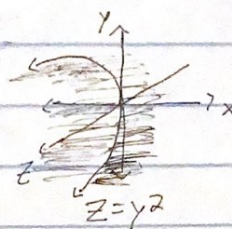
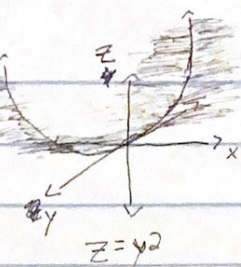
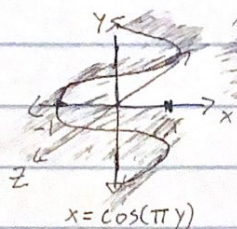
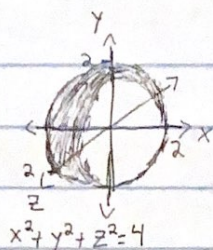


P5. (a)



$x = \cos(\pi y)$ is satisfied for any z -value, while $z = y^2$ is satisfied for any x -value. Thus, we combine them into $x = \cos(\pi\sqrt{z})$ (note: even though $\pm\sqrt{z} = y$, we can ignore $y = -\sqrt{z}$ for now because cosine is an even function and must simply remember that whenever we find a solution (x, y, z) we also have a solution at $(x, -y, z)$). Since $x^2 + y^2 + z^2 = 4$ is a sphere in \mathbb{R}^3 centered at the origin and since $x = \cos(\pi\sqrt{z})$ starts on the z -axis, moving only in the positive x -direction they must intersect once at some (x, y, z) .

Recalling the note above,

this means all three equations will be satisfied only at (x, y, z) and at $(x, -y, z)$. Both solutions will be inside the closed box $-1 \leq x \leq 1, -2 \leq y \leq 2, 0 \leq z \leq 2$ because $-2 \leq x, y, z \leq 2$ since the radius of the sphere is 2 and centered at the origin. Since $z = y^2$, z is positive, so $0 \leq z \leq 2$. Since $-2 \leq y \leq 2$ and $x = \cos(\pi y)$, $\cos(-\pi) \leq x \leq \cos(\pi)$, $-1 \leq x \leq 1$, as desired. ■

$$(b) \underbrace{\begin{bmatrix} 2(-1) & 2(1) & 2(1) \\ 1 & \pi \sin(\pi) & 0 \\ 0 & 2(1) & -1 \end{bmatrix}}_{J(x_0)} \underbrace{\begin{bmatrix} s_1 \\ s_2 \\ s_3 \end{bmatrix}}_S = - \underbrace{\begin{bmatrix} -1+1+1-4 \\ -1-\cos(-\pi) \\ 1-1 \end{bmatrix}}_{-1f(x_0)} \quad x_0 = (-1, 1, 1)$$

```
function sol=myeq(x)
sol(1)=x(1)^2+x(2)^2+(x(3)^2)-4;
sol(2)=x(1)-cos(pi*x(2));
sol(3)=x(2)^2-x(3);
sol=sol';
```

```
function j=myj(x)
j=[2*x(1) 2*x(2) 2*x(3);1 pi*sin(pi*x(2)) 0;0 2*x(2) -1];
```

```
function mynewton(x)
format long
for ii=(1:5)

    f=myeq(x);
    jac=myj(x);

    s=jac\f;
    x=x-s';
end
f
x
```

```
>> x=[-1 1 1]
```

```
x =
```

```
    -1     1     1
```

```
>> mynewton(x)
```

```
f =
```

```
    1.0e-08 *
```

```
    0.284940071537676
```

```
   -0.062497951258678
```

```
    0.014789236502111
```

```
x =
```

```
   -0.856360744261663    1.172720052019146    1.375272320407788
```

```
>> x=[-1,-1,1]
```

```
x =
```

```
    -1    -1     1
```

```
>> mynewton(x)
```

```
f =
```

```
    1.0e-08 *
```

```
    0.284940071537676
```

```
   -0.062497951258678
```

```
    0.014789236502111
```

```
x =
```

```
   -0.856360744261663   -1.172720052019146    1.375272320407788
```

```
>>
```


