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Tutorial Solutions Booklet

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## 1 Tutorial 1 (on Lectures 1 and 2)

- 1.1 Let  $\mathbf{A}$  be a square matrix. Show that there is a symmetric matrix  $\mathbf{B}$  and there is a skew-symmetric matrix  $\mathbf{C}$  such that  $\mathbf{A} = \mathbf{B} + \mathbf{C}$ . Are  $\mathbf{B}$  and  $\mathbf{C}$  unique?

Given  $\mathbf{B}$  should be symmetric and  $\mathbf{C}$  should be skew-symmetric such that  $\boxed{\mathbf{A} = \mathbf{B} + \mathbf{C}}$ . Take transpose on both sides of this equation. This gives us  $\mathbf{A}^T = \mathbf{B}^T + \mathbf{C}^T \Rightarrow \boxed{\mathbf{A}^T = \mathbf{B} - \mathbf{C}}$ . Solve these two boxed equations simultaneously to get  $\mathbf{B} = \frac{\mathbf{A} + \mathbf{A}^T}{2}$  and  $\mathbf{C} = \frac{\mathbf{A} - \mathbf{A}^T}{2}$ . Thus we have  $\mathbf{A} = \mathbf{B} + \mathbf{C}$  and clearly,  $\mathbf{B}$  is symmetric and  $\mathbf{C}$  is skew-symmetric.  
**By our solution,  $\mathbf{B}$  and  $\mathbf{C}$  must be unique**

- 1.2 Let  $\mathbf{A} := \begin{bmatrix} 1 & 2 \\ 3 & 4 \\ 5 & 6 \end{bmatrix}$  and  $\mathbf{B} := \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix}$ . Write (i) the second row of  $\mathbf{AB}$  as a linear combination of the rows of  $\mathbf{B}$  and (ii) the second column of  $\mathbf{AB}$  as a linear combination of the columns of  $\mathbf{A}$ .

(i)  $\mathbf{AB}$  is a  $3 \times 3$  matrix. The elements of the second row of  $\mathbf{AB}$  are given by the expression:  $AB_{2,j} = \sum_{k=1}^2 A_{2,k}B_{k,j}$ . Thus, the second row can be written as the linear combination of rows of  $\mathbf{B}$  as follows:

$$3 \begin{bmatrix} 1 & 2 & 3 \end{bmatrix} + 4 \begin{bmatrix} 4 & 5 & 6 \end{bmatrix}$$

(ii) Similarly, the second column of  $\mathbf{AB}$  can be written as as the linear combination of columns of  $\mathbf{A}$  as follows:

$$2 \begin{bmatrix} 1 \\ 3 \\ 5 \end{bmatrix} + 5 \begin{bmatrix} 2 \\ 4 \\ 6 \end{bmatrix}$$

- 1.3 Let  $\mathbf{A} := \begin{bmatrix} 1 & 1 & 1 & 0 \\ -3 & -17 & 1 & 2 \\ 4 & -24 & 8 & -5 \\ 0 & -7 & 2 & 2 \end{bmatrix}$ . Assuming that  $\mathbf{A}$  is invertible, find the last column and the last row of  $\mathbf{A}^{-1}$ .

$\mathbf{AA}^{-1} = \mathbf{I}_4$ , Thus we have the following system of equations to get the last column of  $\mathbf{A}^{-1}$ :

$$\begin{bmatrix} 1 & 1 & 1 & 0 \\ -3 & -17 & 1 & 2 \\ 4 & -24 & 8 & -5 \\ 0 & -7 & 2 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix} \text{ Solve this to get the last column of } \mathbf{A}^{-1}$$

$$\text{We get: } \begin{bmatrix} x_1 & x_2 & x_3 & x_4 \end{bmatrix}^T = \begin{bmatrix} 2.75 & -0.5 & -2.25 & 1 \end{bmatrix}^T$$

Do a similar process to get the last row. Since we already know  $x_4$ , now we'll have to solve a system of only 3 equations and 3 unknowns. Last Row of  $\mathbf{A}^{-1} = \begin{bmatrix} -1.5 & -0.5 & 0 & 1 \end{bmatrix}$

- 1.4 Show that the product of two upper triangular matrices is upper triangular. Is this true for lower triangular matrices?

Assume  $\mathbf{A}$  and  $\mathbf{B}$  are two upper triangular matrices. For these upper triangular matrices,  $A_{ij}$  and  $B_{ij} = 0$  for  $i > j$ . We have to show that  $AB_{ij} = 0$  for  $i > j$  also holds true. We have  $AB_{ij} = A_i^T B_j$  where  $A_i^T$  is the  $i^{\text{th}}$  row of  $\mathbf{A}$  and  $B_j^T$  is the  $j^{\text{th}}$  column of  $\mathbf{B}$ .

$$\begin{aligned}\text{Thus, } AB_{i,j} &= A_i^T B_j = \sum_{k=1}^n A_{ik} B_{kj} \\ &= \sum_{k=1}^j A_{ik} B_{kj} + \sum_{k=j+1}^n A_{ik} B_{kj}\end{aligned}$$

Now given  $A, B$  are upper triangular. So  $A_{ij} = 0, B_{ij} = 0$  for  $i > j$ . Here we are only checking  $AB_{ij}$  for  $i > j$ , so we get  $\sum_{k=1}^j A_{ik} B_{kj} = 0$  since  $A_{ik}$  is zero in the summation.  $\sum_{k=j+1}^n A_{ik} B_{kj} = 0$  since  $B_{kj}$  is zero in the summation.

Similarly we can show that product of two lower triangular matrix is also lower triangular but there we would consider  $i < j$  in our analysis.

- 1.5 The **trace** of a square matrix is the sum of its diagonal entries. Show that  $\text{trace}(\mathbf{A} + \mathbf{B}) = \text{trace}(\mathbf{A}) + \text{trace}(\mathbf{B})$  and  $\text{trace}(\mathbf{AB}) = \text{trace}(\mathbf{BA})$  for  $\mathbf{A}, \mathbf{B} \in \mathbb{R}^{n \times n}$ .

Part (a) is trivial.

$$\begin{aligned}\text{trace}(AB) &= \sum_{i=1}^n (AB)_{ii} = \sum_{i=1}^n \sum_{k=1}^n A_{ik} B_{ki} \\ \text{trace}(BA) &= \sum_{i=1}^n (BA)_{ii} = \sum_{i=1}^n \sum_{k=1}^n B_{ik} A_{ki} = \sum_{k=1}^n \sum_{i=1}^n A_{ki} B_{ik}\end{aligned}$$

We have just switched the order of summation as the two summations are over independent axes. Thus we see that  $\text{trace}(AB) = \text{trace}(BA)$  as the two expressions are equivalent

- 1.6 Find all solutions of the linear system  $\mathbf{Ax} = \mathbf{b}$ , where (i)  $\mathbf{A} := \begin{bmatrix} 1 & 3 & -2 & 0 & 2 & 0 \\ 2 & 6 & -5 & -2 & 4 & -3 \\ 0 & 0 & 5 & 10 & 0 & 15 \\ 2 & 6 & 0 & 8 & 4 & 18 \end{bmatrix}$ ,  $\mathbf{b} :=$

$$\begin{bmatrix} 0 & -1 & 6 & 6 \end{bmatrix}^T,$$

$$\text{(ii) } \mathbf{A} := \begin{bmatrix} 2 & 1 & 1 \\ 4 & -6 & 0 \\ -2 & 7 & 2 \end{bmatrix}, \mathbf{b} := \begin{bmatrix} 5 & -2 & 9 \end{bmatrix}^T,$$

$$\text{(iii) } \mathbf{A} := \begin{bmatrix} 0 & 2 & -2 & 1 \\ 2 & -8 & 14 & -5 \\ 1 & 3 & 0 & 1 \end{bmatrix} \text{ and } \mathbf{b} := \begin{bmatrix} 2 & 2 & 8 \end{bmatrix}^T$$

by reducing  $\mathbf{A}$  to a row echelon form.

(i) We perform the row operations to the augmented matrix

$$\left[ \begin{array}{cccccc|c} 1 & 3 & -2 & 0 & 2 & 0 & 0 \\ 2 & 6 & -5 & -2 & 4 & -3 & -1 \\ 0 & 0 & 5 & 10 & 0 & 15 & 6 \\ 2 & 6 & 0 & 8 & 4 & 18 & 6 \end{array} \right]$$

$$R_4 := R_4 - 2R_1$$

$$\left[ \begin{array}{cccccc|c} 1 & 3 & -2 & 0 & 2 & 0 & 0 \\ 2 & 6 & -5 & -2 & 4 & -3 & -1 \\ 0 & 0 & 5 & 10 & 0 & 15 & 6 \\ 0 & 0 & 4 & 8 & 0 & 18 & 6 \end{array} \right]$$

$$R_2 := R_2 - 2R_1$$

$$\left[ \begin{array}{cccccc|c} 1 & 3 & -2 & 0 & 2 & 0 & 0 \\ 0 & 0 & -1 & -2 & 0 & -3 & -1 \\ 0 & 0 & 5 & 10 & 0 & 15 & 6 \\ 0 & 0 & 4 & 8 & 0 & 18 & 6 \end{array} \right]$$

$$R_3 := R_3 + 5R_2$$

$$\left[ \begin{array}{cccccc|c} 1 & 3 & -2 & 0 & 2 & 0 & 0 \\ 0 & 0 & -1 & -2 & 0 & -3 & -1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 4 & 8 & 0 & 18 & 6 \end{array} \right]$$

Swap  $R_3$  and  $R_4$

$$\left[ \begin{array}{cccccc|c} 1 & 3 & -2 & 0 & 2 & 0 & 0 \\ 0 & 0 & -1 & -2 & 0 & -3 & -1 \\ 0 & 0 & 4 & 8 & 0 & 18 & 6 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 \end{array} \right]$$

$$R_3 = R_3 + 4R_2$$

$$\left[ \begin{array}{cccccc|c} 1 & 3 & -2 & 0 & 2 & 0 & 0 \\ 0 & 0 & -1 & -2 & 0 & -3 & -1 \\ 0 & 0 & 0 & 0 & 0 & 6 & 2 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 \end{array} \right]$$

The last row of the augmented matrix is inconsistent. So the system has no solution.

(ii) Performing row operations on the augmented matrix,

$$\left[ \begin{array}{ccc|c} 2 & 1 & 1 & 5 \\ 4 & -6 & 0 & -2 \\ -2 & 7 & 2 & 9 \end{array} \right]$$

$$R_2 := R_2 - 2R_1$$

$$\left[ \begin{array}{ccc|c} 2 & 1 & 1 & 5 \\ 0 & -8 & -2 & -12 \\ -2 & 7 & 2 & 9 \end{array} \right]$$

$$R_3 := R_3 + R_1$$

$$\left[ \begin{array}{ccc|c} 2 & 1 & 1 & 5 \\ 0 & -8 & -2 & -12 \\ 0 & 8 & 3 & 14 \end{array} \right]$$

$$R_3 := R_3 + R_2$$

$$\left[ \begin{array}{ccc|c} 2 & 1 & 1 & 5 \\ 0 & -8 & -2 & -12 \\ 0 & 0 & 1 & 2 \end{array} \right]$$

So we get  $x_3 = 2$ . Back-substituting in  $8x_2 + 2x_3 = 12$  we get  $x_2 = 1$  and back-substituting in  $2x_1 + x_2 + x_3 = 5$ , we get  $x_1 = 1$ .

The solution is;  $\mathbf{x} := [1 \ 1 \ 2]^T$

(iii) Here the augmented matrix is

$$\left[ \begin{array}{cccc|c} 0 & 2 & -2 & 1 & 2 \\ 2 & -8 & 14 & -5 & 2 \\ 1 & 3 & 0 & 1 & 8 \end{array} \right]$$

Performing the following operations, we get; Swap  $R_1$  and  $R_3$

$$\left[ \begin{array}{cccc|c} 1 & 3 & 0 & 1 & 8 \\ 2 & -8 & 14 & -5 & 2 \\ 0 & 2 & -2 & 1 & 2 \end{array} \right]$$

$$R_2 := R_2 - 2R_1$$

$$\left[ \begin{array}{cccc|c} 1 & 3 & 0 & 1 & 8 \\ 0 & -14 & 14 & -7 & -14 \\ 0 & 2 & -2 & 1 & 2 \end{array} \right]$$

$$\text{Then } R_3 := 7R_3 + R_2$$

$$\left[ \begin{array}{cccc|c} 1 & 3 & 0 & 1 & 8 \\ 0 & -14 & 14 & -7 & -14 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right]$$

Since the last row is 0, there are infinitely many solutions.

