

CIS 700: “algorithms for Big Data”

Lecture 6: Graph Sketching

Slides at <http://grigory.us/big-data-class.html>

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Sketching Graphs?

- We know how to sketch vectors: $v \rightarrow Mv$
- How about sketching graphs?
- $G(V, E) \equiv A_G$ (adjacency matrix): $A_G \rightarrow MA_G$
- Sketch columns of A_G
- $n = |V|, m = |E|$
- $O(\text{poly}(\log n))$ sketch per vertex / $\tilde{O}(n)$ total
 - Check connectivity
 - Check bipartiteness
- As always, space rather than dimension. Why?

Graph Streams

- Semi-streaming model: [Muthukrishnan '05; Feigenbaum, Kannan, McGregor, Suri, Zhang'05]
 - Graph defined by the stream of edges e_1, \dots, e_m
 - Space $\tilde{O}(n)$, edges processed in order
 - Connectivity is easy on $\tilde{O}(n)$ space for insertion-only
- Dynamic graphs:
 - Stream of insertion/deletion updates
 $+ e_{i_1}, -e_{i_2}, \dots, -e_{i_t}$ (assume sequence is correct)
 - Resulting graph has edge e_i if it wasn't deleted after the last insertion
- Linear sketching dynamic graphs:

$$MA_{G \setminus e} = MA_G - MA_e$$

Distributed Computing

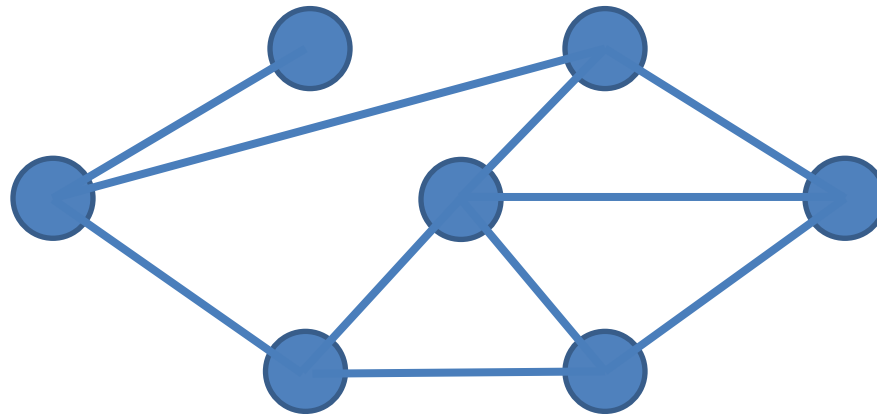
- Linear sketches for distributed processing
- S servers with $o(m)$ memory:
 - Send m/S edges (E_1, \dots, E_S) to each server
 - Compute sketches ME_1, \dots, ME_S locally
 - Send sketches to a central server
 - Compute $MA_G = \sum_i^S ME_i$
- M has to have a small representation (same issue as in streaming)

Connectivity

- **Thm.** Connectivity is sketchable in $\tilde{O}(n)$ space
- **Framework:**
 - Take existing connectivity algorithm (Boruvka)
 - Sketch $A_G \rightarrow MA_G$
 - Run Boruvka on MA_G
- Important that the sketch is homomorphic w.r.t the algorithm

Part 1: Parallel Connectivity (Boruvka)

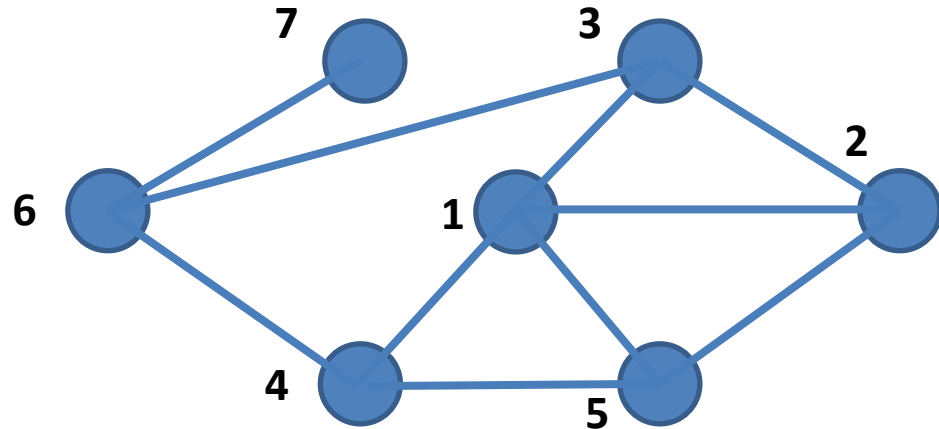
- Repeat until no edges left:
 - For each vertex, select any incident edge
 - Contract selected edges