P5 (d) Notice, $J(x) = \frac{df}{dx} = f'(x)$. Therefore, (1) turns into:

$$f'(x)s = -f(x_n)$$

$$s = \frac{-f(x_n)}{f'(x_n)}$$

Plugging into (2) yields: $x_{n+1} = x_n - \frac{f(x_n)}{f'(x_n)}$

$$\begin{aligned}
 \text{P6(a)} \quad \det \begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{pmatrix} &= 1 \begin{vmatrix} 5 & 6 \\ 8 & 9 \end{vmatrix} - 2 \begin{vmatrix} 4 & 6 \\ 7 & 9 \end{vmatrix} + 3 \begin{vmatrix} 4 & 5 \\ 7 & 8 \end{vmatrix} \\
 &= 1(45 - 48) - 2(36 - 42) + 3(32 - 35) \\
 &= 0
 \end{aligned}$$

- (b) 3×3 is $(2 \cdot 3 + 3)$ multiplications
 4×4 is $4(2 \cdot 3 + 3) + 4$ multiplications
 5×5 is $5(4(2 \cdot 3 + 3) + 4) + 5$ multiplications
 \vdots

Pattern is $m + m(m-1) + m(m-1)(m-2) + \dots + m!$

So, $\sum_{i=1}^{m-1} \frac{m!}{i!}$ is # of multiplications to compute $\det(A)$ by expansion in minors ($A \in \mathbb{C}^{m \times m}$).

- (c) Suppose A is a diagonal matrix.

When A is 3×3 , $\det(A) = a_{11} a_{22} a_{33}$.

When A is $\mathbb{C}^{m \times m}$, $\det(A) = a_{11} a_{22} a_{33} \dots a_{mm}$.

Thus, $\det(A) = \prod_{i=1}^m a_{ii}$ and $A^{-1} = \frac{1}{\prod_{i=1}^m a_{ii}} A^*$ ($\det(A) \neq 0$).

```
function detchecker(~)
format long
n=10;
detA=[];
detB=[];
for i=1:n
    A = rand(10,10);
    d = diag(A);

    if (max(d, [], 'all')/min(d, [], 'all'))<10    %well conditioned
        detA(i)=prod(d);
    else    %not well conditioned
        detB(i)=prod(d);
    end
end
detA
detB

%both are small
```



```
>> detchecker
```

```
detA =
```

```
Columns 1 through 6
```

```
0.000050322789348      0      0      0.005524035757532 ✓  
0  0.001394211470358
```

```
Columns 7 through 10
```

```
0.007142256188470      0      0      0.002008324794775
```

```
detB =
```

```
1.0e-03 *
```

```
Columns 1 through 6
```

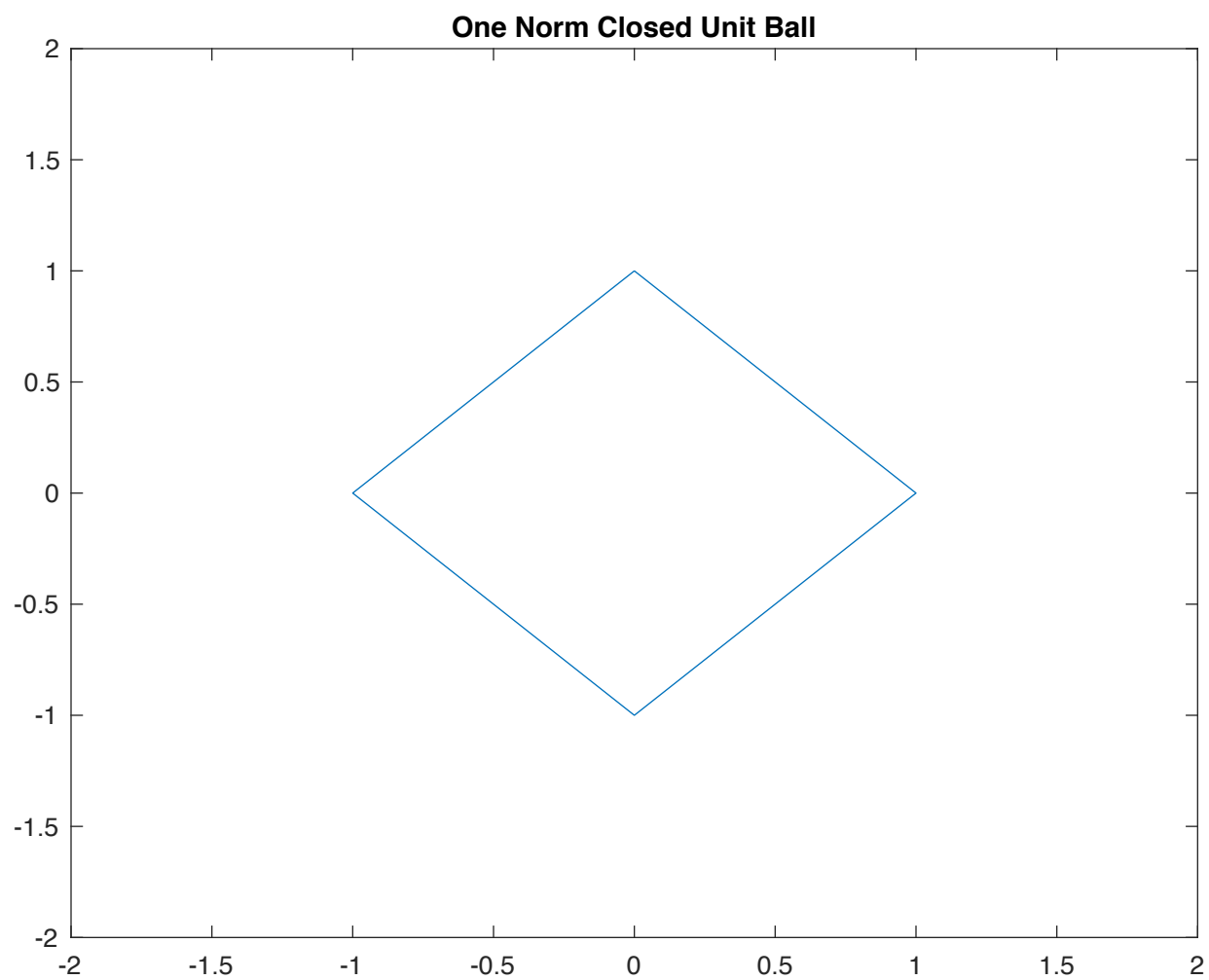
```
0  0.196077060646668      0.014910904085730      0 ✓  
0.093568754356011      0
```

```
Columns 7 through 9
```

```
0  0.000652621027165      0.015980434733288
```

```
>>
```

```
x=pi/4;  
y=x+pi/2;  
z=y+pi/2;  
m=z+pi/2;  
t=[x y z m x];  
a=cos(t+pi/4);  
b=sin(t+pi/4);  
plot(a,b)  
xlim([-2 2])  
ylim([-2 2])  
title('One Norm Closed Unit Ball')
```