## 2 Tutorial 2 (on Lectures 3, 4 and 5)

2.1 Find the Row Canonical Form of  $\begin{bmatrix} 1 & 2 & 1 & 1 \\ 0 & 0 & 1 & -1 \\ 1 & 1 & 2 & 0 \end{bmatrix}$ .

Row1 Pivot1 = 1

Swap  $R_2$  and  $R_3$

$$\begin{bmatrix} 1 & 2 & 1 & 1 \\ 1 & 1 & 2 & 0 \\ 0 & 0 & 1 & -1 \end{bmatrix}$$

$R_2 := R_2 - R_1$

$$\begin{bmatrix} 1 & 2 & 1 & 1 \\ 0 & -1 & 1 & -1 \\ 0 & 0 & 1 & -1 \end{bmatrix}$$

Row2 Pivot2 = -1

$R_2 := R_2 / (-1)$

$$\begin{bmatrix} 1 & 2 & 1 & 1 \\ 0 & 1 & -1 & 1 \\ 0 & 0 & 1 & -1 \end{bmatrix}$$

$R_1 := R_1 - 2R_2$

$$\begin{bmatrix} 1 & 0 & 3 & -1 \\ 0 & 1 & -1 & 1 \\ 0 & 0 & 1 & -1 \end{bmatrix}$$

Row3 Pivot3= 1

$R_1 := R_1 - 3R_3$

$$\begin{bmatrix} 1 & 0 & 0 & 2 \\ 0 & 1 & -1 & 1 \\ 0 & 0 & 1 & -1 \end{bmatrix}$$

$R_2 := R_2 + R_3$

$$\begin{bmatrix} 1 & 0 & 0 & 2 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & -1 \end{bmatrix}$$

Above Matrix is the row canonical form of the given Matrix.

2.2 Let  $\mathbf{A} := \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 1 & 1 & 1 \end{bmatrix}$ . Find  $\mathbf{A}^{-1}$  by Gauss-Jordan method.

2.3 An  $m \times m$  matrix  $\mathbf{E}$  is called an **elementary matrix** if it is obtained from the identity matrix  $\mathbf{I}$  by an elementary row operation. Write down all elementary matrices.

(i) Let  $\mathbf{A} \in \mathbb{R}^{m \times n}$ . If an elementary row operation transforms  $\mathbf{A}$  to  $\mathbf{A}'$ , then show that  $\mathbf{A}' = \mathbf{EA}$ , where  $\mathbf{E}$  is the corresponding elementary matrix.

- (ii) Show that every elementary matrix is invertible, and find its inverse.
- (iii) Show that a square matrix  $\mathbf{A}$  is invertible if and only if it is a product of finitely many elementary matrices.

Part i

Each row operation is represented by  $\mathbf{E}_i$  matrices. Let's take  $\mathbf{E}_1, \mathbf{E}_2, \dots, \mathbf{E}_k$  be elementary row transformation matrix such that  $\mathbf{E} = \mathbf{E}_1 \mathbf{E}_2 \dots \mathbf{E}_k \mathbf{I}$  so we get

$$\mathbf{A}' = \mathbf{E}_1 \mathbf{E}_2 \dots \mathbf{E}_k \mathbf{A}$$

Finally

$$\mathbf{A}' = \mathbf{E} \mathbf{A}$$

Part ii

Earlier we got to know that  $\mathbf{E} = \mathbf{E}_1 \mathbf{E}_2 \dots \mathbf{E}_k \mathbf{I}$ , here we can see that  $E_i$  are elementary matrices which are invertible and hence the product of all such  $\mathbf{E}_i$  are invertible. We can get the inverse by

$$\mathbf{E}^{-1} = (\mathbf{E}_1 \mathbf{E}_2 \dots \mathbf{E}_k)^{-1}$$

$$\mathbf{E}^{-1} = \mathbf{E}_k^{-1} \mathbf{E}_{k-1}^{-1} \dots \mathbf{E}_1^{-1}$$

Think how can you prove part3 on the basis of first part and second part

Part iii

A square matrix  $\mathbf{A}$  is invertible if and only if you can row reduce  $\mathbf{A}$  to an identity matrix  $\mathbf{I}$

Let's take the forward case so we have been given matrix is invertible. So on performing  $k$  row operations we obtain  $\mathbf{I}$

$$\mathbf{E}_1 \mathbf{E}_2 \dots \mathbf{E}_k \mathbf{A} = \mathbf{I}$$

$$\mathbf{A} = \mathbf{E}_k^{-1} \mathbf{E}_{k-1}^{-1} \dots \mathbf{E}_1^{-1}$$

Hence its proved

- 2.4 Let  $S$  and  $T$  be subsets of  $\mathbb{R}^{n \times 1}$  such that  $S \subset T$ . Show that if  $S$  is linearly dependent then so is  $T$ , and if  $T$  is linearly independent then so is  $S$ . Does the converse hold?

Let  $S = [v_1, v_2, \dots, v_s]$ . Since  $S \subset T$  let  $T = [v_1, v_2, \dots, v_s, u_1, u_2, \dots, u_t]$ . Now suppose if  $S$  is **Linearly dependant** then  $\exists \alpha_1, \alpha_2, \dots, \alpha_s$  such that  $\alpha_1 v_1 + \alpha_2 v_2 + \dots + \alpha_s v_s = 0$  and not all  $\alpha_i$  are zero. Now let  $\beta_1 v_1 + \beta_2 v_2 + \dots + \beta_s v_s + \beta_{s+1} u_1 + \beta_{s+2} u_2 + \dots + \beta_{s+t} u_t = 0$ . Put  $\beta_{s+i} = 0$  where  $i \geq 1$  and  $\beta_i = \alpha_i$  for  $i \leq s$ . So this tuple value of  $\beta$  isn't zero hence  $T$  is **Linearly dependant**.

If  $T$  is Linearly independent then the only solution for  $\beta_1 v_1 + \beta_2 v_2 + \dots + \beta_s v_s + \beta_{s+1} u_1 + \beta_{s+2} u_2 + \dots + \beta_{s+t} u_t = 0$  is  $\beta_i = 0$ . Suppose if  $S$  is **Linearly dependant** then it means  $\exists \alpha_1, \alpha_2, \dots, \alpha_s$  such that  $\alpha_1 v_1 + \alpha_2 v_2 + \dots + \alpha_s v_s = 0$ . So put  $\beta_i = \alpha_i$  for  $i \leq s$  and  $\beta_{s+i} = 0$ . This tuple satisfies the above equation yet  $\beta \neq 0$ . So this contradicts that  $T$  is Linearly independent. Hence  $S$  is **Linearly independent**

- 2.5 Are the following sets linearly independent?



(i)  $\{[1 \ -1 \ 1], [3 \ 5 \ 2], [1 \ 2 \ 1], [1 \ 1 \ 1]\} \subset \mathbb{R}^{1 \times 3},$

(ii)  $\{[1 \ 9 \ 9 \ 8], [2 \ 0 \ 0 \ 3], [2 \ 0 \ 0 \ 8]\} \subset \mathbb{R}^{1 \times 4},$

(iii)  $\{[1 \ -1 \ 0]^\top, [3 \ -5 \ 2]^\top, [1 \ -2 \ 1]^\top\} \subset \mathbb{R}^{3 \times 1}.$

2.6 Given a set of  $s$  linearly independent row vectors  $\{\mathbf{a}_1, \dots, \mathbf{a}_i, \dots, \mathbf{a}_j, \dots, \mathbf{a}_s\}$  in  $\mathbb{R}^{1 \times n}$  and  $\alpha \in \mathbb{R}$ , show that the set  $\{\mathbf{a}_1, \dots, \mathbf{a}_{i-1}, \mathbf{a}_i + \alpha \mathbf{a}_j, \mathbf{a}_{i+1}, \dots, \mathbf{a}_j, \dots, \mathbf{a}_s\}$  is linearly independent.

$$c_1 a_1 + c_2 a_2 + \dots c_i a_i + \dots c_j a_j \dots + c_s a_s = 0.$$

Since these vectors are linearly independent,  $\forall_k c_k = 0$ .

$$\text{Now consider } \beta_1 a_1 + \beta_2 a_2 + \dots \beta_i (a_i + \alpha a_j) + \dots \beta_j a_j \dots + \beta_s a_s = 0.$$

$$\text{So } \beta_1 a_1 + \beta_2 a_2 + \dots \beta_i a_i + \dots (\beta_j + \beta_i \alpha) a_j \dots + \beta_s a_s = 0.$$

$$\text{So } \beta_1 = \beta_2 = \dots \beta_i = \beta_s = 0, \beta_j + \alpha \beta_i = 0.$$

Hence  $\forall_k \beta_k = 0$ . So this set of vectors is also linearly independent.

2.7 Find the ranks of the following matrices.

(i)  $\begin{bmatrix} 8 & -4 \\ -2 & 1 \\ 6 & -3 \end{bmatrix},$  (ii)  $\begin{bmatrix} 0 & 8 & -1 \\ 1 & 2 & 0 \\ 0 & 0 & 3 \\ 0 & 4 & 5 \end{bmatrix}.$

2.8 Are the following subsets of  $\mathbb{R}^{3 \times 1}$  subspaces?

(i)  $\{[x_1 \ x_2 \ x_3]^\top : x_1, x_2, x_3 \in \mathbb{R}, x_1 + x_2 + x_3 = 0\},$

(ii)  $\{[x_1 + x_2 + x_3 \ x_2 + x_3 \ x_3]^\top : x_1, x_2, x_3 \in \mathbb{R}\},$

(iii)  $\{[x_1 \ x_2 \ x_3]^\top : x_1, x_2, x_3 \in \mathbb{R}, x_1 x_2 x_3 = 0\}$

(iv)  $\{[x_1 \ x_2 \ x_3]^\top : x_1, x_2, x_3 \in \mathbb{R}, |x_1|, |x_2|, |x_3| \leq 1\}.$

If so, find a basis for each, and also its dimension.

2.9 Describe all subspaces of  $\mathbb{R}, \mathbb{R}^{2 \times 1}, \mathbb{R}^{3 \times 1}$  and  $\mathbb{R}^{4 \times 1}$ . Can you visualise them geometrically?

### 3 Tutorial 3 (on Lectures 6 and 7)

3.1 Let  $V$  be a subspace of  $\mathbb{R}^{n \times 1}$  with  $\dim V = r$ , and let  $S$  be a finite subset of  $V$  such that  $\text{span } S = V$ . Suppose  $S$  has  $s$  elements. Show that (i)  $s \geq r$ , (ii) if  $s = r$ , then  $S$  is a basis for  $V$ , (iii) if  $s > r$ , then  $S$  contains basis for  $V$ .

3.2 Let  $\mathbf{A}' \in \mathbb{R}^{m \times n}$  be in a REF. Show that the pivotal columns of  $\mathbf{A}'$  form a basis for the column space  $\mathcal{C}(\mathbf{A}')$ .

3.3 Let  $\mathbf{A} \in \mathbb{R}^{m \times n}$ . The set  $\mathcal{R}(\mathbf{A})$  consisting of all linear combinations of the rows of  $\mathbf{A}$  is called the **row space** of  $\mathbf{A}$ . Show that  $\mathcal{R}(\mathbf{A})$  is a subspace of  $\mathbb{R}^{1 \times n}$ . If  $\mathbf{A}'$  is obtained from  $\mathbf{A}$  by EROs, then prove that  $\mathcal{R}(\mathbf{A}') = \mathcal{R}(\mathbf{A})$ . Further, show that the dimension of  $\mathcal{R}(\mathbf{A})$  is equal to the rank of  $\mathbf{A}$ .

