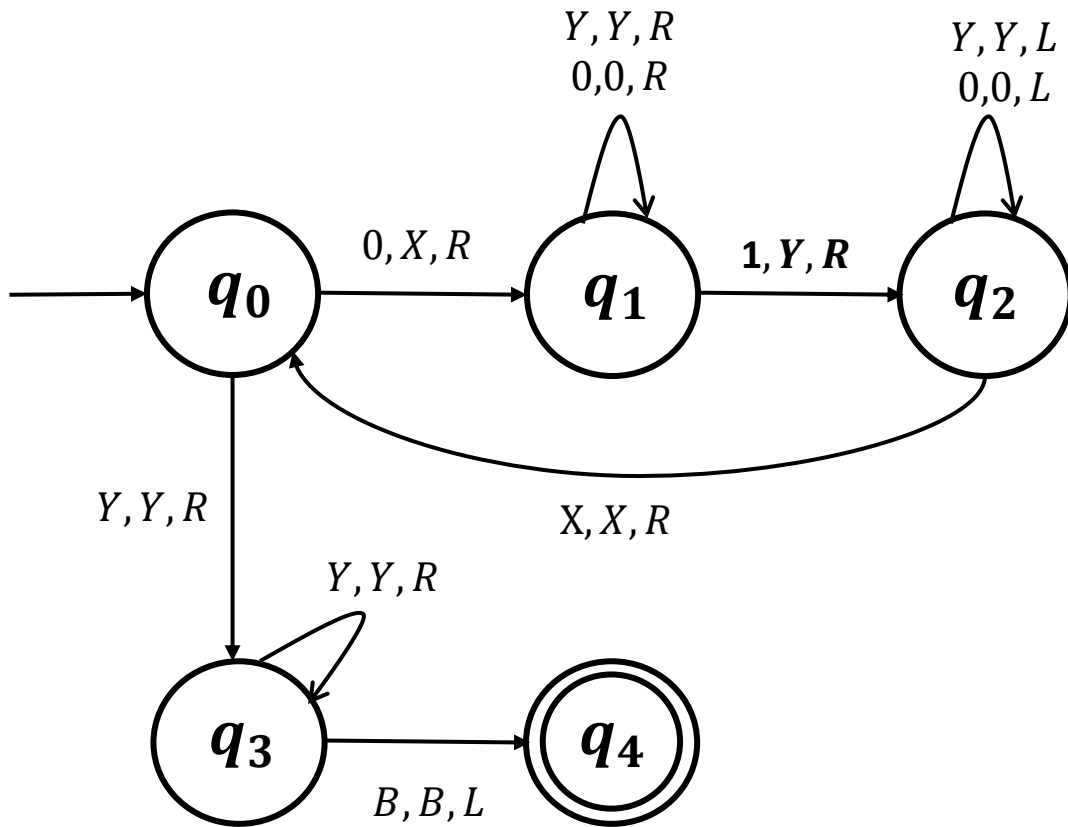


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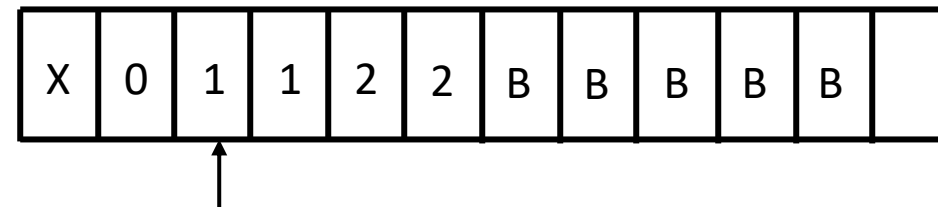


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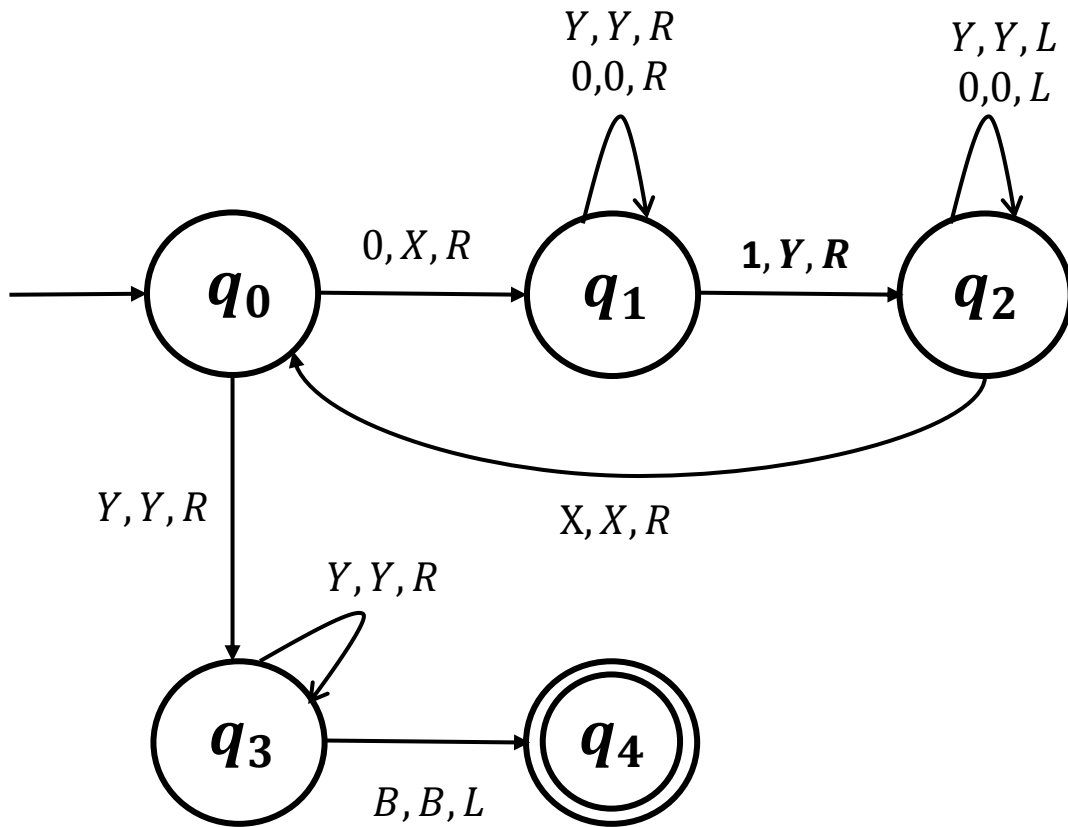


- Continue to go right to mark the next 2 with a Z.

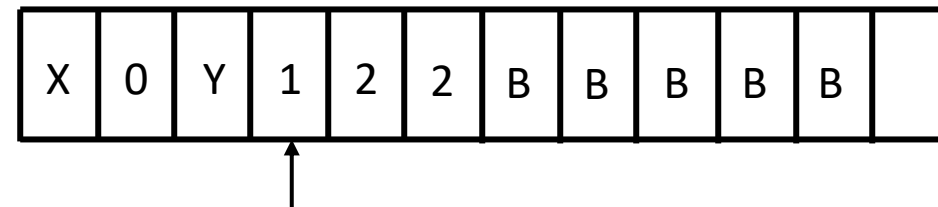


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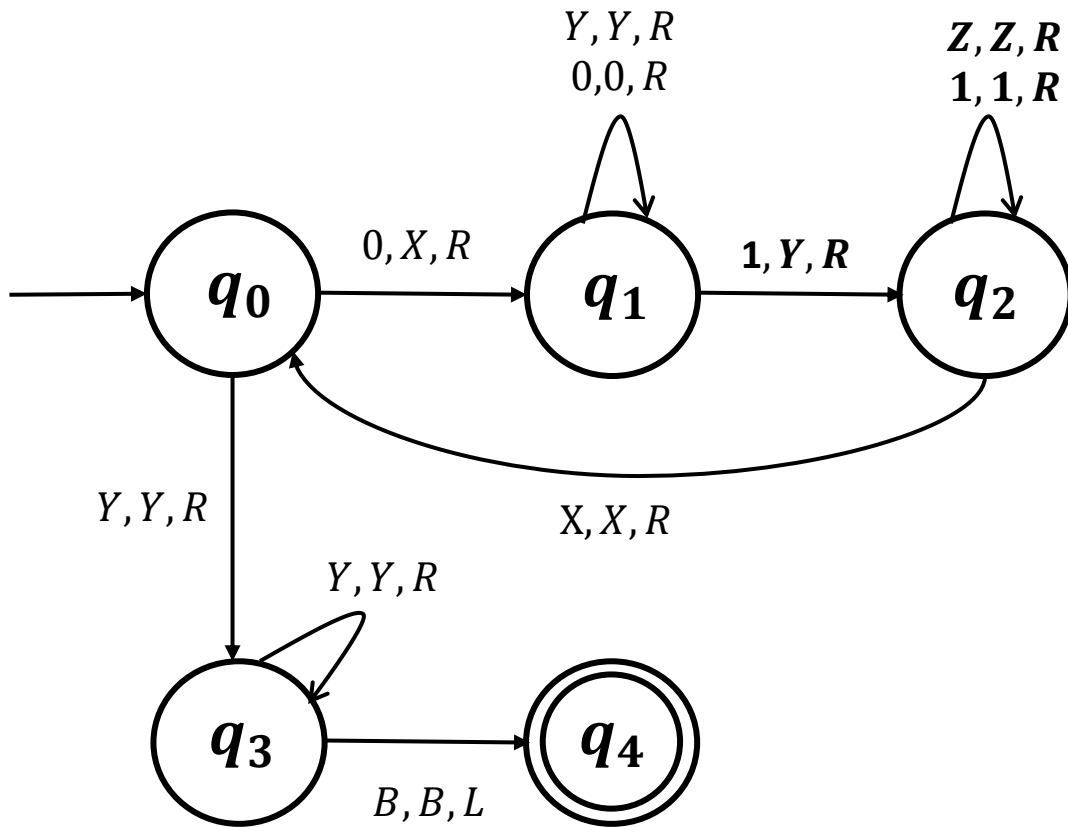


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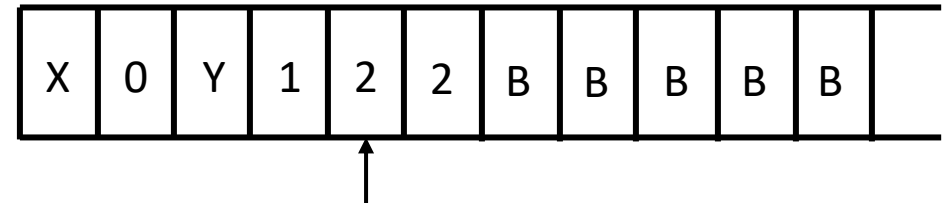


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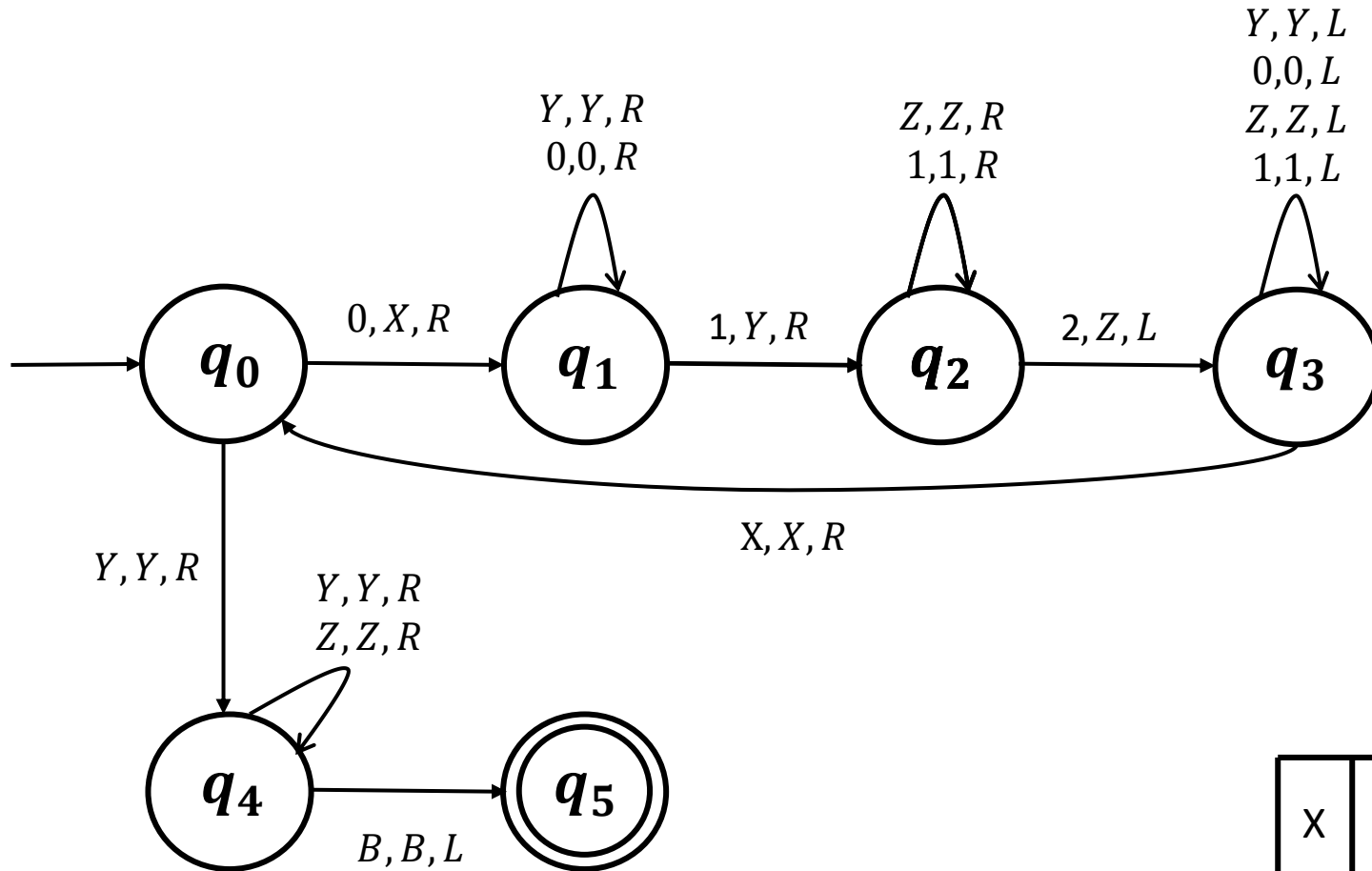


