

Project #2(Pjt02_uart_busy) step1

Simple /IO through UART0 device UART0 device driver with Dumb Waiting

```
#include <avr/io.h>
#include <compat/deprecated.h>
#include <util/delay.h>
```

```
void uart_init()
{
    UBRROH = 0x00; UBRROL = 0x07; // 115.2Kbps
    sbi(UCSROA, U2X0);           // 115.2Kbps
    sbi(UCSROB, TXEN0);           // TX enable
}
```

```
int uart_putchar(char ch)
{
    if (ch == '\n')
        uart_putchar('r');
    _delay_ms(100);
    UDRO = ch;
    return(1);
}
```

```
main()
{
    char c;
    for (c = 'A' ; c <= 'Z' ; c++)
        uart_putchar(c);
    uart_putchar('\n');
    while(1);
}
```

Project #2(Pjt02_uart_busy) step2

Simple /IO through UART0 device UART0 device driver with Dumb Waiting

```
#include <avr/io.h>
#include <compat/deprecated.h>
#include <util/delay.h>

void uart_init()
{
    UBRROH = 0x00; UBRROL = 0x07; // 115.2Kbps
    sbi(UCSROA, U2X0);           // 115.2Kbps
    sbi(UCSROB, TXEN0);          // TX enable
}
```

```
int uart_putchar(char ch)
{
    if (ch == '\n')
        uart_putchar('\r');
    _delay_ms(100);
    UDR0 = ch;
    return(1);
}
```

```
int uart_putstr(char *sp)
{
    for ( ; *sp; sp++)
        uart_putchar(*sp);
    return(1);
}
```

```
main()
{
    char c;
    for (c = 'A' ; c <= 'D' ; c++)
        uart_putchar(c);
    uart_putchar('\n');

    uart_putstr("ABCD\n");
    while(1);
}
```