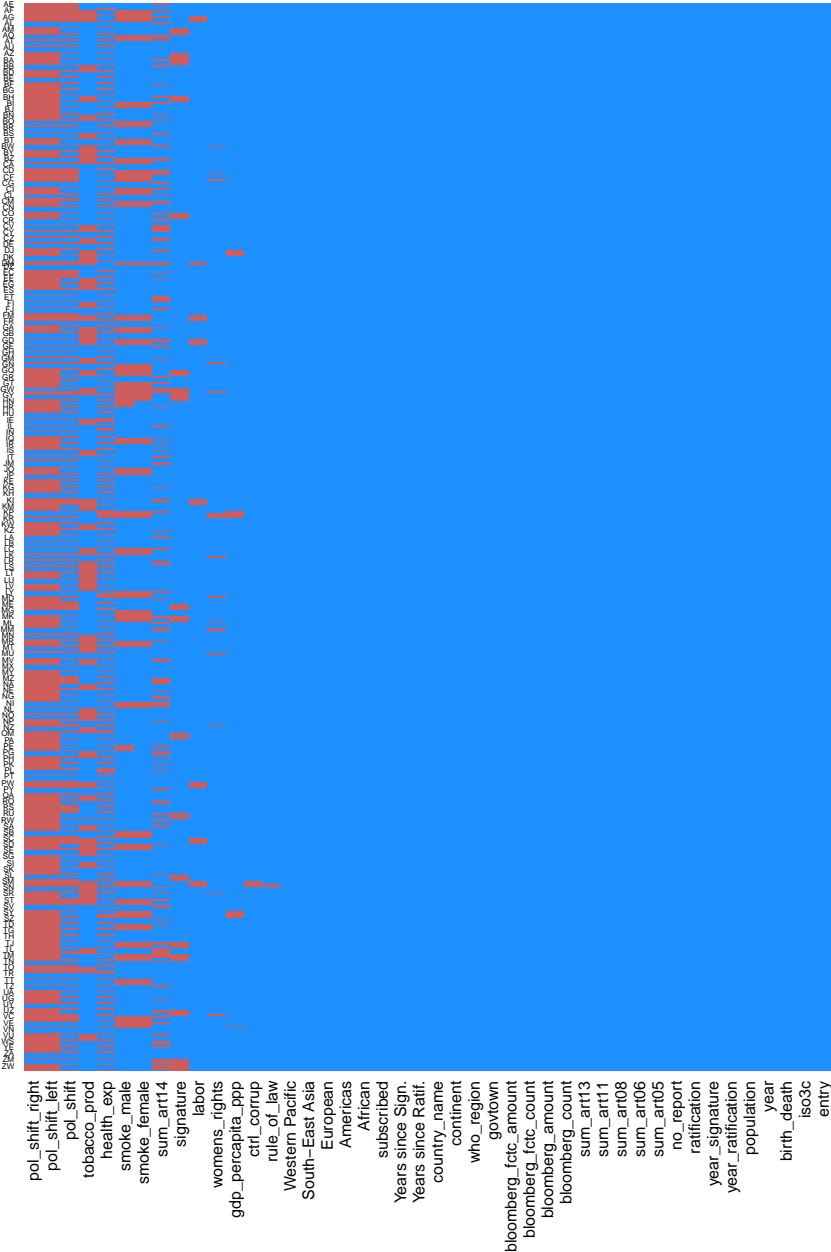


Missingness Map



■ Missing (7%)
■ Observed (93%)