3.4 Let  $\mathbf{A} \in \mathbb{R}^{m \times n}$  and  $\mathbf{B} \in \mathbb{R}^{n \times p}$ . Show that  $\text{rank } \mathbf{AB} \leq \min\{\text{rank } \mathbf{A}, \text{rank } \mathbf{B}\}$ .

3.5 Let  $\mathbf{A} := \begin{bmatrix} 0 & 0 & 0 & -2 & 1 \\ 0 & 2 & -2 & 14 & -1 \\ 0 & 2 & 3 & 13 & 1 \end{bmatrix}$ . Find the rank and the nullity of  $\mathbf{A}$ . What is the dimension of the solution space of the homogeneous equation  $\mathbf{Ax} = \mathbf{0}$ ? If  $\mathbf{b} := [2 \ 2 \ 3]^T$ , find the general solution of  $\mathbf{Ax} = \mathbf{b}$ .

3.6 Prove that  $\det \begin{bmatrix} 1 & 1 & 1 \\ a & b & c \\ a^2 & b^2 & c^2 \end{bmatrix} = (b-a)(c-a)(c-b)$ , where  $a, b, c \in \mathbb{R}$ . Also, prove an analogous formula for a determinant of order  $n$ , known as the **Vandermonde determinant**.

$$\det \begin{bmatrix} 1 & 1 & 1 \\ a & b & c \\ a^2 & b^2 & c^2 \end{bmatrix}$$

Use  $\det(A) = \det(A^T)$  and perform  $R_k = R_k - R_1 \ \forall \ k=2 \text{ to } 3$

$$\det \begin{bmatrix} 1 & a & a^2 \\ 1 & b & b^2 \\ 1 & c & c^2 \end{bmatrix} = \det \begin{bmatrix} 1 & a & a^2 \\ 0 & b-a & b^2-a^2 \\ 0 & c-a & c^2-a^2 \end{bmatrix} = (b-a)(c-a)(c-b)$$

Part 2

To prove general result use induction for  $n=2$  we have

$$\det \begin{bmatrix} 1 & 1 \\ a_1 & a_2 \end{bmatrix} = (a_2 - a_1)$$

Now assume it to be true for  $n-1$  order matrix and if we are able to prove  $n$  order matrix from the  $n-1$  order matrix we are done

$$\det \begin{bmatrix} 1 & 1 & 1 & \dots & \dots & \dots & 1 \\ a_1 & a_2 & a_3 & \dots & \dots & \dots & a_n \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ a_1^{n-1} & a_2^{n-1} & a_3^{n-1} & \dots & \dots & \dots & a_n^{n-1} \end{bmatrix} = \prod_{1 \leq i < j \leq n} (a_j - a_i)$$

$$\det(A) = \det(A^T)$$

$$\det \begin{bmatrix} 1 & a_1 & a_1^2 & \dots & \dots & \dots & a_1^{n-1} \\ 1 & a_2 & a_2^2 & \dots & \dots & \dots & a_2^{n-1} \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ 1 & a_n & a_n^2 & \dots & \dots & \dots & a_n^{n-1} \end{bmatrix} = \prod_{1 \leq i < j \leq n} (a_j - a_i)$$

$$R_k = R_k - R_1 \quad \forall k=2 \text{ to } n$$

$$\det \begin{bmatrix} 1 & a_1 & a_1^2 & \dots & \dots & \dots & a_1^{n-1} \\ 0 & a_2 - a_1 & a_2^2 - a_1^2 & \dots & \dots & \dots & a_2^{n-1} - a_1^{n-1} \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ 0 & a_n - a_1 & a_n^2 - a_1^2 & \dots & \dots & \dots & a_n^{n-1} - a_1^{n-1} \end{bmatrix} \rightarrow \text{eqn}(I)$$

$$\prod_{1 \leq j \leq n} (a_j - a_1) \det \begin{bmatrix} 1 & a_2 + a_1 & \dots & \dots & \sum_{i=0}^{n-1} a_2^{n-2-i} a_1^i \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ 1 & a_n + a_1 & \dots & \dots & \sum_{i=0}^{n-1} a_n^{n-2-i} a_1^i \end{bmatrix}$$

Now keep on splitting the det by column wise starting from col(2) to col(n) and see only one non zero det would survive and others would vanish

$$\prod_{1 \leq j \leq n} (a_j - a_1) \det \begin{bmatrix} 1 & a_1 & a_1^2 & \dots & \dots & \dots & a_1^{n-2} \\ 1 & a_2 & a_2^2 & \dots & \dots & \dots & a_2^{n-2} \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ 1 & a_{n-1} & a_{n-1}^2 & \dots & \dots & \dots & a_{n-1}^{n-2} \end{bmatrix}$$

$$\prod_{1 \leq i < j \leq n} (a_j - a_i) * \prod_{2 \leq j \leq n} (a_j - a_i)$$

$$\prod_{1 \leq j \leq n} (a_j - a_i)$$

Other method

Look at eqn(I) matrix

Use  $\det(A) = \det(A^T)$  and consecutively perform  $R_k = R_k - R_{k-1} * a_1 \forall k=2$  to  $n$  Try out

3.7 For  $n \in \mathbb{N}$ , prove that

$$\det \begin{bmatrix} 0 & 0 & 0 & \dots & 0 & 0 & 1 \\ 0 & 0 & 0 & \dots & 0 & 1 & 0 \\ & & & & & & \cdot \\ & & & & & & \\ & & & & & & \cdot \\ 0 & 1 & 0 & \dots & 0 & 0 & 0 \\ 1 & 0 & 0 & \dots & 0 & 0 & 0 \end{bmatrix} = (-1)^{n(n-1)/2}.$$

Use induction Method:

For  $n=1$  we have,

$$\det [1] = (-1)^{1(1-1)/2} = 1$$

Now assume it to be true for  $n-1$  order matrix and if we are able to prove  $n$  order matrix from the  $n-1$  order matrix we are done

$$\text{To prove:: } \det \begin{bmatrix} 0 & 0 & 0 & \dots & 0 & 0 & 1 \\ 0 & 0 & 0 & \dots & 0 & 1 & 0 \\ & & & & & & \cdot \\ & & & & & & \\ & & & & & & \cdot \\ 0 & 1 & 0 & \dots & 0 & 0 & 0 \\ 1 & 0 & 0 & \dots & 0 & 0 & 0 \end{bmatrix} = (-1)^{n(n-1)/2}$$

$$\det \begin{bmatrix} 0 & 0 & 0 & \dots & 0 & 0 & 1 \\ 0 & 0 & 0 & \dots & 0 & 1 & 0 \\ & & & & & & \cdot \\ & & & & & & \\ & & & & & & \cdot \\ 0 & 1 & 0 & \dots & 0 & 0 & 0 \\ 1 & 0 & 0 & \dots & 0 & 0 & 0 \end{bmatrix}$$

Now if we expand via the first row to find  $\det$  and use result of  $\det(A)_{n-1}$ , we get

$$(-1)^{n+1} \det \begin{bmatrix} 0 & 0 & 0 & \dots & 0 & 0 & 1 \\ 0 & 0 & 0 & \dots & 0 & 1 & 0 \\ & & & & & & \cdot \\ & & & & & & \cdot \\ 0 & 1 & 0 & \dots & 0 & 0 & 0 \\ 1 & 0 & 0 & \dots & 0 & 0 & 0 \end{bmatrix}_{n-1}$$

$$(-1)^{n+1} * (-1)^{(n-1)(n-2)/2} = (-1)^{n(n-1)/2}$$

3.8 For  $n \in \mathbb{N}$ , prove that

$$\det \begin{bmatrix} 1 & 2 & 3 & \dots & n-1 & n \\ 2 & 2 & 3 & \dots & n-1 & n \\ 3 & 3 & 3 & \dots & n-1 & n \\ \vdots & \vdots & \vdots & & \vdots & \vdots \\ n-1 & n-1 & n-1 & \dots & n-1 & n \\ n & n & n & \dots & n & n \end{bmatrix} = (-1)^{n+1} n.$$

$$R_n \mapsto \frac{1}{n} R_n$$

$$R_i \mapsto R_i - i R_n \text{ for all } i \in \{1, \dots, n-1\}.$$

For example, in the case of  $n = 4$ , you should have arrived at the following conclusion:

$$\det \begin{bmatrix} 1 & 2 & 3 & 4 \\ 2 & 2 & 3 & 4 \\ 3 & 3 & 3 & 4 \\ 4 & 4 & 4 & 4 \end{bmatrix} = 4 \det \begin{bmatrix} 0 & 1 & 2 & 3 \\ 0 & 0 & 1 & 2 \\ 0 & 0 & 0 & 1 \\ 1 & 1 & 1 & 1 \end{bmatrix}$$

Write the general case.

Now, expand along the first column. This is simple to do as it has only one non-zero entry.

(Note that you'll get a  $(-1)^n$ .)

Thus, you get that the original determinant equals the following expression:

$$(-1)^n n \det \begin{bmatrix} 1 & 2 & \dots & n-1 \\ 0 & 1 & \dots & n-2 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & 1 \end{bmatrix}.$$

Note that the determinant written above is just 1 as it's a triangular matrix with all diagonal entries 1.

Thus, the answer is  $(-1)^n n$ .

3.9 Find rank  $\mathbf{A}$  using determinants, where  $\mathbf{A}$  is

$$(i) \begin{bmatrix} 0 & 2 & -3 \\ 2 & 0 & 5 \\ -3 & 5 & 0 \end{bmatrix}, \quad (ii) \begin{bmatrix} 4 & 3 \\ -8 & -6 \\ 16 & 12 \end{bmatrix}.$$

Verify by transforming  $\mathbf{A}$  to a REF.

## 4 Tutorial 4 (on Lectures 8, 9 and 10)

4.1 Find the value(s) of  $\alpha$  for which Cramer's rule is applicable. For the remaining value(s) of  $\alpha$ , find the number of solutions, if any.

$$\begin{array}{rrcr} x & + & 2y & + & 3z & = & 20 \\ x & + & 3y & + & z & = & 13 \\ x & + & 6y & + & \alpha z & = & \alpha. \end{array}$$

4.2 Find the cofactor matrix  $\mathbf{C}$  of the matrix  $\mathbf{A}$ , and verify  $\mathbf{C}^T \mathbf{A} = (\det \mathbf{A}) \mathbf{I} = \mathbf{A} \mathbf{C}^T$ . If  $\det \mathbf{A} \neq 0$ , find  $\mathbf{A}^{-1}$ , where  $\mathbf{A}$  is

$$(i) \begin{bmatrix} a & b \\ c & d \end{bmatrix}, (ii) \begin{bmatrix} 0 & 9 & 5 \\ 2 & 0 & 0 \\ 0 & 2 & 0 \end{bmatrix}, (iii) \begin{bmatrix} 1 & 1/2 & 1/3 \\ 1/2 & 1/3 & 1/4 \\ 1/3 & 1/4 & 1/5 \end{bmatrix}.$$

4.3 Find the matrix of the linear transformation  $T : \mathbb{R}^{3 \times 1} \rightarrow \mathbb{R}^{4 \times 1}$  defined by  $T([x_1 \ x_2 \ x_3]^T) := [x_1 + x_2 \ x_2 + x_3 \ x_3 + x_1 \ x_1 + x_2 + x_3]^T$  with respect to the ordered bases (i)  $E = (\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3)$  of  $\mathbb{R}^{3 \times 1}$  and  $F = (\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3, \mathbf{e}_4)$  of  $\mathbb{R}^{4 \times 1}$ ,  
(ii)  $E' = (\mathbf{e}_1 + \mathbf{e}_2, \mathbf{e}_2 + \mathbf{e}_3, \mathbf{e}_3 + \mathbf{e}_1)$  of  $\mathbb{R}^{3 \times 1}$  and  $F' = (\mathbf{e}_1 + \mathbf{e}_2 + \mathbf{e}_3, \mathbf{e}_2 + \mathbf{e}_3 + \mathbf{e}_4, \mathbf{e}_3 + \mathbf{e}_4 + \mathbf{e}_1, \mathbf{e}_4 + \mathbf{e}_1 + \mathbf{e}_2)$  of  $\mathbb{R}^{4 \times 1}$ , first showing that  $E'$  is a basis for  $\mathbb{R}^{3 \times 1}$  and  $F'$  is a basis for  $\mathbb{R}^{4 \times 1}$ .

