Centralized and Decentralized Fault Diagnosis of Partially **Observable Discrete-Event Systems**

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The proofs of the following lemmas are omitted because they follow directly from the definitions of $\mathbf{G}_{I}^{\sigma_{o0}}$ and $\mathbf{G}_{dc}^{\sigma_{o0}}$.

Lemma 1. For any path $p = q_{-1} \xrightarrow{\sigma_{o0}} (q_0, \ell_0) \xrightarrow{\sigma_{o1}}$

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1) $\ell_j = \ell_r$ for any $j, r \in [k, n]$; 2) There exists a path $\bar{p} = \bar{q}_0 \xrightarrow{\sigma_1} \bar{q}_1 \xrightarrow{\sigma_2} \bar{q}_2 \cdots \bar{q}_{b-1} \xrightarrow{\sigma_b}$ $\bar{q}_b \cdots \bar{q}_c \xrightarrow{\sigma_c} \bar{q}_b$ in **G** such that $P(\sigma_1 \sigma_2 \cdots \sigma_b \cdots \sigma_c) =$ $\sigma_{o0}\sigma_{o1}\cdots\sigma_{ok}\cdots\sigma_{o(n+1)}$ and $Q_p\subseteq Q_{\bar{p}}$, where Q_p and $Q_{\bar{p}}$ are the set of states composed of paths p and \bar{p} , respectively.

In a cycle, all the pairs have the same condition labels, which are either normal or F_i ($i \in [1, m]$), due to the assumption that all failure modes are permanent. We know that $\hat{\mathbf{G}}_{I}^{\sigma_{o0}}$ is defined on the basis of $\hat{\mathbf{G}}^{\sigma_{o0}}$ and $\hat{\mathbf{G}}^{\sigma_{o0}}$ derives from **G**. Thus, there exists a transition path \bar{p} in **G** corresponding to the path p with fault information in $\mathbf{G}_{I}^{\sigma_{o0}}$.

Lemma 2. For any path $p = (q_{-1}, q_{-1}) \xrightarrow{\sigma_{o0}} (q_{o0}^1, q_{o0}^2) \xrightarrow{\sigma_{o1}} (q_{o1}^1, q_{o1}^2) \xrightarrow{\cdots} (q_{o(k-1)}^1, q_{o(k-1)}^2) \xrightarrow{\sigma_{ok}} (q_{ok}^1, q_{ok}^2) \xrightarrow{\cdots} (q_{ok}^1, q_{ok}^2)$ $\begin{array}{cccc} (q_{on}^1,q_{on}^2) & \xrightarrow{\sigma_{o(n+1)}} & (q_{ok}^1,q_{ok}^2) & \textit{with } q_{ot}^1 & = (q_{\mathbf{n}t}^1,\ell_t^1) & \in \hat{Q}_{\mathbf{n}} \\ \textit{and } q_{ot}^2 & = (q_{\mathbf{f}t}^2,\ell_t^2) \in \hat{Q}_{\mathbf{f}} & (0 \leq t \leq n) \textit{ in } \hat{\mathbf{G}}_{dc}^{\sigma_{o0}} \textit{ ending with } a \end{array}$ cycle, the following hold:

1) There exist a path $p_{\mathbf{n}}^1$ in $\hat{\mathbf{G}}_{\mathbf{n}}^{\sigma_{o0}}$ and a path $p_{\mathbf{f}}^2$ in $\hat{\mathbf{G}}_{\mathbf{f}}^{\sigma_{o0}}$ ending with cycles, namely, $p_{\mathbf{n}}^1 = q_{-1} \xrightarrow{\sigma_{o0}} q_{00}^1 \xrightarrow{\sigma_{o1}} q_{01}^1 \cdots q_{o(k-1)}^1 \xrightarrow{\sigma_{ok}} q_{0k}^1 \cdots q_{0n}^1 \xrightarrow{\sigma_{o(n+1)}} q_{0k}^1$ and $p_{\mathbf{f}}^2 = q_{-1} \xrightarrow{\sigma_{o0}} q_{00}^2 \xrightarrow{\sigma_{o1}} q_{01}^2 \cdots q_{o(k-1)}^2 \xrightarrow{\sigma_{ok}}$ $\begin{array}{c} q_{ok}^2 \cdots q_{on}^2 \xrightarrow{\sigma_{o(n+1)}} q_{ok}^2; \\ \text{2)} \ \ \ell_1^1 = \ell_r^1 = \{N\} \ \text{and} \ \ell_j^2 = \ell_r^2 \text{ for any } j, \ r \in [k,n]. \end{array}$

Based on Lemmas 1 and 2. the proof of Theorem 1 is shown as follows.

