

Integer Linear Programming: Introduction to Branch & Bound

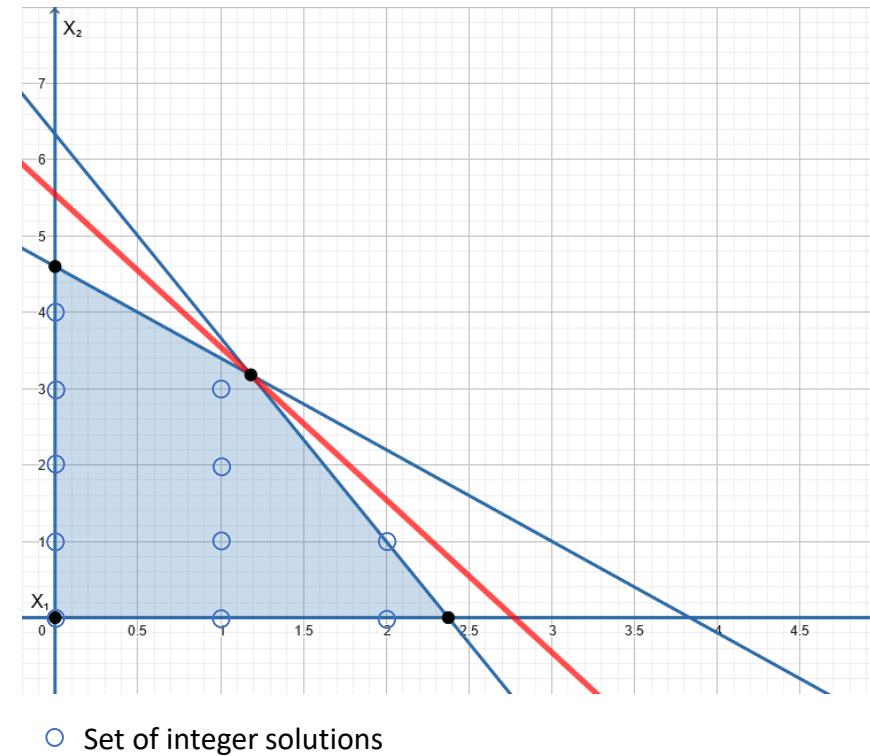
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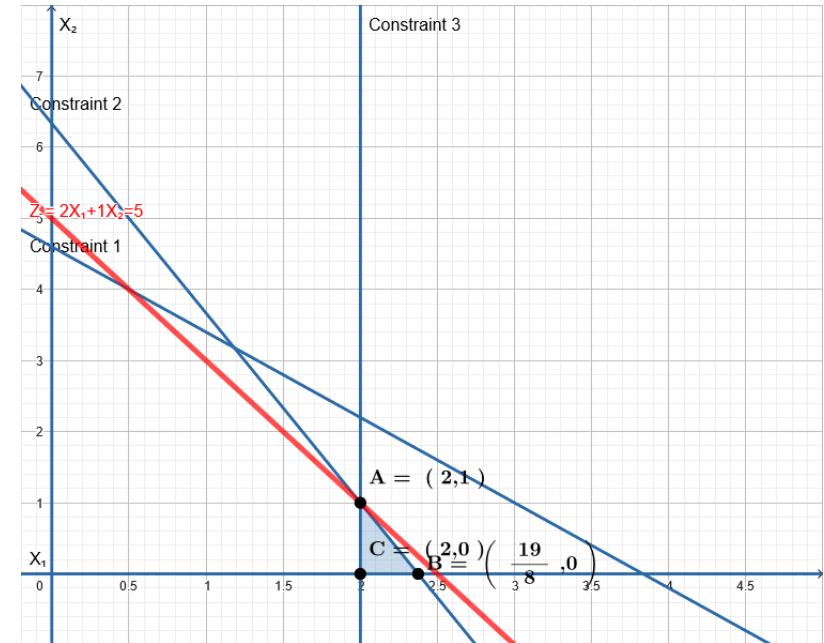
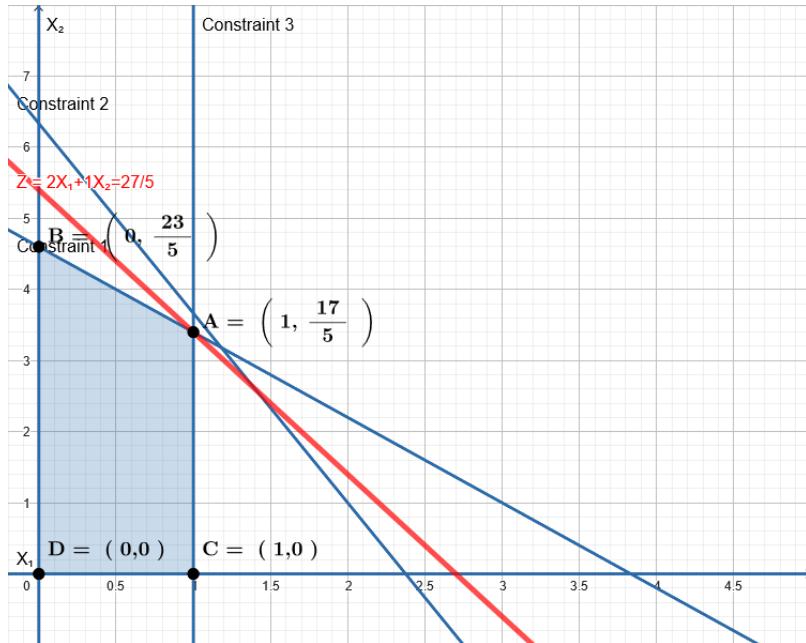
Example