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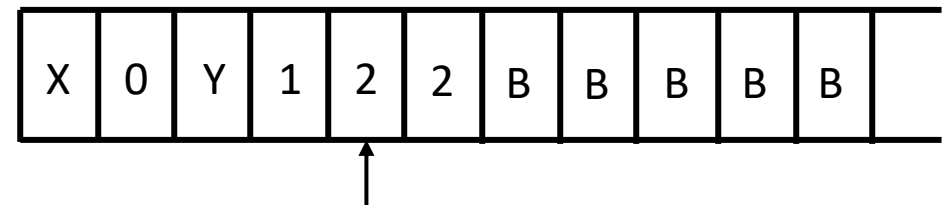


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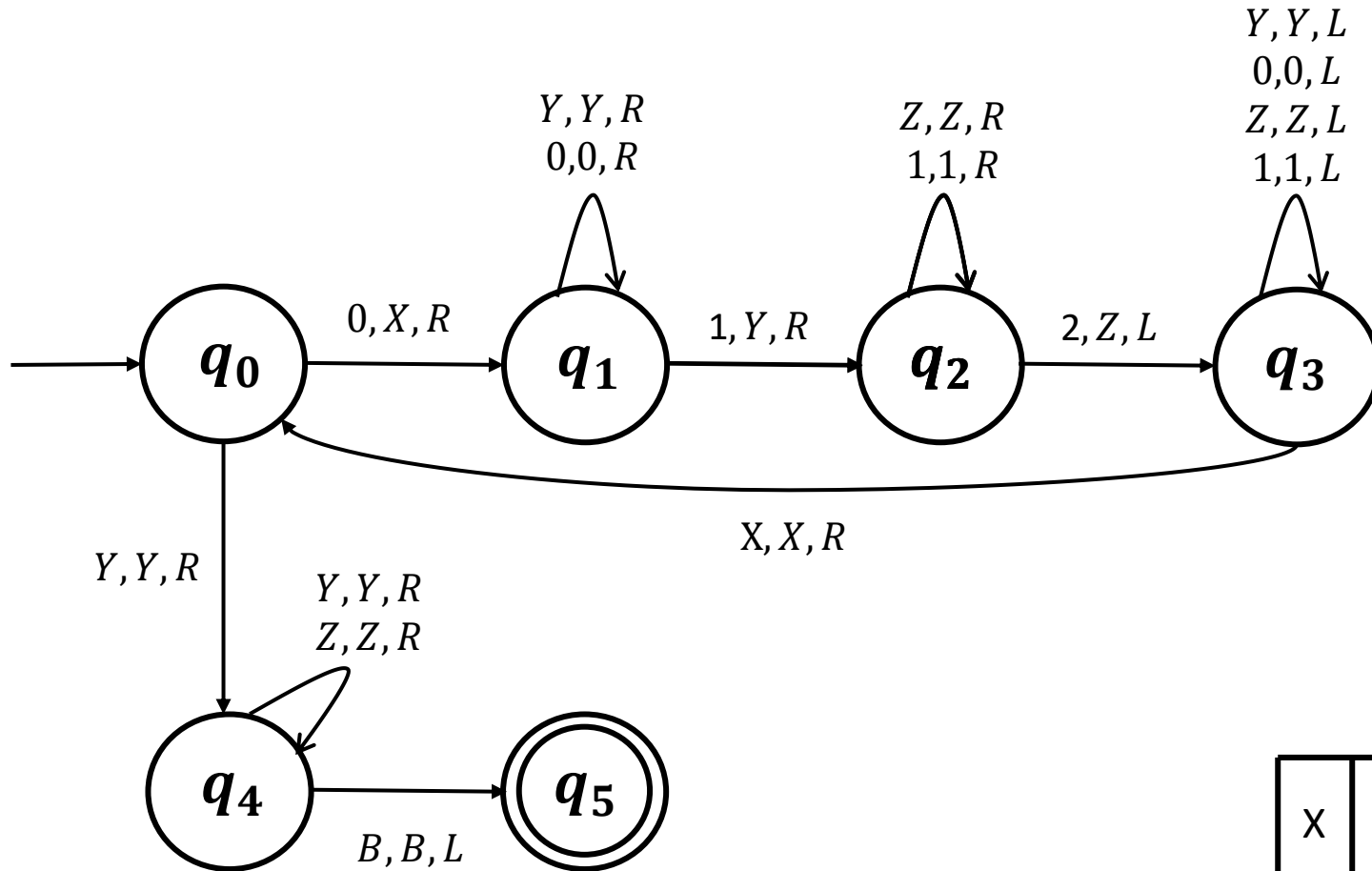


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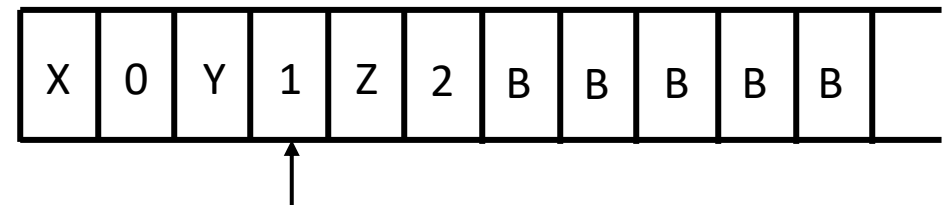


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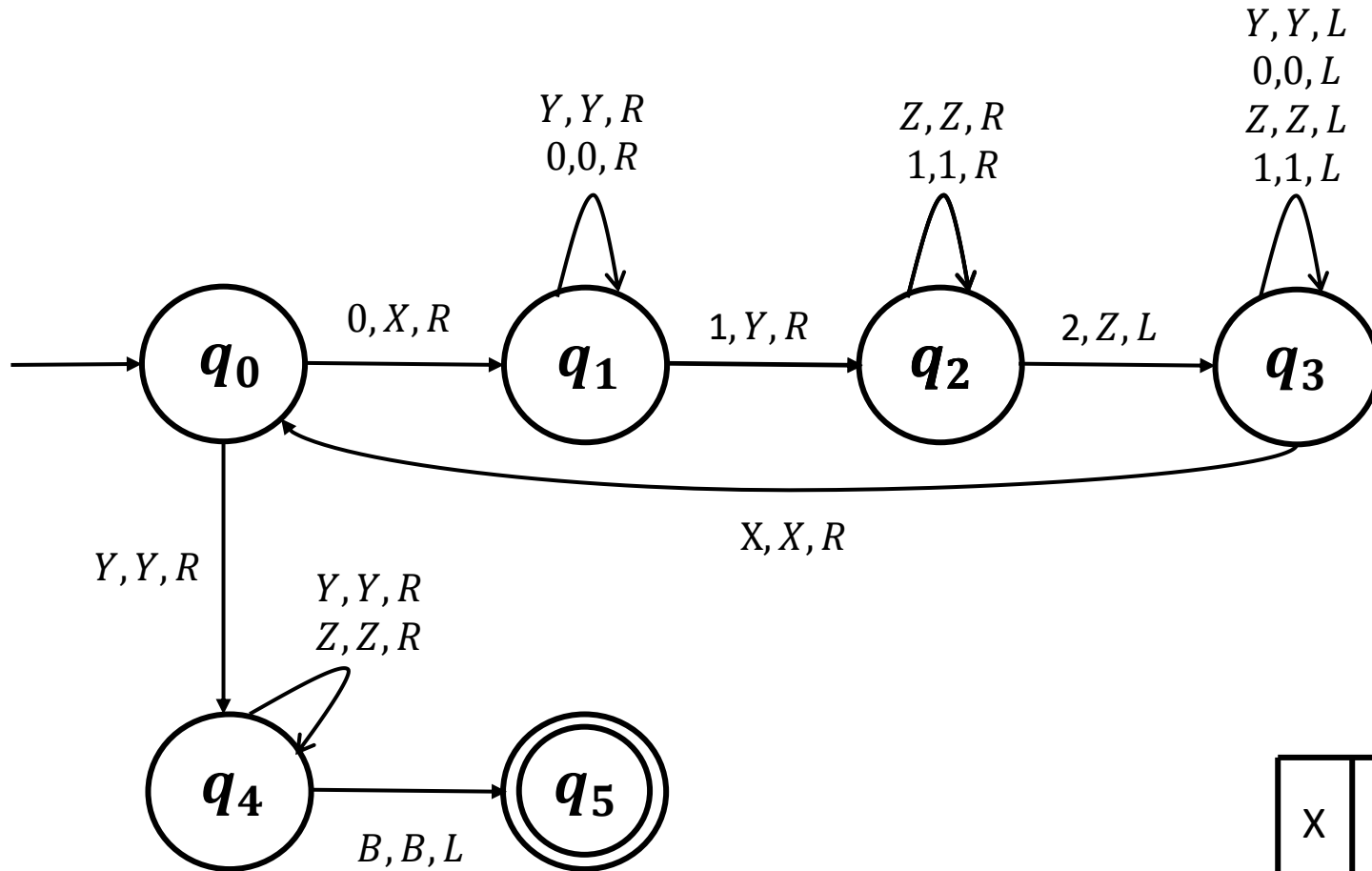


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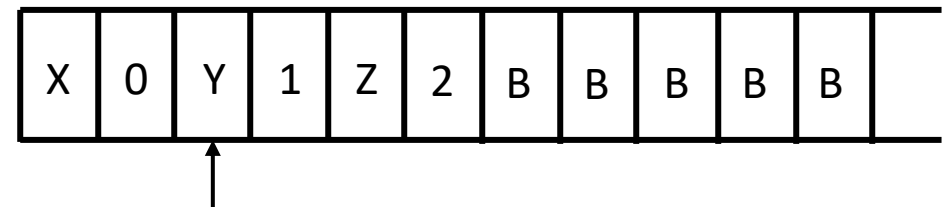


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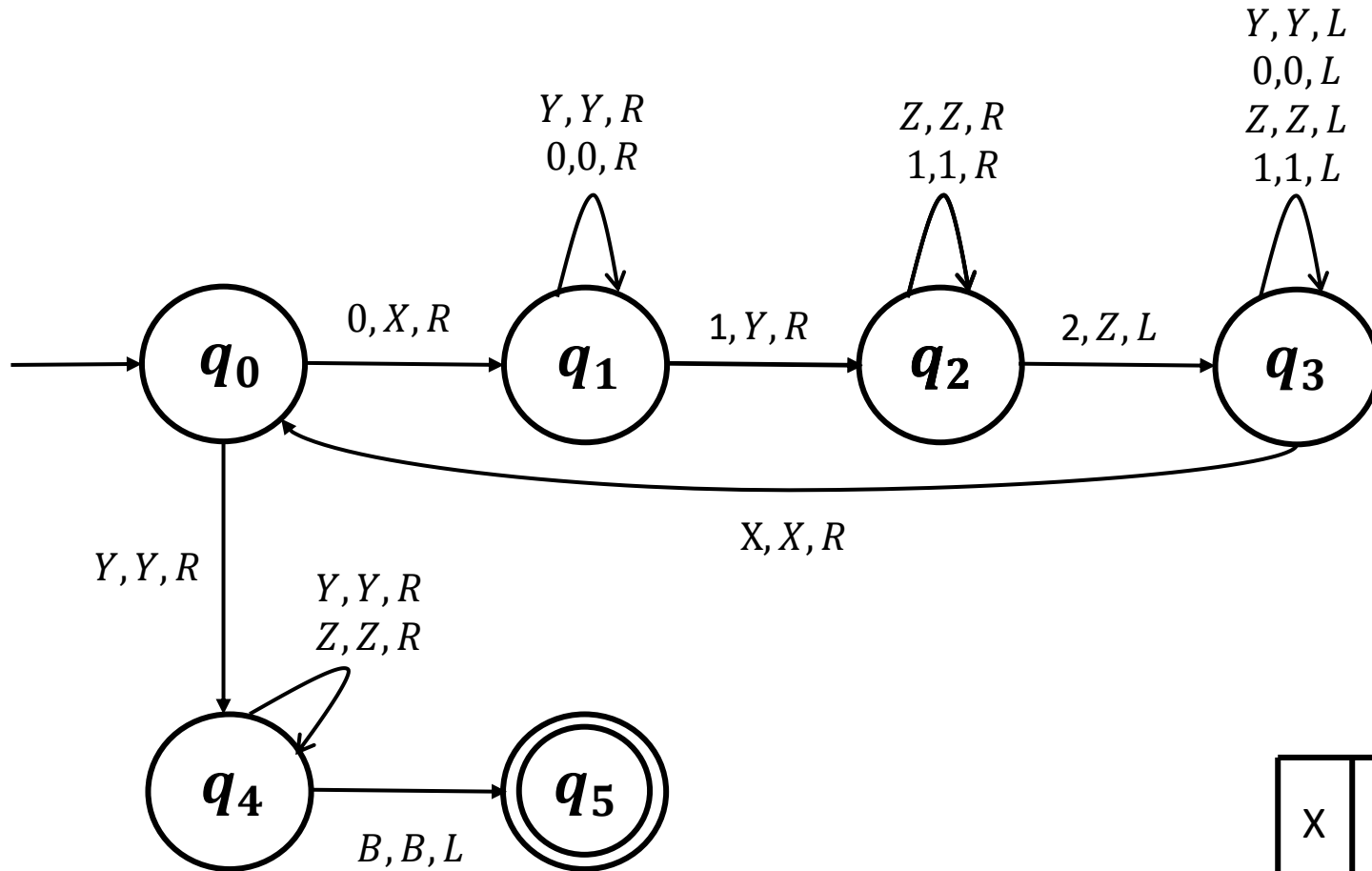


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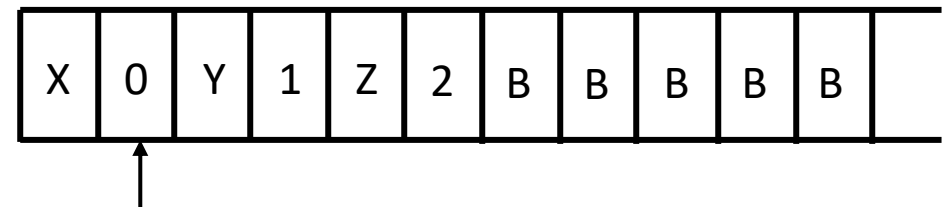


