

Bálint Gyevnár

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EDUCATION

University of Edinburgh

Centre for Doctoral Training in Natural Language Processing, PhD

Supervisors: Stefano V. Albrecht, Shay Cohen, and Christopher G. Lucas

Edinburgh, UK

Sep. 2021 – May 2025

University of Edinburgh

Integrated Master of Informatics

Supervisor: Maria Wolters

Edinburgh, UK

Sep. 2016 – May 2021

Nanyang Technological University

Exchange in Computer Science

Singapore

Aug. 2018 – May 2019

PEER-REVIEWED PUBLICATIONS

Conference

- S. Albrecht, C. Brewitt, J. Wilhelm, B. Gyevnar, F. Eiras, M. Dobre, S. Ramamoorthy. Interpretable Goal-based Prediction and Planning for Autonomous Driving, *International Conference on Robotics and Automation (ICRA)*, 2021
- C. Brewitt, B. Gyevnar, S. Garcin., S. Albrecht. GRIT: Fast, Interpretable, and Verifiable Goal Recognition with Learned Decision Trees for Autonomous Driving, *IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)*, 2021

Workshop

- C. Brewitt, S. V. Albrecht, J. Wilhelm, B. Gyevnar, F. Eiras, M. Dobre, S. Ramamoorthy. Autonomous Driving with Interpretable Goal Recognition and Monte Carlo Tree Search, *Workshop at RSS on Interaction and Decision-Making in Autonomous-Driving*, 2020

EXPERIENCE

Teaching Assistant

University of Edinburgh

Sep. 2020 – Dec. 2020

Edinburgh, UK

- Deliver and moderate online tutorial sessions of ~12 students for introductory level Machine Learning course.
- Use online tools to effectively communicate with students and explain new concepts.
- Mark and provide feedback on quiz for Computer Systems course of 300+ students.

Research Intern

Five

May 2020 – Oct 2020

Edinburgh, UK

- Develop interpretable prediction and planning system for autonomous vehicles using goal-based rational inverse planning and Monte-Carlo tree search.
- Develop fixed-scenario testing and evaluation of prediction and planning system.
- Implement open-world testing environment for prediction and planning system with random map generation.
- Present work at the Royal Society during entrepreneurial workshop.

Explainable Autonomous Vehicle Intelligence | *XAI, MCTS, Autonomous Vehicles* Sep 2021 – Present

- * Generating causally justifiable explanations of actions from Monte Carlo search trees.
- * Integrating explanation generation with dialogue systems to deliver relevant natural language explanations.
- * Evaluation of methods with human participants to measure the effect of explanations on trust and understanding.

Learnability & Communicative Efficiency of Colour Terms Sep 2021 – Present

- * Information theoretic measures of communicative efficiency and learnability of human language colour terms.
- * Simulate developmental trajectories of human colour term learning using self-organising maps and the World Colour Survey.
- * Comparison of the joint cognitive effects of communicative efficiency and learnability on colour term acquisition.