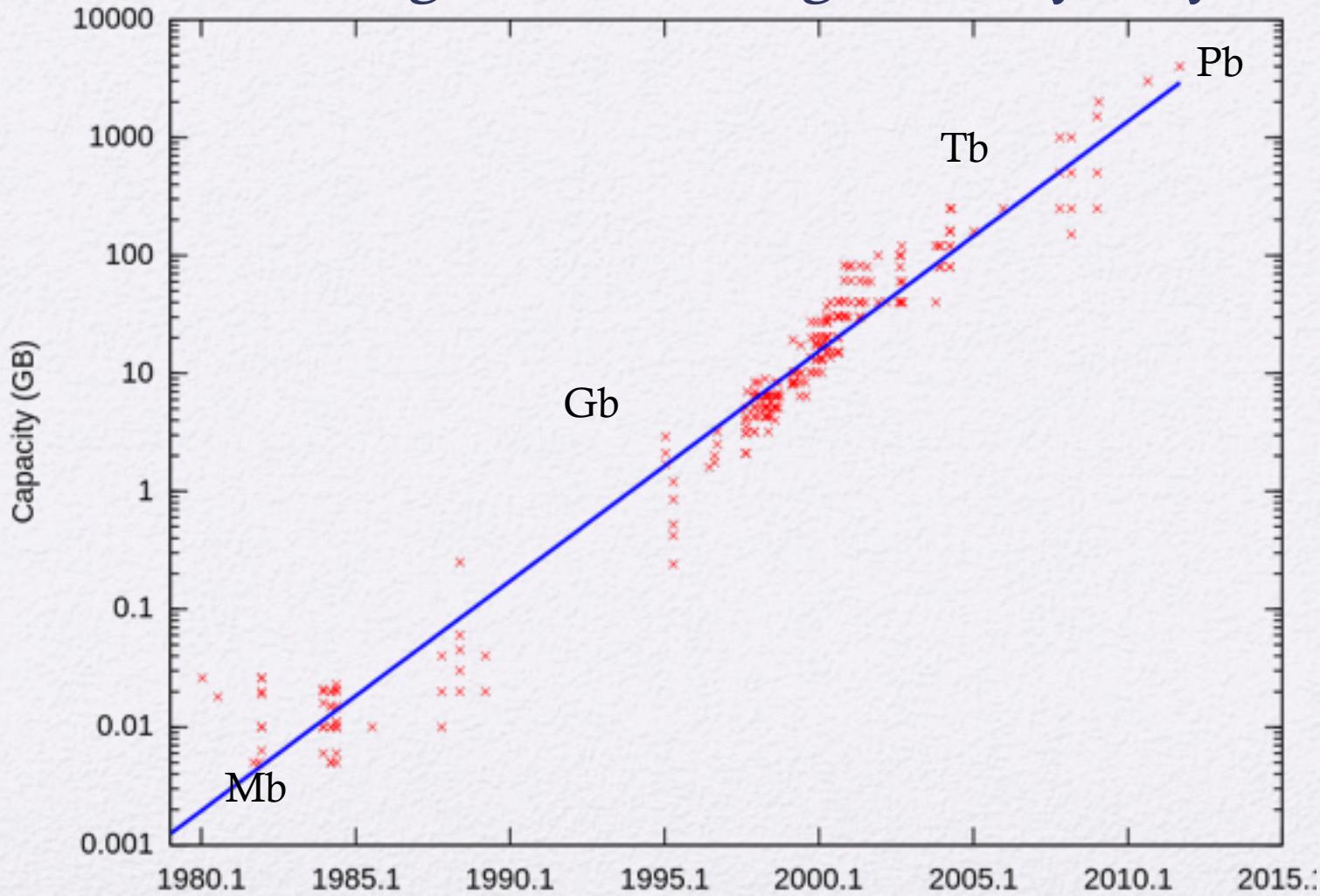


Clustering in a Few Rounds

Ravi Kumar
Google

Data

“640k ought to be enough for anybody.”



Graph mining challenges

- Can be **implicitly** defined
 - Similarities
- Nodes/edges can **change**
 - Social connections
- Can have special **properties**
 - Heavy-tailed, small-world, bipartite, ...
- Can be **noisy**
 - Some edges missing, some spurious

Why are graphs hard?

- Poor **locality** of memory access
 - Neighbors of a node can be arbitrarily located in memory
- Degree of **parallelism** change during execution
 - Can depend on sub-graph structures
- Nodes by themselves do not do much work
 - Edge interactions form the bulk of many graph algorithms

Graph stream

- Graph arrives as an **edge stream**
 - No random access to graph
 - Can be new edge or updates to existing edges
- Typically single CPU
- Very **limited** amount of RAM
 - Some cases, only Mb even for Tb+ data
 - May not be able to store any portion of the graph in memory
 - Graph size may be infinite/unknown in advance
- Ideally, make a **single pass** over the graph
 - In some cases, can take multiple rounds

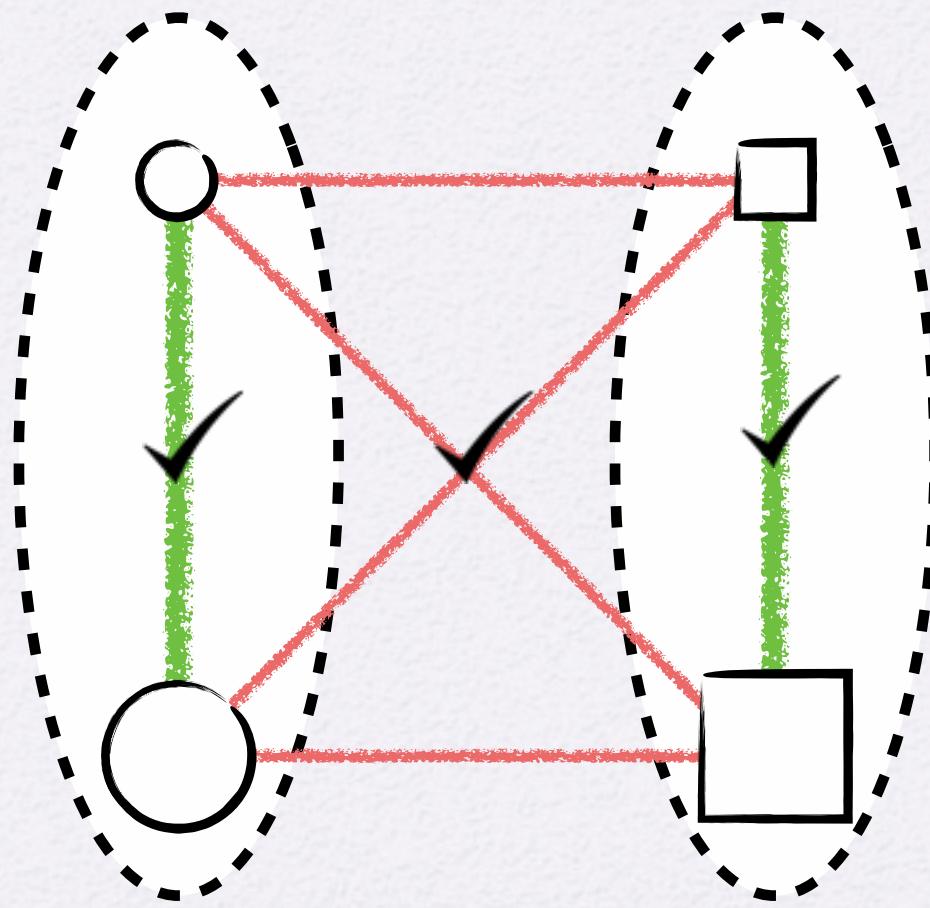
Graph clustering

- How to solve large-scale clustering problems on graphs?
- Many flavors of clustering definitions
 - k-means, k-median, densest subgraphs, correlation clustering, ..
- Focus on algorithms
 - with provable guarantees
 - that run in a small number of rounds