maximize $z = 2x_1 + x_2$
subject to $6x_1 + 5x_2 \leq 23$
 $8x_1 + 3x_2 \leq 19$
 $x_1, x_2 \geq 0$
 $x_1, x_2 \in \mathbb{N}$

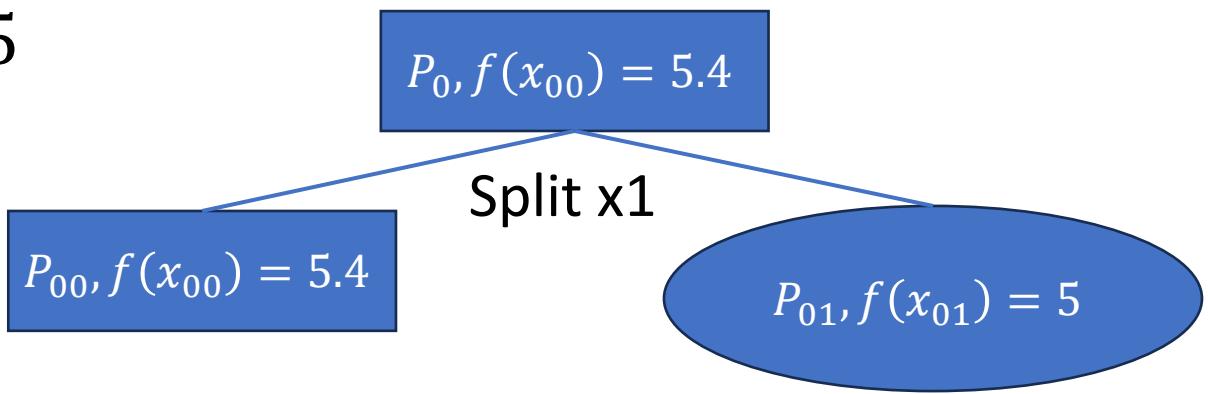


Divide step 1

- The best solution of P_0 is $X_1=1.182, X_2=3.182$.
- Divide P_0 according to variable x_1 . Solve graphically the subproblems P_{00} and P_{01} .