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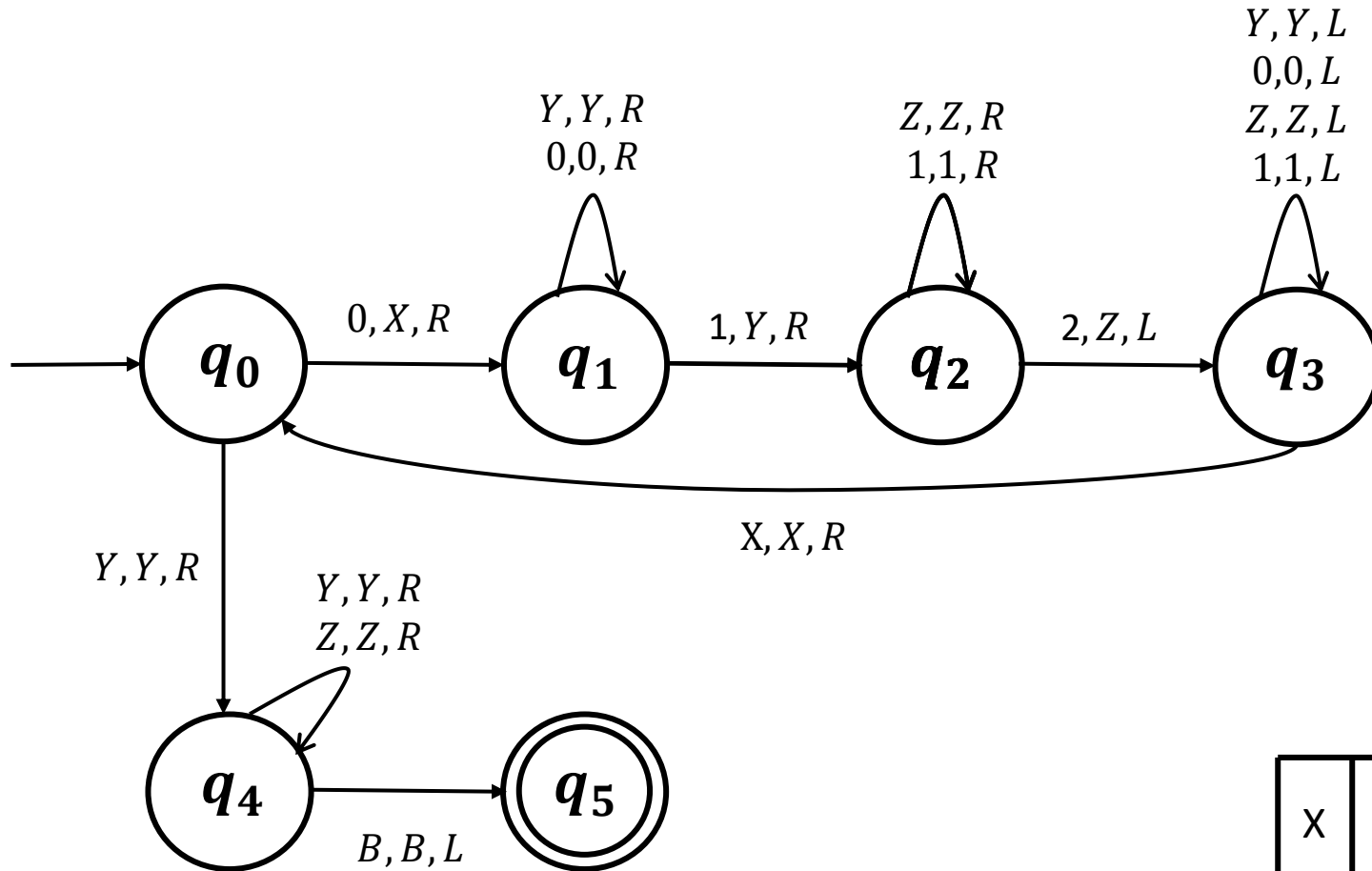


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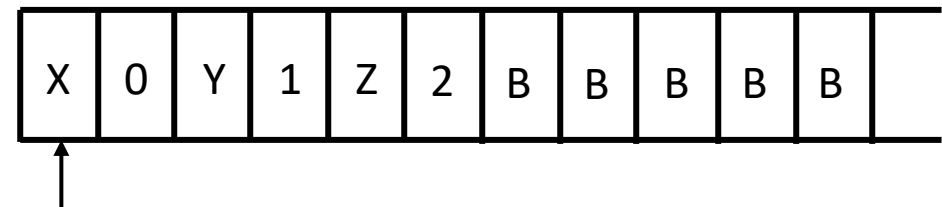


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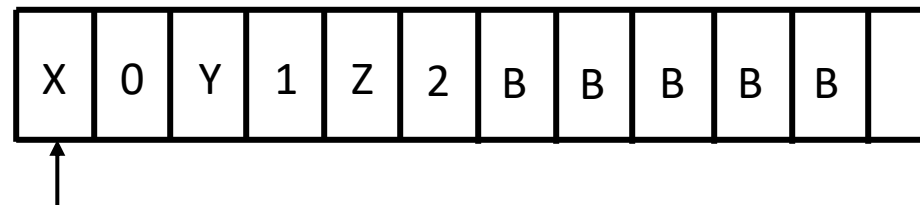
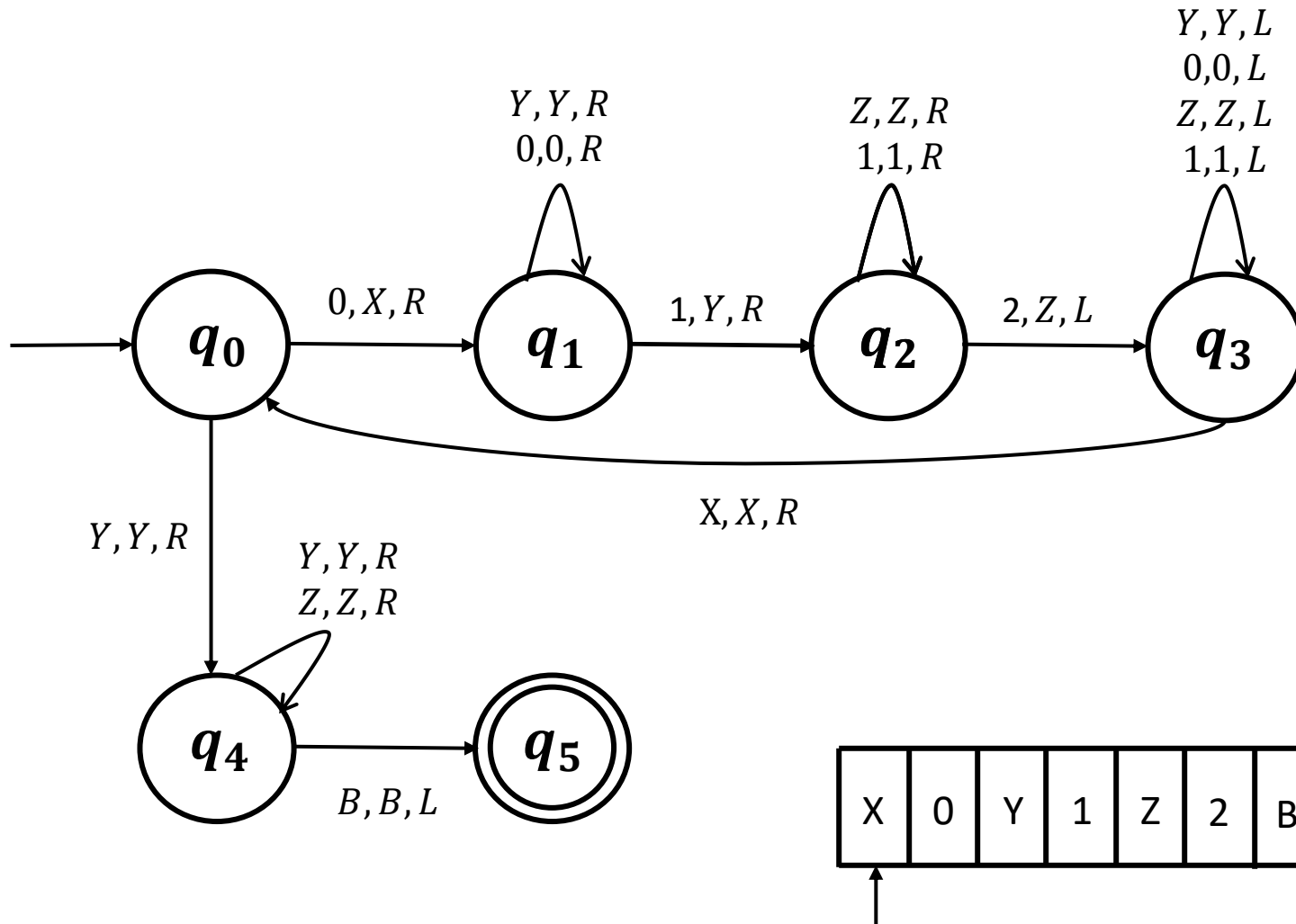


