# Bálint Gyevnár

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## Research Interests

PhD student focusing on multi-step LLM reasoning with grounding, explainable multi-agent systems, and AI safety with the goal of achieving trustworthy human-agent collaboration.

# SKILLS

**Programming:** Python (PyTorch, vLLM, Transformers, uv, etc.), R, C++, C#, Haskell, etc;

Human-computer interaction: human-subjects experiments, online crowdsourcing, survey design;

**Data analysis:** qualitative coding, unsupervised topic modelling, graph analysis, mixed effects regression, statistical hypothesis testing, data visualization;

Languages: English, German, Japanese, Hungarian.

# EDUCATION

PhD in Natural Language Processing	09/2021 - 05/2025 (est.)
University of Edinburgh Supervised by Stefano V. Albrecht, Shay B. Cohen, and Christopher G. Lucas	$Edinburgh,\ UK$
Bachelor and Master of Informatics	09/2016 - 05/2021
University of Edinburgh Supervised by Maria Wolters	$Edinburgh,\ UK$
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Academic Exchange in Computer Science	08/2018 - 06/2019
Nanyang Technological University	Singapore

## EXPERIENCE

#### Research Assistant

University of Edinburgh

Jul. 2023 – Dec. 2024

Edinburgh, UK

- Researching the intersection of AI safety and AI ethics to build bridges among research problems;
- Quantitative literature analysis with unsupervised natural language processing and network analysis;
- Curation, topic coding, and qualitative analysis of large corpora of papers.

Research Intern May 2020 – Oct. 2020

Five AI Ltd.

Edinburgh, UK

- Development and evaluation of goal-based interpretable prediction and planning for autonomous vehicles;
- Scenario-based and open-world testing against baselines;
- Open-source implementation on GitHub with added support for CARLA.

# Volunteering

#### **Sports Club Executive Committee**

Edinburgh University Volleyball Club

Sep. 2022 – Jun. 2025

Edinburgh, UK

- (2024-25; Secretary) Public outreach and networking with alumni members and organizing an event series;
- (2023-24; VP) Large-scale events, public speaking, timetabling, HR management of 220+ members;
- (2022-23; Treasurer) Setting up an annual budget and managing a cash flow of £70k.

## TEACHING

- Teaching assistant for machine learning, computing systems, data analysis courses (2020-present);
- Assistant supervisor to two master's students (2022-2023);
- Marker for natural language processing, reinforcement learning, and machine learning courses (2020-present).

## Research Projects

# Combining multi-step LLM reasoning with world simulators for generating complex explanations

Jan. 2025 – present

- Development of multi-step reasoning framework for complex explanation generation;
- Integration of LLM inference with world simulators in a RAG approach;
- Evaluation with a wide range of models (Llama, Qwen, Phi, GPT, etc.) and humans.

## Bridging shared research challenges amid responsible AI wars

Jul. 2024 – present

- Curation of corpus of 3K+ papers on AI safety and AI ethics;
- Qualitative data analysis and visualization (e.g., topic coding, graph analysis);
- Quantitative unsupervised topic modelling and analysis (e.g., BERTopic);

#### Understanding how humans explain multi-agent systems

May 2024 - Present

- Large-scale human-agent interaction study of human explanatory modes.
- Curation and release of HEADD: the Human Explanations for Autonomous Driving Decisions dataset.
- Quantitative analysis and statistical hypothesis testing in R.

# Generating causal explanations for sequential decision-making in multi-agent systems

Sep. 2021 – May 2024

- Conversion of Monte Carlo Tree Search to probabilistic graph for counterfactual inference;
- Counterfactual reasoning with RL planning for causally-grounded explanations in natural language;
- Two large-scale human subjects studies to evaluate natural and automatically generated explanations.

#### Studying how humans acquire/communicate colour naming systems

Sep. 2021 – Nov. 2022

- Understanding the effects of communicative efficiency and acquisition on the patterns of human colour naming systems via computational information-theoretic measures.
- Simulating patterns of colour term acquisition using self-organising maps and the World Colour Survey.

# Interpretable goal-based prediction and planning for autonomous vehicles

May 2020 – May 2021

- Integration of rational inverse planning-based prediction module with Monte Carlo Tree Search for interpretable autonomous vehicle planning;
- Functional scenario-based and open-world evaluation against multiple baselines;
- Main developer and maintainer of open-source Python implementation.