- $f(x^*) = 5$

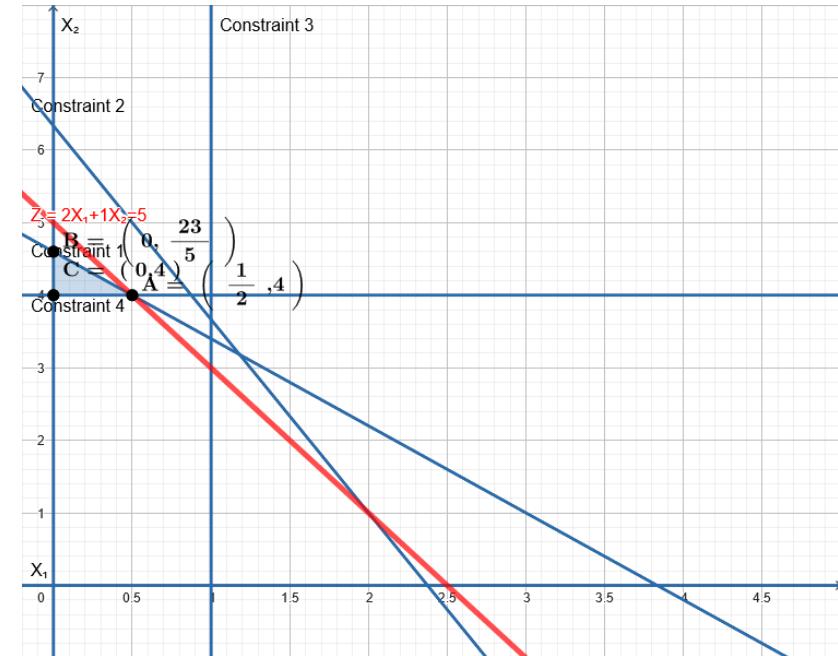
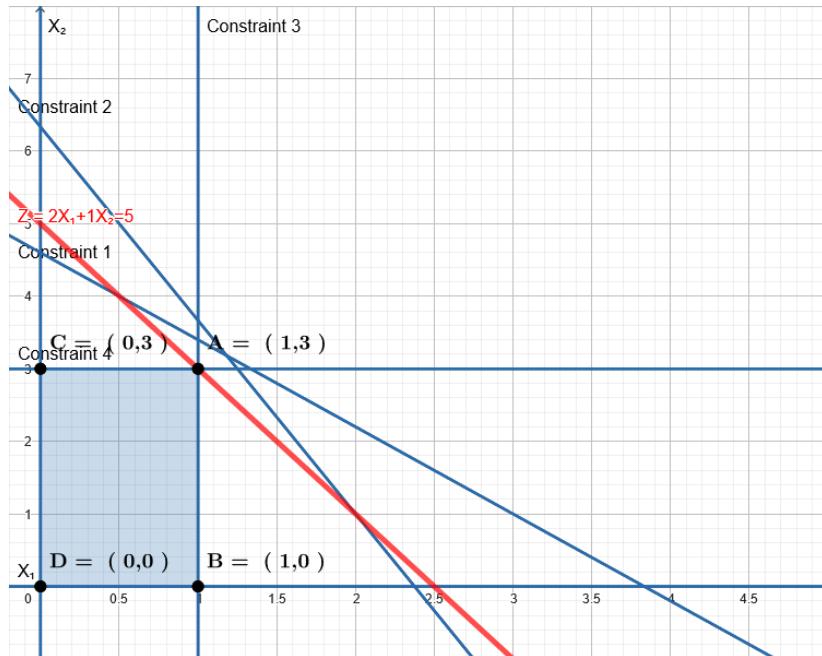