Proof. (only if): Suppose G is F_i -asynchronously diagnosable w.r.t. Σ_f and Σ_o , but there exists a cycle cl = $(0 \le k \le j \le n)$ in $\hat{\mathbf{G}}_{dc}^{\sigma_{o0}}$ such that $\ell_j^2 = \{F_i\}$ $(i \in [1, m])$. Since $\hat{\mathbf{G}}_{dc}^{\sigma_{o0}}$ is reachable, there exists a path p in $\hat{\mathbf{G}}_{dc}^{\sigma_{o0}}$ ending with the cycle cl, i.e., $p=(q_{-1},q_{-1})\xrightarrow{\sigma_{o0}}$ $(q_{00}^1,q_{00}^2)\xrightarrow{\sigma_{o1}}(q_{01}^1,q_{01}^2)\cdots(q_{0(k-1)}^1,q_{0(k-1)}^2)\xrightarrow{\sigma_{ok}}(q_{0k}^1,q_{0k}^2)$ \cdots $(q_{0n}^1,q_{0n}^2)\xrightarrow{\sigma_{o(n+1)}}(q_{0k}^1,q_{0k}^2)$. Based on Lemma 2, we

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know that there exist one path $p_{\mathbf{n}}^1$ in $\hat{\mathbf{G}}_{\mathbf{n}}^{\sigma_{o0}}$ and one path $p_{\mathbf{f}}^2$ in $\hat{\mathbf{G}}_{\mathbf{f}}^{\sigma_{o0}}$ ending with cycles, namely, $p_{\mathbf{n}}^1 = q_{-1} \xrightarrow{\sigma_{o0}} q_{o0}^1 \xrightarrow{\sigma_{o1}} q_{o1}^1$ ther from Lemma 1, we know that for the path $p_{\mathbf{f}}^2$ there exists a path $\bar{p}^2 = \bar{q}_0^2 \xrightarrow{\sigma_1} \bar{q}_1 \xrightarrow{\sigma_2} \bar{q}_2^2 \cdots \bar{q}_{b-1}^2 \xrightarrow{\sigma_b} \bar{q}_b^2 \cdots \bar{q}_c \xrightarrow{\sigma_c} \bar{q}_b^2$ in \mathbf{G} such that $\mathsf{P}(\sigma_1 \sigma_2 \cdots \sigma_b \cdots \sigma_c) = \sigma_{o0} \sigma_{o1} \cdots \sigma_{ok} \cdots \sigma_{o(n+1)}$ and $Q_{p_{\mathbf{f}}^2} \subseteq Q_{\bar{p}^2}$.

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Let $Q_e(q, n')$ denote the set of state estimations calculated after the occurrence of n' events from state q. Suppose the state estimation $x_{0e} \in \mathcal{Q}_e(\bar{q}_s^2,0)$ $(s \in [1,b])$, where \bar{q}_s^2 is the first faulty state in the path \bar{p}^2 , is given. When the system evolves along the path \bar{p}^2 , there exists a state estimation $x_e^{n''} \in$ $\mathcal{Q}_e(\bar{q}_s^2,n'')$ $(n''=d+m_2*k_2,\,d=b-s,\,$ and $m_2=c-b+1$ is the length of $\bar{q}_b^2\cdots\bar{q}_c^2)$ such that $q_k^1\in x_e^{n''}$ and $q_k^2\in x_e^{n''}$ for any nonnegative integer k_2 . Then $\mathbf{D}(x_e^{n''})=-1$. Since \mathbf{G} is asynchronously diagnosable, there exists an integer N_i such that for any $x_e^{n'} \in \mathcal{Q}(q_s^2, n')$, $x_e^{n'} \subseteq Q_{F_i}$ holds for $n' \ge N_i$. We choose an integer k_2 such that $n'' \ge N_i$. Then we have that $x_e^{n''} \subseteq Q_{F_i}$, i.e., $\mathbf{D}(x_e^{n''}) = i$, which leads to a contraction. So the necessity holds.