Part(i)

We have the basis set  $E = (\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3)$  of  $\mathbb{R}^{3 \times 1}$  and  $F = (\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3, \mathbf{e}_4)$  of  $\mathbb{R}^{4 \times 1}$ ,

$$T(\mathbf{e}_1) = [1 \ 0 \ 1 \ 1]^T = 1\mathbf{e}_1 + 0\mathbf{e}_2 + 1\mathbf{e}_3 + 1\mathbf{e}_4$$

$$T(\mathbf{e}_2) = [1 \ 1 \ 0 \ 1]^T = 1\mathbf{e}_1 + 1\mathbf{e}_2 + 0\mathbf{e}_3 + 1\mathbf{e}_4$$

$$T(\mathbf{e}_3) = [0 \ 1 \ 1 \ 1]^T = 0\mathbf{e}_1 + 1\mathbf{e}_2 + 1\mathbf{e}_3 + 1\mathbf{e}_4$$

$$\mathbf{M}_F^E(T) = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 1 & 0 & 1 \\ 1 & 1 & 1 \end{bmatrix}$$

Part(ii)

Check whether the set  $E'$  and set  $F'$  forms a basis set? Indeed yes they form ( Try it out )

$$T(\mathbf{e}_1 + \mathbf{e}_2) = [2 \ 1 \ 1 \ 2]^T = 0(\mathbf{e}_1 + \mathbf{e}_2 + \mathbf{e}_3) + 0(\mathbf{e}_2 + \mathbf{e}_3 + \mathbf{e}_4) + 1(\mathbf{e}_3 + \mathbf{e}_4 + \mathbf{e}_1) + 1(\mathbf{e}_4 + \mathbf{e}_1 + \mathbf{e}_2)$$

=

$$T(\mathbf{e}_2 + \mathbf{e}_3) = [1 \ 2 \ 1 \ 2]^T = 0(\mathbf{e}_1 + \mathbf{e}_2 + \mathbf{e}_3) + 1(\mathbf{e}_2 + \mathbf{e}_3 + \mathbf{e}_4) + 0(\mathbf{e}_3 + \mathbf{e}_4 + \mathbf{e}_1) + 1(\mathbf{e}_4 + \mathbf{e}_1 + \mathbf{e}_2)$$

=

$$T(\mathbf{e}_3 + \mathbf{e}_1) = [1 \ 1 \ 2 \ 2]^T = 0(\mathbf{e}_1 + \mathbf{e}_2 + \mathbf{e}_3) + 1(\mathbf{e}_2 + \mathbf{e}_3 + \mathbf{e}_4) + 1(\mathbf{e}_3 + \mathbf{e}_4 + \mathbf{e}_1) + 0(\mathbf{e}_4 + \mathbf{e}_1 + \mathbf{e}_2)$$

=

$$\mathbf{M}_{F'}^{E'}(T) = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 1 \\ 1 & 0 & 1 \\ 1 & 1 & 0 \end{bmatrix}$$

4.4 Let  $\mathbf{A} \in \mathbb{R}^{4 \times 4}$ . Let  $\mathbf{P} := \begin{bmatrix} 1 & 0 & 1 & 1 \\ 1 & 1 & 0 & 1 \\ 1 & 1 & 1 & 0 \\ 0 & 1 & 1 & 1 \end{bmatrix}$ . Show that  $\mathbf{P}$  is invertible. Find an ordered bases  $E$  of  $\mathbb{R}^{4 \times 1}$

such that  $\mathbf{P}^{-1}\mathbf{A}\mathbf{P} = \mathbf{M}_E^E(T_{\mathbf{A}})$ .

Using the theorem we get  $\mathbf{E} = \{\mathbf{P}_1, \mathbf{P}_2, \mathbf{P}_3, \mathbf{P}_4\}$

4.5 Let  $\lambda \in \mathbb{K}$ . Find the geometric multiplicity of the eigenvalue  $\lambda$  of each of the following matrices:

$$\mathbf{A} := \begin{bmatrix} \lambda & 0 & 0 \\ 0 & \lambda & 0 \\ 0 & 0 & \lambda \end{bmatrix}, \mathbf{B} := \begin{bmatrix} \lambda & 1 & 0 \\ 0 & \lambda & 0 \\ 0 & 0 & \lambda \end{bmatrix}, \mathbf{C} := \begin{bmatrix} \lambda & 1 & 0 \\ 0 & \lambda & 1 \\ 0 & 0 & \lambda \end{bmatrix}.$$

Also, find the eigenspace associated with  $\lambda$  in each case.

For  $|\mathbf{A} - \mu\mathbf{I}| = 0 = (\mu - \lambda)^3$  its true for all vector  $\mathbf{x} = (x_1, x_2, x_3)$  and hence eigen space is  $\mathbb{R}^3$

For  $|\mathbf{B} - \mu\mathbf{I}| = 0 = (\mu - \lambda)^3$  and for corresponding eigen vector  $\mathbf{x} = (x_1, x_2, x_3)$   
Solve  $(\mathbf{B} - \lambda\mathbf{I})\mathbf{x} = 0 \implies x_2 = 0$  and hence eigen space is  $\mathbb{R}^2$

For  $|\mathbf{C} - \mu\mathbf{I}| = 0 = (\mu - \lambda)^3$  and for corresponding eigen vector  $\mathbf{x} = (x_1, x_2, x_3)$   
Solve  $(\mathbf{B} - \lambda\mathbf{I})\mathbf{x} = 0 \implies x_2 = 0, x_3 = 0$  and hence eigen space is  $\mathbb{R}$

4.6 Let  $\mathbf{A} := \begin{bmatrix} 3 & 0 & 0 \\ -2 & 4 & 2 \\ -2 & 1 & 5 \end{bmatrix}$ . Show that 3 is an eigenvalue of  $\mathbf{A}$ , and find all eigenvectors of  $\mathbf{A}$  corresponding

to it. Also, show that  $\begin{bmatrix} 0 & 1 & 1 \end{bmatrix}^T$  is an eigenvector of  $\mathbf{A}$ , and find the corresponding eigenvalue of  $\mathbf{A}$ .

Check  $|\mathbf{A} - 3\mathbf{I}| = 0$ , we get  $\det \begin{bmatrix} 0 & 0 & 0 \\ -2 & 1 & 2 \\ -2 & 1 & 2 \end{bmatrix} = 0$

$$\mathbf{A}\mathbf{x} = 3\mathbf{x}$$

,

$$\begin{bmatrix} 3 & 0 & 0 \\ -2 & 4 & 2 \\ -2 & 1 & 5 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = 3 \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

We get  $x_1 = 0$  and  $x_2 + 2x_3 = 0$ . So all eigen vectors  $\mathbf{x} = x_3(0, -2, 1)$  where  $x_3 \in \mathbb{R}$

To prove  $\begin{bmatrix} 0 & 1 & 1 \end{bmatrix}^T$  is an eigenvector of  $\mathbf{A}$

$$\begin{bmatrix} 3 & 0 & 0 \\ -2 & 4 & 2 \\ -2 & 1 & 5 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 6 \\ 6 \end{bmatrix} = 6 \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}$$

We get the eigen value to be 6.

4.7 Let  $\theta \in (-\pi, \pi]$ ,  $\mathbf{A} := \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$  and  $\mathbb{K} = \mathbb{C}$ . Show that  $\cos \theta \pm i \sin \theta$  are eigenvalues of  $\mathbf{A}$ .

Find an invertible matrix  $\mathbf{P}$  such that  $\mathbf{P}^{-1}\mathbf{A}\mathbf{P}$  is a diagonal matrix, and check your answer.



For  $|\mathbf{A} - \mu\mathbf{I}| = 0$ ,

$$\det\left(\begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} - \mu \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}\right) = 0$$

$$\det\left(\begin{bmatrix} \cos \theta - \mu & -\sin \theta \\ \sin \theta & \cos \theta - \mu \end{bmatrix}\right) = 0$$

$$\mu^2 - 2\mu \cos \theta + 1 = 0 \implies \mu = \cos \theta \pm i \sin \theta$$

$$\mathbf{x} = (x_1, x_2) \text{ where } x_1, x_2 \in \mathbb{C}$$

$$\begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \mu \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

$$\text{We get } \cos \theta x_1 - \sin \theta x_2 = (\cos \theta - i \sin \theta)x_1 \implies x_2 = ix_1$$

$$\text{We get } \mathbf{x} = x_1(1, i) \text{ where } x_1 \in \mathbb{C}$$

$$\text{For other eigen value } \cos \theta x_1 + \sin \theta x_2 = (\cos \theta + i \sin \theta)x_1 \implies x_2 = -ix_1$$

$$\text{We get } \mathbf{x} = x_1(1, -i) \text{ where } x_1 \in \mathbb{C}$$

$$\mathbf{P} := \begin{bmatrix} 1 & 1 \\ i & -i \end{bmatrix} \text{ and Check it } \mathbf{P}^{-1}\mathbf{A}\mathbf{P} = \begin{bmatrix} \cos \theta - i \sin \theta & 0 \\ 0 & \cos \theta + i \sin \theta \end{bmatrix}$$

4.8 Let  $n \geq 2$  and  $\mathbf{A} := \begin{bmatrix} 1 & \cdots & 1 \\ \vdots & \vdots & \vdots \\ 1 & \cdots & 1 \end{bmatrix} \in \mathbb{R}^{n \times n}$ , that is,  $a_{jk} = 1$  for all  $j, k = 1, \dots, n$ . Find rank  $\mathbf{A}$  and

nullity  $\mathbf{A}$ . Find an eigenvector of  $\mathbf{A}$  corresponding to a nonzero eigenvalue by inspection. Find two distinct eigenvalues of  $\mathbf{A}$  along with their geometric multiplicities, and find bases for the eigenspaces. Show that  $\mathbf{A}$  is diagonalizable, and find an invertible matrix  $\mathbf{P}$  such that  $\mathbf{P}^{-1}\mathbf{A}\mathbf{P}$  is a diagonal matrix.

$$\text{Rank } \mathbf{A} = 1, \text{ Nullity } \mathbf{A} = n - 1$$

$$\text{Eigen vector} = [1 \ 1 \ \dots \ 1]^T \text{ for eigen value} = n$$

To find  $|\mathbf{A} - \mu\mathbf{I}| = 0$ , Swap all rows initially and perform  $R_1 \mapsto \sum_{i=1}^n R_i$  and take  $(n-\mu)$  common and then  $R_k \mapsto R_k - R_1 \forall k=2$  to  $n$  and then expand via last column

$$\text{we get } \mu^{n-1}(\mu - n) = 0 \implies \mu = 0 \text{ GM is } n-1, \mu = n \text{ GM is } 1$$

Now find eigen vectors corresponding to all eigen values  $(\mathbf{A} - \mu\mathbf{I})\mathbf{x} = 0$  we get

$$\text{For } \mu = 0, v = \{ \mathbf{x} : \sum_{i=1}^n x_i = 0 \}$$

$$\text{For } \mu = n \text{ we get } \mathbf{v} = x_1(1, 1, 1, \dots)^T \forall x_1 \in \mathbb{R} \quad \mathbf{P} := \begin{bmatrix} -1 & -1 & -1 & \dots & -1 & 1 \\ 1 & 0 & 0 & \dots & 0 & 1 \\ 0 & 1 & 0 & \dots & 0 & 1 \\ 0 & 0 & 1 & \dots & 0 & 1 \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\ \vdots & \vdots & \vdots & \dots & \vdots & \vdots \\ 0 & 0 & 0 & \dots & 1 & 1 \end{bmatrix}$$

Perform  $\mathbf{P}^{-1}\mathbf{A}\mathbf{P}$  to get to a diagonal matrix

## 5 Tutorial 5 (on Lectures 11, 12 and 13)

5.1 Find all eigenvalues, and their geometric as well as algebraic multiplicities of the following matrices. Are they diagonalizable? If so, find invertible  $\mathbf{P}$  such that  $\mathbf{P}^{-1}\mathbf{A}\mathbf{P}$  is a diagonal matrix.

$$(i) \mathbf{A} := \begin{bmatrix} 5 & -1 \\ 1 & 3 \end{bmatrix}, \quad (ii) \mathbf{A} := \begin{bmatrix} 3 & 2 & 1 & 0 \\ 0 & 1 & 0 & 1 \\ 0 & 2 & -1 & 0 \\ 0 & 0 & 0 & 1/2 \end{bmatrix}, \quad (iii) \mathbf{A} := \begin{bmatrix} 2 & 1 & 0 \\ 0 & 2 & 1 \\ 0 & 0 & 2 \end{bmatrix}.$$

Similar to exercise 4.7 and 4.8

5.2 Let  $\mathbf{A} := \begin{bmatrix} 2 & a & b \\ 0 & 1 & c \\ 0 & 0 & 2 \end{bmatrix}$ . Find a necessary and sufficient condition on  $a, b, c$  for  $\mathbf{A}$  to be diagonalizable.