Non integer solution

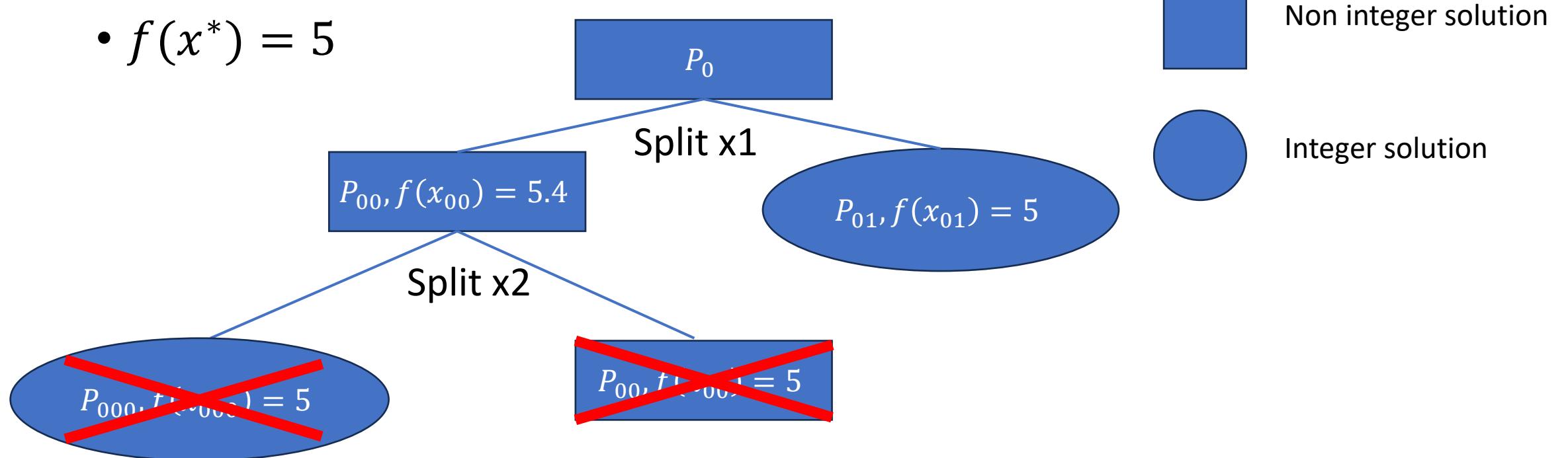
Integer solution

Divide step 2

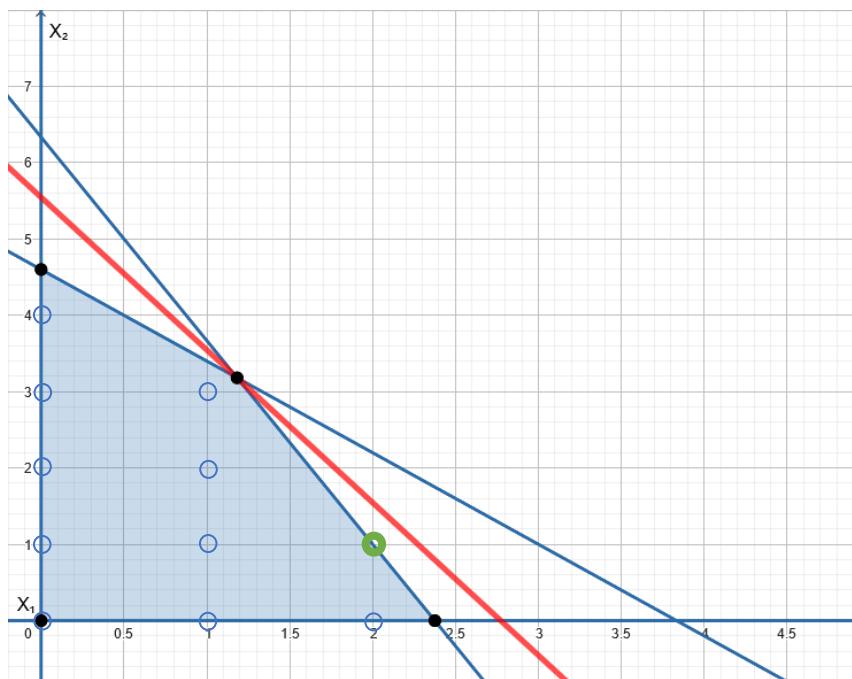
- The best solution of P_{00} is $x_1=1, x_2=3.4$
- Divide P_{00} according to variable x_2 . Solve graphically the subproblems P_{000} and P_{001} .