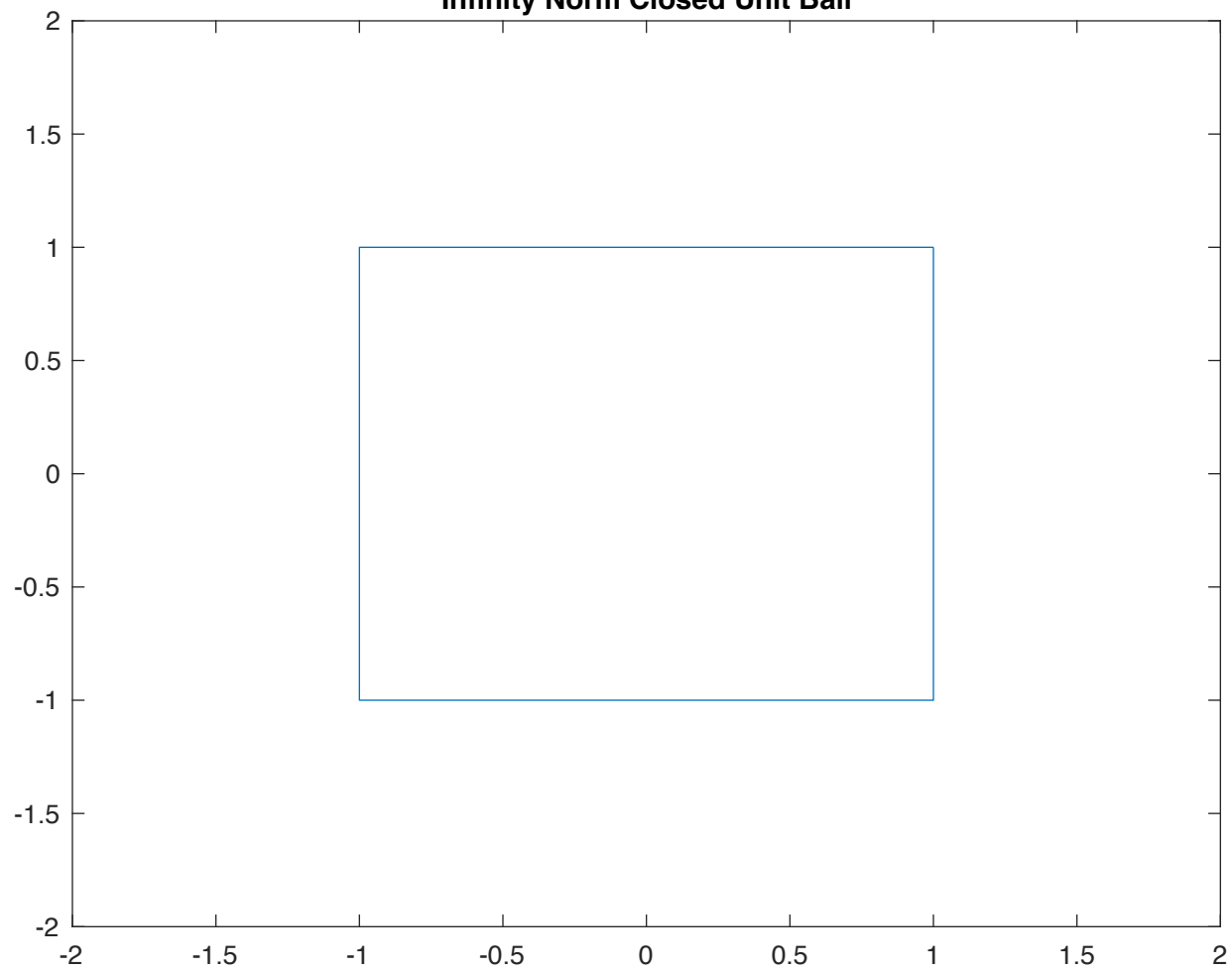


```
fimplicit(@(x,y)x.^2+y.^2-1)
title('Two Norm Closed Unit Ball')
```