You can easily see eigen values are 2,1,2

Just you need to check for nullspace  $(\mathbf{A} - \mu\mathbf{I})\mathbf{x} = 0$  or find nullity for  $\mu = 2$

$$\begin{bmatrix} 2-\mu & a & b \\ 0 & 1-\mu & c \\ 0 & 0 & 2-\mu \end{bmatrix} \mapsto \begin{bmatrix} 0 & a & b \\ 0 & -1 & c \\ 0 & 0 & 0 \end{bmatrix}$$

So for nullity equal to 2 we need rank =1 hence  $R_2$  must to be a scalar multiple of  $R_1$

$$\frac{a}{-1} = \frac{b}{c} \implies b = -ac$$

5.3 Let  $k \in \mathbb{N}$  and

$$\mathbf{A} := \begin{bmatrix} 0 & -1 & 0 & 0 & 0 & \cdots & \cdots & 0 \\ 1 & 0 & 0 & 0 & 0 & \cdots & \cdots & 0 \\ 0 & 0 & 0 & -1 & 0 & \cdots & \cdots & 0 \\ 0 & 0 & 1 & 0 & 0 & \cdots & \cdots & 0 \\ 0 & 0 & 0 & 0 & 0 & \ddots & \cdots & 0 \\ \vdots & \vdots & \ddots & \ddots & \ddots & \ddots & \ddots & \vdots \\ 0 & \cdots & \cdots & 0 & 0 & 0 & 0 & -1 \\ 0 & \cdots & \cdots & 0 & 0 & 0 & 1 & 0 \end{bmatrix} \in \mathbb{K}^{2k \times 2k},$$

that is,  $\mathbf{A}$  has all diagonal entries 0, the subdiagonal entries are  $1, 0, 1, 0, \dots, 1, 0$ , and the superdiagonal entries are  $-1, 0, -1, 0, \dots, -1, 0$ . Find the characteristic polynomial of  $\mathbf{A}$ , all eigenvalues of  $\mathbf{A}$ , and their algebraic as well as geometric multiplicities.

Take  $(\mathbf{A} - \mu\mathbf{I})$  and perform  $R_{2i} \mapsto R_{2i} + R_{2i-1}/\mu \forall i=1$  to  $k$

There was a catch that  $\mu \neq 0$  (how would you prove that). Hint (find nullity of  $\mathbf{A}$ )

It's a Upper triangular matrix and whose det is product of diagonal entries

$$\mu^k(\mu + 1/\mu)^k = 0 \implies (\mu^2 + 1)^k = 0 \implies \mu = \pm i$$

Find Nullity of  $(\mathbf{A} - i\mathbf{I})$  by performing  $R_{2i} \mapsto R_{2i} - iR_{2i-1} \forall i=1$  to  $k$

Characteristic polynomial is  $(\mathbf{A}^2 + 1)^k = 0$

5.4 Let  $\lambda \in \mathbb{K}$ . Show that  $\lambda$  is an eigenvalue of  $\mathbf{A}$  if and only if  $\bar{\lambda}$  is an eigenvalue of  $\mathbf{A}^*$ , but their eigenvectors can be very different.

For forward part,

$$\lambda \|\mathbf{x}\|^2 = \lambda \langle x, x \rangle = \langle x, \lambda x \rangle = \langle x, Ax \rangle$$

Transformation property:  $\langle Ax, y \rangle = (Ax)^* y = x^* (A^* y) = \langle x, A^* y \rangle$

$$\lambda \|\mathbf{x}\|^2 = \langle A^* x, x \rangle$$

Take conjugate on both sides

$$\bar{\lambda} \|\mathbf{x}\|^2 = \overline{\langle A^* x, x \rangle}$$

$$\bar{\lambda} \|\mathbf{x}\|^2 = \langle x, A^* x \rangle$$

Similarly prove the backward part (Try it)

Other method:

$|\mathbf{A} - \lambda \mathbf{I}| = 0$ . Choose  $\mathbf{B} = \mathbf{A} - \lambda \mathbf{I}$  and we get  $\det(\mathbf{B}) = 0$

We can claim that  $\det(\mathbf{B}^*) = 0$ . So  $\mathbf{B}^* = \mathbf{A}^* - \bar{\lambda} \mathbf{I}$ .

Now  $|\mathbf{A}^* - \bar{\lambda} \mathbf{I}| = 0$  hence  $\bar{\lambda}$  is an eigen value of  $\mathbf{A}^*$

- 5.5 Let  $\mathbf{A} \in \mathbb{K}^{n \times n}$ . Show that 0 is an eigenvalue of  $\mathbf{A}$  if and only if 0 is an eigenvalue of  $\mathbf{A}^* \mathbf{A}$ , and its geometric multiplicity is the same. Deduce  $\text{rank } \mathbf{A}^* \mathbf{A} = \text{rank } \mathbf{A}$ .

$$\mathbf{A}x = 0 \implies \mathbf{A}^* \mathbf{A}x = 0 \implies x \in N(\mathbf{A}^* \mathbf{A})$$

$$N(\mathbf{A}) \subseteq N(\mathbf{A}^* \mathbf{A})$$

$$\text{Now consider } \mathbf{A}^* \mathbf{A}x = 0 \implies x^* \mathbf{A}^* \mathbf{A}x = 0 \implies (\mathbf{A}x)^* \mathbf{A}x = 0 \implies \mathbf{A}x = 0 \implies x \in N(\mathbf{A})$$

$$N(\mathbf{A}^* \mathbf{A}) \subseteq N(\mathbf{A})$$

$$\text{Hence } N(\mathbf{A}) = N(\mathbf{A}^* \mathbf{A})$$

All part follows from this because geometric multiplicity of 0 is nullity of the matrix.

- 5.6 Let  $\mathbf{A} := \begin{bmatrix} 2 & i & 1+i \\ -i & 3 & 1 \\ 1-i & -1 & 8 \end{bmatrix}$ . Show that no eigenvalue of  $\mathbf{A}$  is away from one of the diagonal entries of  $\mathbf{A}$  by more than  $1 + \sqrt{2}$ .

By the Gerschgorin Theorem we know  $|\lambda - a_{jj}| \leq \sum_{j \neq k} |a_{jk}|$

Lets calculate  $\sum_{j \neq k} |a_{jk}|$  for  $j=1$  it's  $1 + \sqrt{2}$

For  $j=2$  it's 2, For  $j=3$  it's  $1 + \sqrt{2}$

- 5.7 A square matrix  $\mathbf{A} := [a_{jk}]$  is called **strictly diagonally dominant** if  $|a_{jj}| > \sum_{k \neq j} |a_{jk}|$  for each  $j = 1, \dots, n$ . If  $\mathbf{A}$  strictly diagonally dominant, show that  $\mathbf{A}$  is invertible.

By the Gerschgorin Theorem we know  $|\lambda - a_{jj}| \leq \sum_{j \neq k} |a_{jk}|$

We have  $\lambda - a_{jj} > -\sum_j |a_{jk}| \mapsto \text{I}$

We already have that  $|a_{jj}| > \sum_{k \neq j} |a_{jk}| \implies a_{jj} - \sum_{k \neq j} |a_{jk}| > 0 \mapsto \text{II}$

From I and II we get  $\lambda > 0$  hence the matrix is invertible

- 5.8 Let  $\mathbf{A} \in \mathbb{K}^{n \times n}$ . Define  $\alpha_2 := \max\{\|\mathbf{A}\mathbf{x}\| : \|\mathbf{x}\| = 1\}$ ,  $\alpha_\infty := \max\{\sum_{k=1}^n |a_{jk}| : j = 1, \dots, n\}$  and  $\alpha_1 := \max\{\sum_{j=1}^n |a_{jk}| : k = 1, \dots, n\}$ , where  $\mathbf{A} := [a_{jk}]$ . Show that  $|\lambda| \leq \min\{\alpha_2, \alpha_\infty, \alpha_1\}$  for every eigenvalue  $\lambda$ .

consider  $\lambda$  to be max of all eigen value

$$\alpha_2 \geq \|\mathbf{Ax}\| = \|\lambda\mathbf{x}\| = |\lambda|$$

By the Gerschgorin Theorem we know  $|\lambda - a_{jj}| \leq \sum_{j \neq k} |a_{jk}|$

$$||\lambda| - |a_{jj}|| \leq |\lambda - a_{jj}| \leq \sum_{j \neq k} |a_{jk}|$$

$$||\lambda| - |a_{jj}|| \leq \sum_{j \neq k} |a_{jk}| \implies |\lambda| - |a_{jj}| \leq \sum_{j \neq k} |a_{jk}|$$

$$|\lambda| = |a_{jj}| + \sum_{j \neq k} |a_{jk}| \leq \alpha_\infty$$

Eigen values of  $\mathbf{A}$  and  $\mathbf{A}^T$  are same and performing same operations as we did above we can say  $|\lambda| \leq \alpha_1$

Other method (An Important General result):

Let  $(\lambda, \mathbf{x})$  be eigen pair s.t  $\rho(\mathbf{A}) = \max |\lambda|$

Find  $\mathbf{y} \neq 0$  s.t  $\mathbf{xy}^*$  is a non zero matrix,  $\|\cdot\|$  is a matrix norm

$$\lambda\mathbf{x} = \mathbf{Ax} \implies \lambda\mathbf{xy}^* = \mathbf{Axy}^* \implies |\lambda|\|\mathbf{xy}^*\| = \|\mathbf{Axy}^*\| \leq \|\mathbf{A}\|\|\mathbf{xy}^*\| \implies \rho(\mathbf{A}) \leq \|\mathbf{A}\|$$

- 5.9 Let  $\mathbf{x}, \mathbf{y} \in \mathbb{K}^{n \times 1}$ . Prove the **parallelogram law**:  $\|\mathbf{x} + \mathbf{y}\|^2 + \|\mathbf{x} - \mathbf{y}\|^2 = 2\|\mathbf{x}\|^2 + 2\|\mathbf{y}\|^2$ . In case  $\mathbf{x}$  and  $\mathbf{y}$  are both nonzero, prove the **cosine law**, which says that  $\|\mathbf{x} - \mathbf{y}\|^2 = \|\mathbf{x}\|^2 + \|\mathbf{y}\|^2 - 2\|\mathbf{x}\|\|\mathbf{y}\|\cos\theta$ , where the angle  $\theta \in [0, \pi]$  between nonzero  $\mathbf{x}$  and  $\mathbf{y}$  is defined to be  $\cos^{-1}(\Re \langle \mathbf{x}, \mathbf{y} \rangle / \|\mathbf{x}\|\|\mathbf{y}\|)$ .