- $f(x^*) = 5$



Optimal solution graphically



○ Set of integer solutions

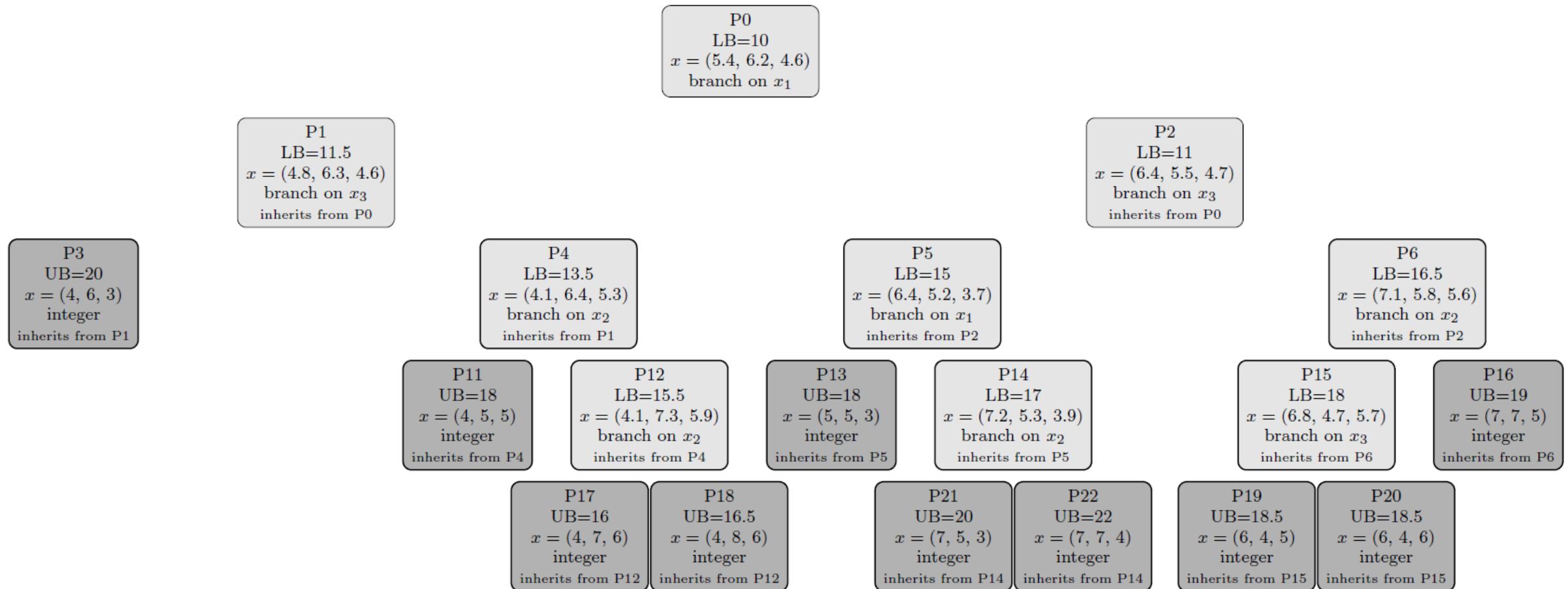
● One optimal solution

Going Deeper in Branch and Bound

