Yunhao Ge

□ (+1) 2136759836 | wyunhaoge@usc.edu | gyhandy.github.io | gyhandy

Education

University of Southern California

Los Angeles, USA

PHD, ilab, Computer Science Department

Aug. 2019 - Present

- Annenberg Graduate Fellowship at University of Southern California
- · Advisor: Prof. Laurent Itti

Shanghai Jiao Tong University

Shanghai, China

MASTER OF SCIENCE, Robotics and Intelligence Group, Robotics Institute

Sep. 2016 - June 2019

- Overall Ranking 6th/210
- Advisor: Prof. Weixin Yan & Huanhua Liao & Prof. Yanzheng zhao
- · Honor: Outstanding Graduate Thesis Award

Shandong University

Jinan, China

BACHELOR OF ENGINEERING, Control Engineering and Mechatronics

Sep. 2012 - June 2016

- Overall Ranking 1st/66
- · Honor: Outstanding Undergraduate Thesis Award

Research Interests

My research interests lie in Machine Learning, Computer vision, and AGI. Currently, I am focusing on simulating Cognitive Baby Learning (Imagination, Reasoning, Attention) by using various learning algorithms (Unsupervised learning, Representation Learning, Generative models, GNN, Reinforcement Learning, Meta-Learning, etc.).

Selected Publications

[1] Zero-shot Synthesis with Group-Supervised Learning

Yunhao Ge, Sami Abu-El-Haija, Gan Xin and Laurent Itti PDF **Fonts Dataset** *International Conference on Learning Representations (ICLR)*, 2021.

[2] Pose Augmentation: Class-agnostic Object Pose Transformation for Object Recognition

Yunhao Ge, Jiaping Zhao, Laurent Itti PDF Code

European Conference on Computer Vision (ECCV), 2020.

[3] Beneficial Perturbation Network for designing general adaptive artificial intelligence systems

Shixian Wen, Amanda Rios*, **Yunhao Ge*** and Laurent Itti (*=equal contribution) | PDF IEEE Transactions on Neural Networks and Learning Systems (**TNNLS**), Jan 2021.

[4] Unpaired MR to CT Synthesis with Explicit Structural Constrained Adversarial Learning

Yunhao Ge*, Dongming Wei*, Zhong Xue, Qian Wang, Xiang Zhou, Yiqiang Zhan, Shu Liao (*=equal contribution) PDF Code *IEEE International Symposium on Biomedical Imaging (ISBI)*, 2019.

[5] Synthesis and inpainting-based MR-CT registration for image-guided thermal ablation of liver tumors

Dongming Wei, Sahar Ahmad, Jiayu Huo, Wen Peng, **Yunhao Ge**, Zhong Xue, Pew-Thian Yap, Wentao Li, Dinggang Shen, Qian Wang PDF

International Conference on Medical Image Computing and Computer-Assisted Intervention (MICCAI), 2019.

[6] Unpaired Whole-body MR to CT Synthesis with Correlation Coefficient Constrained Adversarial Learning

Yunhao Ge, Zhong Xue, Tuoyu Cao, Shu Liao PDF Code SPIE-Medical Imaging, 2019 [oral]

[7] A Real-time Gesture Prediction System Using Neural Networks and Multimodal Fusion based on Data Glove

Yunhao Ge, Bin Li, Weixin Yan, Yanzheng Zhao PDF Paper Link

IEEE International Conference on Advanced Computational Intelligence (ICACI), 2018. [oral]

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[8] HH-Net: Image driven microscope fast auto-focus with deep neural network

Yunhao Ge, Bin Li, Yanzheng Zhao, Weixin Yan PDF

International Conference on Biomedical Engineering and Technology (ICBET), 2019. [oral]

[9] Melanoma Segmentation and Classification in Clinical Images Using Deep Learning

Yunhao Ge, Bin Li, Weixin Yan PDF Paper Link

ACM International Conference on Machine Learning and Computing (ICMLC), 2018. [oral]

[10] Benign and Malignant Mammographic Image Classification Based on Convolutional Neural Networks

Bin Li, **Yunhao Ge**, Yanzheng Zhao, Enguang Guan, Weixin Yan PDF Paper Link

ACM International Conference on Machine Learning and Computing (ICMLC), 2018. [oral]

[11] Effect of Mechanical Error on Dual-Wedge Laser Scanning System and Error Correction

Yunhao Ge, Jihao Liu, Fenfen Xue, Enguang Guan, Weixin Yan, Yanzheng Zhao PDF Paper Link Applied Optics (**Appl. Opt. IF:1.79**) 57, pp. 6047-6054, 2018

Research Experience _____

UII America, Inc Boston, MA, USC

Research Intern May 2020 - Aug. 2020

- Research topic: General Visual Reasoning Framework
- Advisor: Ziyan Wu, Srikrishna Karanam

Flexiv Robotics Shanghai, China

Computer Vision Research Engineer

May 2019 - Aug. 2019

- Research topic: Robotics adaptive massage based on human pose detection and tracking with a lightweight local human 3D pose detection framework
- · Advisor: Cewu Lu, Shuyun Chong

United Imaging Intelligence

Shanghai, China

Research Intern June 2018 - Apr. 2019

- Research topic: Unpaired Image Synthesis with Adversarial Learning
- Advisor: Dinggang Shen, Shu Liao

Robotics Institute @ Shanghai Jiao Tong University

Shanghai, China

Research Assistant

Sep. 2016 - Apr. 2019

- Research topic: (1) Robotics: Achieved automatic target localization, customization of scanning path, automatic focusing, defocus image restoration, automatic stitching of global imaging and other automated processing in the process of full slice scanning diagnosis of microscopy
- · Research topic: (2) MAI: Automatic Detection and Segmentation of Colorectal Tumor in Medical Imag
- Research topic: (3) Robotics:Real-time Gesture Prediction on Medical Robotics
- Research topic: (4) Robotics: Effect of Mechanical Error on Dual-Wedge Laser Scanning System and Error Correction
- · Advisor: Weixin Yan, Huanhua Liao, and Yanzheng Zhao

Honors & Awards_

SCHOLARSHIPS

National Scholarship (Graduate), top graduate nationwide	Nov. 2017
National Scholarship (UnderGraduate), top undergraduate nationwide	Nov. 2015
KaiYuan Motivational Scholarship, top 0.5% in Shanghai Jiao Tong University	Apr. 2018
Presidential Scholarship, top 0.2% in Shandong University	Nov. 2015
BaoGang Excellent student Scholarship, 4 Places per year at Shandong University	Nov. 2015
First Prize Scholarship, three-year continuous	2013-2015

CONTESTS

The first prize, 2017 ROBOMASTER The World's Leading Robotics Competition

(Responsible for the design of electronic control in robotics)

Aug. 2017

Rank 1st (preliminary competition), Tianchi: Precision medical competition-Artificial Intelligence Aided genetic

risk prediction of diabetes OPred-diabetes

Dec. 2017

The first prize, 9th International college students Ican innovation and entrepreneurship competition

Oct. 2015

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Patent & software _____

Pulmonary Nodular Assisted Detection System Based on AI(V1.0)

Bin Li, **Yunhao Ge** 2018SR037095

Software Jan. 2018

A two-layer barrier free parking robotics based on bionic manipulator

Yunhao Ge, Shangze Yang, Zheng Zhang, Weixin Yan, Yanzheng Zhao CN201610712048

Patent for invention

Jan. 2017

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