

Week1

There are total 3 node named as
name , **roll**, **student_data**

Name node publishes both names to topic **name_publish** , Message type **string** , rate **1Hz**

Roll node publishes both roll no to topic **roll_publish** , Message type **string** , rate **1Hz**

Student_data subscribes to topic **name_publish** and **roll_publish** , Message type **string** , rate **1Hz**

Rosgraph :