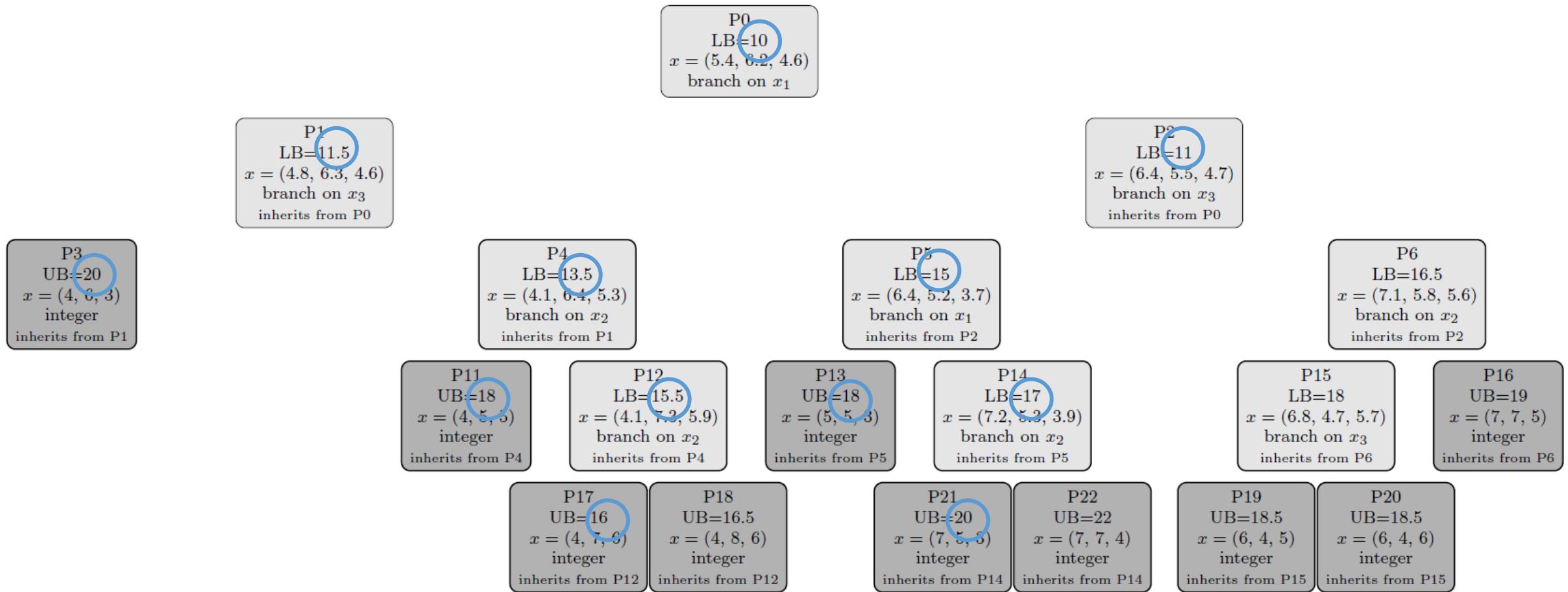
Different branching, searching strategies

From Constraint Integer Programming, Achterberg, PhD thesis, 2007[1]