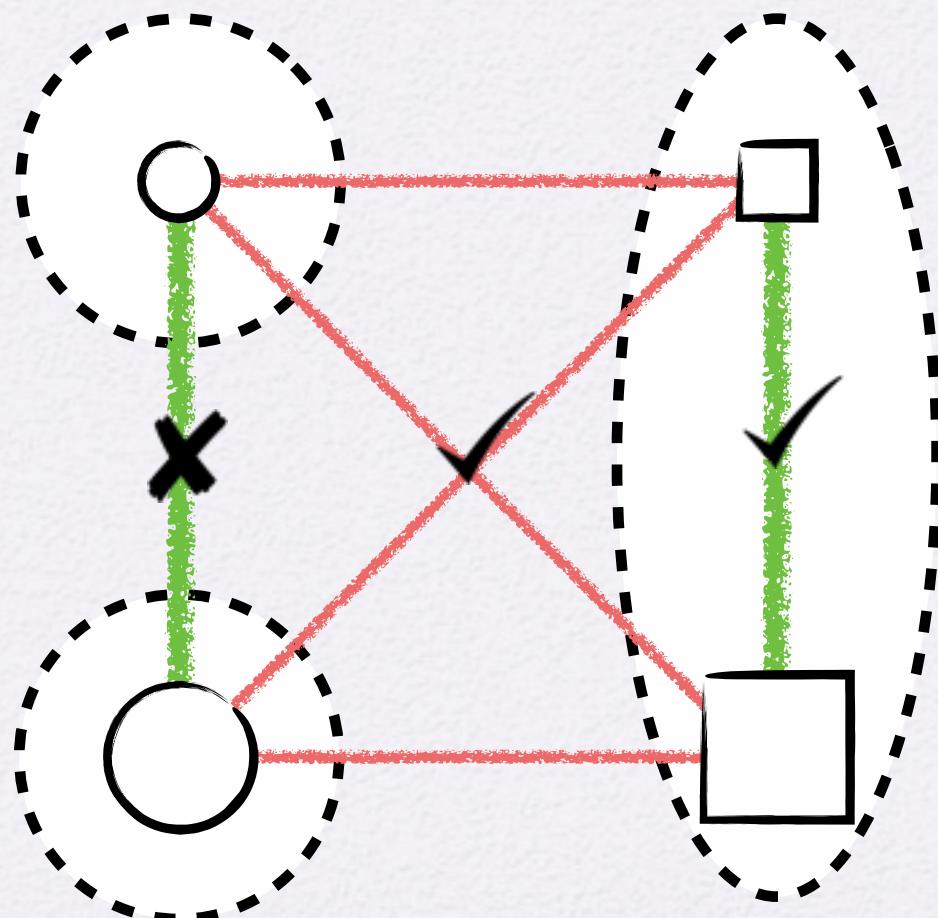
1. Correlation clustering (CC)

- Given a complete graph where each edge is +1 or -1, partition the nodes to minimize the total number of mistakes
[Bansal, A. Blum, Chawla]
- Number of clusters not specified a priori
- Often, missing edges are interpreted -1
- Machine learning / data mining applications

Eg: o mistakes



Eg: 1 mistake



The Pivot algorithm

A simple iterative algorithm

Pick a node p uniformly at random

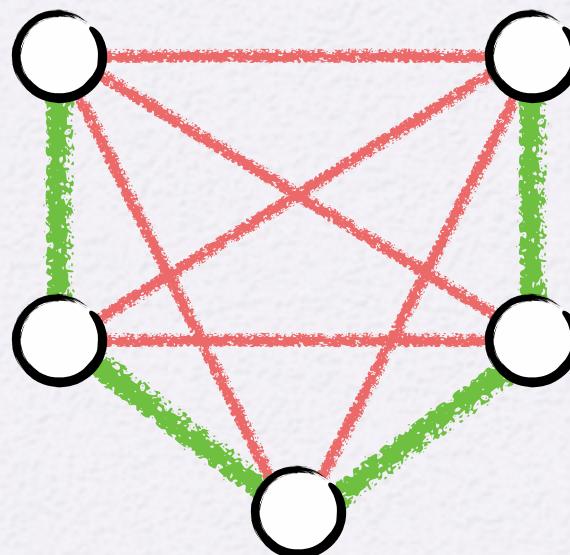
Create a cluster around p by including all nodes connected to p by a +1 edge

Delete the nodes in this cluster

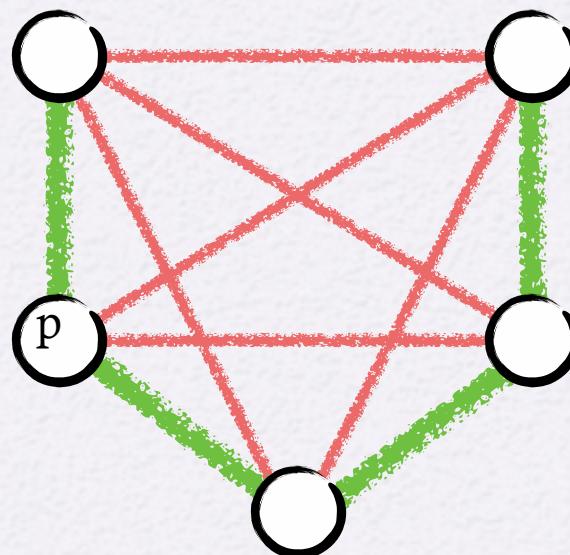
Repeat with the remaining graph

[Ailon, Charikar, Newman]