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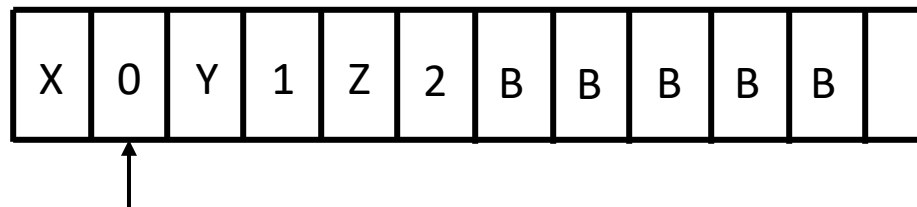
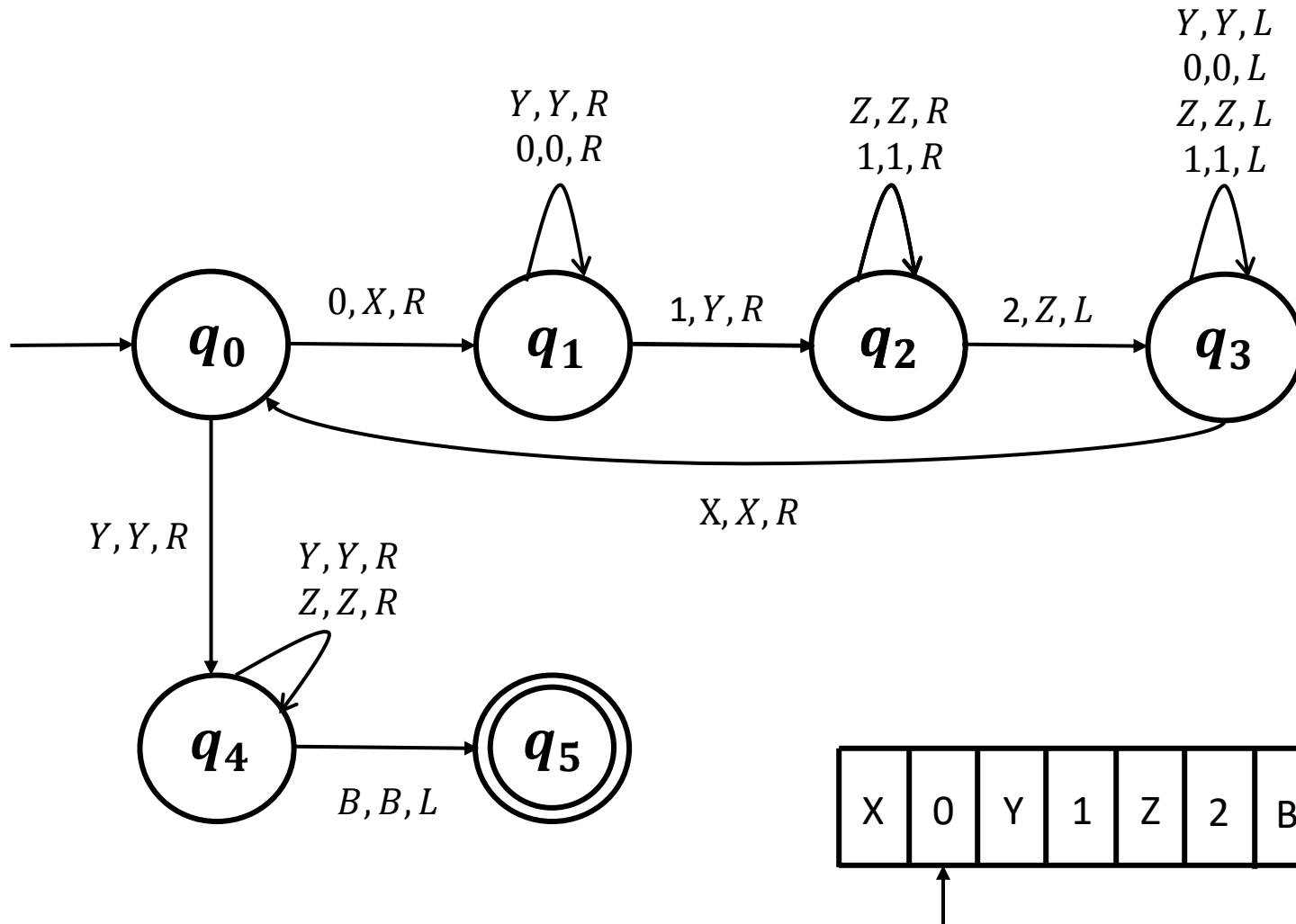
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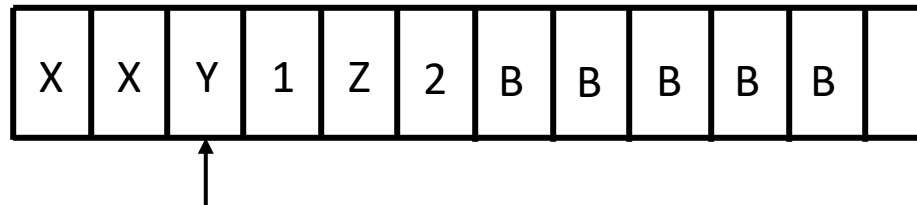
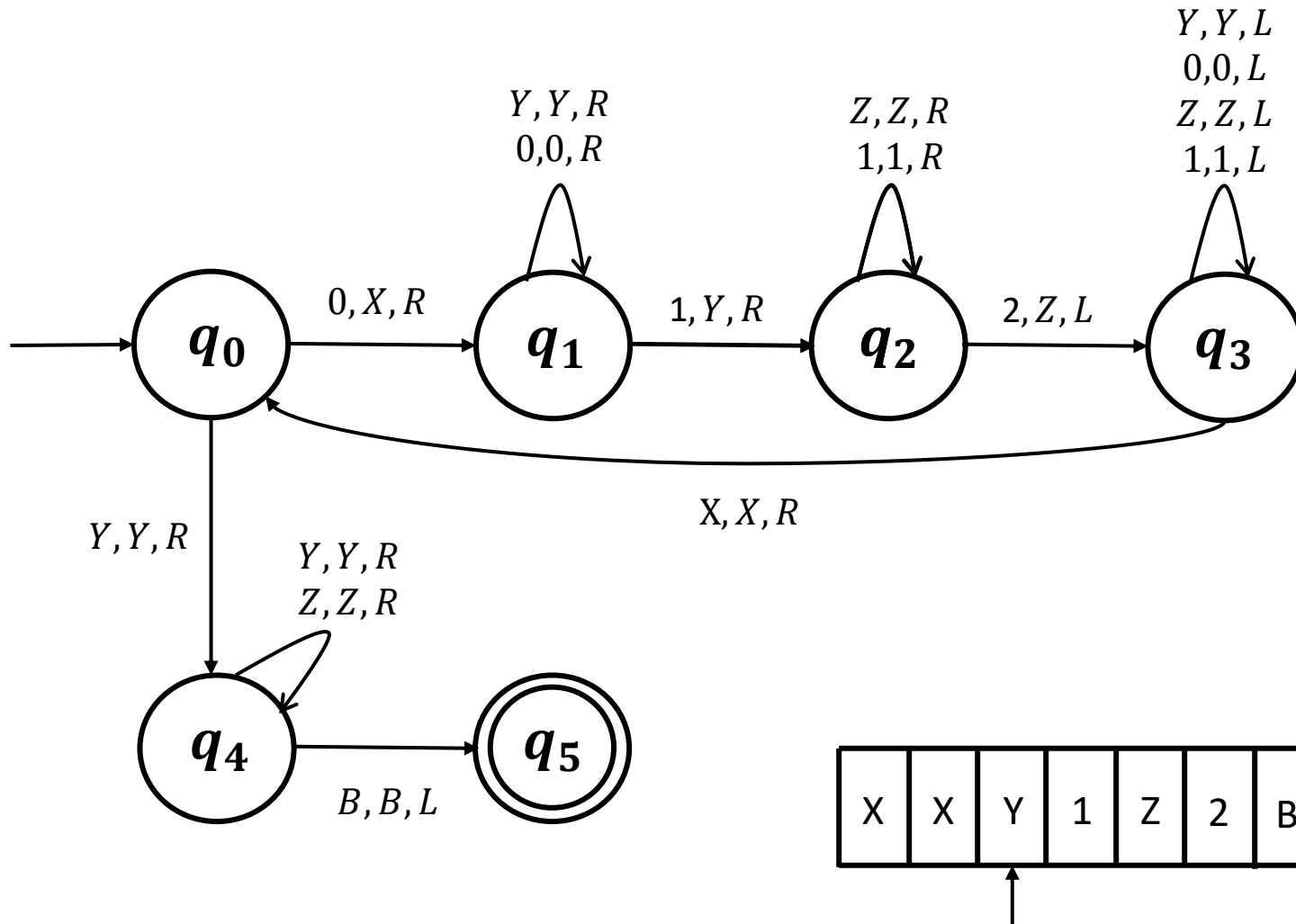
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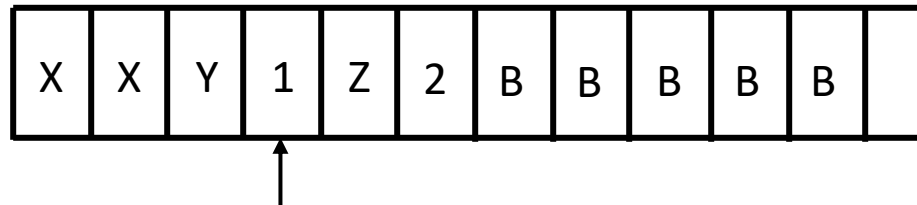
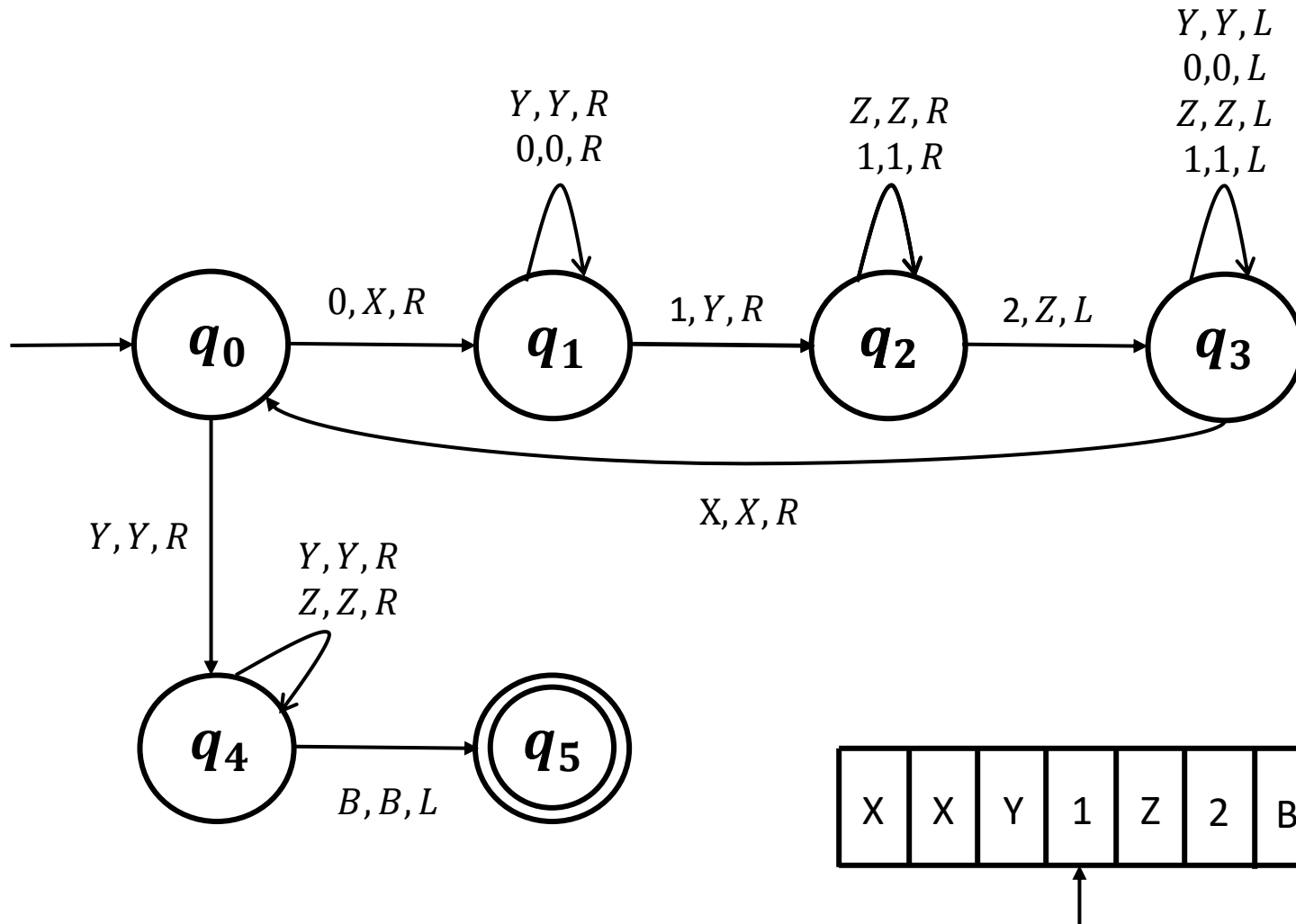
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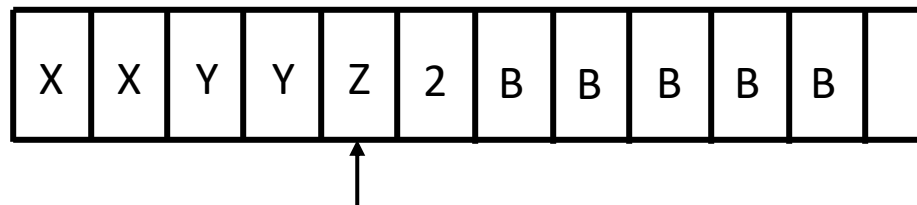
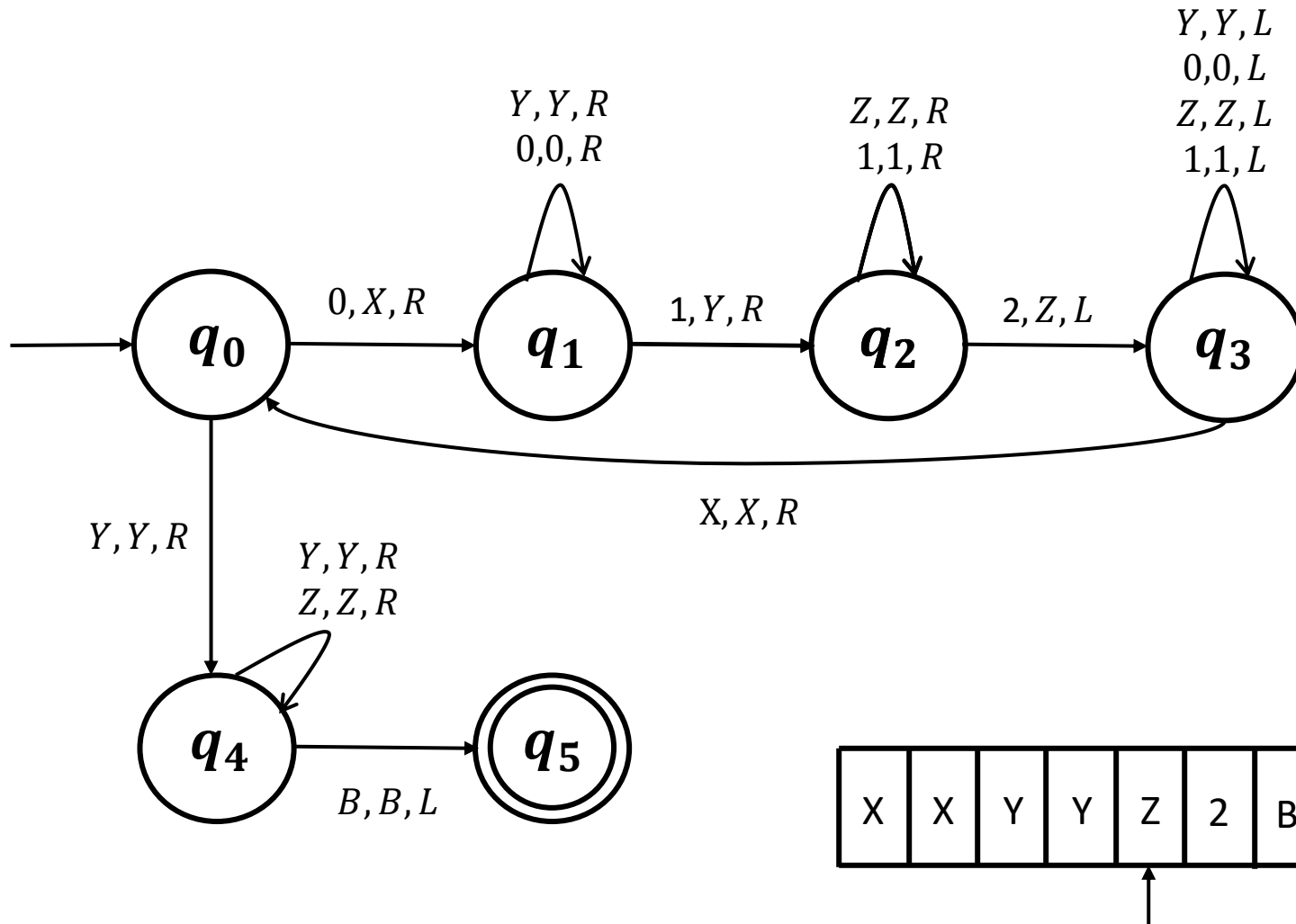
