

# cs805 Assignment 1

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## Abstract

This assignment is written in literate programming style, generated by noweb, and rendered by LaTeX.

## 1 Question 1

Let  $n$  be a 3 tuple vector, and given that it is along  $V1$ . It is trivial that we can imply:

$$n = \frac{V1}{[|V1|, |V1|, |V1|]}$$

where  $|V1| = \sqrt{V1_x^2 + V1_y^2 + V1_z^2}$

Thus  $n$  is now known.

By the definition of cross product, denoted as  $\times$  here, knowing that  $V1$  and  $V2$  is non-collinear, we can also derive:

$$u = \frac{V2 \times V1}{[|V2 \times V1|, |V2 \times V1|, |V2 \times V1|]}$$

Finally, it is also trivial that:

$$v = n \times u$$

## 2 Question 2

According to the requirement, we need a function that gets the new coordination U, V, N from our two vectors.

First, assuming we have the function already. Thus giving it two points, our function will get the U, V, N from them.

```
<<src/main.cpp>>=
#include <iostream>
#include <typeinfo>//debugging only
#include "util.h"

int main () {
    Point V1;
    decltype(V1) V2;//c11: V2 is of same type of V1

    V1 = {0,0,1};
    V2 = {0,1,1};

    auto uvn = get_uvn(V1, V2);//c11: compiler will replace 'auto' with the right type

    for (auto point : uvn) { //c11:for each point in uvn
        for (auto num : point) { //c11:for each number in point
            std::cout<<num<<',';
        }
        std::cout<<std::endl;
    }

    return 0;
}
@
```

here is the function.

```
<<src/util.cpp>>=
#include "util.h"
#include <math.h>
```

```

UVN get_uvn(Point V1, Point V2) {

    //get n, which is just normalized V1
    Point n = { V1[0]/get_length(V1),
                V1[1]/get_length(V1),
                V1[2]/get_length(V1) };

    //get u, which is normalized V2 x V1
    Point u_ = { V2[1]*V1[2] - V2[2]*V1[1],
                V2[2]*V1[0] - V2[0]*V1[2],
                V2[0]*V1[1] - V2[1]*V1[0] };
    Point u = { (V2[1]*V1[2] - V2[2]*V1[1])/get_length(u_),
                (V2[2]*V1[0] - V2[0]*V1[2])/get_length(u_),
                (V2[0]*V1[1] - V2[1]*V1[0])/get_length(u_) };

    //get v, which is n x u
    Point v_ = { n[1]*u[2] - n[2]*u[1],
                n[2]*u[0] - n[0]*u[2],
                n[0]*u[1] - n[1]*u[0] };
    Point v = { (n[1]*u[2] - n[2]*u[1])/get_length(v_),
                (n[2]*u[0] - n[0]*u[2])/get_length(v_),
                (n[0]*u[1] - n[1]*u[0])/get_length(v_) };

    UVN result_uvn = {u, v, n};
    return result_uvn;
}

float get_length(Point X) {
    return abs(sqrt(pow(X[0],2)+pow(X[1],2)+pow(X[2],2)));
}
@

```

we need a header file to avoid complicated typedefs.

```

<<src/util.h>>=
#ifndef POINTS_HPP
#define POINTS_HPP
#include <tr1/array>

```

```
typedef std::tr1::array<float, 3> Point;  
typedef std::tr1::array<Point, 3> UVN;
```

```
UVN get_uvn(Point V1, Point V2);  
float get_length(Point X);  
#endif  
@
```

here is the command to link these files. Notice that I am using `-std=c++11` flag to enable c++ 11 features.

```
<<compile.sh>>=  
clang++ -std=c++11 -o bin/a.out src/main.cpp src/util.cpp  
@
```

Finally, the output binary executable is `bin/a.out`

### 3 Question 3