(if): Suppose for every cycle $cl = (q_{ok}^1, q_{ok}^2) \xrightarrow{\sigma_{o(k+1)}} (q_{o(k+1)}^1, q_{o(k+1)}^2) \xrightarrow{(q_{on}^1, q_{on}^2)} (q_{on}^1, q_{on}^2) \xrightarrow{\sigma_{o(n+1)}} (q_{ok}^1, q_{ok}^2)$ with $q_{oj}^1 = (q_{\mathbf{n}j}^1, \ell_j^1) \in \hat{Q}_{\mathbf{n}}$ and $q_{oj}^2 = (q_{\mathbf{f}j}^2, \ell_j^2) \in \hat{Q}_{\mathbf{f}}$ ($0 \le k \le j \le n$), we have $\ell_j^1 = \ell_j^2 = \{N\}$ ($j \in [k, n]$). From the second clause of Lemma 2, we can infer that for any $q^d = ((q^1, \ell^1), (q^2, \ell^2))$ in $\hat{\mathbf{G}}_{dc}^{\sigma_{o0}}$, q^d is not contained in a loop if $\ell^1 \neq \ell^2$, which further implies that for any path $p = q_1^d \xrightarrow{\sigma_1} q_2^d \cdots \xrightarrow{\sigma_l} q_l^d$ in $\hat{\mathbf{G}}_{dc}^{\sigma_{o0}}$ with $q_r^d = ((q_r^1, \ell_r^1), (q_r^2, \ell_r^2))$ $(r \in [1, l])$ if $\ell_r^1 \neq \ell_r^2$, then the length of this path is finite, which is less than the number of states in $\hat{\mathbf{G}}_{dc}^{\sigma_{o0}}$.

Suppose the state estimation $x_{0e} \in \mathcal{Q}_e(q_{F_i}, 0) \ (i \in [1, m])$ is given when the system first reaches the fault state q_{F_i} . For any $x_e^{n'} \in \mathcal{Q}_e(q_{F_i}, n')$ with $n' > |\hat{Q}_d| \times (|\Sigma| - 1)$, we claim that $\mathbf{D}(x_e^{n'}) = i$. After n' transitions from state q_{F_i} , we have the path $p' = q_{F_i} \xrightarrow{\sigma_1} q_{F_i}^1 \cdots \xrightarrow{\sigma_{n'}} q_{F_i}^n$ with the observed event sequence $s_o = \mathsf{P}(\sigma_1 \sigma_2 \cdots \sigma_{n'}) \ (n'' = |s_o| \text{ is the length})$ of s_o). From above, for any state $q^d \in \hat{Q}_d$ that can be reached from (q_{-1},q_{-1}) in $\hat{\mathbf{G}}_{dc}^{\sigma_{o0}}$, we have that for any path starting from q^d , a state $\hat{q}^d=((\hat{q}^1,\hat{\ell}^1),(\hat{q}^2,\hat{\ell}^2))\in \hat{Q}_d$ with $\hat{\ell}^1=\hat{\ell}^2$ can be reached within $|\hat{Q}_d| - 1$ transitions. This implies that for any $n'' > |\hat{Q}_d| - 1$ and $x_e^{n''} \in \mathcal{Q}_e(q_{F_i}, n'')$, we have that $\mathcal{D}(x_e^{n''}) = i$. From the assumption in Remark 2, each observed event can be followed by at most $|\Sigma|-1$ unobserved events. It follows that for the above path p', $n' \leq (n'' + 1) \times (|Q| - 1)$, i.e., $n'' \ge n'/(|\Sigma| - 1) - 1$. So if $n' > |\hat{Q}_d| \times (|\Sigma| - 1)$, then $n'' \ge n'/(|Q|-1)-1 > |\hat{Q}_d|-1$, establishing our claim.

Note that we have assumed implicitly that |Q|>1; otherwise if |Q|=1, then from the assumption of no path cycles, no transition labeled by a failure event exists, so that the system is trivially diagnosable. Based on Definition 7, we can conclude that \mathbf{G} is diagnosable w.r.t, Σ_f and Σ_o . So the sufficiency also holds.