Education

Shanghai Jiao Tong University

Shanghai, China

MASTER OF SCIENCE, Robotics and Intelligence Group, Robotics Institute

Sep. 2016 - Jun. 2019(expected)

- Overall Ranking 6th/210 | GPA: Mechanical 3.43/4 | Computer science courses 3.80/4
- Advisor: Prof. Weixin Yan & Prof. Yanzheng zhao

Shandong University

Jinan, China Sep. 2012 - Jun. 2016

BACHELOR OF ENGINEERING, Control Engineering and Mechatronics

- Overall **Ranking 1st/66** | GPA: Overall: 86.08/100 | Major: 93.38/100
- · Honor: Outstanding Undergraduate Thesis Award

Research Interests_

My research interests broadly include Machine learning, Deep Learning, and Medical Image Analysis. Currently, I am focusing on interdisciplinary researches at Deep Learning and Medical Image Analysis.

Publications _

[1] Unpaired Whole-body MR to CT Synthesis with Correlation Coefficient Constrained Adversarial Learning

Yunhao Ge, Zhong Xue, Tuoyu Cao, Shu Liao 🖹 PDF

SPIE-Medical Imaging (accepted oral)

Aug. 2018

[2] Unpaired MR to CT Synthesis with Explicit Structural Constrained Adversarial Learning

Yunhao Ge*, Dongming Wei*, Zhong Xue, Qian Wang, Shu Liao (*=equal contribution) PDF

IEEE International Symposium on Biomedical Imaging (ISBI)

> (under review) Oct. 2018

[3] Automatic Detection and Segmentation of rectal cancer based on combination of Deep Neural Network and Machine learning methods

Yunhao Ge, Bin Li, Weixin Yan 🖹 PDF

Medical Image Analysis

(under review)

June. 2018

[4] A Real-time Gesture Prediction System Using Neural Networks and Multimodal Fusion based on data glove

Yunhao Ge, Bin Li, Weixin Yan, Yanzheng Zhao PDF Paper Link

IEEE International Conference on Advanced Computational Intelligence (ICACI'18)

Mar. 2018

[5] Melanoma Segmentation and Classification in Clinical Images Using Deep Learning

Yunhao Ge, Bin Li, Enguang Guan, Weixin Yan, Yanzheng Zhao PDF Paper Link

ACM International Conference on Machine Learning and Computing (ICMLC'18)

Jan. 2018

[6] Benign and Malignant Mammographic Image Classification Based on Convolutional Neural Networks

Bin Li, **Yunhao Ge**, Enguang Guan, Weixin Yan, Yanzheng Zhao 🖹 PDF 🖹 Paper Link

ACM International Conference on Machine Learning and Computing (ICMLC'18)

Jan. 2018

[7] Effect of Mechanical Error on Dual-Wedge Laser Scanning System and Error Correction

Yunhao Ge, Jihao Liu, Fenfen Xue, Enguang Guan, Weixin Yan, Yanzheng Zhao 🖹 PDF 🖹 Paper Link

Applied Optics

June. 2018

[8] Dynamic Drive Performances of the Bionic Suction Cup Actuator Based on Shape Memory Alloy

Yunhao Ge, Jihao Liu, Bin Li, Huihua Miao, Weixin Yan, Yanzheng Zhao 🖹 PDF 🖹 Paper Link

Intelligent Robotics and Applications

Aug. 2017

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Research Projects

Unpaired Cross modality Image Synthesis

United Image Intelligence

Advisor: Dinggang Shen, Huanhua Liao

June. 2018 - Nov. 2018

- Proposed an explicit structural constrained adversarial learning method to address the mismatch of anatomical structures in the synthesized results which is unique in MR to CT image synthesis
- Designed a novel correlation coefficient loss and a shape discriminator incorporating the shape consistency to overcome the big variance in whole body image mapping and reduce the MAE from 107.03 to 78.34

Automatic Detection and Segmentation of Rectal Cancer

Shanghai Jiao Tong University

Advisor: Hongtao Lu, Weixin Yan

Jan. 2018 - Jul. 2018

- Designed a Co-predicted neural network which using complementary decision algorithm imitating the diagnostic process of doctors to improve image-level detection accuracy
- Proposed an automatic detection and segmentation algorithm with multimodality medical image input and multialgorithm fusion, which
 achieved the rectal cancer detection accuracy improved from 88% to 92% as well as the segmentation AP from 0.4 to 0.7

Real-time Gesture Prediction on Medical Robotics

Shanghai Jiao Tong University

Advisor: Weixin Yan, Huanhua Liao

Nov. 2017 - Mar. 2018

- Proposed a real-time gesture prediction system achieving 99.9% accuracy in judging the intention of hand motion and predicting the exact final gesture before the end of hand movement
- Combined Position, velocity, acceleration and the adjacent finger-coupling feature information as well as fused neural network and multiclass support vector machine (SVM) to make multi-level decision which shorten the reaction time in 0.1ms

Classification and Segmentation: Computer-Aided Diagnosis and Deep Learning

Shanghai Jiao Tong University

Advisor: Hongtao Lu, Weixin Yan

Mar. 2017 - Dec. 2017

- Built four CNN models to study the impact of depth and hidden layer structure on model performance and achieved a balance of high sensitivity (90.63%) and high specificity (87.67%), improved accuracy from 86.7% tp 89.05% in mammographic images diagnose
- Proposed a deep learning computer aided diagnosis system (CADs) for automatic segmentation and classification of melanoma lesions by combining high level features, the DLCM features, statistical and contrast location features

Skills

Programming Python (Numpy, Pytorch, Tensorflow, Caffe, Keras, Sklearn), OpenCV, PyQt, Matlab, C, C++, CUDA, Shell, LaTeX

Design Solidworks, CAD, UG, Ansys

Honors & Awards_

SCHOLARSHIPS

Sep 2017 National Scholarship (Graduate), top 1% nationwide	Shanghai, China
Sep 2015 National Scholarship (Under Graduate), top 2% nationwide	Jinan, China
Sep 2015 Presidential Scholarship , top 0.2% in Shandong University	Jinan, China
Sep 2015 BaoGang Excellent student Scholarship, 4 Places per year at Shandong University	Jinan, China
May 2018 KaiYuan Motivational Scholarship, top 0.5% in Shanghai Jiao Tong University	Shanghai, China
2013-2015 First Prize Scholarship , three-year continuous	Jinan, China

CONTESTS

Aug 2017	The first prize , 2017 ROBOMASTER The World's Leading Robotics Competition (Responsible for the design of electronic control in robotics)	Shenzhen, China
Mar 2018 Rank 1st (preliminary competition), Tianchi: Precision medical competition-Artificial Intelligence Aided genetic risk prediction of diabetes Opred-diabetes	Shanghai, China	
		Oct 2015

Patent & software __

Pulmonary Nodular Assisted Detection System Based on AI(V1.0)

Software

Bin Li, Yunhao GE 2018SR037095

Jan. 2018

A two-layer barrier free parking robotics based on bionic manipulator

Patent for invention

Yunhao GE, Shangze Yang, Zheng Zhang, Weixin Yan, Yanzheng Zhao CN201610712048

Jan. 2017

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