Part.a) You need to use  $\|\mathbf{x} + \mathbf{y}\|^2 = \langle \mathbf{x} + \mathbf{y}, \mathbf{x} + \mathbf{y} \rangle =$

$$\langle \mathbf{x}, \mathbf{x} + \mathbf{y} \rangle + \langle \mathbf{y}, \mathbf{x} + \mathbf{y} \rangle = \langle \mathbf{x}, \mathbf{x} \rangle + \langle \mathbf{x}, \mathbf{y} \rangle + \langle \mathbf{y}, \mathbf{x} \rangle + \langle \mathbf{y}, \mathbf{y} \rangle \text{ and}$$

Similarly for the other term  $\|\mathbf{x} - \mathbf{y}\|^2 = \langle \mathbf{x} - \mathbf{y}, \mathbf{x} - \mathbf{y} \rangle =$

$$\langle \mathbf{x}, \mathbf{x} - \mathbf{y} \rangle + \langle -\mathbf{y}, \mathbf{x} - \mathbf{y} \rangle = \langle \mathbf{x}, \mathbf{x} \rangle - \langle \mathbf{x}, \mathbf{y} \rangle - \langle \mathbf{y}, \mathbf{x} \rangle + \langle \mathbf{y}, \mathbf{y} \rangle$$

Part.b)  $(\Re \langle \mathbf{x}, \mathbf{y} \rangle) = \|\mathbf{x}\|\|\mathbf{y}\|\cos\theta$  where  $\theta \in [0, \pi]$

## 6 Tutorial 6 (on Lectures 14, 15 and 16)

6.1 Orthonormalize the following ordered subsets of  $\mathbb{K}^{4 \times 1}$ .

(i)  $(\mathbf{e}_1, \mathbf{e}_1 + \mathbf{e}_2, \mathbf{e}_1 + \mathbf{e}_2 + \mathbf{e}_3, \mathbf{e}_1 + \mathbf{e}_2 + \mathbf{e}_3 + \mathbf{e}_4)$

(ii)  $(\mathbf{e}_1 + \mathbf{e}_2 + \mathbf{e}_3 + \mathbf{e}_4, -\mathbf{e}_1 + \mathbf{e}_2, -\mathbf{e}_1 + \mathbf{e}_3, -\mathbf{e}_1 + \mathbf{e}_4)$ .

6.2 Use the Gram-Schmidt Orthogonalization Process to orthonormalize the ordered subset

$$([1 \ -1 \ 2 \ 0]^\top, [1 \ 1 \ 2 \ 0]^\top, [3 \ 0 \ 0 \ 1]^\top)$$

and obtain an ordered orthonormal set  $(\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3)$ . Also, find  $\mathbf{u}_4$  such that  $(\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3, \mathbf{u}_4)$  is an ordered orthonormal basis for  $\mathbb{K}^{4 \times 1}$ . Express the vector  $[1 \ -1 \ 1 \ -1]^\top$  as a linear combination of these four basis vectors.

Let  $W$  be the subspace of  $\mathbb{K}^{4 \times 1}$  spanned by the vectors  $\mathbf{x}_1 := [1 \ -1 \ 2 \ 0]^\top$ ,  $\mathbf{x}_2 := [1 \ 1 \ 2 \ 0]^\top$  and  $\mathbf{x}_3 := [3 \ 0 \ 0 \ 1]^\top$ . Let us apply the G-S OP.

$$\text{Let } u_1 := \frac{\mathbf{x}_1}{\|\mathbf{x}_1\|} = \frac{[1 \ -1 \ 2 \ 0]^\top}{\sqrt{6}}$$

$$, u_2 := \frac{\mathbf{x}_2 - P_{u_1}(\mathbf{x}_2)}{\|\mathbf{x}_2 - P_{u_1}(\mathbf{x}_2)\|} = \frac{[1 \ 5 \ 2 \ 0]^\top}{\sqrt{30}}$$

$$u_3 := \frac{\mathbf{x}_3 - P_{u_1}(\mathbf{x}_3) - P_{u_2}(\mathbf{x}_3)}{\|\mathbf{x}_3 - P_{u_1}(\mathbf{x}_3) - P_{u_2}(\mathbf{x}_3)\|} = \frac{[12 \ 0 \ -6 \ 5]^\top}{\sqrt{205}}$$

You can check for yourself that  $\{u_1, u_2, u_3\}$  is an orthonormal basis

To extend  $\{u_1, u_2, u_3\}$  to an orthonormal basis for  $V := \mathbb{K}^{4 \times 1}$ , we look for  $u_4 := [\alpha_1 \ \alpha_2 \ \alpha_3 \ \alpha_4]^\top$  which is orthogonal to the set  $\{x_1, x_2, x_3\}$ . Try on your own

6.3 Show that  $\mathbf{A} \in \mathbb{K}^{n \times n}$  is unitary if and only if its rows form an orthonormal subset of  $\mathbb{K}^{1 \times n}$ .

6.4 Let  $E := (\mathbf{e}_1, \dots, \mathbf{e}_n)$  be the standard basis for  $\mathbb{K}^{n \times 1}$ , and let  $F := (\mathbf{u}_1, \dots, \mathbf{u}_n)$  be an orthonormal basis for  $\mathbb{K}^{n \times 1}$ . If  $I$  denotes the identity map from  $\mathbb{K}^{n \times 1}$  to  $\mathbb{K}^{n \times 1}$ , then show that the matrix  $\mathbf{M}_E^F(I)$  is unitary.

6.5 Let  $\mathbf{A} \in \mathbb{C}^{n \times n}$  and let  $\lambda$  be an eigenvalue of  $\mathbf{A}$ . Show that  $p(\lambda)$  is an eigenvalue of  $p(\mathbf{A})$  for every polynomial  $p(t)$ .

6.6 Suppose  $\mathbf{A} \in \mathbb{C}^{3 \times 3}$  satisfies  $\mathbf{A}^3 - 6\mathbf{A}^2 + 11\mathbf{A} = 6\mathbf{I}$ .

If  $5 \leq \det \mathbf{A} \leq 7$ , determine the eigenvalues of  $\mathbf{A}$ .

Is  $\mathbf{A}$  diagonalizable?

6.7 Let  $\mathbf{A} \in \mathbb{K}^{n \times n}$ , and let  $\lambda_1, \dots, \lambda_n$  be the eigenvalues of  $\mathbf{A}$  with a corresponding orthonormal set of eigenvectors  $\mathbf{u}_1, \dots, \mathbf{u}_n$ . Show that  $\mathbf{A} = \lambda_1 \mathbf{u}_1 \mathbf{u}_1^* + \dots + \lambda_n \mathbf{u}_n \mathbf{u}_n^*$ . ( $\mathbf{xy}^*$  = outer product of  $\mathbf{x}, \mathbf{y}$ )

6.8 Let  $\mathbf{A} \in \mathbb{K}^{n \times n}$ , and  $\lambda \in \mathbb{K}$ .

(i) Show that  $\lambda$  is an eigenvalue of  $\mathbf{A}$  if and only if  $\bar{\lambda}$  is an eigenvalue of  $\mathbf{A}^*$ .

(ii) Let  $\mathbf{A}$  be unitary. Show that  $\|\mathbf{Ax}\| = \|\mathbf{x}\|$  for all  $\mathbf{x} \in \mathbb{K}^{n \times 1}$ . If  $\lambda$  is an eigenvalue of  $\mathbf{A}$ , then show that  $|\lambda| = 1$ .

(iii) Let  $\mathbb{K} = \mathbb{C}$  and let  $\mathbf{A}$  skew self-adjoint. If  $\lambda$  is an eigenvalue of  $\mathbf{A}$ , then show that  $i\lambda \in \mathbb{R}$ .

- 6.9 Let  $\mathbf{A} := [a_{jk}] \in \mathbb{C}^{n \times n}$ , and let  $\lambda_1, \dots, \lambda_n$  be the eigenvalues of  $\mathbf{A}$ , counting algebraic multiplicities. Show that  $\mathbf{A}$  is normal  $\iff \sum_{1 \leq j, k \leq n} |a_{jk}|^2 = \sum_{j=1}^n |\lambda_j|^2$ .
- 6.10 A matrix  $\mathbf{A} \in \mathbb{K}^{n \times n}$  is called **nilpotent** if there is  $m \in \mathbb{N}$  such that  $\mathbf{A}^m = \mathbf{O}$ . If  $\mathbf{A}$  is upper triangular with all diagonal entries equal to 0, then show that  $\mathbf{A}$  is nilpotent. Further, if  $\mathbf{A} \in \mathbb{C}^{n \times n}$ , then show that  $\mathbf{A}$  is nilpotent if and only if 0 is the only eigenvalue of  $\mathbf{A}$ .

## 7 Tutorial 7 (on Lectures 17, 18 and 19)

- 7.1 Let  $\mathbf{A} \in \mathbb{C}^{n \times n}$ . Show that  $\mathbf{A}$  is self-adjoint if and only if  $\mathbf{A}$  is normal and all eigenvalues of  $\mathbf{A}$  are real.
- 7.2 State and prove a spectral theorem for skew self-adjoint matrices with complex entries.
- 7.3 Find an orthonormal basis for  $\mathbb{K}^{4 \times 1}$  consisting of eigenvectors of

$$\mathbf{A} := \begin{bmatrix} -1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & -1 & -4 \\ 0 & 0 & -4 & -1 \end{bmatrix}.$$

Write down a spectral representation of  $\mathbf{A}$ , and find  $\mathbf{A}^7 \mathbf{x}$ , where  $\mathbf{x} := [1 \ 2 \ 3 \ 4]^T$

- 7.4 A self adjoint matrix  $\mathbf{A}$  is called **positive definite** if  $\langle \mathbf{A} \mathbf{x}, \mathbf{x} \rangle > 0$  for all nonzero  $\mathbf{x} \in \mathbb{K}^{n \times 1}$ . Show that a self-adjoint matrix is positive definite if and only if all eigenvalues of  $\mathbf{A}$  are positive.
- 7.5 Real numbers  $\alpha_1, \alpha_2, \alpha_3, \alpha_4$  are placed on the 4 corners of a square in clockwise order initially. In the next step,
- $\alpha_1$  is replaced by  $\beta_1 := (\alpha_2 + \alpha_4)/2$ ,
- $\alpha_2$  is replaced by  $\beta_2 := (\alpha_3 + \alpha_1)/2$ ,
- $\alpha_3$  is replaced by  $\beta_3 := (\alpha_4 + \alpha_2)/2$  and
- $\alpha_4$  is replaced by  $\beta_4 := (\alpha_1 + \alpha_3)/2$ .

Find the numbers placed on the corners of the square after  $k$  such steps. (Hint: Find a set of 4

orthonormal eigenvectors of the matrix  $\mathbf{A} := \begin{bmatrix} 0 & 1/2 & 0 & 1/2 \\ 1/2 & 0 & 1/2 & 0 \\ 0 & 1/2 & 0 & 1/2 \\ 1/2 & 0 & 1/2 & 0 \end{bmatrix}$  and use the spectral theorem for  $\mathbf{A}$ .)

- 7.6 Let  $Q$  be a real quadratic form, and let  $\mathbf{A}$  denote the associated real symmetric matrix. Let  $g(\mathbf{x}) = \|\mathbf{x}\|^2 - 1$ . If  $Q$  has a local extremum at a vector  $\mathbf{x}_0$  subject to the constraint  $g(\mathbf{x}) = 0$ , then show that  $\mathbf{x}_0$  is a unit eigenvector of  $\mathbf{A}$ , and the corresponding eigenvalue  $\lambda_0$  is the corresponding Lagrange multiplier and equals  $Q(\mathbf{x}_0)$ .

In particular, the largest eigenvalue of  $\mathbf{A}$  is the constrained maximum and the smaller eigenvalue of  $\mathbf{A}$  is the constrained minimum of  $Q$ .

- 7.7 Which quadric surface does the equation  $7x^2 + 7y^2 - 2z^2 + 20yz - 20zx - 2xy - 36 = 0$  describe? Explain by reducing the quadratic form involved to a diagonal form. Express  $x, y, z$  in terms of the new coordinates  $u, v, w$ .

$Q(x) = 7x^2 + 7y^2 - 2z^2 + 20yz - 20zx - 2xy - 36$  to a diagonal form.

Here  $\mathbf{A} := \begin{bmatrix} 7 & -1 & -10 \\ -1 & 7 & 10 \\ -10 & 10 & -2 \end{bmatrix}$  is the associated matrix.