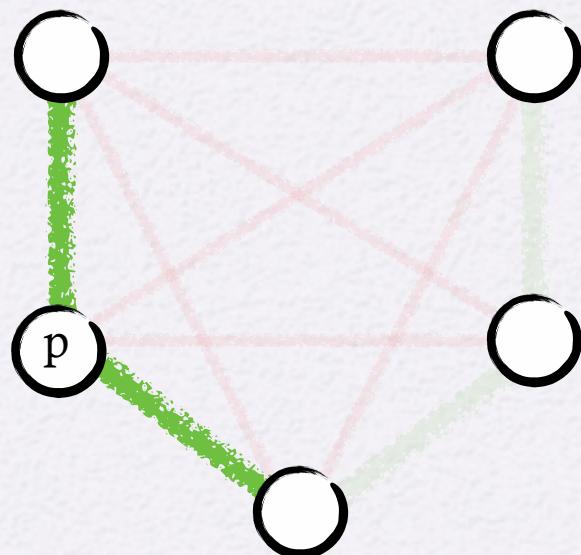
Eg: Pivot Algorithm



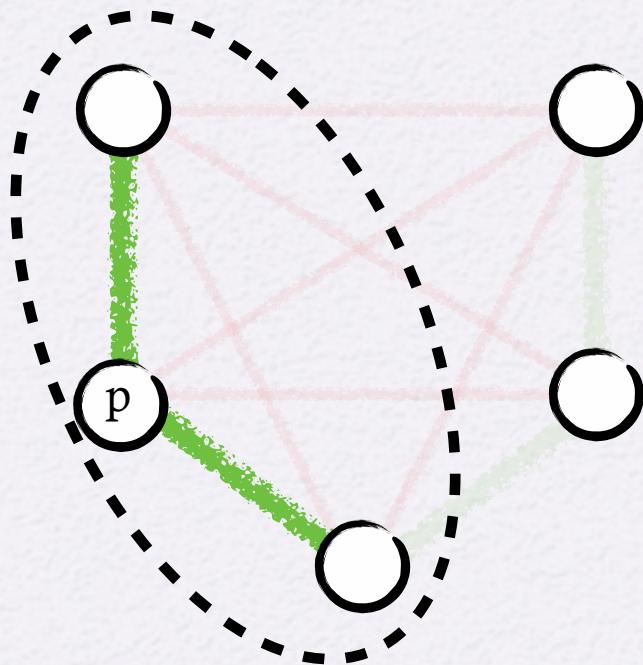
Eg: Pivot Algorithm



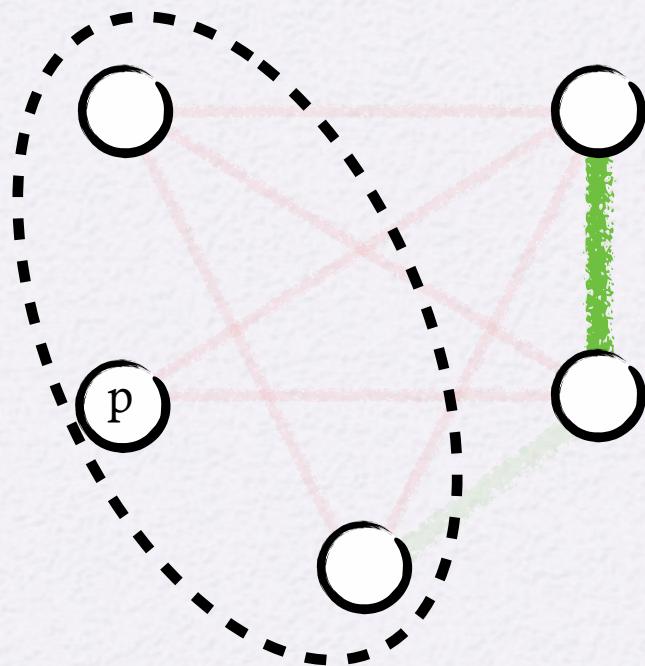
Eg: Pivot Algorithm



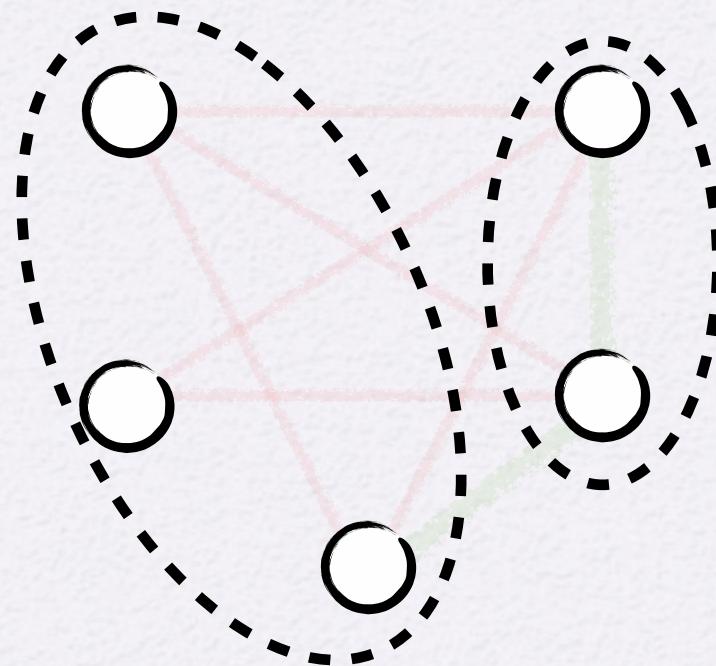
Eg: Pivot Algorithm



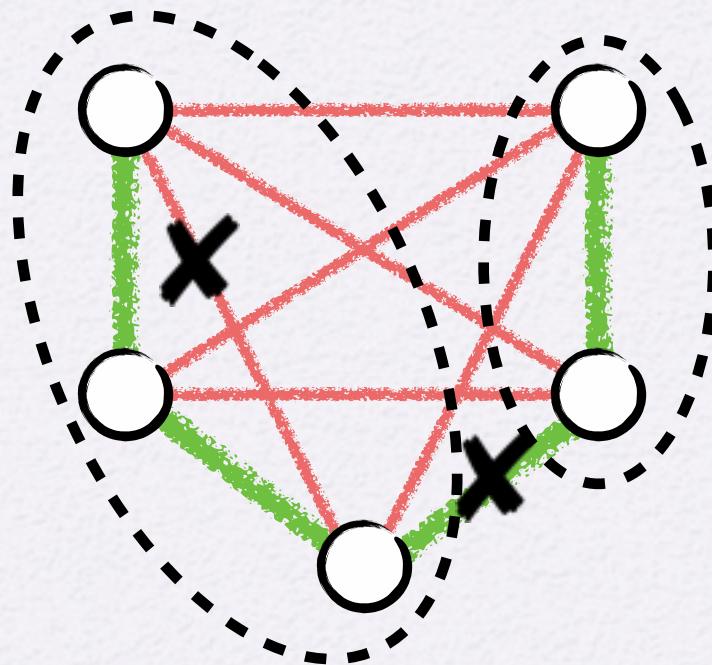
Eg: Pivot Algorithm



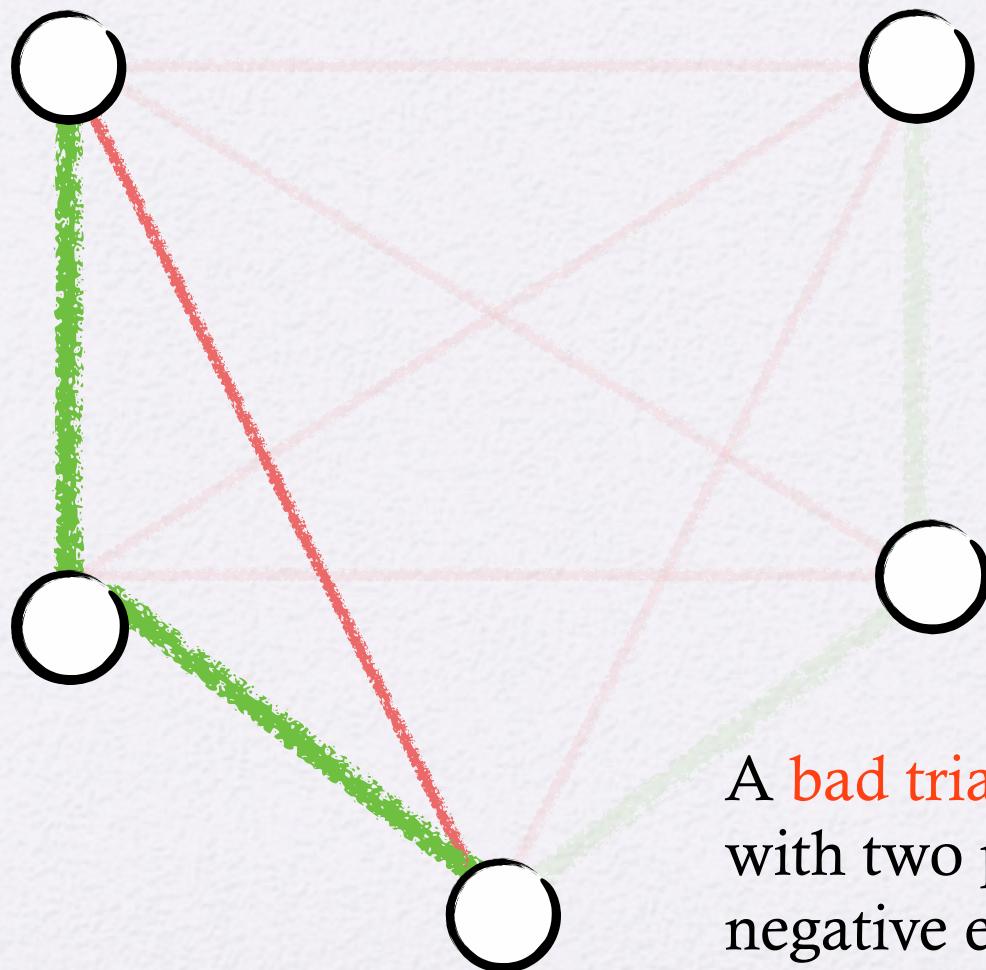
Eg: Pivot Algorithm



Eg: Pivot Algorithm



Bad triangles



A **bad triangle** is a triple of nodes with two positive edges and one negative edge

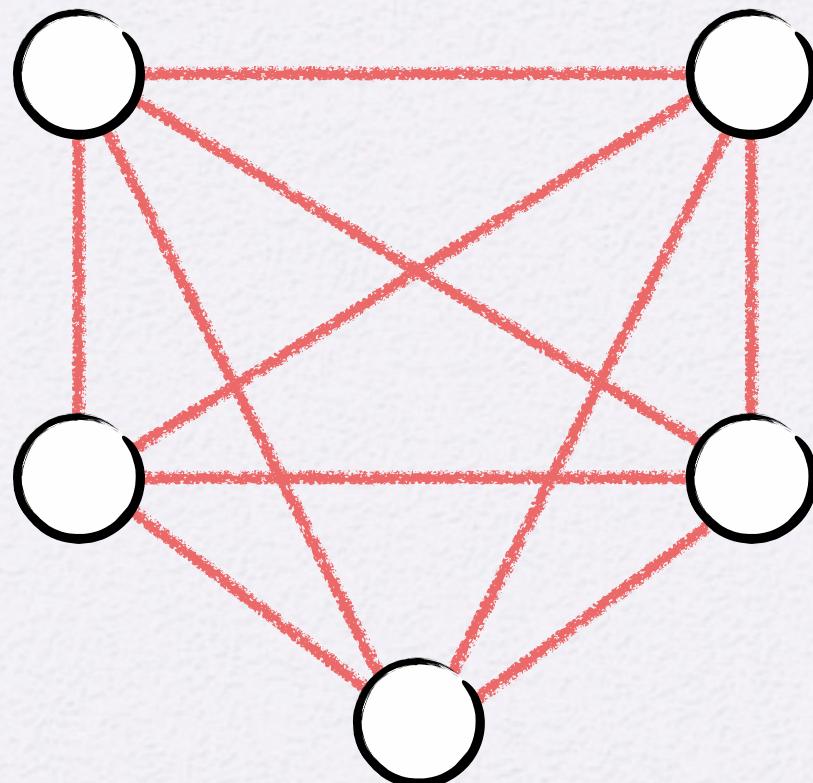
Properties

Claim [ACN]. Pivot gives (in expectation) a 3-approximation to minimizing the number of mistakes

Proof focuses on bad triangles and uses LP duality

The algorithm is inherently sequential

A bad example



Pivot takes $\Omega(n)$ rounds

Parallel Pivot

- A parallel version of Pivot Algorithm
 - runs in $O(\log^2 n)$ rounds
 - obtains a $3+\epsilon$ approximation

[Chierichetti, Dalvi, Kumar]

- Easily implemented in streaming (also Map-Reduce, Pregel, ...)