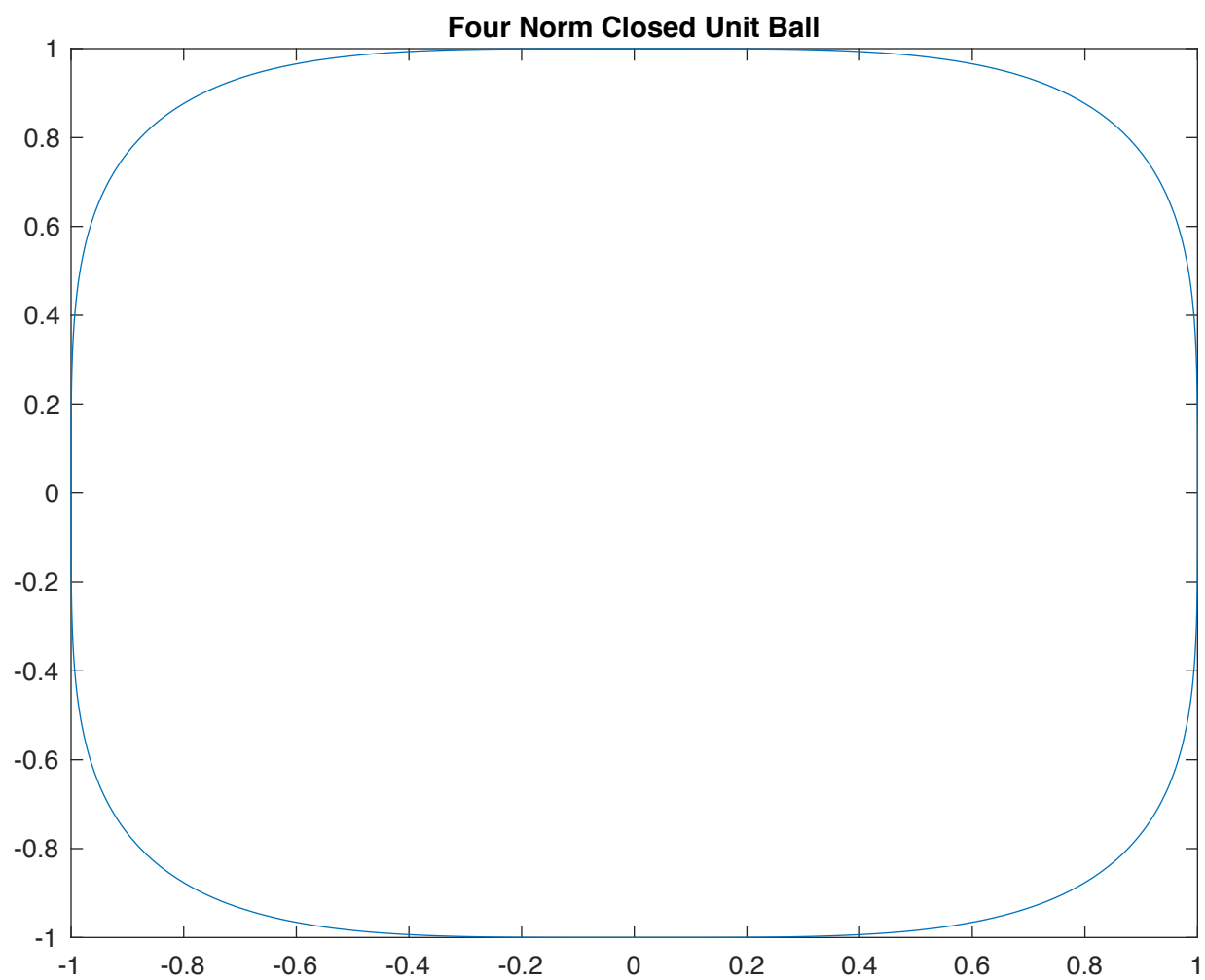



```
x=pi/4;  
y=x+pi/2;  
z=y+pi/2;  
m=z+pi/2;  
t=[x y z m x];  
a=(2/sqrt(2))*cos(t);  
b=(2/sqrt(2))*sin(t);  
plot(a,b)  
xlim([-2 2])  
ylim([-2 2])  
title('Infinity Norm Closed Unit Ball')
```