#### Awards

Colours Award for Outstanding Volunteering Contribution to Sports	Jun. 2024
Edinburgh University Sports Union	$Edinburgh,\ UK$
AI100 Early Career Essay Competition Featured Essay	Aug. 2023
One Hundred Year Study on Artificial Intelligence (AI100)	Stanford University
Trustworthy Autonomous Systems Early Career Researcher Award	Jun. 2023
4,000 GBP; UK Research & Innovation	$South ampton,\ UK$
Shape the Future of ITS Competition; 3rd Place	Aug. 2022
1,000 USD; IEEE Intelligent Transportation Systems Society	USA

• AI Safety for Everyone

Nature Machine Intelligence, 2025;

B. Gyevnar, A. Kasirzadeh

- Objective Metrics for Human-Subjects Evaluation in Explainable Reinforcement Learning Multi-Disciplinary Conference on Reinforcement Learning and Decision Making, RLDM 2025

  B. Gyevnar, M. Towers
- People Attribute Purpose to Autonomous Vehicles When Explaining Their Behavior: Insights From Cognitive Science for Explainable AI

ACM Conference on Human Factors in Computing Systems, CHI 2025;

B. Gyevnar, S. Droop, T. Quillien, S.B. Cohen, N.R. Bramley, C.G. Lucas, S.V. Albrecht.

- Towards Trustworthy Autonomous Systems via Conversations and Explanations
   *AAAI Conference on Artificial Intelligence*, *AAAI 2024*;
   B. Gyevnar.
- Causal Explanations for Sequential Decision-Making in Multi-Agent Systems 23rd International Conference on Autonomous Agents and Multiagent Systems, AAMAS 2024; B. Gyevnar, C. Wang, S.B. Cohen, C.G. Lucas, S.V. Albrecht.
- Building Trustworthy Human-Centric Autonomous Systems Via Explanations 23rd International Conference on Autonomous Agents and Multiagent Systems, AAMAS 2024; B. Gyevnar.
- Explainable AI for Safe and Trustworthy Autonomous Driving: A Systematic Review *IEEE Transactions on Intelligent Transportation Systems, 2024;*A. Kuznietsov\*, B. Gyevnar\*, C. Wang, S. Peters, S.V. Albrecht. [\* equal contribution]
- Bridging the Transparency Gap: What Can Explainable AI Learn From the AI Act? 26th European Conference on Artificial Intelligence, ECAI 2023;
  B. Gyevnar, N. Ferguson, B. Schafer.
- Deep Reinforcement Learning for Multi-Agent Interaction

AI Communications, 35(4), 357-368, 2022;

I.H. Ahmed, C. Brewitt, I. Carlucho, F. Christianos, M. Dunion, E. Fosong, S. Garcin, S. Guo, <u>B. Gyevnar</u>, T. McInroe, G. Papoudakis, A. Rahman, L. Schäfer, M. Tamborski, G. Vecchio, C. Wang, S.V. Albrecht.

• Communicative Efficiency or Iconic Learning: Do Communicative and Acquisition Pressures Interact to Shape Colour-Naming Systems?

Entropy, 24(11), 1542, 2022;

B. Gyevnar, G. Dagan, C. Haley, S. Guo, F. Mollica.

• A Human-Centric Method for Generating Causal Explanations in Natural Language for Autonomous Vehicle Motion Planning [best paper runner-up]

Workshop on Artificial Intelligence for Autonomous Driving, IJCAI 2022;

B. Gyevnar, M. Tamborski, C. Wang, C.G. Lucas, S.B. Cohen, S.V. Albrecht.

 $\bullet$  Interpretable Goal-based Prediction and Planning for Autonomous Driving

International Conference on Robotics and Automation, ICRA 2021;

S.V. Albrecht, C. Brewitt, J. Wilhelm, B. Gyevnar, F. Eiras, M. Dobre, S. Ramamoorthy.

• GRIT: Fast, Interpretable, and Verifiable Goal Recognition with Learned Decision Trees for Autonomous Driving

IEEE/RSJ International Conference on Intelligent Robots and Systems, IROS, 2021;

C. Brewitt, B. Gyevnar, S. Garcin., S.V. Albrecht.

# EVENT ORGANISER

### • Evaluating Explainable AI and Complex Decision-Making

Workshop at the 28th European Conference on Artificial Intelligence, ECAI 2025; H. Baier, B. Gyevnar, M. Towers, Y. Zhang

## • The Explainable Reinforcement Learning Competition

Under review at NeurIPS 2025;

M. Towers, B. Gyevnar, A. Nowé, C.G. Lucas, D. Abel, H. Baier, T. Miller, T.J. Norman, T. Huber, T. Bewley, S.V. Albrecht

# INVITED TALKS

# • How do we make explainable AI work for people?

Machine Learning and Modelling Seminar Series, Charles University of Prague, 2024.

## Peer Review

- IEEE Transactions on Intelligent Transportation Systems Reviewer (2025)
- 3<sup>rd</sup> World Conference on eXplainable Artificial Intelligence Program Chair (2025)
- IEEE International Conference on Robotics and Automation Reviewer (2025)
- IEEE/RSJ International Conference on Intelligent Robots and Systems Reviewer (2023)