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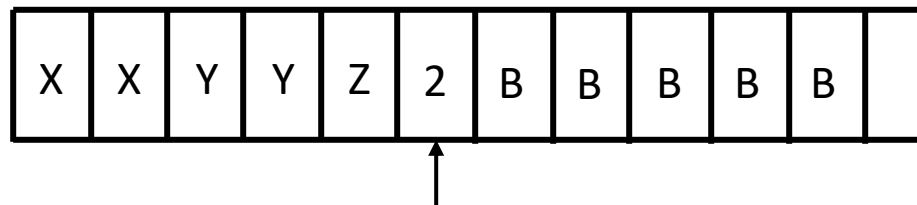
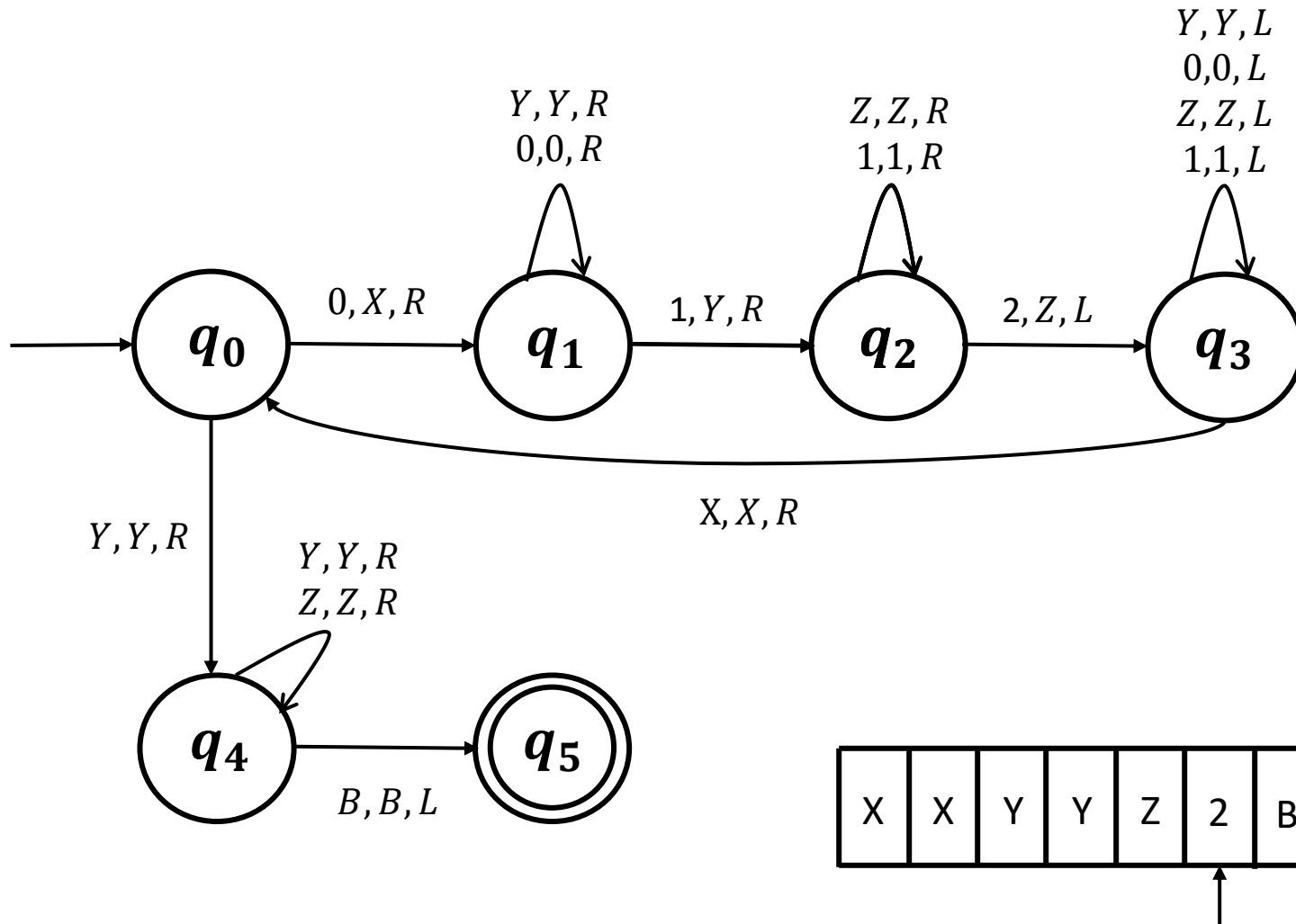
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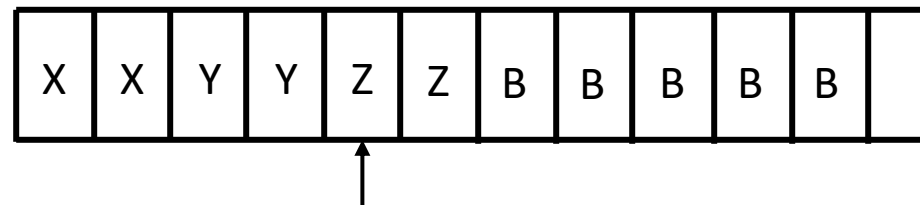
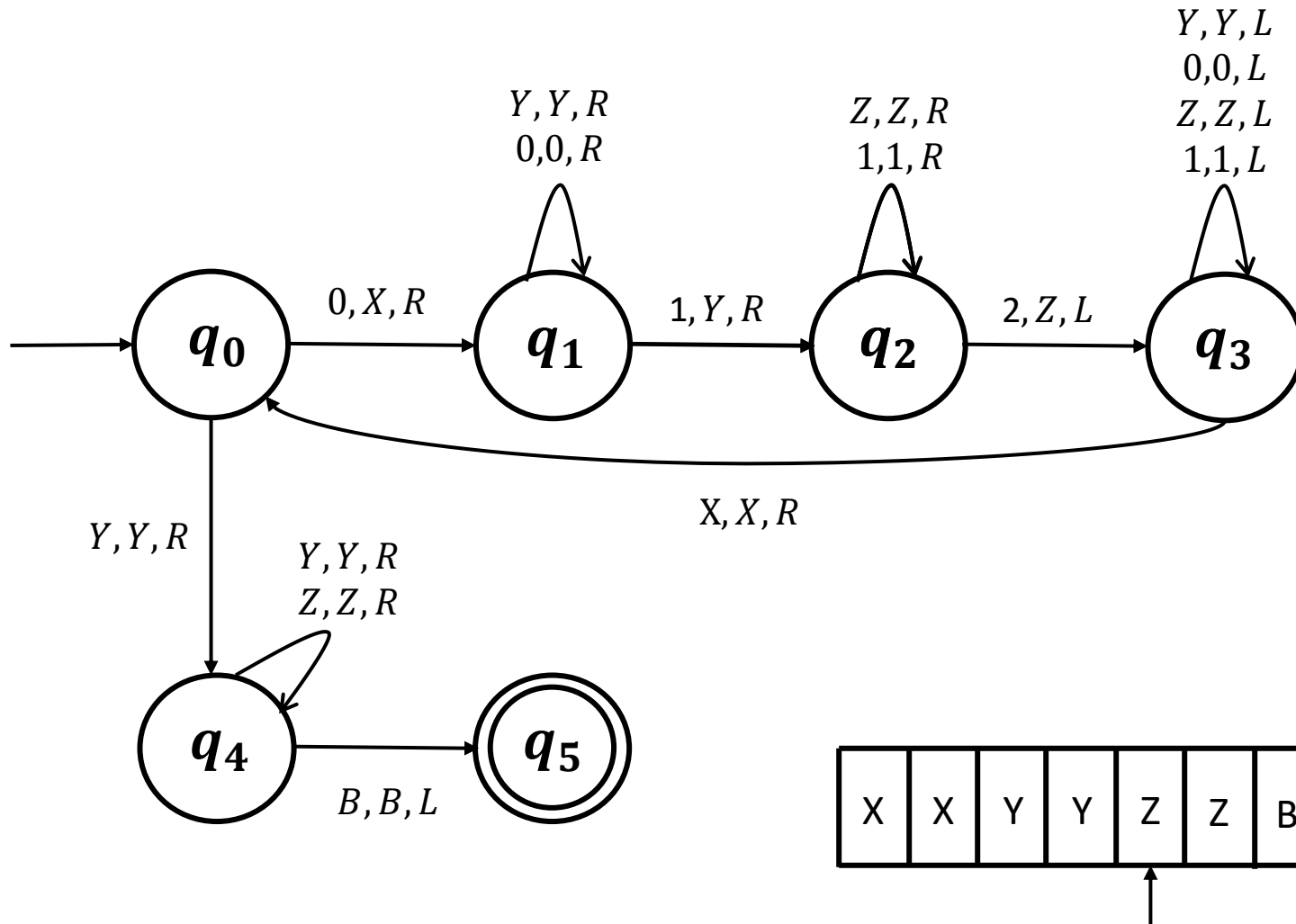
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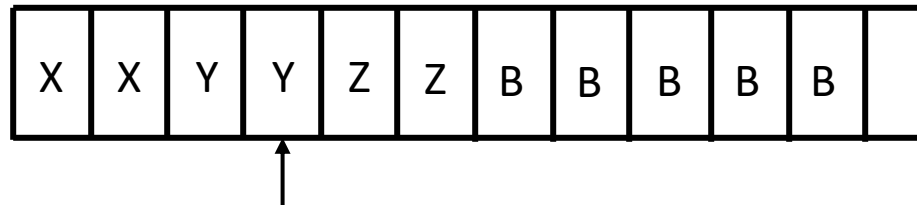
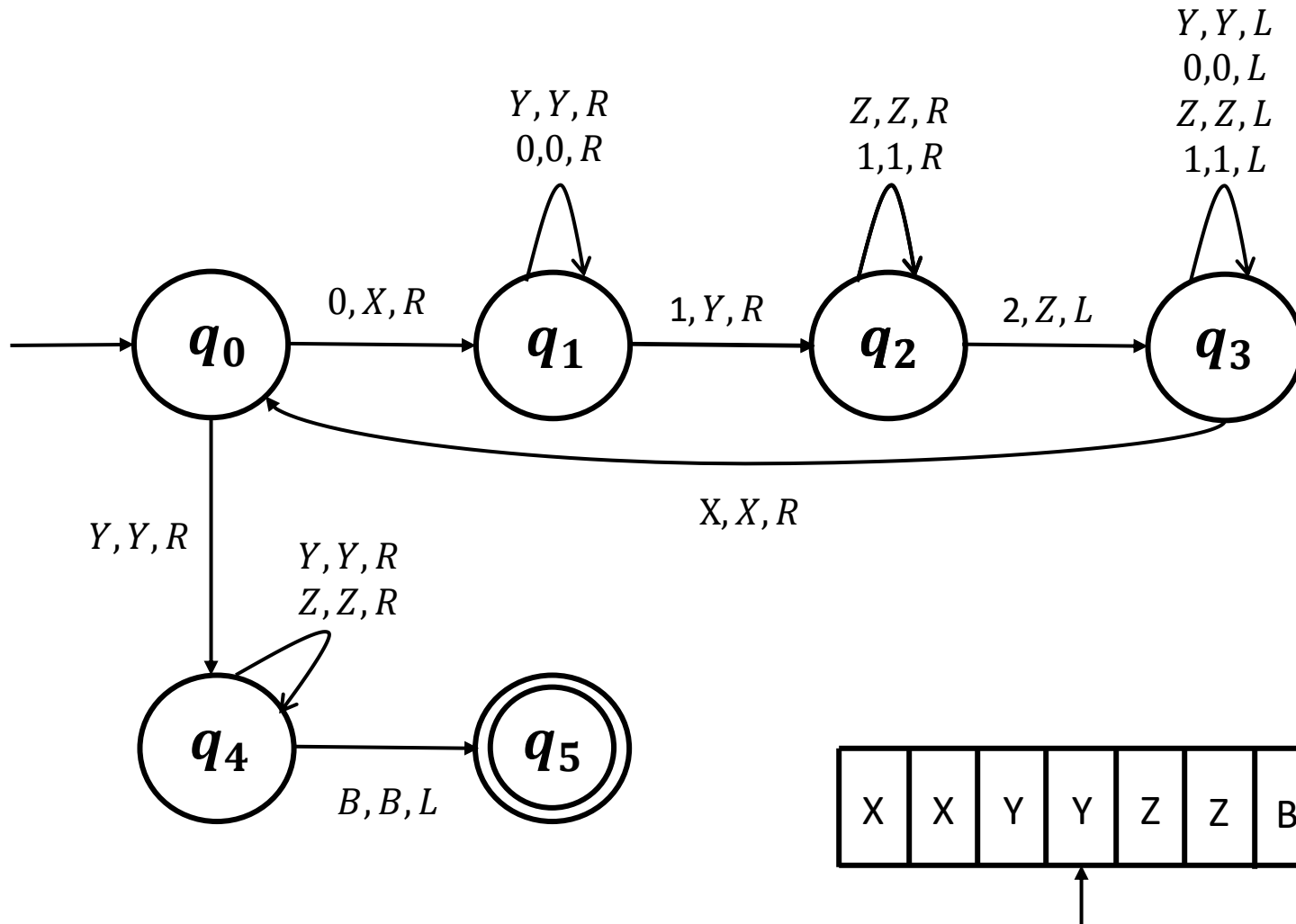
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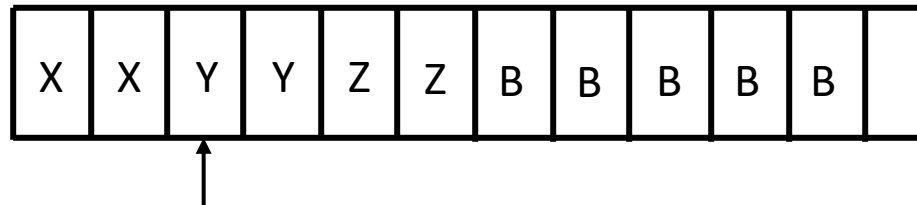
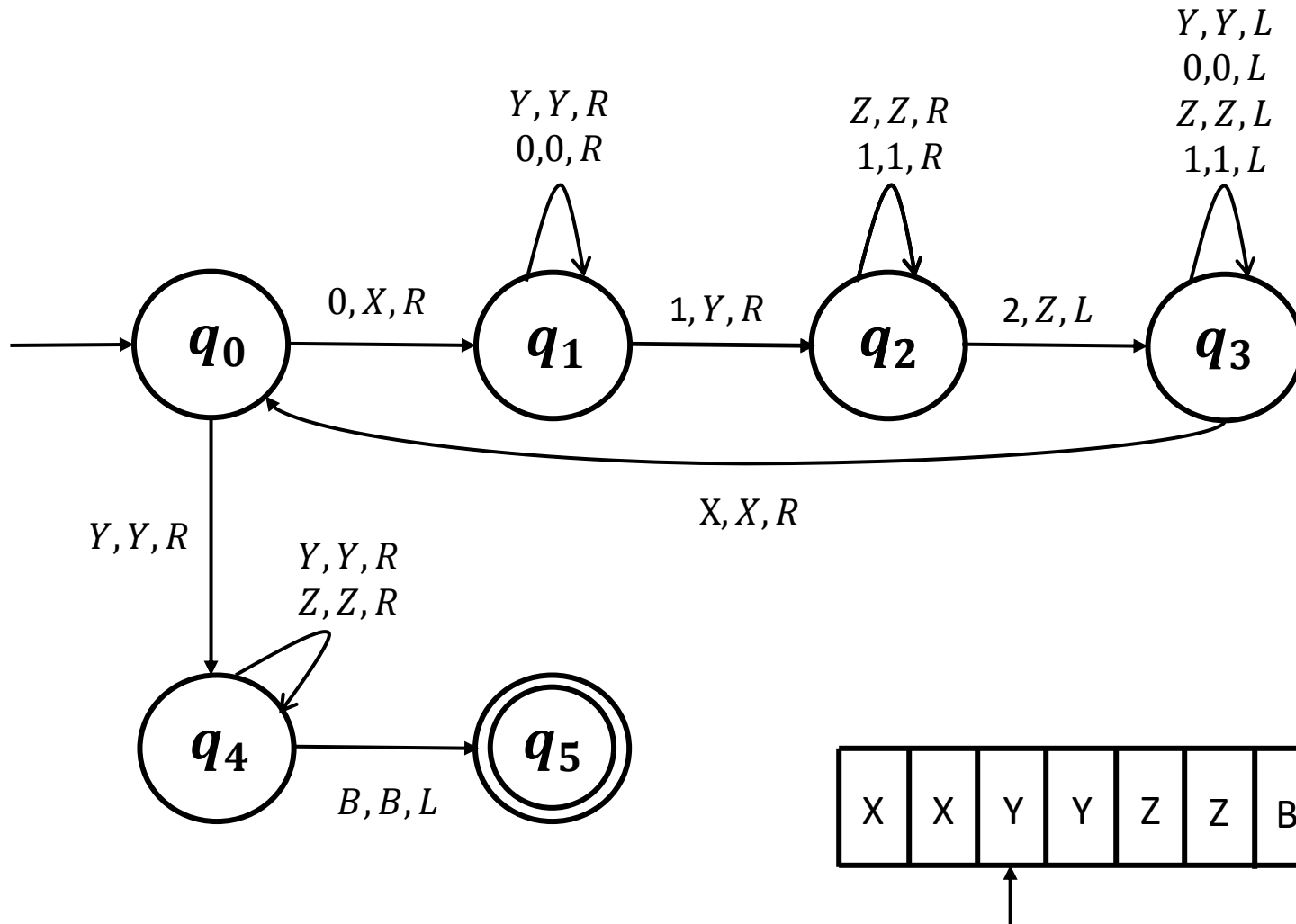