Infinity Norm Closed Unit Ball



```
fimplicit(@(x,y)x.^4+y.^4-1)
title('Four Norm Closed Unit Ball')
```

Hypothesis: If A is both triangular and unitary, A is diagonal.

Exercise 2.1, pf: WLOG, assume $A \in \mathbb{C}^{m \times m}$ is upper triangular,
(Lecture 2)

$$A = \begin{bmatrix} a_{11} & \dots & a_{1m} \\ 0 & \ddots & \vdots \\ 0 & 0 & a_{mm} \end{bmatrix}; A^* = \begin{bmatrix} a_{11}^* & 0 & 0 \\ \vdots & \ddots & 0 \\ a_{1m}^* & \dots & a_{mm}^* \end{bmatrix}$$

$$A^*A = \begin{bmatrix} a_{11}^* & 0 & 0 \\ \vdots & \ddots & 0 \\ a_{1m}^* & \dots & a_{mm}^* \end{bmatrix} \begin{bmatrix} a_{11} & \dots & a_{1m} \\ 0 & \ddots & \vdots \\ 0 & 0 & a_{mm} \end{bmatrix} = \begin{bmatrix} 1 & \dots & \\ & \ddots & \\ & & 1 \end{bmatrix} = I_{m \times m}$$

since A is unitary

If there existed $a_{ij} \neq 0$, $i \neq j$, then A^*A would contain a_{ij}^2 not on the diagonal. This is a contradiction because $A^*A = I_{m \times m}$. Thus, A is diagonal. ■

Exercise 2.3(a) Hypothesis: Let $A \in \mathbb{C}^{m \times m}$ be hermitian. All eigenvalues of A are real.

pf: For eigenvectors of A , we have a nonzero vector $v \in \mathbb{C}^m$ such that $Av = \lambda v$ for some $\lambda \in \mathbb{C}$. We have:

$$\begin{aligned} (Av)^* &= (\lambda v)^* \\ v^* A^* &= \lambda^* v^* \\ v^* A &= \lambda^* v^* && \text{Since } A \text{ is hermitian, } A^* = A. \\ v^* Av &= \lambda^* v^* v \\ \lambda v^* v - \lambda^* v^* v &= 0 \\ \lambda &= \lambda^* \end{aligned}$$

Hence, λ must be real. ■

Exercise 23(b) Hypothesis: If x and y are eigenvectors corresponding to distinct eigenvalues, then x and y are orthogonal.

pf. We have $Ax = \lambda_x x$ and $Ay = \lambda_y y$.

Observe:

$$(Ay)^* = (\lambda_y y)^*$$

$$y^* A^* = \lambda_y y^*$$

$$y^* A^* x = \lambda_y y^* x$$

$$y^* Ax = \lambda_y y^* x$$

$$y^* \lambda_x x = \lambda_y y^* x$$

$$\lambda_x y^* x - \lambda_y y^* x = 0$$

$$y^* x (\lambda_x - \lambda_y) = 0$$

$$y^* x = 0$$

$$\lambda_y = \lambda_y^* \text{ b/c part (a)}$$

$$A = A^* \text{ b/c } A \text{ is Hermitian}$$

$$\text{since } \lambda_x \neq \lambda_y \quad \blacksquare$$