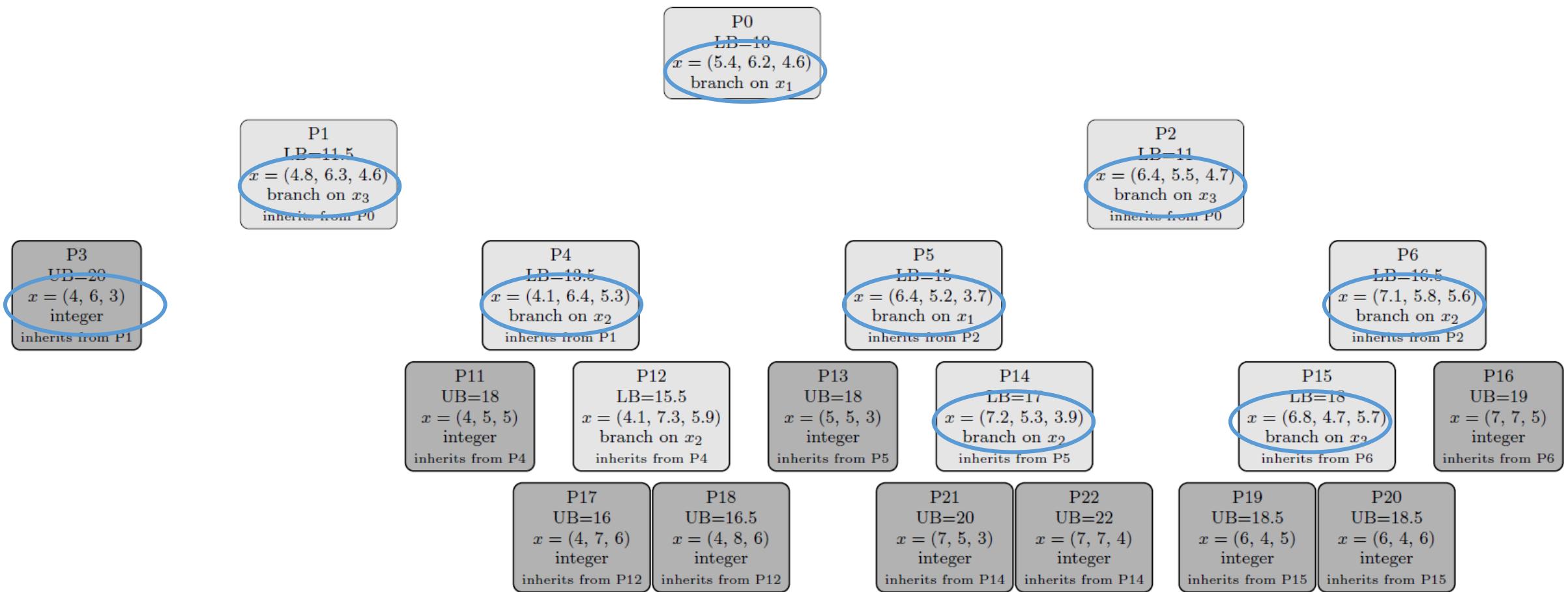
Recap about the B&B tree



Recap about the B&B tree



Recap about the B&B tree



Recap about the B&B tree

- Relaxed solutions (LB, UB) always get bigger from a parent to a child in minimization problem : → less solutions so poorer solutions
- When you branch on a variable, the children will respect for sure $x_i^k \leq \lfloor x_i^k \rfloor$ and $\lfloor x_i^k \rfloor \leq x_i^k$
 - If solution is integer, then the subproblem is solved

Branching

Branching Strategies

Answer the question: which variable to select to split one problem into 2 subproblems?

- The objective is to have the highest lower bound on both side of a child= the best approximation of optimal solution of the subproblem
→good approximation = good pruning possibilities.

In [1], show that a random branching can lead to ~+200% of solving time compared to a tuned one.

Branching Strategies: most infeasible

Consider a subproblem P^k , non integer solution x^k , $I^k = \{i \in [1, n] \mid x_i^k \notin \mathbb{N}\}$

For one solution candidate x_i^k , its fractional parts are $f_{i-}^k = x_i^k - \lfloor x_i^k \rfloor$ and $f_{i+}^k = \lfloor x_i^k \rfloor - x_i^k$

- Known one: variable the closest to 0.5: $\max_{i \in I^k}(\min(f_{i-}^k, f_{i+}^k))$

→ in practice not used because not significantly better than random.

Branching Strategies: strong branching

Consider a subproblem P^k , non integer solution x^k , $I^k = \{i \in [1, n] \mid x_i^k \notin \mathbb{N}\}$.

The trick: doing the branching for each variable, and compare the increasing in the lower bound → tighter lower bound for a same optimal solution
→ better chance of pruning

For $i \in I^k$, P^k leads to P_{i-}^k and P_{i+}^k , with improvement of the LB being Δ_{i-}^k for P_{i-}^k and Δ_{i+}^k for P_{i+}^k . We want the variable that maximizes the increase of lower bound

One way is:

$$\max_{i \in I^k} (\Delta_{i-}^k \times \Delta_{i+}^k)$$

Drawback: doing the branching for each candidate then computing the LB is really expensive

Branching Strategies: Pseudo Cost

Consider a subproblem P^k , non integer solution x^k , $I^k = \{i \in [1, n] \mid x_i^k \notin \mathbb{N}\}$

The trick: instead of computing the improvement of the lower bound for each case, just use experience and approximate it!