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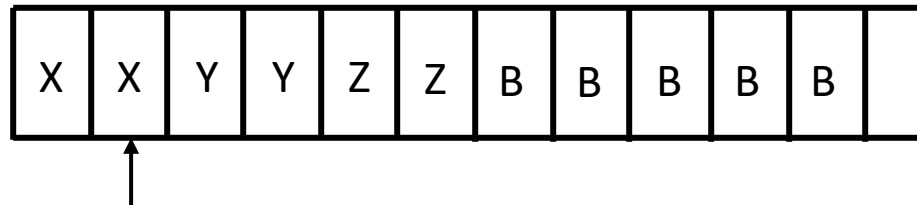
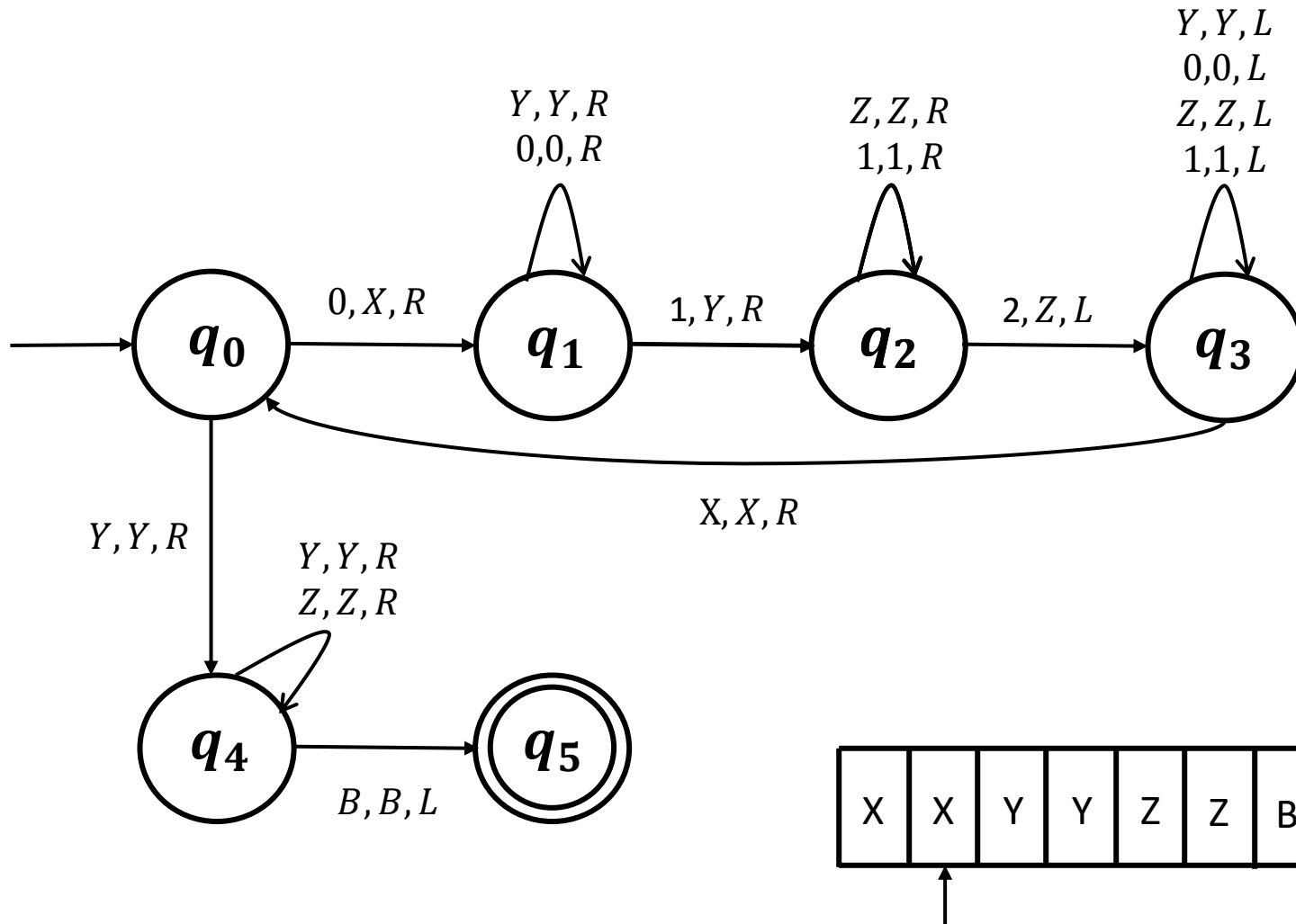
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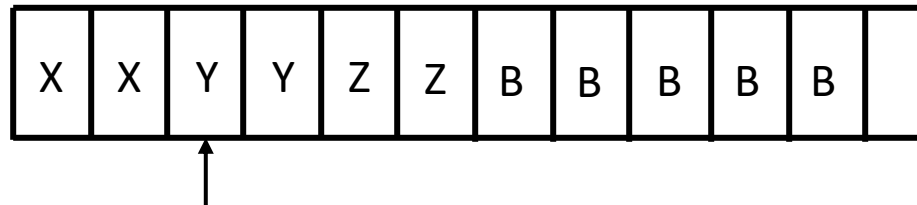
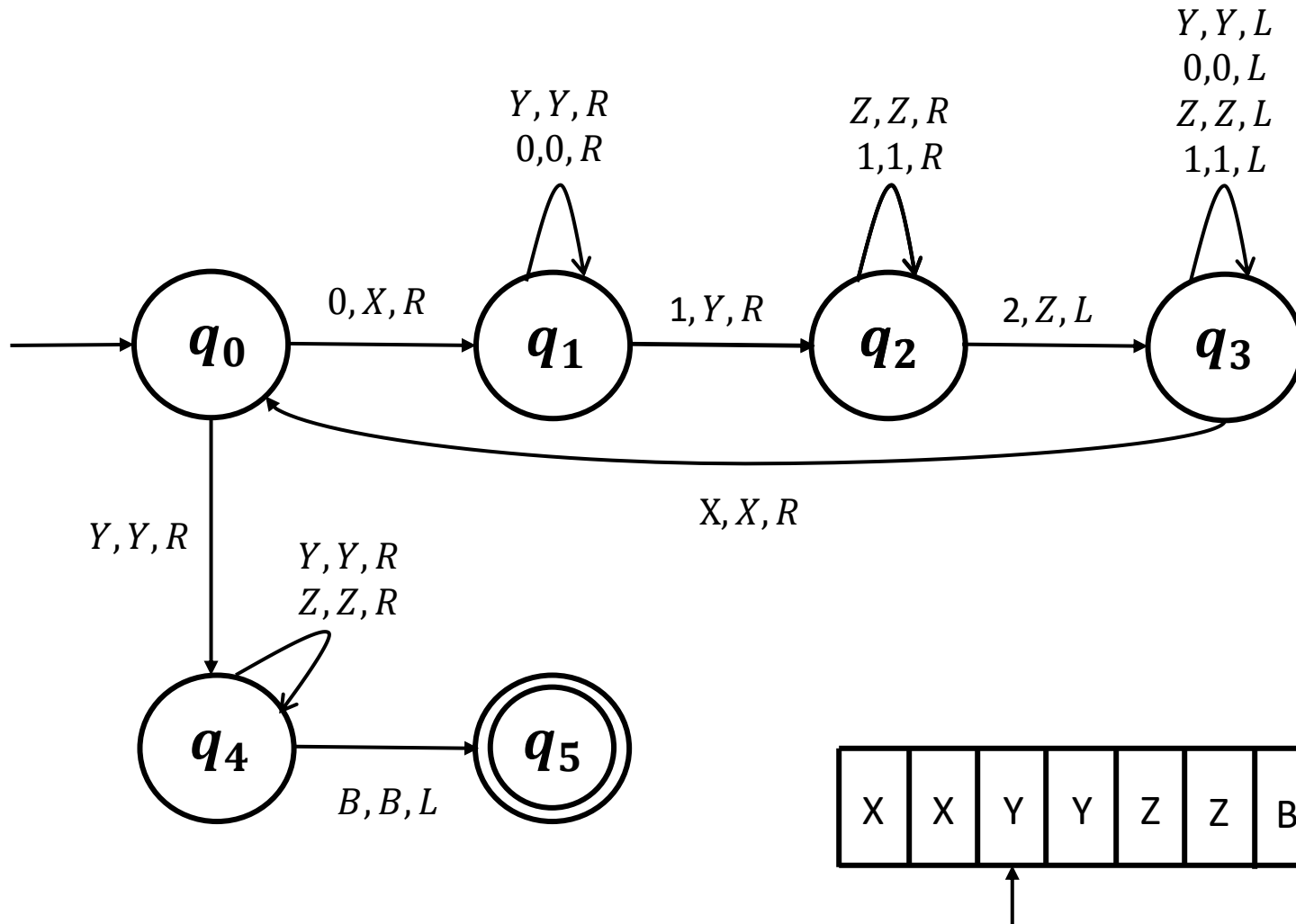
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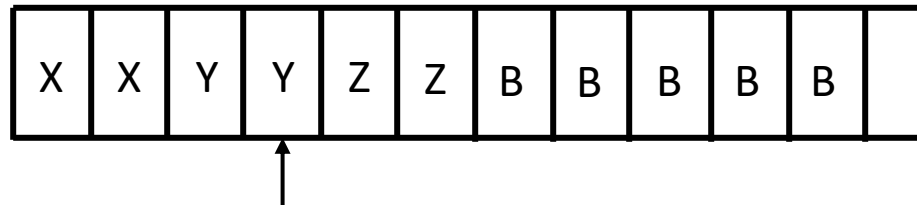
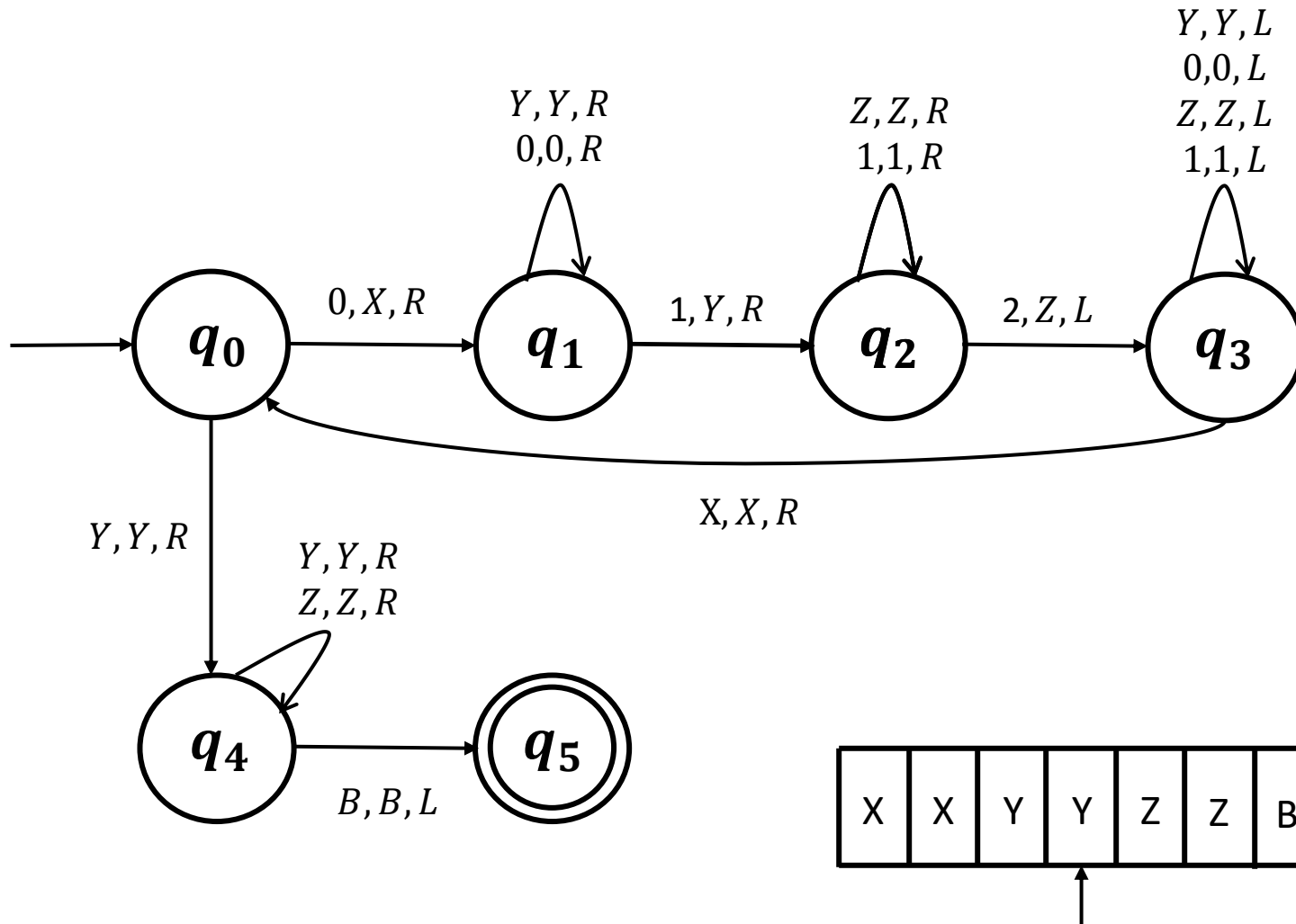
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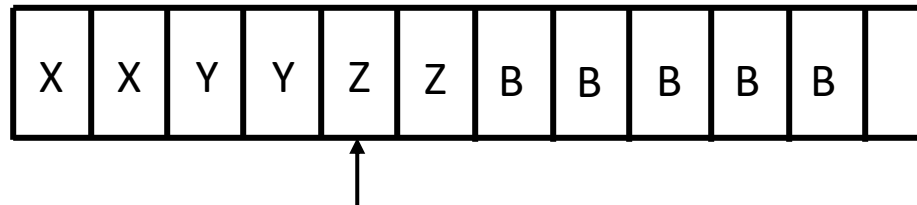
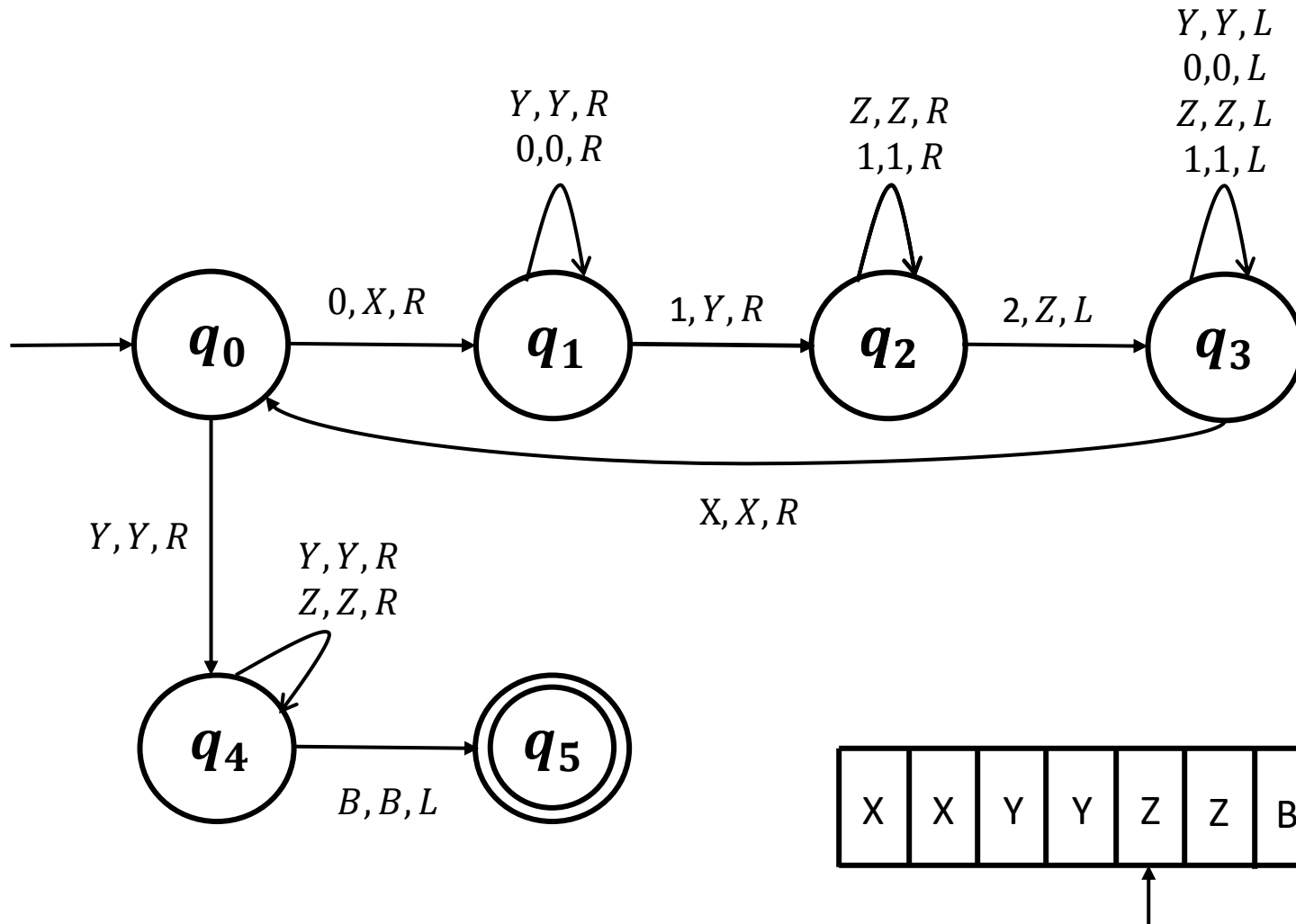
