

Audio DSP

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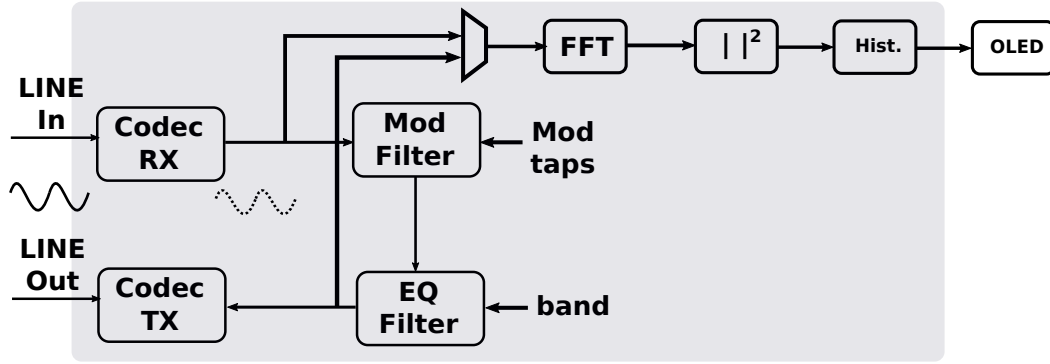
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This project is an application of basic signal processing on audio signal, using Zynq/Zedboard platforms.

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1 System



Bloc design

All processing is real time and synchronous to the input stream. The initial sample rate is 48 MHz, making the input data rate which leads to a 1.152 Gb/s input data rate, this is much more than needed.

We reduce the internal sample rate to 24 kHz (a little more than needed), reducing the bit rate to 576 kB/s. Data rate reduction is done using a CIC decimation filter.

The modulation filter as well as the EQ filter are controlled from the User Interface.

The FFT processes either the direct RX input or the output signal. This allows to visualize the effect of the modulation & the EQ filters. Switching is done in real time on user specs.

The resulting power spectrum is converted to histogram & displayed on the onboard OLED display. The display is 128x32 pixel wide, which in our case gives a spectral resolution of 187.5 Hz on the display, which is more than decent.

The internal data stream obviously needs a final interpolation, this is done by a CIC interpolation filter, feeding a 1.152 Gb/s stream to the TX side. The CIC interpolation filter is strictly symmetrical to the CIC decimation filter.

1.1 CIC filters

CIC filter being defined by R, M, N parameters where

- R : decimation/interpolation factor
- M : time delay, can either be 1 or 2 cycle
- N : number of stages

To reduce the initial rate from 1.152 Gb/s we fix $R = 128$.

Both the interpolation & decimation filters are comprised of a N stages of integration filters & comb filters.

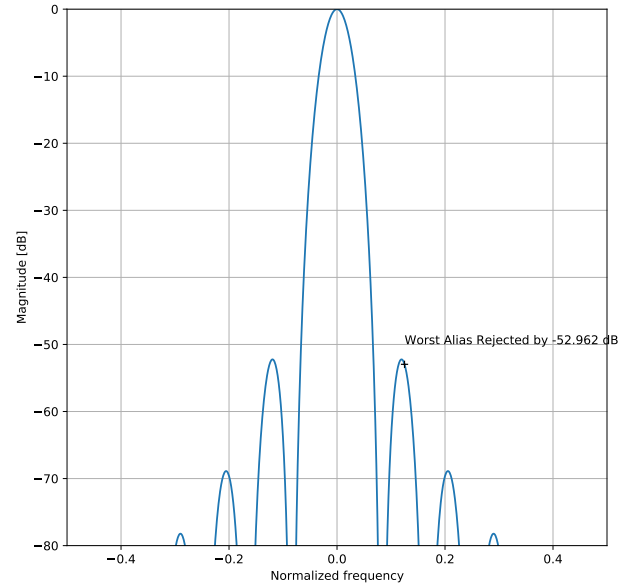
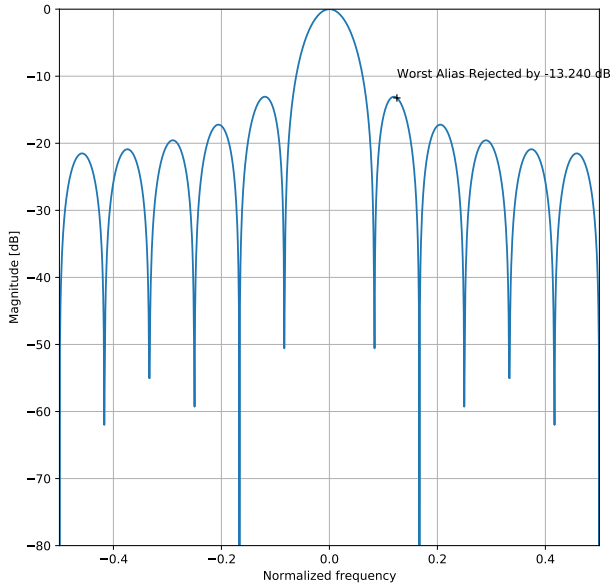
The `$git/dsp/cic.py` Python script can plot the frequency response of a given CIC filter:

```
$git/dsp/cic.py R=4 M=1 N=12
```

```
$git/dsp/cic.py R=8 M=2 N=4
```