Parallel Pivot Algorithm

While the graph is not empty

 Let D^+ be the current maximum positive degree

 Activate each node independently wp ϵ/D^+

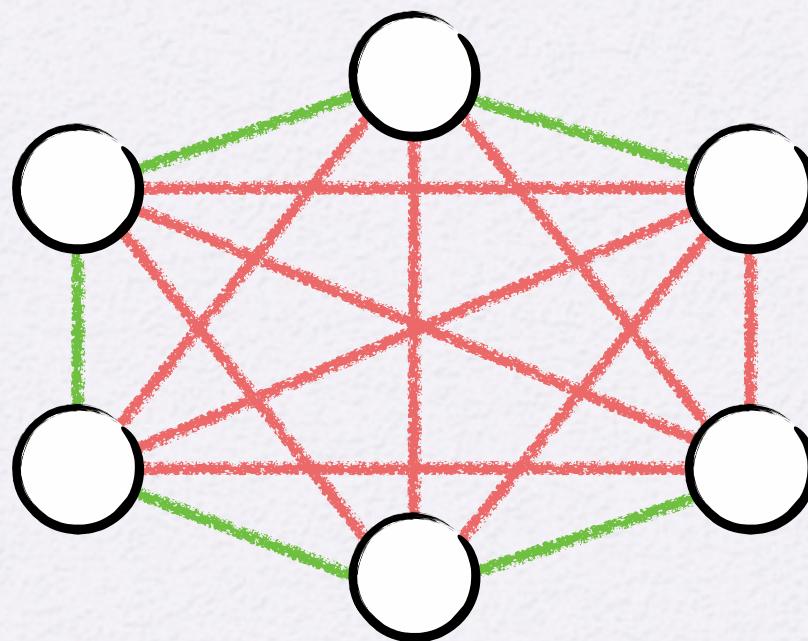
 Deactivate nodes connected to other active nodes by
 +1 edges

 The remaining nodes are **pivots**

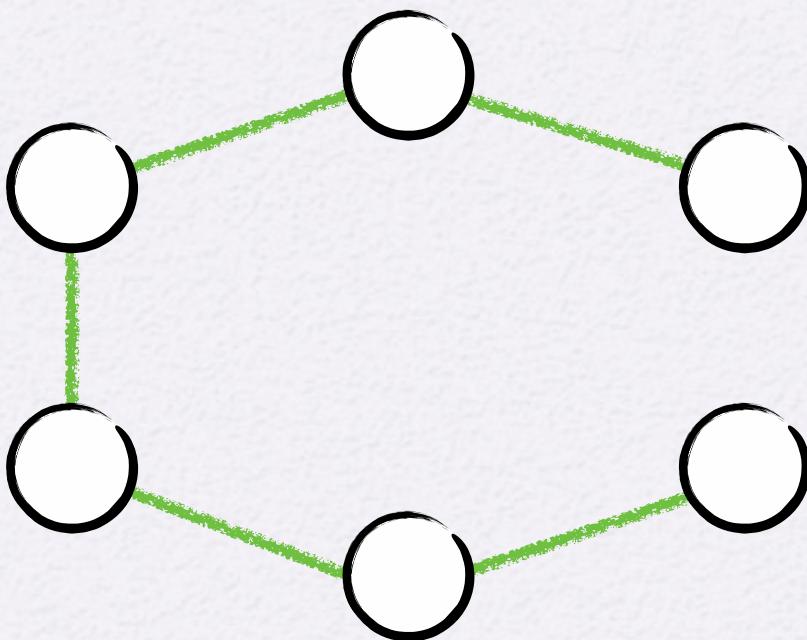
 Create cluster around each pivot as before