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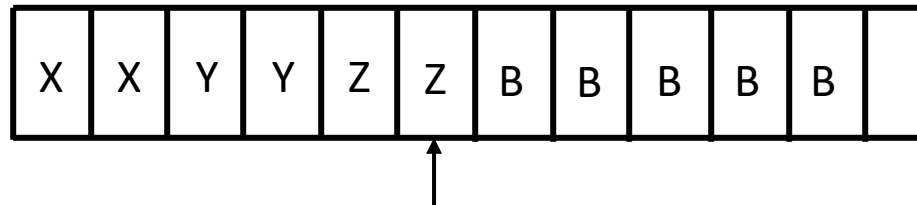
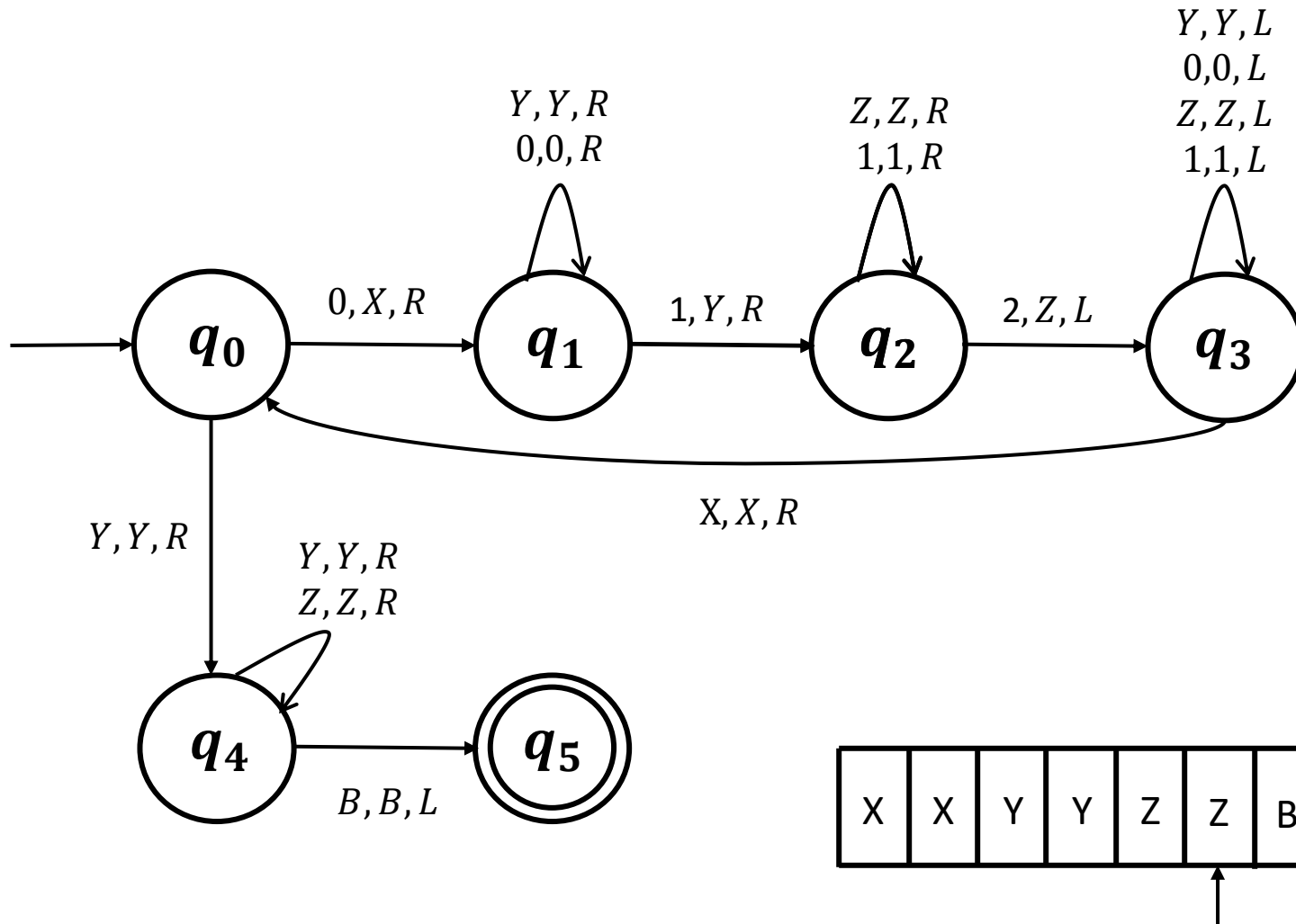
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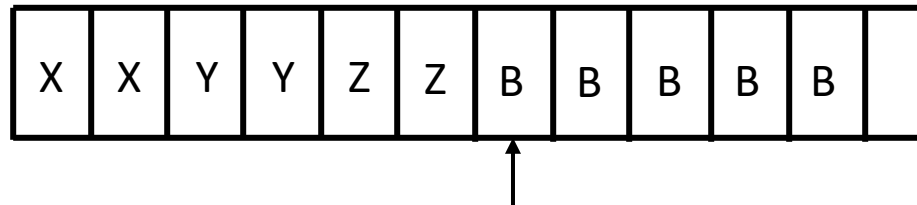
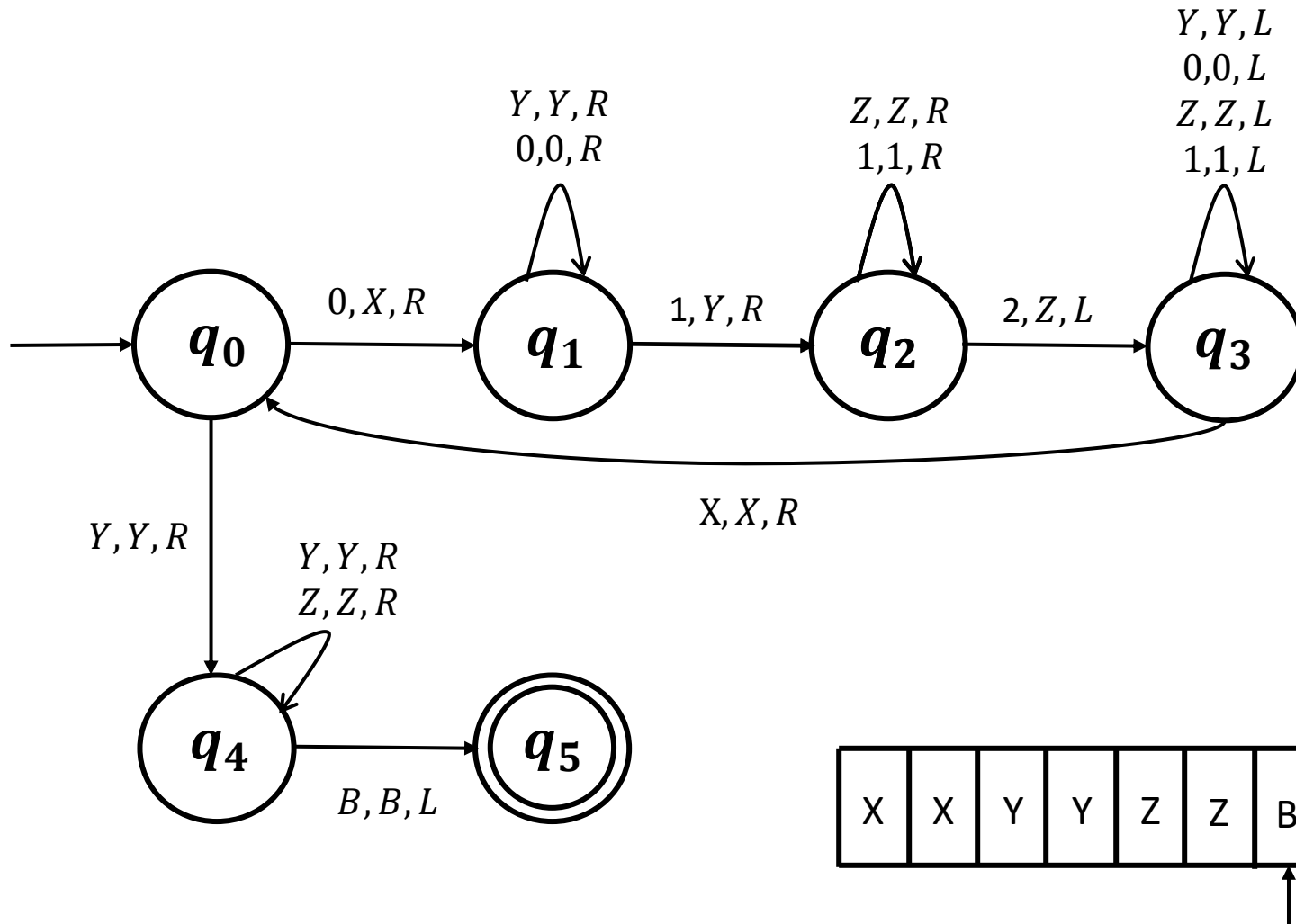
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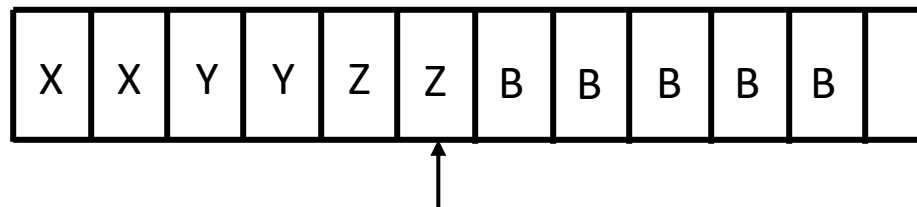
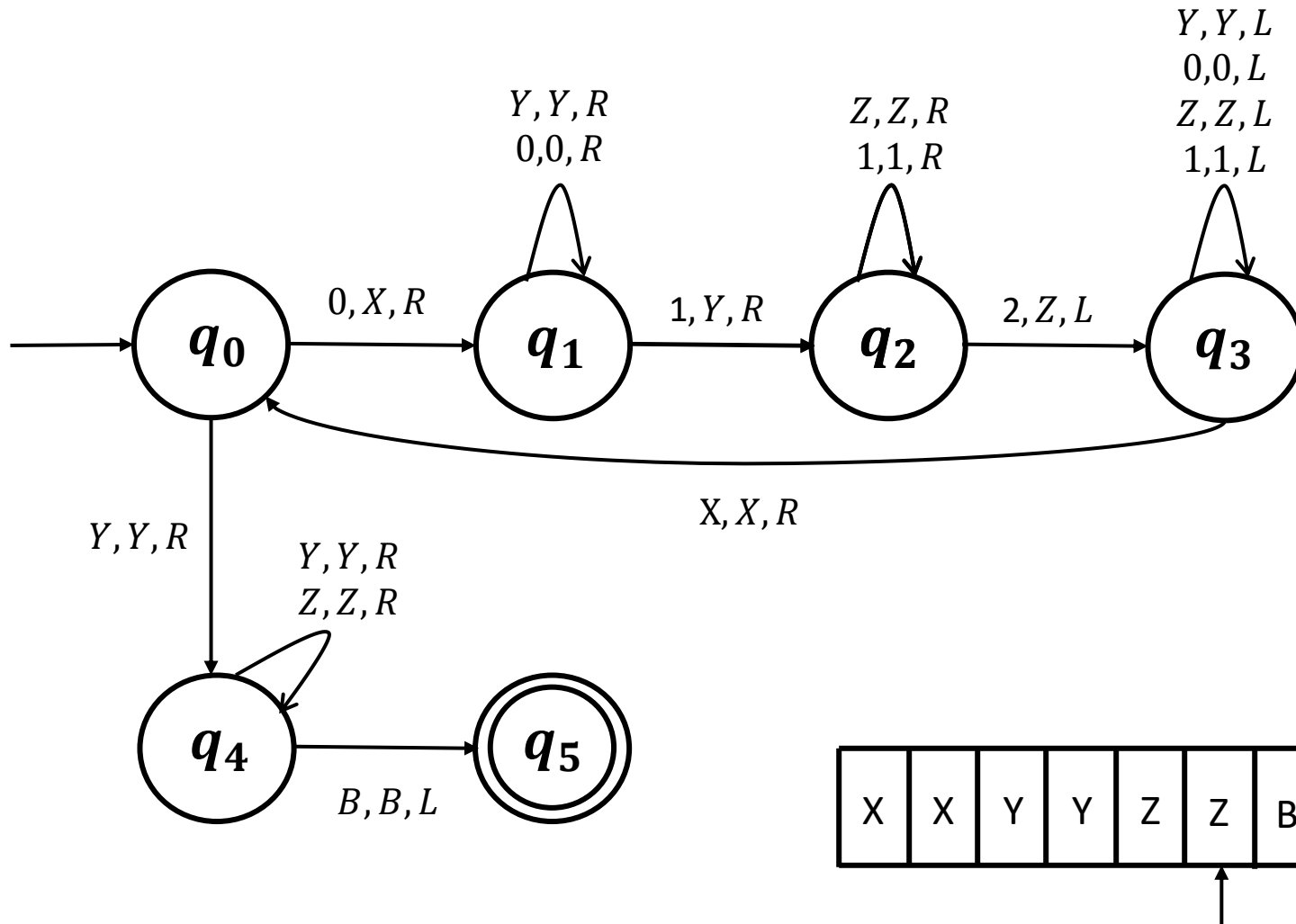
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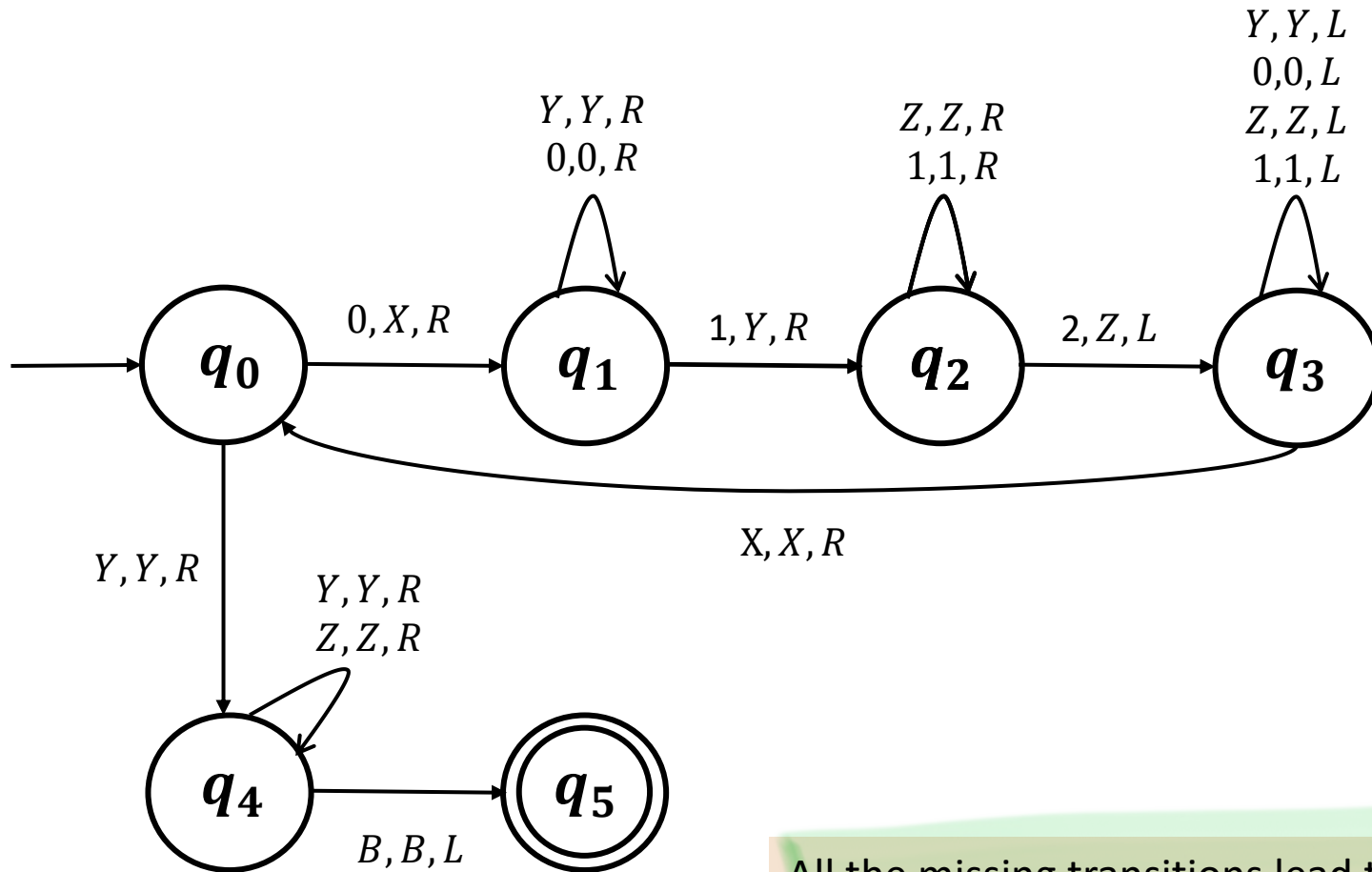
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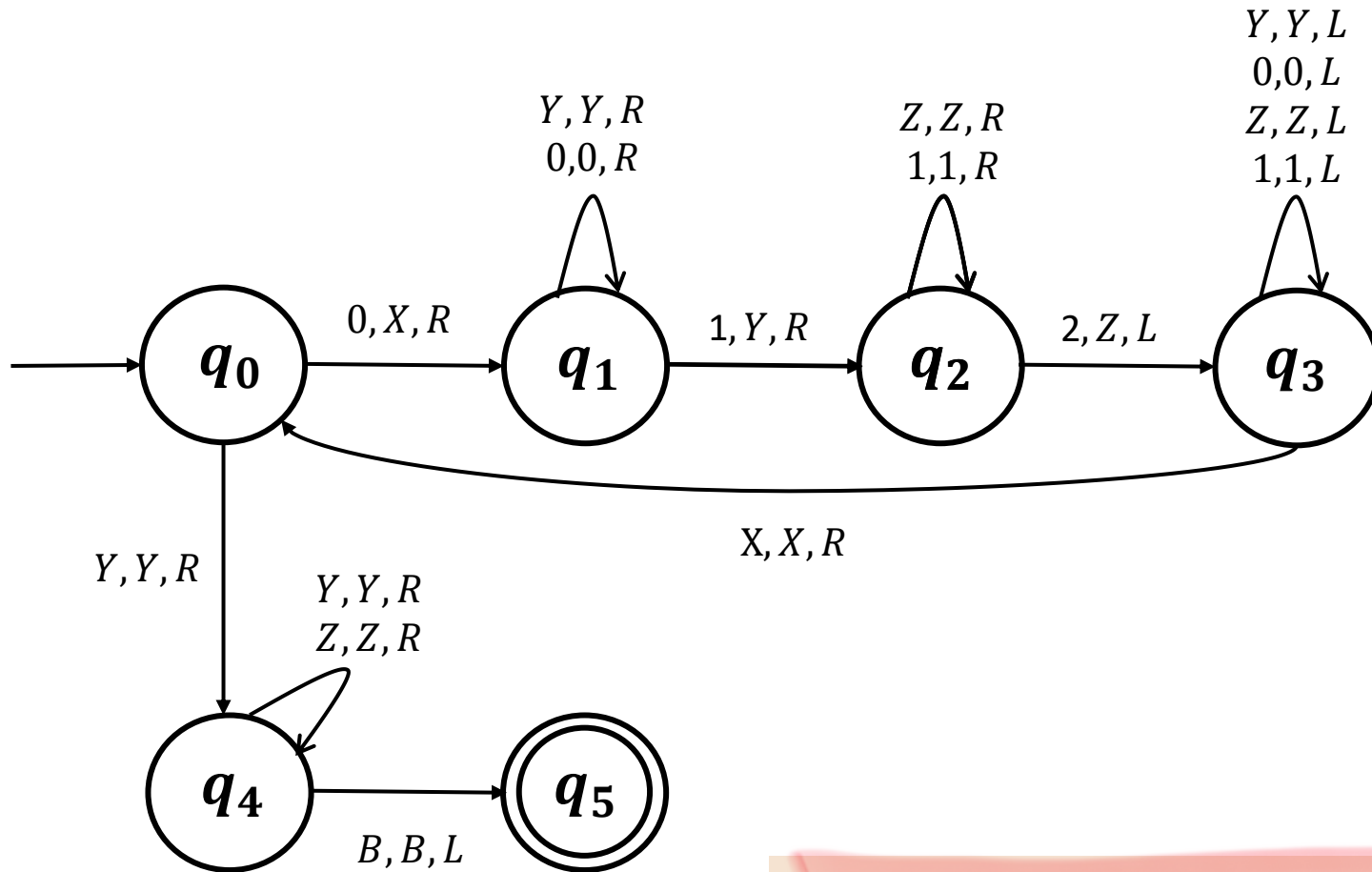