- an integrator stage is defined as $H(z) = \frac{1}{1-z^{-1}}$
- a comb stage is defined as $H(z) = 1 - z^{-M}$
- total CIC filter response is therefore $H(z) = \left| \frac{1-z^{-M}}{1-z^{-1}} \right|^N$
- the total magnitude response is approximated by $H(\nu) = \left| \frac{\sin(RM\pi\nu)}{RM\sin(\pi\nu)} \right|^N$
- the worst alias is encountered at frequency $\nu = \frac{3}{2MR}$
- the total filter gain is $(RM)^N$
- hence the total bit growth in our implementation will be $\lceil \log_2 (RM^N) \rceil_{\text{ceil}}$

Increasing N (number of stages) increases the filter performance:



Comparing a CIC decimation filter with N=2 stages, the Increasing the number of stages to N=8 improves the worst worst alias is rejected by -13 dB alias rejection to -53 dB

We fix $N = 8$ in our case, not to consume too much ressources. This will give a rejection of -53 dB for the worst alias ever encountered.

As you can see, the CIC filter frequency reponse has a $f(\nu) = \frac{\sin(\nu)}{\nu}$ shape. Which means we completely lose the flatness of within the system bandwidth, and the transition bandwidth to cutoff is very large.

To compensate for the flatness loss and to reduce the transition bandwidth, we introduce a compensation filter (in the form of an FIR filter) after the CIC decimation filter and prior the CIC interpolation filter.

