```
//Pressure sensor glove - Gymnasio Vamou 2019
#include <Wire.h>
#include <LiquidCrystal_I2C.h>
LiquidCrystal_I2C lcd(0x27,16,2); // set the LCD address to 0x27, set 16 chars and 2 line
display
int fsr1Pin = 14; // the FSR and 10K pulldown are connected to a0
int fsr1Reading; // the analog reading from the FSR resistor divider
int fsr2Pin = 15; // the FSR and 10K pulldown are connected to a1
int fsr2Reading;
int fsr3Pin = 16; // the FSR and 10K pulldown are connected to a2
int fsr3Reading;
int fsr4Pin = 17; // the FSR and 10K pulldown are connected to a3
int fsr4Reading;
int greenLEDpin1 = 5;
int redLEDpin1 = 6;
int greenLEDpin2 = 7;
int redLEDpin2 = 8;
int greenLEDpin3 = 9;
int redLEDpin3 = 10;
int greenLEDpin4 = 11;
int redLEDpin4 = 12;
void setup() {
  Serial.begin(9600);
  pinMode(greenLEDpin1, OUTPUT);
  pinMode(redLEDpin1, OUTPUT);
  pinMode(greenLEDpin2, OUTPUT);
  pinMode(redLEDpin2, OUTPUT);
  pinMode(greenLEDpin3, OUTPUT);
  pinMode(redLEDpin3, OUTPUT);
```

```
pinMode(greenLEDpin4, OUTPUT);
  pinMode(redLEDpin4, OUTPUT);
  pinMode(14, INPUT);
  pinMode(15, INPUT);
  pinMode(16, INPUT);
  pinMode(17, INPUT);
  lcd.init();
  lcd.backlight();
  lcd.setCursor(0,0);
  lcd.print("Gymmnasio Vamou");
}
void loop() {
fsr1Reading = analogRead(fsr1Pin);
fsr2Reading = analogRead(fsr2Pin);
 fsr3Reading = analogRead(fsr3Pin);
 fsr4Reading = analogRead(fsr4Pin);
 Serial.print(" Analog reading1 = ");
 Serial.print(fsr1Reading); // the raw analog reading
 Serial.print(" Analog reading2 = ");
 Serial.print(fsr2Reading);
 Serial.print(" Analog reading3 = ");
 Serial.print(fsr3Reading); // the raw analog reading
 Serial.print(" Analog reading4 = ");
 Serial.print(fsr4Reading);
 delay(200);
  if (fsr1Reading < 50) {
  Serial.println(" - No pressure");
  digitalWrite(11, LOW);
  digitalWrite(12, LOW);
```

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} else if (fsr1Reading < 300) {
 Serial.println(" - Light squeeze");
 digitalWrite(11, HIGH);
 digitalWrite(12, LOW);
} else if (fsr1Reading < 500) {
 Serial.println(" - Medium squeeze");
 digitalWrite(11, HIGH);
 digitalWrite(12, HIGH);
} else if (fsr1Reading > 500){
 Serial.println(" - Big squeeze");
 digitalWrite(11, LOW);
 digitalWrite(12, HIGH);
 if (fsr2Reading < 50) {
 Serial.println(" - No pressure");
 digitalWrite(9, LOW);
 digitalWrite(10, LOW);
} else if (fsr2Reading < 300) {
 Serial.println(" - Light squeeze");
 digitalWrite(9, HIGH);
 digitalWrite(10, LOW);
   } else if (fsr2Reading < 500) {
 Serial.println(" - Medium squeeze");
 digitalWrite(9, HIGH);
 digitalWrite(10, HIGH);
 } else if (fsr2Reading > 500){
 Serial.println(" - Big squeeze");
 digitalWrite(9, LOW);
 digitalWrite(10, HIGH);
}
```

```
if (fsr3Reading < 50) {
 Serial.println(" - No pressure");
 digitalWrite(7, LOW);
 digitalWrite(8, LOW);
} else if (fsr3Reading < 300) {
 Serial.println(" - Light squeeze");
 digitalWrite(7, HIGH);
 digitalWrite(8, LOW);
 } else if (fsr3Reading < 500) {
 Serial.println(" - Medium squeeze");
 digitalWrite(7, HIGH);
 digitalWrite(8, HIGH);
} else if (fsr3Reading > 500){
 Serial.println(" - Big squeeze");
 digitalWrite(7, LOW);
 digitalWrite(8, HIGH);
}
 if (fsr4Reading < 50) {
 Serial.println(" - No pressure");
 digitalWrite(5, LOW);
 digitalWrite(6, LOW);
} else if (fsr4Reading < 300) {
 Serial.println(" - Light squeeze");
 digitalWrite(5, HIGH);
 digitalWrite(6, LOW);
} else if (fsr4Reading < 500) {
 Serial.println(" - Medium squeeze");
 digitalWrite(5, HIGH);
 digitalWrite(6, HIGH);
} else if (fsr4Reading > 500){
```

```
Serial.println(" - Big squeeze");
  digitalWrite(5, LOW);
  digitalWrite(6, HIGH);
}
 delay(200);
if ((fsr1Reading < 50) && (fsr2Reading < 50)&&(fsr4Reading < 50)) {
  lcd.setCursor(0,1);
  lcd.print(" No pressure ");
 }
else if ((fsr1Reading < 350) && (fsr2Reading < 350)&&(fsr3Reading < 350)&&(fsr4Reading <
350)) {
 lcd.setCursor(0,1);
 lcd.print("Medium squeeze ");
}
else if ((fsr1Reading > 350) && (fsr2Reading > 350)&&(fsr3Reading > 350)&&(fsr4Reading >
350)){
 lcd.setCursor(0,1);
 lcd.print(" Big squeeze ");}
}
```