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All the missing transitions lead to a reject state and so any input not of the form $\{0^n 1^n 2^n\}$ is rejected.

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$CFL \subseteq \text{Language recognized by TM}$

Turing Machines

Formally, a Turing Machine is a 7-tuple $(Q, \Sigma, \Gamma, \delta, q_0, q_{accept}, q_{reject})$ where

- Q is a finite set called the **states**.
- Σ is the set of input **alphabets** not containing the blank symbol B .
- Γ is the **tape alphabet**, where $B \subseteq \Gamma$ and $\Sigma \subseteq \Gamma$.
- $\delta: Q \times \Gamma \mapsto Q \times \Gamma \times \{L, R\}$ is the **transition function**
- $q_0 \in Q$ is the **start state**.
- $q_{accept} \in Q$ is the **accepting state**.
- $q_{reject} \in Q - \{q_{accept}\}$ is the **reject state**.

Configuration of a TM: Combination of the current state, the current tape contents and the current head location.

Formally, it is a triple: (q, a, x) , where $q \in Q, a \in \Gamma, x \in \mathbb{Z}_+$

At each step, the Turing machine configuration changes. We say C_1 **yields** C_2 if the TM changes from C_1 to C_2 in one step.

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A TM **M** **accepts** **w** if there exists a sequence of configurations C_1 to C_k , where

- C_1 is the start configuration M on w .
- Each C_i yields C_{i+1} .
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Language recognized a TM M :

$$L(M) = \{w | M \text{ accepts } w\}$$

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$X\ 0\ 0\ 1\ 1\ 1\ B\ B\ B\ B\ \dots$
 ↑
 q_1

Start configuration:

$0\ 0\ 0\ 1\ 1\ 1\ B\ B\ B\ B\ \dots$
 ↑
 q_0

Accept configuration:

$X\ X\ X\ Y\ Y\ Y\ B\ B\ B\ B\ \dots$
 ↑
 q_{accept}

Reject configuration:

$X\ X\ X\ Y\ Y\ 0\ B\ B\ B\ B\ \dots$
 ↑
 q_{reject}

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Next Lecture

Various TM model **variants**: Robustness of the standard TM model

Thank You!