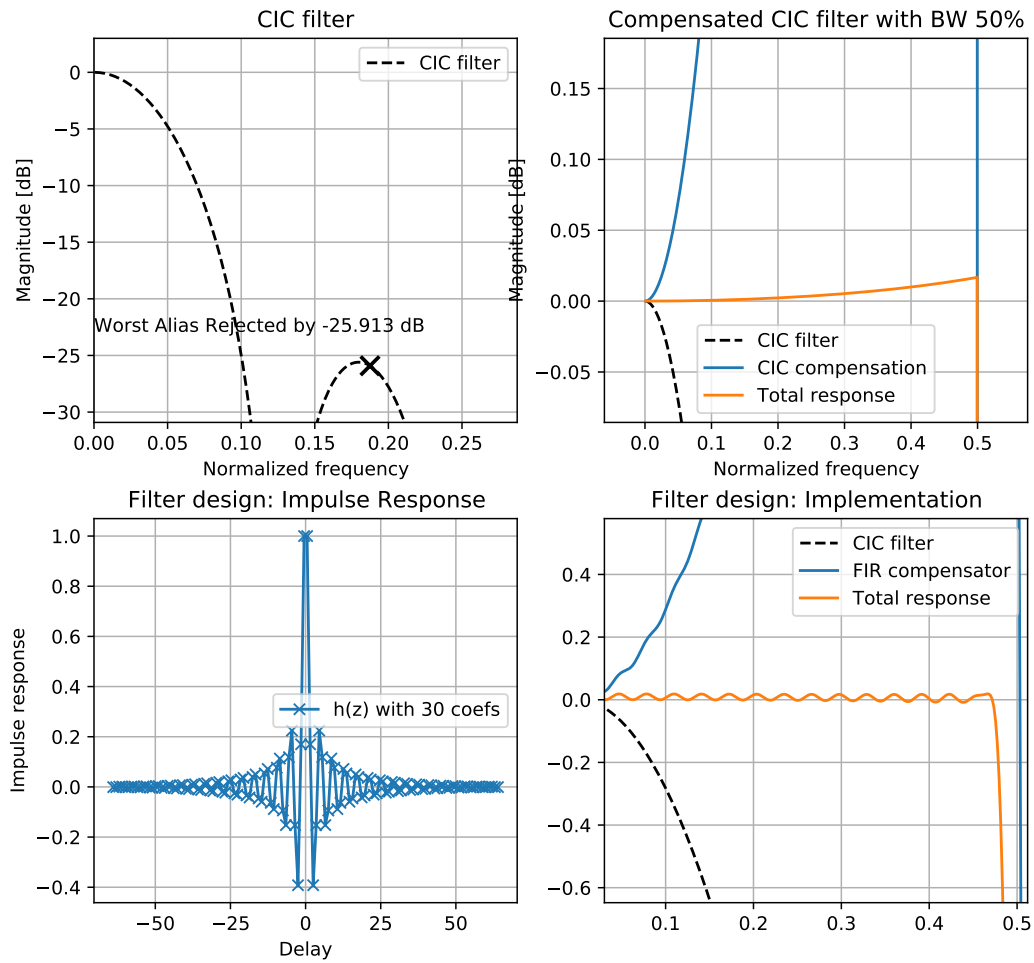
1.2 CIC compensation filter

The compensation filter response is the exact inverse of the CIC filter response $G(\nu) = \frac{1}{H(\nu)}$ within the new established band, ranging from 0 to $\frac{f_s}{R}$, $\frac{f_s}{R}$ being the first null of the $\frac{\sin(\nu)}{\nu}$ response.

The CIC compensation filter is designed using the python script `$git/dsp/cic-compensator.py`.

```
$git/dsp/cic-compensator.py R=4 N=12 BW=30
$git/dsp/cic-compensator.py R=8 N=4 BW=45 ncoef=128
```

Use BW (in %) to set the pass band edge location within the new established Nyquist band. The ncoef parameter allows to compare different implementation of the FIR filter.



The CIC filter compensator designer designs a CIC filter to compensate for the CIC filtering stage. One can compare the effect of the BW cut off frequency (design the new user bandwidth) and the ripple effect, for different FIR filters implementation.

Upper left: theoretical CIC filter as described in previous section.

Upper right: theoretical CIC filter versus its optimum compensation, for a given BW parameter. Total theoretical response is CIC+FIR.

Below - left: designed Impulse Response to be implemented, for given BW and ncoef parameters.

Below - right: filter implementation: theoretical CIC filter compensated by implemented FIR filter. Total implemented response is CIC+FIR.

CIC filter compensation will be implemented in both the decimation & the interpolation filter, using Xilinx's optimized FIR filter IP core.

The CIC decimation is very important to our system, without heavily downsampling the input signal (we chose $R=128$), the displayed FFT resolution would be 37.5 MHz, which is totally unusable for audio data. The Modulation Filter & EQ filter would require so many bands to be computed that it would also be impossible to implement them in the system.

1.2.1 CIC interpolation filter

Using previously designed compensated CIC decimator, we reduce the input rate by a factor of 128. We need to interpolate by a factor of 128 prior outputting the signal to the DAC.

1.3 Equalization filter

The EQ filter allows the user to modify the signal's frequency response, in real time.

The frequency response is divided into 16 bands, considering our internal sample rate of $f_s = \frac{48e8}{128} = 24$ kHz, each band is 1.5 kHz wide.

The user interface allows the user to define the weighting of each band, so define the custom frequency response $H(\nu)$.

The GUI transforms $H(\nu)$ into $h(z)$ to be applied in the FIR filter:

$$h(z) = FFT^{-1}(H(z)) = Bilinear(H(\nu)) \quad (1)$$

1.4 FFT Histogram

The Histogram IP core converts the power spectrum from the magnitude IP core to a histogram to be displayed on the OLED.

It is a simple mapping of the resulting power spectrum to a 2D array (X,Y) describing the power spectrum along a frequency axis.

2 Simulation

2.1 GHDL

Most IPs are simple unitary functions and can be simulated using `ghdl`. Any IP that comes with a `/sim/Makefile` can be simulated with `ghdl`.

Install `ghdl` to easily simulate modules that come with a testbench:

```
git clone https://github.com/ghdl/ghdl
cd ghdl
./configure
make
sudo make install
```

Once this is done, you can safely simulate a module that comes with a testbench by using *make* in its `sim` folder. For example:

```
cd $git/ip/adau1761/sim
make
```

2.2 Vivado - xsim

IPs that require Xilinx's dedicated functions, such as BRAM or FIFOs to buffer the input/output data, can only be simulated in Vivado.

To simulate those IPs on your side, either import the IP sources & dependencies and the testbench into Vivado, or use the `sim-project.tcl` if it is delivered with the IP.