

1. The equation of the undamped oscillation :

$$m \frac{d^2x}{dt^2} + kx = 0$$

At $t = 0$ we have $x = 0$ and at this moment as the mass is in equilibrium, the velocity $\frac{dx}{dt} = 0$. Now with this initial conditions we apply a constant force F . The new EOM is

$$m \frac{d^2x}{dt^2} + kx = F$$

Solving this we can get the path of the particle

$$x(t) = \frac{F}{k} + A \cos \omega_0 t + B \sin \omega_0 t$$

, where A and B are constant with time and $\omega_0 = \sqrt{k/m}$ is the fundamental frequency of the undamped oscillator.

Using the above initial conditions, $A = -\frac{F}{k}$ and $B = 0$. So,

$$x(t) = \frac{F}{k} (1 - \cos \omega_0 t) = \frac{2F}{k} \sin^2 \frac{\omega_0 t}{2}$$

So At $t = \tau$ the position and velocity of the particle are $x(\tau) = \frac{2F}{k} \sin^2 \frac{\omega_0 \tau}{2}$ and $\dot{x}(\tau) = \frac{2F\omega_0}{k} \sin \frac{\omega_0 \tau}{2} \cos \frac{\omega_0 \tau}{2}$.

After $t = \tau$, In absense of the external force, the eom $m \frac{d^2x}{dt^2} + kx = 0$ with the solution $x(t) = a \cos \omega(t - \tau) + b \sin \omega(t - \tau)$. Now at $t = \tau$ the state of the paricle is already obtained, using that, we can find $a = \frac{2F}{k} \sin^2 \frac{\omega_0 \tau}{2}$ and $b = \frac{2F}{k} \sin \frac{\omega_0 \tau}{2} \cos \frac{\omega_0 \tau}{2}$. So the amplitude of the oscillation

$$\text{Amp} = \sqrt{a^2 + b^2} = \frac{2F}{k} \left| \sin \frac{\omega_0 \tau}{2} \right|$$

2. The eom of the undamped forced oscillation

$$\ddot{x}(t) + \omega_0^2 x(t) = f \cos \omega t$$

with the initial conditions $x(t = 0) = \dot{x}(t = 0) = 0$. The total solution of this differential equation $x = x_h + x_p$. The homogeneous solution (without the force) $x_h = A \cos \omega_0 t + B \sin \omega_0 t$. The particular solution $x_p = \frac{f}{\omega_0^2 - \omega^2} \cos \omega t$. So the total solution

$$x = A \cos \omega_0 t + B \sin \omega_0 t + \frac{f}{\omega_0^2 - \omega^2} \cos \omega t$$

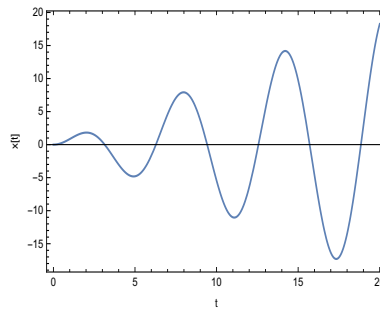
Using the initial condition, $A = -\frac{f}{\omega_0^2 - \omega^2}$ and $B = 0$.

$$x(t) = \frac{f}{\omega_0^2 - \omega^2} (\cos \omega t - \cos \omega_0 t)$$

Near the resonance ($\omega = \omega_0$), we take $\omega = \omega_0 - \Delta\omega$

$$\begin{aligned}
 x(t) &= \frac{f}{\omega_0^2 - \omega^2} (\cos \omega t - \cos \omega_0 t) \\
 &= \frac{f}{\omega_0^2 - (\omega_0 - \Delta\omega)^2} (\cos((\omega_0 - \Delta\omega)t) - \cos \omega_0 t) \\
 &= \frac{f}{\omega_0^2 - \omega_0^2 + 2\omega_0 \Delta\omega} (\cos \omega_0 t + t \Delta\omega \sin \omega_0 t - \cos \omega_0 t) \\
 &= \frac{f}{2\omega_0} t \sin \omega_0 t
 \end{aligned} \tag{1}$$

To plot this amplitude near the resonance, we take $f/2 = \omega_0 = 1$.



3. Using the equation for amplitude in the case of a damped oscillator with a driven force $F(t) = F_0 \cos \omega t$

$$a = \frac{F_0}{m \sqrt{(\omega_0^2 - \omega^2)^2 + 4\beta^2 \omega^2}} \tag{2}$$

Given $F(t) = 10 \cos \omega t$ Where, $F_0 = 10$, $\omega_0 \approx 1\text{MHz}$ and quality factor, $Q = 1100$
Using these values $\beta = \frac{\omega_0}{2Q} = 454.5$

(a) To find the spring constant we take $\omega = 1\text{KHz}$, where $\omega_0 \gg \omega$ and $a = 8.26\text{mm}$.
Using low frequency limit in (2)

$$a = \frac{F_0}{m\omega_0^2} = \frac{F_0}{k}$$

this gives the spring constant $k = 1210.65\text{N/m}$.