 Remove the clusters

Example

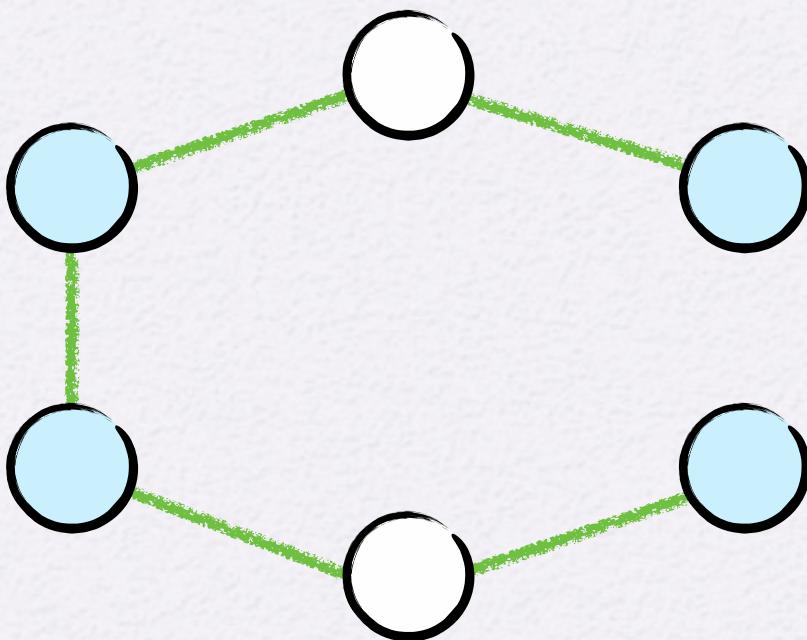


Example

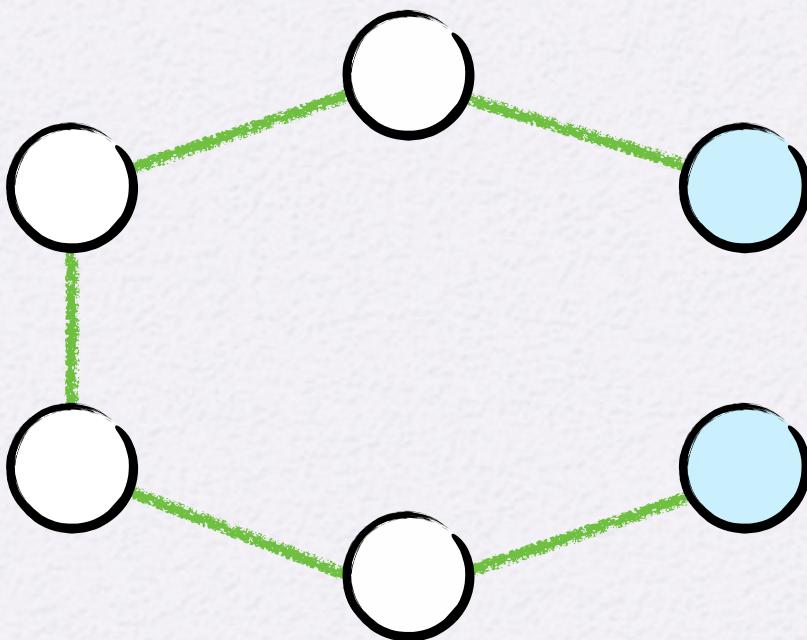


$$D^+ = 2$$

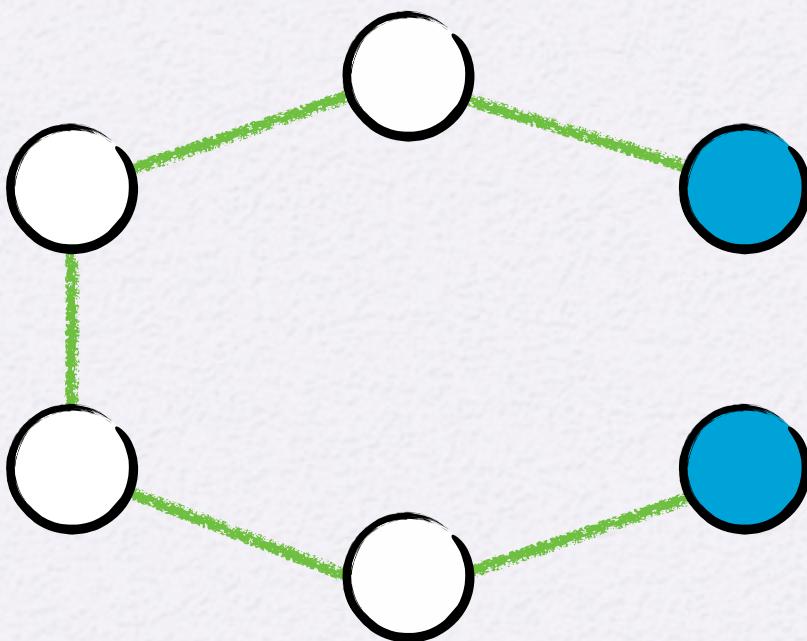
Example



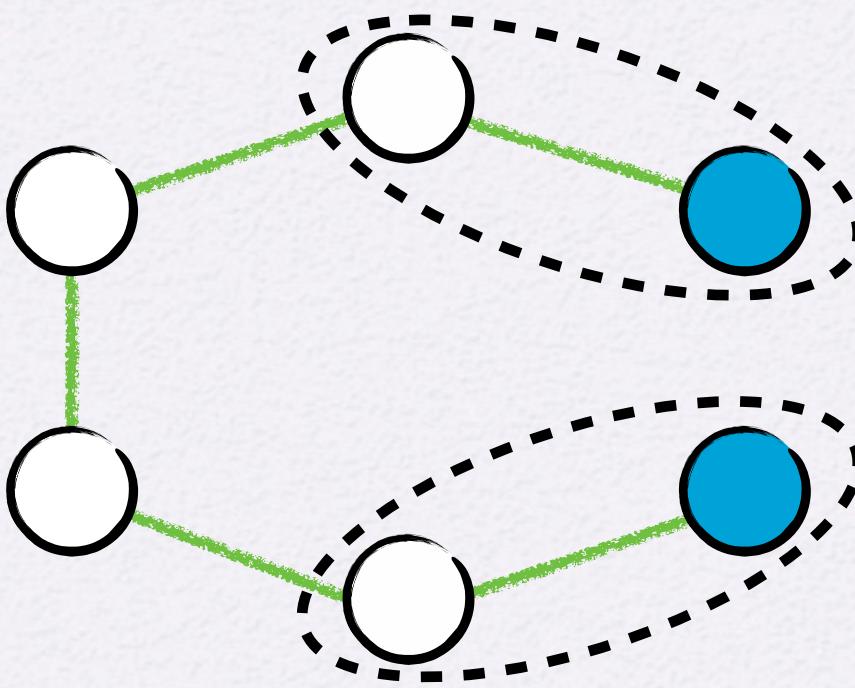
Example



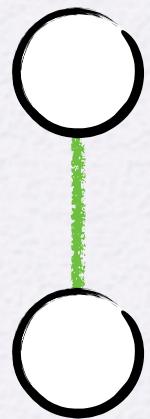
Example



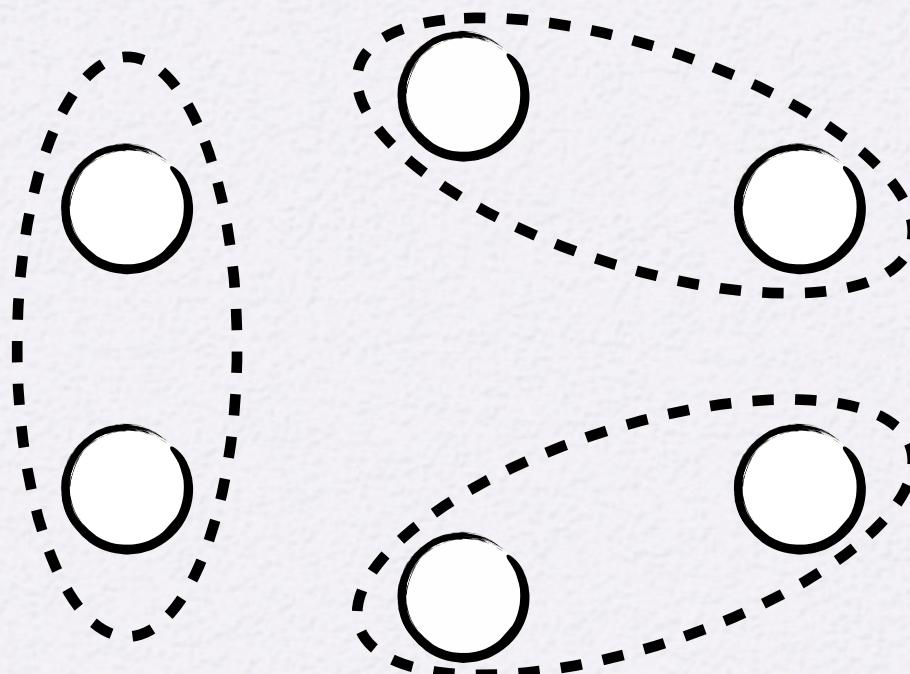
Example



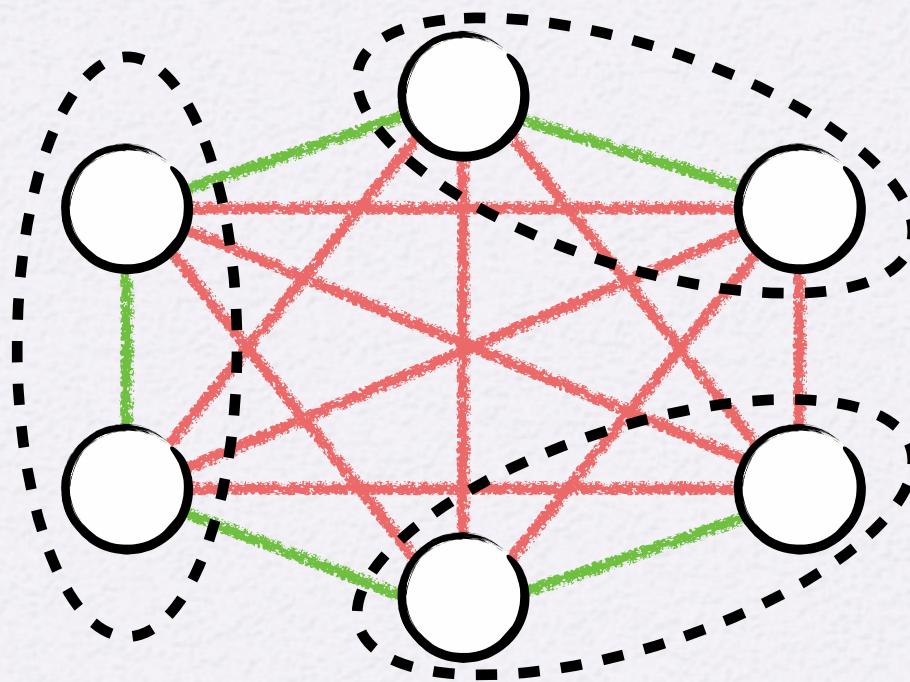
Example



Example



Example



Properties

Claim. Parallel Pivot halves the maximum degree D^+ after $(1/\varepsilon) \log n$ rounds

Algorithm terminates in $(1/\varepsilon) (\log n) (\log D^+)$ rounds

Claim. Induces a close to uniform marginal distribution of the pivots

Can extend the LP dual-based proof of [ACN] to show $3 + \varepsilon$ approximation

Halving max degree

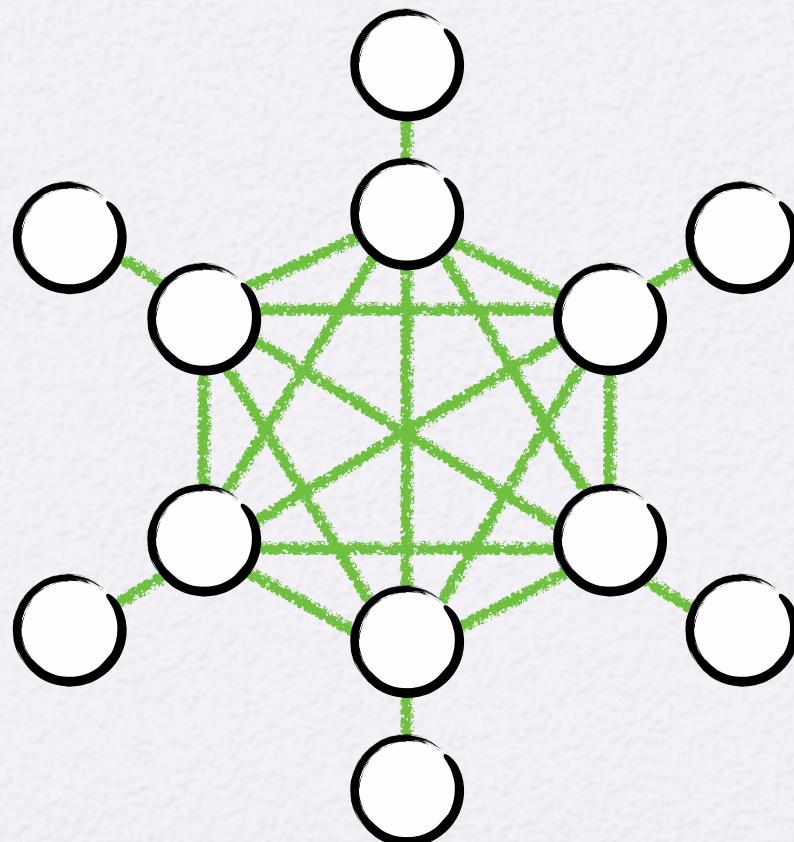
- Event $e(v)$: exactly one positive neighbor w of node v gets activated and no positive neighbor of w gets activated
 - w becomes a pivot and hence v is removed
- Key property: $\Pr[e(v)] > \varepsilon/8$ if $\deg^+(v) > D^+/2$
- After logarithmic number of rounds, either v 's positive degree halves or v will end up in a cluster

Different sampling?