- **Lemma:** process converges in $O(\log n)$ steps

Part 2: Graph Representation

- For a vertex i let a_i be a vector in $\mathbb{R}^{\binom{n}{2}}$
- Non-zero entries for edges (i, j)
 - $a_i[i, j] = 1$ if $j > i$
 - $a_i[i, j] = -1$ if $i < j$



- Example:

$$a_1 = (1, 1, 1, 1, 0, \dots, 0)$$

$$a_2 = (-1, 0, 0, 0, 0, 0, 1, 0, 1, \dots, 0)$$

$\{1,2\}, \{1,3\}, \{1,4\}, \{1,5\}, \{1,6\}, \{1,7\}, \{2,3\}, \{2,4\}, \{2,5\}, \dots$

- Lem: For any $S \subseteq V$ $\text{supp}(\sum_{i \in S} a_i) = E(S, V \setminus S)$

Part 3: L_0 -Sampling

- There is a distribution over $M \in \mathbb{R}^{d \times m}$ with $d = O(\log^2 m)$ such w.p. 9/10 that $\forall a \in \mathbb{R}^m$:
 $Ca \rightarrow e \in \text{supp}(a)$

[Cormode, Muthukrishnan, Rozenbaum'05; Jowhari, Saglam, Tardos '11]

- Constant probability suffices — still $O(\log n)$ Boruvka iterations

Final Algorithm

- Construct $\log n$ ℓ_0 -samplers for each a_i
- Run Boruvka on sketches:
 - Use $C_1 a_j$ to get an edge incident on a node j
 - For $i = 2$ to t :
 - To get incident edge on a component $S \subseteq V$ use:

$$\sum_{j \in S} C_i a_j = C_i \left(\sum_{j \in S} a_j \right) \rightarrow$$
$$\rightarrow e \in \text{supp} \left(\sum_{j \in S} a_j \right) = E(S, V \setminus S)$$

K-Connectivity

- Graph is k -connected if every cut has size $\geq k$
- **Thm:** There is a $O(nk \log^3 n)$ -size linear sketch for k -connectivity
- **Generalization:** There is an $O(n \log^5 n / \epsilon^2)$ -size linear sketch which allows to approximate all cuts in a graph up to error $(1 \pm \epsilon)$

