

# MA 111 Tutorial 4 Solutions

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# Tutorial Solutions

3.

## Theorem 1 (Green's Theorem)

- 1 Let  $D$  be a bounded region in  $R^2$  with a positively oriented boundary  $C$  consisting of a finite number of non-intersecting simple closed piecewise continuously differentiable curves.
- 2 Let  $\Omega$  be an open set in  $R^2$  such that  $D \cup C \subset \Omega$  and let  $F_1 : \Omega \rightarrow R$  and  $F_2 : \Omega \rightarrow R$  be  $C^1$  functions.

Then the following holds:

$$\int_C F_1 dx + F_2 dy = \iint_D \left( \frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right) dx dy$$

Observe that the integral is defined on  $R^2$  which is simply connected.

Thus we may apply Green's Theorem to get:

$$F_1 = 2xe^{-y} \implies \frac{\partial F_1}{\partial y} = -2xe^{-y} \quad F_2 = 2y - x^2e^{-y} \implies \frac{\partial F_2}{\partial x} = -2xe^{-y}$$

Thus the integrand:  $\left( \frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right)$  is identically zero

$\implies$  line integral is path-independent.

## Tutorial Solutions Contd.

5.

$C_1$  be any line segment on the line:  $x = 2y$

Take  $C_2$  to be the path  $:(x, 0) | x \in [0, \frac{\pi}{2}]$

6. (a)

Evaluating the integrand of Green's Theorem:

$$\left( \frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right)$$

$$= (ye^{xy} + ye^{xy} + xy^2e^{xy}) - (2ye^{xy} + xy^2e^{xy}) = 0.$$

Thus,  $\mathbf{F}$  is conservative. Evaluating its scalar function:

$$\frac{\partial f}{\partial y} = F_2 \implies f(x, y) = \int F_2 dy = ye^{xy} + g(x)$$

$$\text{Similarly: } \frac{\partial f}{\partial x} = F_1 \implies f(x, y) = \int F_1 dx = ye^{xy} + h(y)$$

Equating both equations, we find that  $g(x) = h(y) \implies g(x) = h(y) = c$  where  $c$  is a constant.

## Tutorial Solutions Contd.

**7. (a)** Using the method above, find that a possible scalar function  $f$  is given by:  $f(x, y, z) = x^2yz - \cos(x) + c$

Now, applying Fundamental Theorem of Calculus:  $\int_a^b \nabla f = f(b) - f(a)$

Define  $a = (1, 0, 0)$  and  $b = (-1, 0, \pi^4)$

$$\implies \int_a^b F = \int_a^b \nabla f = f(b) - f(a) = -\cos(1) + \cos(1) = 0$$

**9.(a)**

$$\frac{\partial F_1}{\partial y} = \frac{\partial F_2}{\partial x} = \frac{y^2 - x^2}{(x^2 + y^2)^2}$$

**9.(b)**

Construct a path  $C$  given by  $c(t) = (\cos(t), \sin(t))$ . Recall that the line integral of a field  $\mathbf{F}$  along  $C$  is given by:

$$\int_C F(c(t)) \cdot c'(t) dt = \int_{t=0}^{2\pi} (-\sin(t), \cos(t)) \cdot (-\sin(t), \cos(t)) dt$$

$$\implies \int_C F(c(t)) \cdot c'(t) dt = \int_{t=0}^{2\pi} \sin^2(t) + \cos^2(t) dt = 2\pi$$

**9.(c)**

Therefore,  $\mathbf{F}$  is clearly not conservative despite satisfying the derivative condition due to domain not being simply connected(owing to  $(0,0)$ )

**10.** To show that  $\mathbf{F} = f(r)\mathbf{r}$  is a conservative field, we will show that  $\mathbf{F} = \nabla g$  where  $g$  is a scalar function.

Construct  $g(r, \theta, \phi) = \int_0^r sf(s) \cdot ds$

Thus, by Fundamental Theorem of Calculus:  $\frac{\partial g}{\partial x} = rf(r) \frac{\partial r}{\partial x} = xf(r)$

By symmetry, we can claim that:  $\frac{\partial g}{\partial y} = yf(r)$  and  $\frac{\partial g}{\partial z} = zf(r)$ .

$$\nabla g = \left( \frac{\partial g}{\partial x}, \frac{\partial g}{\partial y}, \frac{\partial g}{\partial z} \right) = (x\hat{i} + y\hat{j} + z\hat{k})f(r) = \mathbf{r}f(r) = \mathbf{F}$$

$$r = (x^2 + y^2 + z^2)^{1/2},$$

$$\frac{\partial r}{\partial x} = \frac{x}{r}, \quad \frac{\partial r}{\partial y} = \frac{y}{r}, \quad \frac{\partial r}{\partial z} = \frac{z}{r}.$$

If  $\mathbf{F}$  is to be  $\nabla \phi$  for some  $\phi$ , then we must have  $\phi_x = f(r)x, \phi_y = f(r)y, \phi_z = f(r)z$ ; that is,

$$\begin{aligned}\phi_x = xf(r) &= \frac{x}{r}rf(r) = \frac{\partial r}{\partial x}rf(r), \\ \phi_y = yf(r) &= \frac{y}{r}rf(r) = \frac{\partial r}{\partial y}rf(r), \\ \phi_z = zf(r) &= \frac{z}{r}rf(r) = \frac{\partial r}{\partial z}rf(r).\end{aligned}$$

Now it can be seen that  $\phi(x, y, z) = \int_{t_0}^r tf(t)dt$ , with some  $t_0$  fixed, satisfies all the desired equations.

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