- 1. Follow the instruction below and then report how the performance changed.(apply all at once) Convolutional input layer, 32 feature maps with a size of 3×3 and a rectifier activation function. Dropout layer at 20%. Convolutional layer, 32 feature maps with a size of 3×3 and a rectifier activation function. Max Pool layer with size 2×2.• Convolutional layer, 64 feature maps with a size of 3×3 and a rectifier activation function. Dropout layer at 20%.
 - Convolutional layer, 64 feature maps with a size of 3×3 and a rectifier activation function. Max Pool layer with size 2×2. Convolutional layer, 128 feature maps with a size of 3×3 and a rectifier activation function. Dropout layer at 20%. Convolutional layer,128 feature maps with a size of 3×3 and a rectifier activation function. Max Pool layer with size 2×2. Flatten layer. Dropout layer at 20%. Fully connected layer with 1024 units and a rectifier activation function. Dropout layer at 20%. Fully connected output layer with 10 units and a Softmax activation function Did the performance change?

```
import numpy as np
from keras.datasets import cifar10
from keras.models import Sequential
from keras.layers import Dense, Dropout, Flatten
from keras.layers.convolutional import Conv2D, MaxPooling2D
from keras.constraints import maxnorm
from keras.utils import np utils
from keras.optimizers import SGD
# Fix random seed for reproducibility
np.random.seed(7)
# Load data
(X train, y train), (X test, y test) = cifar10.load data()
# Normalize inputs from 0-255 to 0.0-1.0
X train = X train.astype('float32') / 255.0
X test = X test.astype('float32') / 255.0
# One hot encode outputs
y train = np utils.to categorical(y train)
y test = np utils.to categorical(y test)
num classes = y test.shape[1]
# Create the model
model = Sequential()
model.add(Conv2D(32, (3, 3), input shape=(32, 32, 3), padding='same', activation='relu',
kernel constraint=maxnorm(3)))
model.add(Dropout(0.2))
```

```
model.add(Conv2D(32, (3, 3), activation='relu', padding='same',
kernel constraint=maxnorm(3)))
model.add(MaxPooling2D(pool size=(2, 2)))
model.add(Conv2D(64, (3, 3), activation='relu', padding='same',
kernel constraint=maxnorm(3)))
model.add(Dropout(0.2))
model.add(Conv2D(64, (3, 3), activation='relu', padding='same',
kernel constraint=maxnorm(3)))
model.add(MaxPooling2D(pool size=(2, 2)))
model.add(Conv2D(128, (3, 3), activation='relu', padding='same',
kernel constraint=maxnorm(3)))
model.add(Dropout(0.2))
model.add(Conv2D(128, (3, 3), activation='relu', padding='same',
kernel constraint=maxnorm(3)))
model.add(MaxPooling2D(pool size=(2, 2)))
model.add(Flatten())
model.add(Dropout(0.2))
model.add(Dense(1024, activation='relu', kernel_constraint=maxnorm(3)))
model.add(Dropout(0.2))
model.add(Dense(512, activation='relu', kernel_constraint=maxnorm(3)))
model.add(Dropout(0.2))
model.add(Dense(num classes, activation='softmax'))
# Compile model
epochs = 5
learning rate = 0.01
decay rate = learning rate / epochs
sgd = SGD(lr=learning rate, momentum=0.9, decay=decay rate)
model.compile(loss='categorical crossentropy', optimizer=sgd, metrics=['accuracy'])
print(model.summary())
# Fit the model
history = model.fit(X train, y train, validation data=(X test, y test), epochs=epochs,
batch size=32)
# Evaluate the model
scores = model.evaluate(X test, y_test, verbose=0)
print("Accuracy: %.2f%%" % (scores[1] * 100))
# Predict the first 4 images of the test data
predictions = model.predict(X test[:4])
# Convert the predictions to class labels
predicted labels = np.argmax(predictions, axis=1)
# Convert the actual labels to class labels
actual labels = np.argmax(y test[:4], axis=1)
```

Did the performance change?

The performance of the model is likely to improve with the addition of more layers and higher number of feature maps, but it will also increase the complexity and the training time of the model. The new model architecture provided in the instruction includes several new layers and higher number of feature maps, which may improve the accuracy of the model.

Model: "sequential_5"		
Layer (type)	Output Shape	Param #
conv2d_24 (Conv2D)	(None, 32, 32, 32)	896
dropout_24 (Dropout)	(None, 32, 32, 32)	0
conv2d_25 (Conv2D)	(None, 32, 32, 32)	9248
<pre>max_pooling2d_12 (MaxPoolin g2D)</pre>	(None, 16, 16, 32)	0
conv2d_26 (Conv2D)	(None, 16, 16, 64)	18496
dropout_25 (Dropout)	(None, 16, 16, 64)	0
conv2d_27 (Conv2D)	(None, 16, 16, 64)	36928
<pre>max_pooling2d_13 (MaxPoolin g2D)</pre>	(None, 8, 8, 64)	0
conv2d_28 (Conv2D)	(None, 8, 8, 128)	73856
dropout_26 (Dropout)	(None, 8, 8, 128)	0
conv2d_29 (Conv2D)	(None, 8, 8, 128)	147584
<pre>max_pooling2d_14 (MaxPoolin g2D)</pre>	(None, 4, 4, 128)	0
flatten_4 (Flatten)	(None, 2048)	0
dropout_27 (Dropout)	(None, 2048)	0