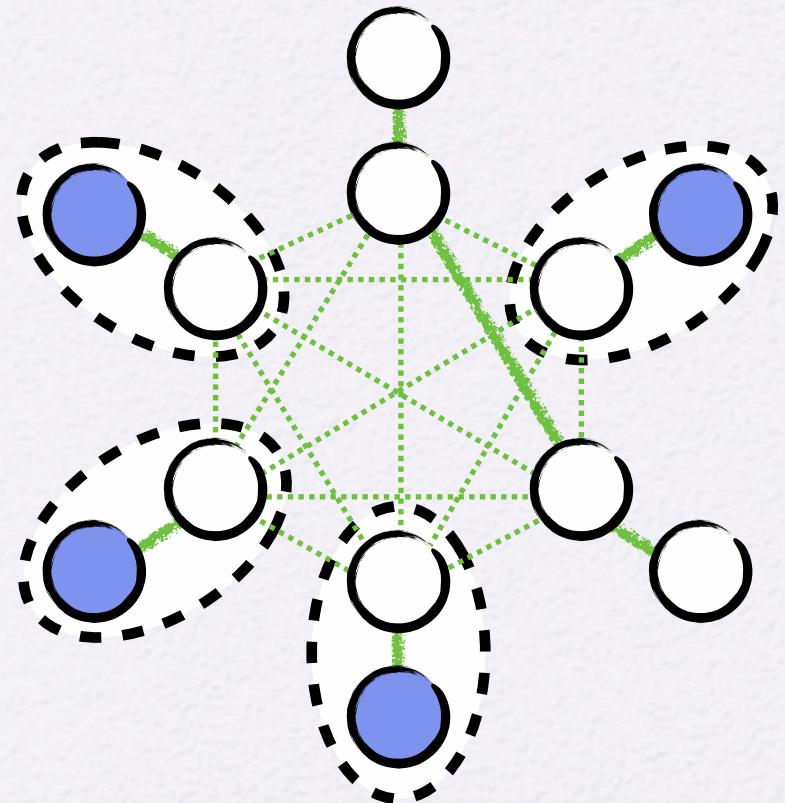
Other natural sampling methods can produce a non-constant approximation

- node u is activated wp $\deg(u)$
 - Eg, star of degree n
- node u is activated wp $1/\deg(u)$ [Luby]
 - Eg, a clique matched to an independent set of nodes

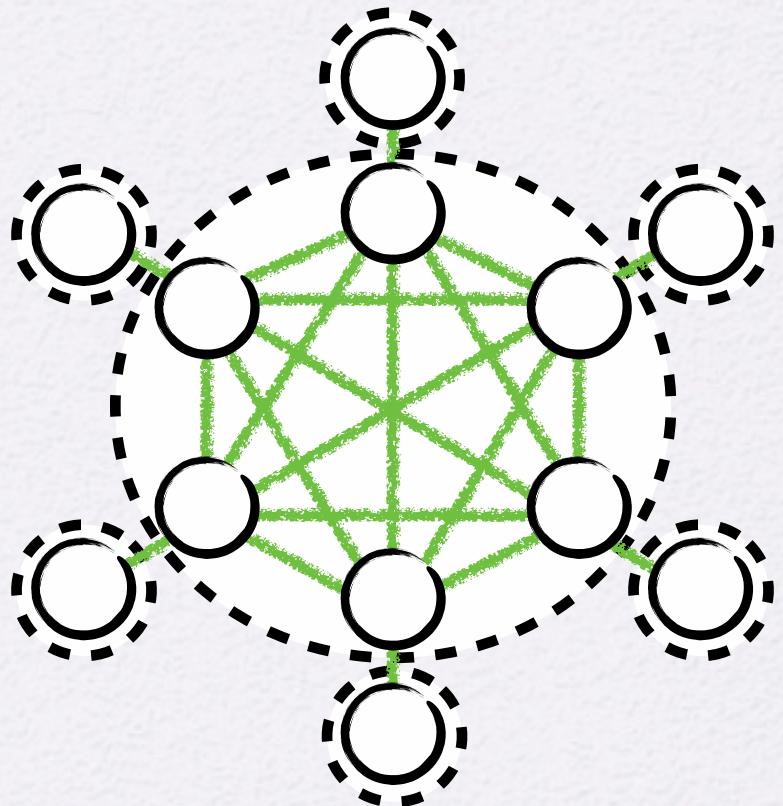
Eg. inverse degree



Algorithm vs Optimum



VS

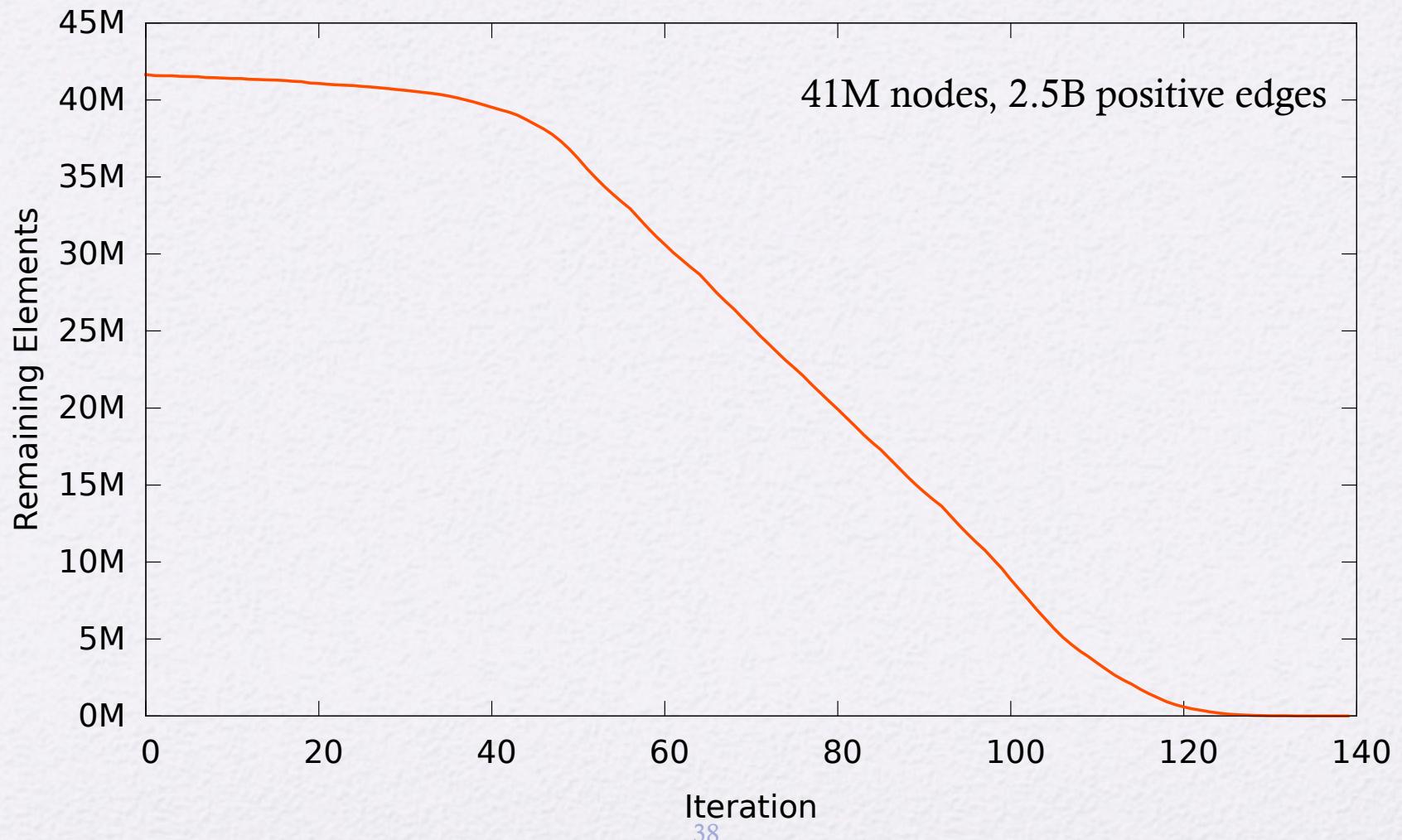


Different sampling?

Other uniform sampling approaches might require more rounds

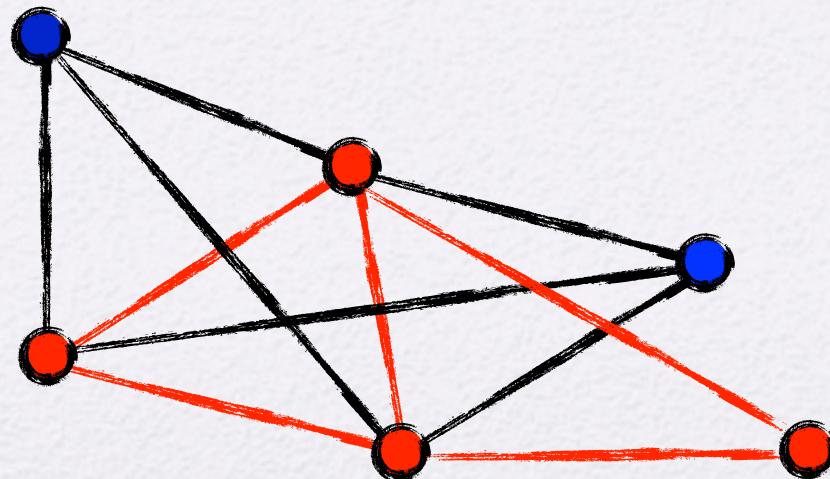
- node u is activated $wp \ll 1/D^+$
 - few active nodes, few pivots, many rounds
- node u is activated $wp \gg 1/D^+$
 - many active nodes, few pivots, many rounds
 - pivots far from uniform distribution