Consider for one variable x_i , and μ_i being the number of time it has been used for branching already in other parts of the tree, each time P^l to P_{i-}^l being Δ_{i-}^l and Δ_{i+}^l for P_{i+}^l ; from this experience, $\frac{\Delta_i^l}{f_i^l}$ the LB gain per fractional part. The mean increasing of LB per fractional is $\varphi_{i-} = \frac{\sum \frac{\Delta_{i-}^l}{f_{i-}^l}}{\mu_i}$ and $\varphi_{i+} = \frac{\sum \frac{\Delta_{i+}^l}{f_{i+}^l}}{\mu_i}$.

- Then the pseudo cost for one variable candidate x_i is

$$\varphi_{i-} \times f_{i-}^k \times \varphi_{i+} \times f_{i+}^k$$

We then choose the variable that maximizes the pseudo cost.

→ no need for extra computations: more lightweight

Branching Strategies: hybrid

- Pseudo cost is a good approximation, but can't be used at the beginning
- Strong branching is expensive but the best choices to make + choices at the beginning of the solving are the most important
- → In modern solvers (like SCIP open source solver), hybrid approach:
 - Use strong branching when the depth is lower than 10
 - Else, use pseudo-cost

It exists many other fine tuning for quantifying the quality of a variable for branching....

Searching

Search strategy

Answer the question: according to a set of unsolved subproblems, which one to solve the first?

The objective is to explore the node (or subproblem) that leads to the best solution.

2 components:

- Node comparing method: how to quantify the quality of a node
- Node selection method: which node will be explored in the end

Search Strategy: LB node comparing

- The objective is to rank open subproblems of the tree search. Usually, a score is given to all node, to then define the ranking.
- Lower Bound(LB): the lower bound on the node can be an estimation of how will be the integer solution of the subproblem: $e_{LB}(P^k) = f(x^k)$

Search Strategy: BP node comparing

- The objective is to rank open subproblems of the tree search. Usually, a score is given to all node, to then define the ranking.
- Best projection (BP): consider $\phi(x^k) = \sum_{i=1}^n \min(f_{i-}^k, f_{i+}^k)$ the distance to the closest integer solution.

$$e_{BP} = f(x^k) + \frac{(f(x^*) - f(x^0))}{\phi(x^0)} \phi(x^k)$$

increase of the score per
fractional unit

Search Strategy: BE node comparing

- The objective is to rank open subproblems of the tree search. Usually, a score is given to all node, to then define the ranking.
- Best Estimate (BE): use the estimator of increasing of the LB according to the experience $\varphi_{i-} - \varphi_{i+}$.

$$e_{BE} = f(x^k) + \sum_i \min(\varphi_{i-} f_{i-}^k, \varphi_{i+} f_{i+}^k)$$

Search Strategy: node selection

There is a total ranking of all the open nodes. Which one to select the first:

- **Best First Search (BFS)**: select the best one

→advantage: if the ranking is accurate, the best choice is the best node

- **Dept First Search (DFS)**: according to the node explored, select the best child; if children are completed, get the closest ancestor.

→advantage: DFS is the fastest way to have one feasible solution

+in practice, the search tree can be big (exponential), and DFS allow to minimize the number of open nodes

Search Strategy: node selection

- Hybrid version
 - As long as the children are unprocessed, do DFS. When you reach integer solutions, you select the next node by BFS, and then from that node on, you do again DFS.
 - →plunging to integer solution but do not get stuck in part of the tree
- Condition can be given to stop the DFS even before finding a good solution: if the score is too far from the best score, then switch again to BFS.

Exercices

University of Luxembourg

Merci | Thank you | Danke