(b) Take $\omega = 100\text{MHz}$, so $\omega_0 \ll \omega$ and $a = 1\mu\text{m}$. Here we take high frequency limit

$$a = \frac{F_0}{m\omega^2}$$

this gives mass $m = 10^{-9}\text{Kg}$.

Note $\omega_0 = \sqrt{k/m} = 1.1\text{MHz}$ which is closed to the resonant frequency.

(c) $\text{FWHM} = 2\beta = \frac{\omega_0}{Q} = 1000\text{Hz}$

(d) The phase difference between the force and the oscillation at $\omega = \omega_0 + \frac{\text{FWHM}}{2} = 1100.5\text{KHz}$ is

$$\phi = \tan^{-1} \frac{-2\beta\omega}{(\omega_0^2 - \omega^2)} = 42.2^\circ$$

4. In this system the solutions are

$$x_0(t) = a_0 \cos \frac{\omega_0 + \omega}{2} t \cos \frac{\omega_0 - \omega}{2} t = \frac{a_0}{2} (\cos \omega t + \cos \omega_0 t)$$

and

$$x_1(t) = a_0 \sin \frac{\omega_0 + \omega}{2} t \sin \frac{\omega_0 - \omega}{2} t = \frac{a_0}{2} (\cos \omega t - \cos \omega_0 t)$$

, where $a_0 = 40\text{cm}$. The frequency modes are $\omega_0 = \sqrt{k/m} = \sqrt{10} = 3.162\text{per sec}$ and $\omega = \sqrt{(k + 2k')/m} = \sqrt{70} = 8.366\text{per sec}$.

(a) the faster normal mode's frequency is 8.366Sec^{-1} .

(b)

$$\dot{x}_1(t) = -\frac{a_0}{2} (\omega \sin \omega t - \omega_0 \sin \omega_0 t)$$

The kinetic energy at time t

$$KE(t) = \frac{1}{2} m \dot{x}_1^2 = m \frac{a_0^2}{8} (\omega_0^2 \sin^2 \omega_0 t + \omega^2 \sin^2 \omega t - \omega_0 \omega \cos(\omega + \omega_0)t + \omega_0 \omega \cos(\omega_0 - \omega)t)$$

Now, $\langle \sin^2 \theta \rangle = \frac{1}{2}$ and $\langle \cos \theta \rangle = 0$. So average kinetic energy is

$$\langle KE(t) \rangle = m \frac{a_0^2}{16} (\omega^2 + \omega_0^2) = m \frac{a_0^2}{16} \left(\frac{k}{m} + \frac{k + 2k'}{m} \right) = \frac{a_0^2}{8} (k + k') = 0.8\text{Joule}$$

(c) As ω_0^2 and ω^2 are proportional to $1/m$, the kinetic energy does not depends on m , mass of the particle.

5. From the previous problem,

$$x_A(t) = x_0 \cos \frac{\omega_0 + \omega}{2} t \cos \frac{\omega_0 - \omega}{2} t$$

and

$$x_B(t) = a_0 \sin \frac{\omega_0 + \omega}{2} t \sin \frac{\omega_0 - \omega}{2} t$$

Here the mass A is pulled by small distance x_0 and released from rest, whereas the B is released from the rest at its equilibrium position. Now $\omega_0 = \sqrt{k_A/m}$ and $\omega = \sqrt{(k_A + 2k_{middle})/m}$. $k_{middle} = k_A/100 = \eta k_A$ [$\eta = 0.01$]. So,

$$\omega = \omega_0 \sqrt{1 + 2\eta} \approx \omega_0 (1 + \eta)$$

The solutions can be approximated as

$$x_A(t) = x_0 \cos \frac{\eta \omega_0}{2} t \cos \omega_0 t$$

and

$$x_B(t) = -a_0 \sin \frac{\eta \omega_0}{2} t \sin \omega_0 t$$

So two mass interchange the state of oscillation with an angular frequency $\eta \omega_0/2$, therefore lifetime of each state is $T_L = \frac{2\pi}{\eta \omega_0}$. In this state the mass oscillates with an angular frequency ω_0 , i.e. frequency $\frac{\omega_0}{2\pi}$

Here we are starting A from a maxima, so for its first die down required time is $T_L/2 = \frac{\pi}{\eta \omega_0}$. During this state the total number of oscillations completed by the mass A is $\frac{\omega_0}{2\pi} \times \frac{\pi}{\eta \omega_0} = \frac{1}{2\eta} = 50$