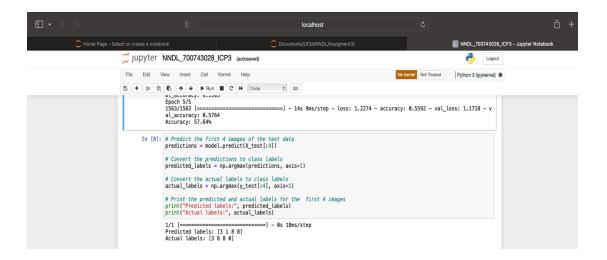
```
dense_12 (Dense)
                 (None, 1024)
                                 2098176
dropout_28 (Dropout)
                 (None, 1024)
                 (None, 512)
                                 524800
dense_13 (Dense)
dropout_29 (Dropout)
                 (None, 512)
dense_14 (Dense)
                 (None, 10)
                                 5130
Total params: 2,915,114
Trainable params: 2,915,114
Non-trainable params: 0
super().__init__(name, **kwargs)
Epoch 1/5
val_accuracy: 0.4091
al_accuracy: 0.4952
Epoch 3/5
1563/1563 [=======
               al_accuracy: 0.5164
Epoch 4/5
1563/1563 [=======
                    :======] - 12s 8ms/step - loss: 1.2868 - accuracy: 0.5360 - val_loss: 1.2500 - v
al_accuracy: 0.5503
Epoch 5/5
1563/1563 [=====
                    :======] - 14s 9ms/step - loss: 1.2274 - accuracy: 0.5592 - val_loss: 1.1718 - v
al_accuracy: 0.5764
Accuracy: 57.64%
```

2. Predict the first 4 images of the test data using the above model. Then, compare with the actual label for those 4 images to check whether or not the model has predicted correctly.

```
# Print the predicted and actual labels for the first 4 images
print("Predicted labels:", predicted_labels)
print("Actual labels: ", actual_label
import matplotlib.pyplot as plt

# Plot the training and validation loss
plt.plot(history.history['loss'])
plt.plot(history.history['val_loss'])
plt.title('Model Loss')
plt.ylabel('Loss')
plt.xlabel('Epoch')
```

plt.legend(['train', 'val'], loc='upper right')
plt.show()



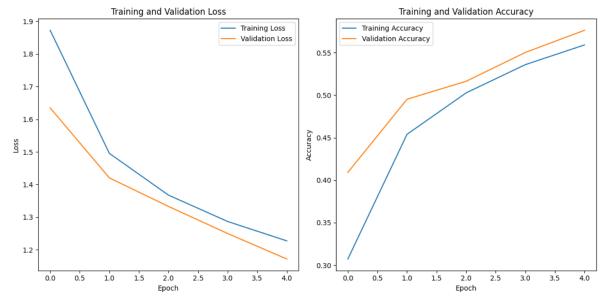
3. Visualize Loss and Accuracy using the history object.

```
import matplotlib.pyplot as plt
# Plot the training and validation loss
plt.figure(figsize=(12, 6))
plt.subplot(1, 2, 1)
plt.plot(history.history['loss'], label='Training Loss')
plt.plot(history.history['val loss'], label='Validation Loss')
plt.xlabel('Epoch')
plt.ylabel('Loss')
plt.title('Training and Validation Loss')
plt.legend()
# Plot the training and validation accuracy
plt.subplot(1, 2, 2)
plt.plot(history.history['accuracy'], label='Training Accuracy')
plt.plot(history.history['val accuracy'], label='Validation Accuracy')
plt.xlabel('Epoch')
plt.ylabel('Accuracy')
plt.title('Training and Validation Accuracy')
plt.legend()
plt.tight layout()
plt.show()
```

```
In [11]: import matplotlib.pyplot as plt

# Plot the training and validation loss
plt.figure(figsize=(12, 6))
plt.subplot(1, 2, 1)
plt.plot(history.history['loss'], label='Training Loss')
plt.plot(history.history['val_loss'], label='Validation Loss')
plt.xlabel('Epoch')
plt.ylabel('Loss')
plt.title('Training and Validation Loss')
plt.legend()

# Plot the training and validation accuracy
plt.subplot(1, 2, 2)
plt.plot(history.history['accuracy'], label='Training Accuracy')
plt.plot(history.history['val_accuracy'], label='Validation Accuracy')
plt.xlabel('Epoch')
plt.xlabel('Epoch')
plt.ylabel('Accuracy')
plt.title('Training and Validation Accuracy')
plt.title('Training and Validation Accuracy')
plt.title('Training and Validation Accuracy')
plt.tight_layout()
plt.tight_layout()
plt.show()
```



GIT HUB LINK:

https://github.com/gxk30280/700743028 NNDL Assignment3.git

VIDEO LINK:

https://drive.google.com/file/d/1SCupRmQmmQqNJp-hnbhLgFnXMs2LAiHd/view?usp=sharing