Twitter Dataset



2. Densest subgraph (DSG)

- Find densest subgraph in undirected graphs
 - Density of a subgraph is the ratio of the number of edges to the number of nodes
 - Motivation: Community finding
 - c -approximation = when density is at most c times worse than the best density



$$\text{Density}(\text{red}) = 5/4 = 1.2$$

Complexity of DSG

- DSG can be computed in **polynomial** time
 - Using parametric flows or LP relaxation
- Natural variants of DSG are **hard**
 - k-DSG, subgraph with exactly k nodes
- Charikar's **2-approximation** algorithm
 - Iteratively remove the lowest degree node until the graph becomes empty
 - One of the intermediate graphs is a 2-approx.
- These algorithms are **hard to scale**

DSG: Algorithm

A simple iterative algorithm

- Compute the average degree

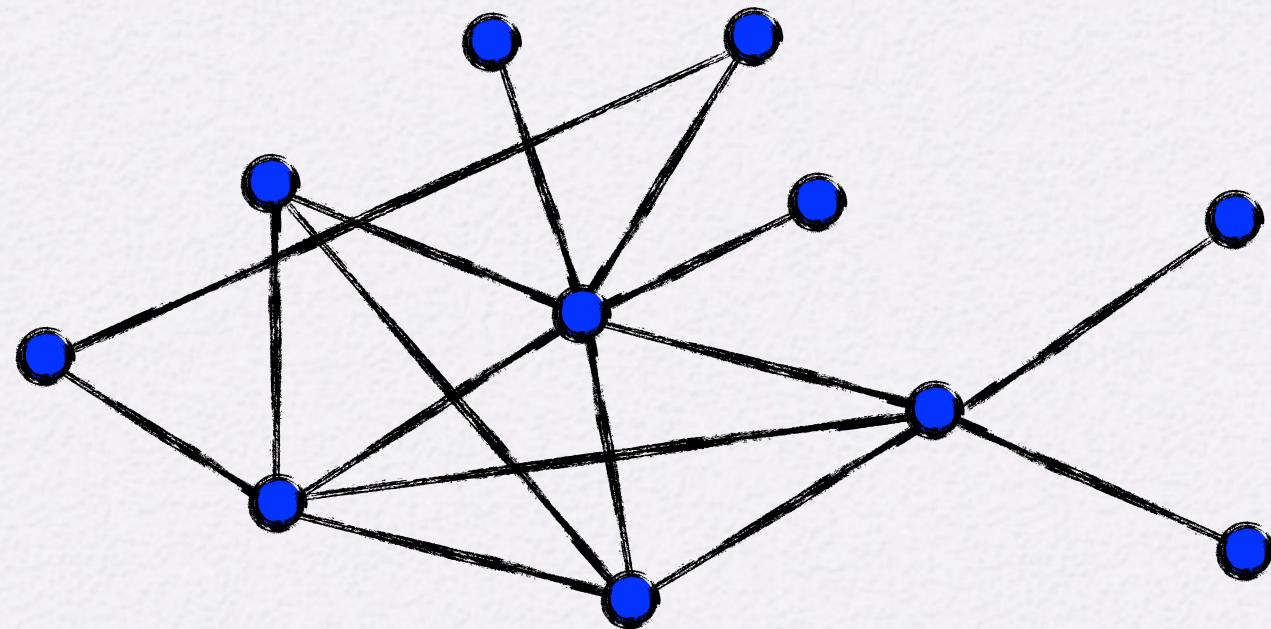
- Delete all nodes whose degree is $(1+\epsilon)$ below the average

- Keep track of the density at each step

- Output the densest graph seen during the iteration

[Bahmani, Kumar, Vassilvitskii]

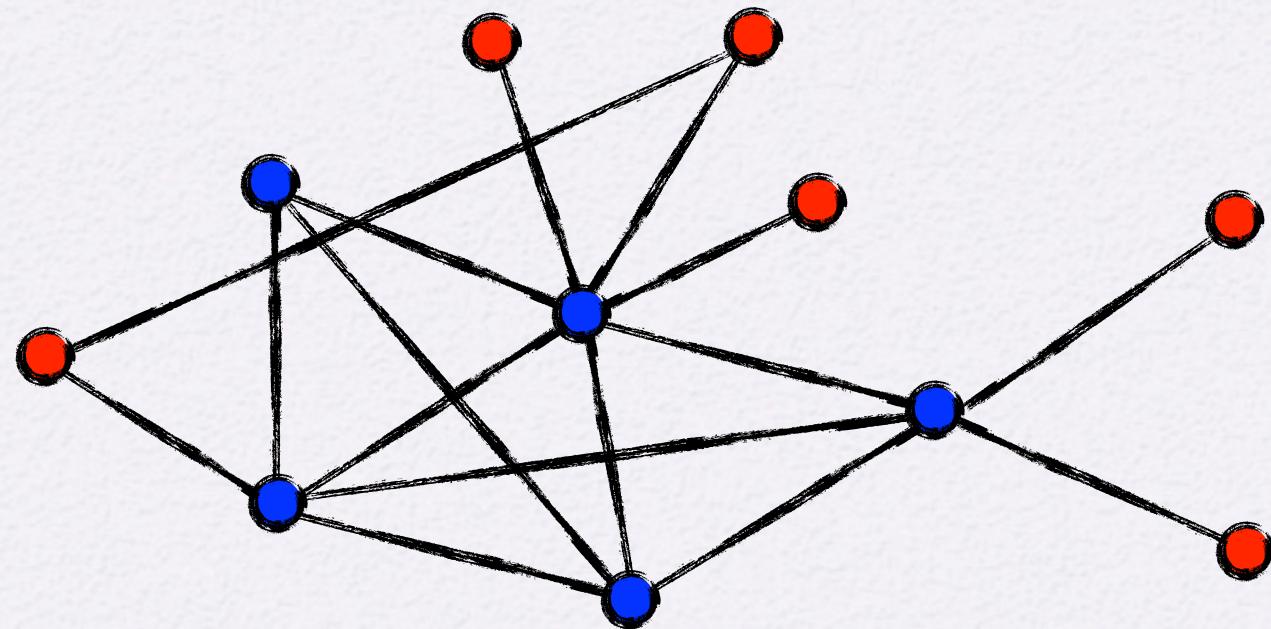
DSG: Example



density = $16/11 = 1.45$; average degree = $2 \times \text{density} = 2.90$

Best density = 1.45

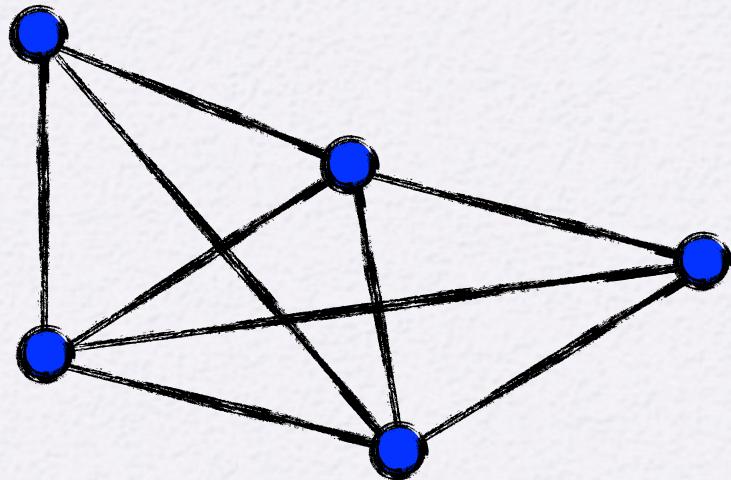
DSG: Example (contd)



density = $16/11 = 1.45$; average degree = $2 \times \text{density} = 2.90$

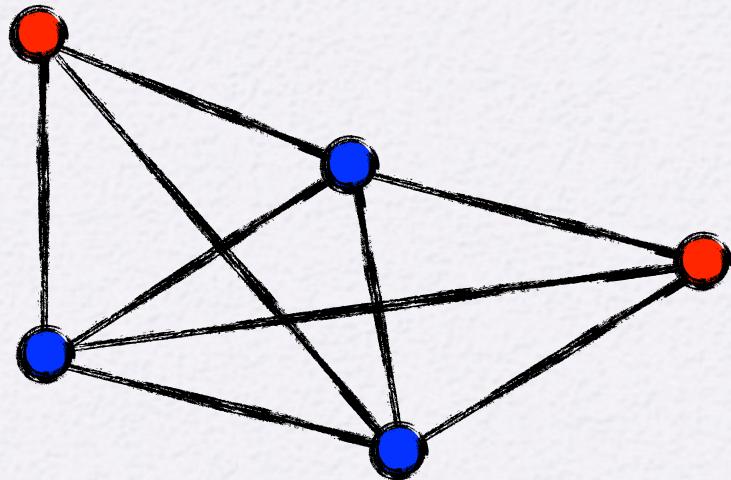
Best density = 1.45

DSG: Example (contd)