Hence the equation of the given quadric surface becomes

$$\begin{bmatrix} x & y & z \end{bmatrix} \begin{bmatrix} 7 & -1 & -10 \\ -1 & 7 & 10 \\ -10 & 10 & -2 \end{bmatrix} \begin{bmatrix} x & y & z \end{bmatrix}^T - 36 = 0$$

Now find eigen value and corresponding eigen vector and then using GSOP find  $\{u_1, u_2, u_3\}$

Change of variable from  $\begin{bmatrix} x & y & z \end{bmatrix}^T = \mathbf{C} \begin{bmatrix} u & v & w \end{bmatrix}^T$ , where  $\mathbf{C} = [\mathbf{u}_1 \mathbf{u}_2 \mathbf{u}_3]$

Characteristic polynomial is  $\lambda^3 - 12\lambda - 180\lambda + 1296 = 0$

Eigen values are  $\{18, -12, 6\}$

Eigen vectors are  $\{[-1 \ 1 \ 1]^T, [1 \ -1 \ 2]^T, [1 \ 1 \ 0]^T\}$

By GSOP Orthonormal eigen vectors are  $\left\{ \frac{[-1 \ 1 \ 1]^T}{\sqrt{3}}, \frac{[1 \ -1 \ 2]^T}{\sqrt{6}}, \frac{[1 \ 1 \ 0]^T}{\sqrt{2}} \right\}$

$$\mathbf{Q}_D(u, v, w) = 18u^2 - 12v^2 + 6w^2$$

The quadric surface reduces to  $18u^2 - 12v^2 + 6w^2 = 36$

Since eigen values two positive, one negative its **1 sheeted hyperboloid**

$$\begin{bmatrix} x & y & z \end{bmatrix}^T = \mathbf{C} \begin{bmatrix} u & v & w \end{bmatrix}^T$$

$$\begin{bmatrix} x & y & z \end{bmatrix}^T = \begin{bmatrix} \frac{-1}{\sqrt{3}} & \frac{1}{\sqrt{6}} & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{3}} & \frac{-1}{\sqrt{6}} & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{3}} & \frac{2}{\sqrt{6}} & 0 \end{bmatrix} \begin{bmatrix} u & v & w \end{bmatrix}^T$$

$$x = \frac{-1}{\sqrt{3}}u + \frac{1}{\sqrt{6}}v + \frac{1}{\sqrt{2}}w, \quad y = \frac{1}{\sqrt{3}}u + \frac{-1}{\sqrt{6}}v + \frac{1}{\sqrt{2}}w, \quad z = \frac{1}{\sqrt{3}}u + \frac{2}{\sqrt{6}}v + 0w$$

7.8 Let  $Y$  be a subspace of  $\mathbb{K}^{n \times 1}$ . Show that  $(Y^\perp)^\perp = Y$ .

Let  $\{u_1, u_2, \dots, u_k\}$  and  $\{w_1, w_2, \dots, w_l\}$  be an orthonormal basis for subspace respectively  $Y$  and  $Y^\perp$

Every vector  $\mathbf{s} \in (Y^\perp)^\perp$  will be perpendicular to  $w_j \forall j=1$  to  $l$

Any vector can be represented in the form of  $\mathbf{s} = \mathbf{x} + \mathbf{y}$  where  $x \in Y$  and  $y \in Y^\perp$

$$\langle \mathbf{s}, w_j \rangle = 0 \forall j$$

$$\langle x + y, \sum \alpha_j w_j \rangle = 0 \forall j$$

Since  $\langle x, w_j \rangle = 0$  and  $y \in Y^\perp \exists$  some  $\alpha_j$  s.t.  $y = \sum \alpha_j w_j$

$$\langle \sum \alpha_j w_j, \sum \alpha_j w_j \rangle = 0 \forall j$$

It gives us all  $\alpha_j$ 's are zero, so  $y=0$ , then  $s \in Y$

Hence every vector in  $(Y^\perp)^\perp$  lies in  $Y$ , i.e  $(Y^\perp)^\perp \subseteq Y$

Now let  $\mathbf{x} \in Y$  then  $x = \sum \alpha_j u_j$

$$\langle x, w_i \rangle = \langle \sum \alpha_j u_j, w_i \rangle = 0$$

So  $x \in W^\perp \implies x \in (Y^\perp)^\perp \implies Y \subseteq (Y^\perp)^\perp$

Hence  $Y = (Y^\perp)^\perp$

7.9 Let  $\mathbf{A}$  be a self-adjoint matrix. If  $\langle \mathbf{A}\mathbf{x}, \mathbf{x} \rangle = 0$  for all  $\mathbf{x} \in \mathbb{K}^{n \times 1}$ , then show that  $\mathbf{A} = \mathbf{O}$ . Deduce that



if  $\|\mathbf{A}^* \mathbf{x}\| = \|\mathbf{A} \mathbf{x}\|$  for all  $\mathbf{x} \in \mathbb{K}^{n \times 1}$ , then  $\mathbf{A}$  is a normal matrix, and if  $\|\mathbf{A} \mathbf{x}\| = \|\mathbf{x}\|$  for all  $\mathbf{x} \in \mathbb{K}^{n \times 1}$ , then  $\mathbf{A}$  is a unitary matrix.

Part i

Self adjoint  $\mathbf{A}^* = \mathbf{A}$  and  $\langle \mathbf{A} \mathbf{x}, \mathbf{x} \rangle = \mathbf{x}^* \mathbf{A}^* \mathbf{x} = \mathbf{x}^* \mathbf{A} \mathbf{x} = 0, \forall \mathbf{x} \in \mathbb{K}^{n \times 1}$

Choose  $\mathbf{x} = \mathbf{e}_k$  you get  $a_{kk} = 0 \forall k = 1$  to  $n$

Choose  $\mathbf{x} = \mathbf{e}_k + \mathbf{e}_j$  and we get  $a_{kj} + a_{jk} = 0 \forall k, j = 1$  to  $n$  and  $k \neq j$

Choose  $\mathbf{x} = \mathbf{e}_k - i\mathbf{e}_j$  and we get  $a_{kj} - a_{jk} = 0 \forall k, j = 1$  to  $n$  and  $k \neq j$

Hence  $\mathbf{A} = \mathbf{O}$

Part ii) Choose  $\mathbf{B} = \mathbf{A} \mathbf{A}^* - \mathbf{A}^* \mathbf{A}, \mathbf{B} = \mathbf{B}^*$

$$\|\mathbf{A}^* \mathbf{x}\| = \|\mathbf{A} \mathbf{x}\|$$

Square on both sides

$$\|\mathbf{A}^* \mathbf{x}\|^2 = \|\mathbf{A} \mathbf{x}\|^2 \implies \langle \mathbf{A}^* \mathbf{x}, \mathbf{A}^* \mathbf{x} \rangle = \langle \mathbf{A} \mathbf{x}, \mathbf{A} \mathbf{x} \rangle$$

$$(\mathbf{A}^* \mathbf{x})^* \mathbf{A}^* \mathbf{x} = \langle \mathbf{x}, \mathbf{A}^* \mathbf{A} \mathbf{x} \rangle \implies \mathbf{x}^* \mathbf{A} \mathbf{A}^* \mathbf{x} = \mathbf{x}^* \mathbf{A}^* \mathbf{A} \mathbf{x}$$

We get  $\langle \mathbf{B} \mathbf{x}, \mathbf{x} \rangle = 0$

Hence  $\mathbf{A}$  is normal

Part iii) Choose  $\mathbf{B} = \mathbf{A} \mathbf{A}^* - \mathbf{I}, \mathbf{B} = \mathbf{B}^*$

$$\|\mathbf{A} \mathbf{x}\| = \|\mathbf{x}\|$$

Square on both sides

$$\|\mathbf{A} \mathbf{x}\|^2 = \|\mathbf{x}\|^2 \implies \langle \mathbf{A} \mathbf{x}, \mathbf{A} \mathbf{x} \rangle = \langle \mathbf{x}, \mathbf{x} \rangle$$

$$\langle \mathbf{x}, \mathbf{A}^* \mathbf{A} \mathbf{x} \rangle = \langle \mathbf{x}, \mathbf{x} \rangle \implies \mathbf{x}^* \mathbf{A}^* \mathbf{A} \mathbf{x} = \mathbf{x}^* \mathbf{x}$$

We get  $\langle \mathbf{B} \mathbf{x}, \mathbf{x} \rangle = 0$

Hence  $\mathbf{A}$  is unitary

7.10 Let  $E$  be a nonempty subset of  $\mathbb{K}^{n \times 1}$ .

(i) If  $E$  is not closed, then show that there is  $\mathbf{x} \in \mathbb{K}^{n \times 1}$  such that no best approximation to  $\mathbf{x}$  exists from  $E$ .

(ii) If  $E$  is convex, then show that for every  $\mathbf{x} \in \mathbb{K}^{n \times 1}$ , there is at most one best approximation to  $\mathbf{x}$  from  $E$ .

Part i

**Definition:** A non empty subset  $E$  of  $\mathbb{K}^{n \times 1}$  is not closed, then  $\exists \mathbf{x} \in \mathbb{K}^{n \times 1}$  and a sequence  $(x_n)$  of points of  $E$  s.t  $x_n \mapsto x$ , but  $x \notin E$

Suppose  $x$  had a best approximation from  $E$ , say  $y$  then

$$\|x - y\| \leq \|x - u\| \forall u \in E$$

$$\|x - y\| \leq \|x - x_n\| \forall n \in N$$

Now by passing limit we get  $\|x - y\| \leq 0 \implies \|x - y\| = 0 \implies x = y$

But it is a contradiction since  $x \notin E$  and  $y \in E$

Part ii

**Definition:** A set  $E$  is convex if  $u, v \in E \iff (1-\lambda)u + \lambda v \in E \forall \lambda \in [0, 1]$

Suppose there are  $u_1$  and  $u_2$  two best approximations from  $E$  to  $\mathbf{x}$  s.t  $\|\mathbf{x} - u_i\| = \lambda$

Since  $E$  is convex the line joining  $u_1$  and  $u_2$  lies in  $E$

$$\|\mathbf{x} - \frac{u_1 + u_2}{2}\| = \|\frac{\mathbf{x} - u_1}{2} + \frac{\mathbf{x} - u_2}{2}\| \leq \|\frac{\mathbf{x} - u_1}{2}\| + \|\frac{\mathbf{x} - u_2}{2}\| = \lambda$$

But then it contradicts the definition of best approximation

Hence atmost one approximation

- 7.11 Find  $\mathbf{x} := [x_1, x_2]^T \in \mathbb{R}^{2 \times 1}$  such that the straight line  $t = x_1 + x_2 s$  fits the data points  $(-1, 2)$ ,  $(0, 0)$ ,  $(1, -3)$  and  $(2, -5)$  best in the 'least squares' sense.

The data points are  $(s, t) = (-1, 2), (0, 0), (1, -3)$  and  $(2, -5)$

$$\mathbf{A}\mathbf{x} = \mathbf{b} \implies \begin{bmatrix} 1 & -1 \\ 1 & 0 \\ 1 & 1 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 2 \\ 0 \\ -3 \\ -5 \end{bmatrix}$$

To minimise, we need to find the best approximation to the vector  $\mathbf{b}$  from the column space  $\mathbf{C}(\mathbf{A})$

$$\mathbf{A} = [\mathbf{y}_1 \mathbf{y}_2] \text{ and } \mathbf{u}_1 = \frac{\mathbf{y}_1}{\|\mathbf{y}_1\|} = \frac{[1 \ 1 \ 1 \ 1]^T}{\sqrt{4}} \text{ and } \mathbf{u}_2 = \frac{[-1 \ 0 \ 1 \ 2]^T}{\sqrt{6}}$$

$$\text{Best approximation is } \langle \mathbf{u}_1, \mathbf{b} \rangle \mathbf{u}_1 + \langle \mathbf{u}_2, \mathbf{b} \rangle \mathbf{u}_2 = [1 \ -1.5 \ -4 \ -6.5]^T$$

Now solve  $x_1 - x_2 = -1$  and  $x_1 + x_2 = -4$  gives  $x_1 = -2.5, x_2 = -1.5$

- 7.12. Let  $Q(x_1, \dots, x_n) := \sum_{j=1}^n \sum_{k=1}^n \alpha_{jk} x_k \bar{x}_j$ , where  $\alpha_{jk} \in \mathbb{C}$ , be a **complex quadratic form**. Show that there is a unique self-adjoint matrix  $\mathbf{A}$  such that

$$Q(x_1, \dots, x_n) = \mathbf{x}^* \mathbf{A} \mathbf{x} \quad \text{for all } \mathbf{x} := [x_1 \ \dots \ x_n]^T \in \mathbb{C}^{n \times 1}.$$

$$Q(x_1, \dots, x_n) = \sum_{j=1}^n \sum_{k=1}^n \alpha_{jk} x_k \bar{x}_j = \bar{Q} = \sum_{j=1}^n \sum_{k=1}^n \overline{\alpha_{jk}} \bar{x}_k x_j$$

