```
import torch
import torchvision
class Net1(nn.Module):
  def __init__(self, num_classes=10):
    super(Net1, self).__init__()
    self.features = nn.Sequential(
      nn.Conv2d(3, 64, kernel size=7, stride=1),
      nn.ReLU(),
      nn.Conv2d(64, 192, kernel_size=3, stride=1),
      nn.ReLU(),
      nn.Conv2d(192, 384, kernel_size=3, stride=1),
      nn.ReLU(),
      nn.Conv2d(384, 256, kernel_size=3, stride=1),
      nn.ReLU(),
      nn.Conv2d(256, 256, kernel_size=3, stride=1),
    self.classifier = nn.Sequential(
      nn.Linear(256 * 18 * 18, 4096),
      nn.ReLU(),
      nn.Linear(4096, 4096),
      nn.ReLU(),
      nn.Linear(4096, num_classes)
    )
  def forward(self, x):
    x = self.features(x)
    x = torch.flatten(x, 1)
    x = self.classifier(x)
    return x
class Net2(nn.Module):
  def init (self, num classes=10):
    super(Net2, self).__init__()
    self.features = nn.Sequential(
      nn.Conv2d(3, 64, kernel_size=7, stride=1),
      nn.ReLU(),
      nn.Conv2d(64, 192, kernel_size=3, stride=1),
      nn.ReLU(),
      nn.Conv2d(192, 384, kernel size=3, stride=1),
      nn.ReLU(),
      nn.Conv2d(384, 256, kernel size=3, stride=1),
      nn.ReLU(),
      nn.Conv2d(256, 256, kernel_size=3, stride=1),
    )
  ### TODO: Complete initialization of self.classifier ###
          by filling in the ...
```

import torch.nn as nn

```
self.classifier = nn.Sequential(
       nn.Conv2d(256, 4096, kernel_size=18, stride=1),
       nn.ReLU().
       nn.Conv2d(4096, 4096, kernel size= 1, stride=1),
      nn.ReLU(),
       nn.Conv2d(4096, num_classes, kernel_size=1, stride = 1)
    )
  def copy weights from(self, net1):
    with torch.no_grad():
       for i in range(0, len(self.features), 2):
         self.features[i].weight.copy_(net1.features[i].weight)
         self.features[i].bias.copy_(net1.features[i].bias)
      for i in range(0,len(self.classifier),2):
         ### TO DO: Correctly transfer weight of Net1
         shape = [(4096,-1,18,18),(4096,-1,1,1),(10,-1,1,1)]
         self.classifier[i].weight.copy_(net1.classifier[i].weight.reshape(* shape[i//2]))
         self.classifier[i].bias.copy_(net1.classifier[i].bias)
  def forward(self, x):
    x = self.features(x)
    x = self.classifier(x)
    return x
model1 = Net1() # model1 randomly initialized
model2 = Net2()
model2.copy_weights_from(model1)
test dataset = torchvision.datasets.CIFAR10(
  root='./cifar_10data',
  train=False.
  transform=torchvision.transforms.ToTensor()
test_loader = torch.utils.data.DataLoader(
  dataset=test_dataset,
  batch size=10
imgs, = next(iter(test loader))
diff = torch.mean((model1(imgs) - model2(imgs).squeeze()) ** 2)
print(f"Average Pixel Difference: {diff.item()}") # should be small
test_dataset = torchvision.datasets.CIFAR10(
  root='./cifar_10data',
  train=False.
  transform=torchvision.transforms.Compose([
```

)

)

```
torchvision.transforms.Resize((36, 38)),
    torchvision.transforms.ToTensor()
    1),
  download=True
test_loader = torch.utils.data.DataLoader(
  dataset=test_dataset,
  batch_size=10,
  shuffle=False
)
images, _ = next(iter(test_loader))
b, w, h = images.shape[0], images.shape[-1], images.shape[-2]
out1 = torch.empty((b, 10, h - 31, w - 31))
for i in range(h - 31):
  for j in range(w - 31):
    ### TO DO: fill in ... to make out1 and out2 equal ###
    out1[:, :, i, j] = model1(images[:,:,i:i+32,j:j+32])
out2 = model2(images)
diff = torch.mean((out1 - out2) ** 2)
print(f"Average Pixel Diff: {diff.item()}")
```

## Result

Average Pixel Difference: 9.394490725345218e-17

Files already downloaded and verified

Average Pixel Diff: 7.483758435140398e-17