K-connectivity Algorithm

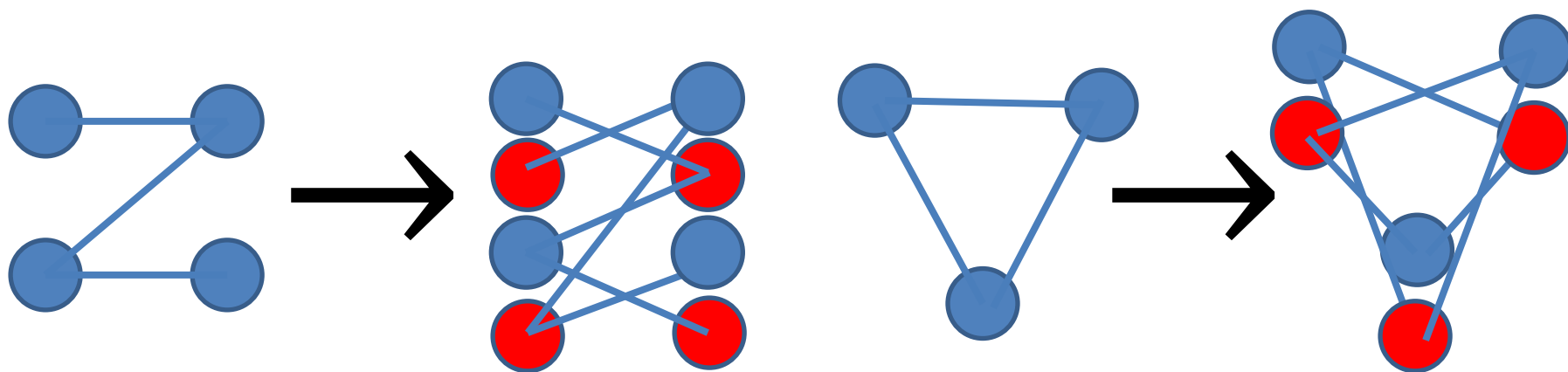
- Algorithm for k -connectivity:
 - Let F_1 be a spanning forest of $G(V, E)$
 - For $i = 2, \dots, k$
 - Let F_i be a spanning forest of $G(V, E \setminus F_1 \setminus \dots \setminus F_{i-1})$
- **Lem:** $G(V, F_1 + \dots + F_k)$ is k -connected iff $G(V, E)$ is.
- \Rightarrow Trivial
- \Leftarrow Consider a cut in $G(V, \sum_{i=1}^k F_i)$ of size $< k$
 - $\Rightarrow \exists i^*$: this cut didn't grow in step i^*
 - \Rightarrow there is a cut in $G(V, E)$ of size $< k$
 - \Rightarrow contradiction

K-connectivity Algorithm

- Construct k independent linear sketches $\{M_1A_G, M_2A_G \dots, M_kA_G\}$ for connectivity
- Run k -connectivity algorithm on sketches:
 - Use M_1A_G to get a spanning forest F_1 of G
 - Use $M_2A_G - M_2A_{F_1} = M_2(A_{G-F_1})$ to find F_2
 - Use $M_3A_G - M_3A_{F_1} - M_3A_{F_2} = M_3(A_{G-F_1-F_2})$ to find F_3
 - ...

Bipartiteness

- **Reduction:** Given G define G' where vertices $v \rightarrow (v_1, v_2)$; edges $(u, v) \rightarrow (u_1, v_2) \text{ \& } (u_2, v_1)$



- **Lem:** # connected components doubles iff the graph is bipartite.
- **Thm:** $O(n \log^3 n)$ -size linear sketch for k -connectivity (sketch G' (implicitly).)

Minimum Spanning Tree

- If $n_i = \#$ connected components in a subgraph induced by edges of weight $\leq (1 + \epsilon)^i$:

$$w(MST) \leq n - (1 + \epsilon)^r + \sum_i \lambda_i n_i \leq (1 + \epsilon)w(MST)$$

where $\lambda_i = ((1 + \epsilon)^i - (1 + \epsilon)^{i-1})$

- $cc(G) = \#$ connected components of G
- Round weights up to the nearest power of $1 + \epsilon$
- $G_i \equiv$ subgraph with edges of weight $\leq (1 + \epsilon)^i$
- Kruskal:
 - $n - cc(G_1)$ edges of weight 1
 - ...
 - $cc(G_i) - cc(G_{i-1})$ edges of weight $(1 + \epsilon)^i$

Minimum Spanning Tree

- Let $r = \log_{1+\epsilon} W$ where $W = \max$ edge weight
- Overall weight:

$$\begin{aligned} n - cc(G_1) + \sum_{i=1}^{r-1} (1 + \epsilon)^i (cc(G_i) - cc(G_{i+1})) \\ = n - (1 + \epsilon)^r + \sum_{i=1}^{r-1} ((1 + \epsilon)^i - (1 + \epsilon)^{i-1}) cc(G_i) \end{aligned}$$

- **Thm:** $(1 + \epsilon)$ -approx. MST weight can be computed with $\tilde{O}(n)$ linear sketch for $W = \text{poly}(n)$