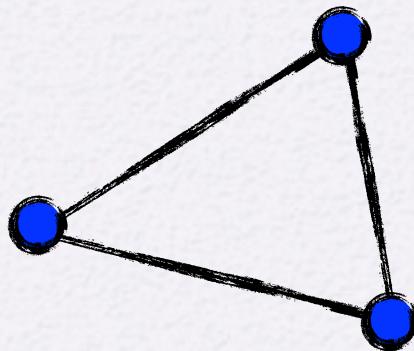
density = $9/5 = 1.8$; average degree = $2 \times \text{density} = 3.6$
Best density = 1.8

DSG: Example (contd)



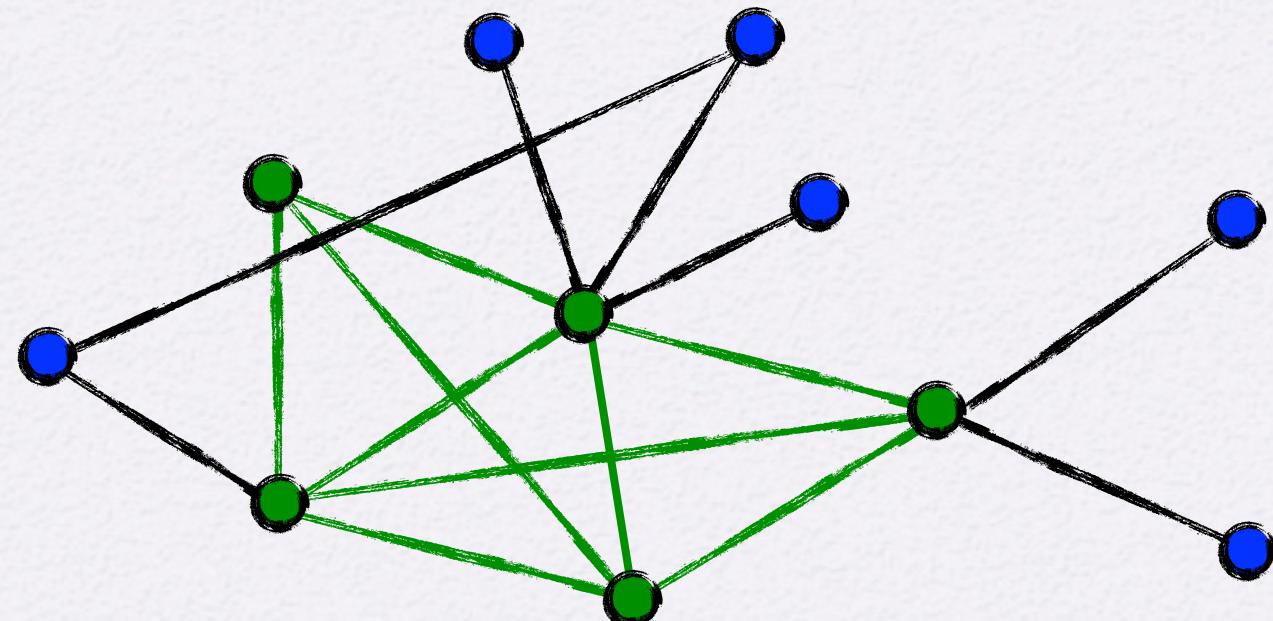
density = $9/5 = 1.8$; average degree = $2 \times \text{density} = 3.6$
Best density = 1.8

DSG: Example (contd)



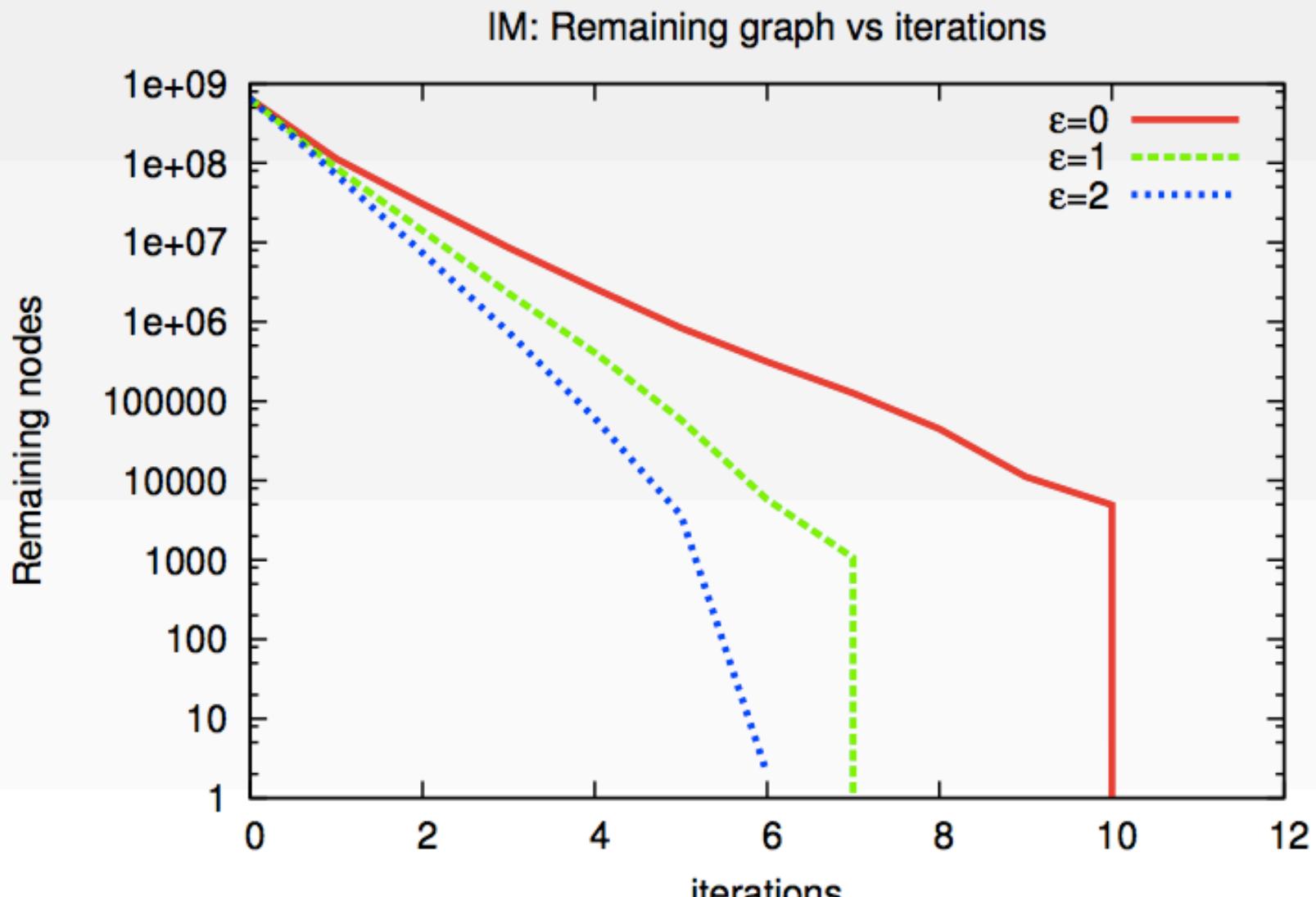
density = $3/3 = 1$; average degree = $2 * \text{density} = 2$
Best density = 1.8

DSG: Example (contd)



Best density = 1.8

DSG: Performance



Properties

Claim. Algorithm makes $O(\log_{1+\varepsilon} n)$ passes and uses $O(n)$ memory

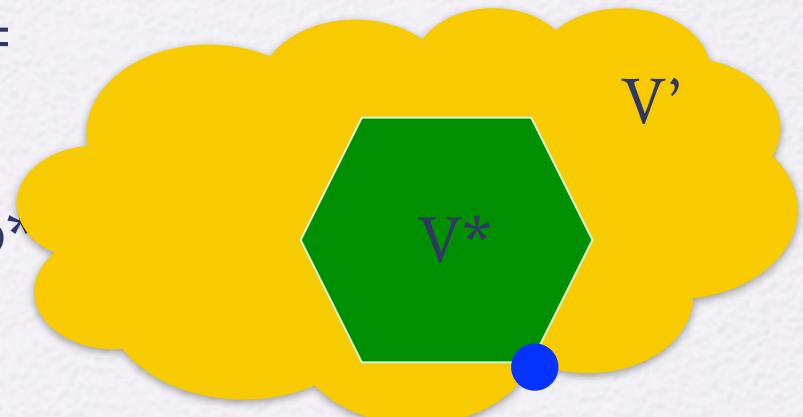
Use an averaging argument

Claim. Output is a $(2+\varepsilon)$ -approx.

V^* = optimal induced subgraph, $p^* = \text{density}(V^*)$

Each node in V^* has degree at least p^* (optimality)

V' = first subgraph where we are about to remove a node in V^*



Concluding thoughts

- Non-traditional computational models are key to managing big graphs
 - Novel algorithmic ideas
 - New programming paradigms
- Round complexity is important
 - One-pass 2-approximation algorithm for DSG [Bhattacharya, Henzinger, Nanongkai, Tsourakakis]
 - Correlation clustering?
 - k-means⁺⁺?
- Managing heavy tail, data skew, asynchrony, communication, ...

Thank you!

Questions/Comments

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