The variable  $j, k$  are dummy variable for the summation

$$Q = \sum_{j=1}^n \sum_{k=1}^n \overline{\alpha_{kj}} \bar{x}_j x_k \implies \alpha_{jk} = \overline{\alpha_{kj}}$$

To prove uniqueness:

$$\text{Suppose } Q = \sum_{j=1}^n \sum_{k=1}^n \alpha_{jk} x_k \bar{x}_j = \sum_{j=1}^n \sum_{k=1}^n \beta_{jk} x_k \bar{x}_j$$

Choose  $\mathbf{x} = \mathbf{e}_k$  you get  $\alpha_{kk} = \beta_{jj} \forall k = 1$  to  $n$  where  $k=j$

Choose  $\mathbf{x} = \mathbf{e}_k + \mathbf{e}_j$  and we get  $\alpha_{kj} + \alpha_{jk} = \beta_{kj} + \beta_{jk} \forall k, j = 1$  to  $n$  and  $k \neq j$

Choose  $\mathbf{x} = \mathbf{e}_k - i\mathbf{e}_j$  and we get  $\alpha_{kj} - \alpha_{jk} = \beta_{kj} - \beta_{jk} \forall k, j = 1$  to  $n$  and  $k \neq j$

Hence unique

- 7.13. Let  $\mathbf{A} \in \mathbb{C}^{n \times n}$  be normal, and let  $\mu_1, \dots, \mu_k$  be the distinct eigenvalues of  $\mathbf{A}$ . Let  $Y_j := \mathcal{N}(\mathbf{A} - \mu_j \mathbf{I})$  for  $j = 1, \dots, k$ . Show that  $\mathbb{C}^{n \times 1} = Y_1 \oplus \dots \oplus Y_k$ . Also, if  $P_j$  is the orthogonal projection onto  $Y_j$ , then show that  $P_1 + \dots + P_k = I$ ,  $P_i P_j = O$  if  $i \neq j$  and  $\mathbf{A}\mathbf{x} = \mu_1 P_1(\mathbf{x}) + \dots + \mu_k P_k(\mathbf{x})$  for all  $\mathbf{x} \in \mathbb{C}^{n \times 1}$ .

Since  $\mathbf{A}$  is normal, it is unitarily diagonalizable. So  $\mathbb{C}^n$  has a basis of eigen vectors of  $\mathbf{A}$ . The form would be  $\{u_{11}, \dots, u_{1g_1}, \dots, u_{k1}, u_{k2}, \dots, u_{kg_k}\}$  where  $g_j = \text{geometric multiplicity of } \mu_j = \dim \mathcal{N}(\mathbf{A} - \mu_j \mathbf{I})$  and  $u_{j1}, \dots, u_{jg_j}$  are eigen vectors of eigen value  $\mu_j$  for  $j=1,2,\dots,k$ . We know  $g_1 + g_2 + \dots + g_k = n$  and since  $\mathbf{A}$  is diagonalizable. So given any  $\mathbf{x} \in \mathbb{C}^n$  we can write

$$\mathbf{x} = \sum_{j=1}^k \sum_{l=1}^{g_j} \alpha_{jl} u_{jl} = y_1 + y_2 + \dots + y_k$$

where  $y_j = \sum_{l=1}^{g_j} \alpha_{jl} u_{jl} \in Y_j = \mathcal{N}(\mathbf{A} - \mu_j \mathbf{I})$ . Thus  $\mathbb{C}^n = Y_1 + \dots + Y_k$ . Since coefficients  $\alpha_{jl}$  are uniquely determined by  $\mathbf{x}$ ,  $\alpha_{jl} = \langle u_{jl}, \mathbf{x} \rangle$ , hence the decomposition is unique and we get  $\mathbb{C}^n = Y_1 \oplus \dots \oplus Y_k$ .

The orthogonal projection map is defined by  $P_j(\mathbf{x}) = y_j$  ( $1 \leq j \leq k$ ) and it is clear that  $\mathbf{x} = P_1(\mathbf{x}) + \dots + P_k(\mathbf{x}) \forall \mathbf{x} \in \mathbb{C}^n$ . So  $P_1 + \dots + P_k = I$ . Also  $P_i P_j = P_i(y_j) = 0$  if  $i \neq j$ . Thus  $P_i P_j = 0$  if  $i \neq j$ . Finally since  $y_j \in \mathcal{N}(\mathbf{A} - \mu_j \mathbf{I})$ , we get  $\mathbf{A}y_j = \mu_j y_j$ .

$$\mathbf{A}\mathbf{x} = \mathbf{A}y_1 + \dots + \mathbf{A}y_k$$

$$\mathbf{A}\mathbf{x} = \mu_1 y_1 + \dots + \mu_k y_k$$

$$\mathbf{A}\mathbf{x} = \mu_1 P_1(\mathbf{x}) + \dots + \mu_k P_k(\mathbf{x}) \forall \mathbf{x} \in \mathbb{C}^n$$

## 8 Tutorial 8 (on Lectures 20 and 21)

8.1 State why the following sets are not subspaces:

- (i) All  $m \times n$  matrices with nonnegative entries.
- (ii) All solutions of the differential equation  $xy' + y = 3x^2$ .
- (iii) All solutions of the differential equation  $y' + y^2 = 0$ .
- (iv) All invertible  $n \times n$  matrices.

- (a)  $\alpha \mathbf{M}$  if  $\alpha < 0$  then it doesn't lie in subspace
- (b)  $xy'_1 + y_1 = 3x^2$  and  $xy'_2 + y_2 = 3x^2$  and  $x(y_1 + y_2)' + y_1 + y_2 - 3x^2 = 3x^2 \neq 0$  it doesn't lie in subspace
- (c)  $y'_1 + y_1^2 = 0$  and  $y'_2 + y_2^2 = 0$  and  $(y_1 + y_2)' + (y_1 + y_2)^2 = 2y_1y_2 \neq 0$  it doesn't lie in subspace
- (d)  $\det(\mathbf{A}), \det(\mathbf{B}) \neq 0$  but  $\det(\mathbf{A} + \mathbf{B})$  can be zero if  $\det(\mathbf{A}) = -\det(\mathbf{B})$  its not invertible and hence doesnt lie

8.2 Let  $V$  denote the vector space of all polynomial functions on  $\mathbb{R}$  of degree at most  $n$ . Are the following subsets of  $V$  in fact subspaces of  $V$ ? (i)  $W_1 := \{p \in V : p(0) = 0\}$ ,

(ii)  $W_2 := \{p \in V : p'(0) = 0 = p''(0)\}$ ,

(iii)  $W_3 := \{p \in V : p \text{ is an odd function}\}$ .

If so, find a spanning set for each.

8.3 Let  $V := C([-\pi, \pi])$ . Show that  $S_1 := \{1, \cos, \sin\}$  is a linearly independent subset of  $V$ , while  $S_2 := \{1, \cos^2, \sin^2\}$  is a linearly dependent subset of  $V$ .

8.4 Let  $V := \mathbb{R}^{1 \times 2}$ , and let  $v_1 := [1 \ 0]$ ,  $v_2 := [1 \ 1]$ ,  $v_3 := [1 \ -1]$ . Explain why  $(24, 12)$  can be written as a linear combination of  $v_1, v_2, v_3$  in two different ways, namely,  $4v_1 + 16v_2 + 4v_3$  and  $6v_1 + 15v_2 + 3v_3$ .

8.5 Let  $n \in \mathbb{N}$ . Let  $W_1, W_2, W_3, W_4$  denote the subspaces of  $n \times n$  real matrices which are diagonal, upper triangular, symmetric and skew-symmetric. Find their dimensions.

8.6 Let  $V$  and  $W$  be vector spaces over  $\mathbb{K}$ . Show that  $V \times W := \{(v, w) : v \in V \text{ and } w \in W\}$  is a vector space over  $\mathbb{K}$  with componentwise addition and scalar multiplication. If  $\dim V = n$  and  $\dim W = m$ , find  $\dim V \times W$ .

8.7 Let  $\mathbf{A} := [a_{jk}] \in \mathbb{K}^{4 \times 4}$ . Define  $T : \mathbb{K}^{2 \times 2} \rightarrow \mathbb{K}^{2 \times 2}$  by

$$T\left(\begin{bmatrix} x_{11} & x_{12} \\ x_{21} & x_{22} \end{bmatrix}\right) = \begin{bmatrix} y_{11} & y_{12} \\ y_{21} & y_{22} \end{bmatrix},$$

where  $\begin{bmatrix} y_{11} & y_{12} & y_{21} & y_{22} \end{bmatrix}^\top := \mathbf{A} \begin{bmatrix} x_{11} & x_{12} & x_{21} & x_{22} \end{bmatrix}^\top$ . Show that  $T$  is linear, and find the matrix of  $T$  with respect to the ordered basis  $(\mathbf{E}_{11}, \mathbf{E}_{12}, \mathbf{E}_{21}, \mathbf{E}_{22})$  of  $\mathbb{K}^{2 \times 2}$ .

8.8 Define  $T : \mathcal{P}_2 \rightarrow \mathbb{K}^{2 \times 1}$  by

$$T(\alpha_0 + \alpha_1 t + \alpha_2 t^2) := \begin{bmatrix} \alpha_0 + \alpha_1 & \alpha_1 + \alpha_2 \end{bmatrix}^\top$$

for  $\alpha_0, \alpha_1, \alpha_2 \in \mathbb{R}$ . If  $E := (1, t, t^2)$  and  $F := (\mathbf{e}_1, \mathbf{e}_2)$ , then find  $\mathbf{M}_F^E$ . Also, if  $E' := (1, 1 + t, (1 + t)^2)$  and  $F' := (\mathbf{e}_1, \mathbf{e}_1 + \mathbf{e}_2)$ , then find  $\mathbf{M}_{F'}^{E'}$ .

8.9 (**Parallelogram law**) Let  $V$  be an inner product space. Prove that the norm on  $V$  induced by the inner product satisfies  $\|v + w\|^2 + \|v - w\|^2 = 2\|v\|^2 + 2\|w\|^2$  for all  $v, w \in V$ .

(Conversely, if there is a norm  $\|\cdot\|$  on a vector space  $V$  which satisfies the parallelogram law, then it can be shown that there is an inner product  $\langle \cdot, \cdot \rangle$  on  $V$  such that  $\langle v, v \rangle = \|v\|^2$  for all  $v \in V$ .)

8.10 For  $\mathbf{A}, \mathbf{B} \in \mathbb{K}^{m \times n}$ , define  $\langle \mathbf{A}, \mathbf{B} \rangle := \text{tr } \mathbf{A}^* \mathbf{B}$ . Show that  $\langle \cdot, \cdot \rangle$  is an inner product on  $\mathbb{K}^{m \times n}$ .

8.11 Show that

$$\left\{ \frac{1}{\sqrt{2\pi}}, \frac{\cos t}{\sqrt{\pi}}, \frac{\sin t}{\sqrt{\pi}}, \frac{\cos 2t}{\sqrt{\pi}}, \frac{\sin 2t}{\sqrt{\pi}}, \dots \right\}$$

is an orthonormal subset of  $C([-\pi, \pi])$ .

(This is the beginning of the theory of [Fourier Series](#).)

8.12 Let  $T$  be a Hermitian operator on a finite dimensional inner product space  $V$  over  $\mathbb{K}$ . Prove the following.

- (i)  $\langle T(v), v \rangle \in \mathbb{R}$  for every  $v \in V$ .
- (ii) Every eigenvalue of  $T$  is real.
- (iii) If  $\lambda \neq \mu$  are eigenvalues of  $T$  with  $v$  and  $w$  corresponding eigenvectors of  $T$ , then  $v \perp w$ .
- (iv) Let  $W$  be a subspace of  $V$  such that  $T(W) \subset W$ . Then  $T(W^\perp) \subset W^\perp$ .