

# Symbolic Fault Diagnosis of Discrete-Event Systems Based on State-Tree Structures

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## APPENDIX

We need the following definitions and lemmas for the proofs later.

**Definition 1.** [Observation-Adjacency] For any two basic state-trees  $b, b' \in \mathcal{B}(\mathbf{ST})$ ,  $b'$  is said to be observation-adjacent to  $b$  (write as  $b \xrightarrow{\sigma} b'$ ) if there exists a string  $s\sigma t$  in which  $s, t \in \Sigma_{uo}^*$  and  $\sigma \in \Sigma_o$  such that  $b' = \Delta(b, s\sigma t)$ .  $\diamond$

Assume in the diagnoser  $\mathbf{G}_d = (\mathcal{A}_d, \Sigma_o, \Delta_d, A_{d0}, \hat{\kappa})$   $cl = (A_1, -1) \xrightarrow{\sigma_1} \dots \xrightarrow{\sigma_{n-2}} (A_{n-1}, -1) \xrightarrow{\sigma_{n-1}} (A_n, -1) \xrightarrow{\sigma_n} (A_1, -1)$  with  $n \geq 1$  is an  $F$ -indeterminate cycle. A cycle  $cl' = b_1 \xrightarrow{\sigma_1} \dots \xrightarrow{\sigma_{n-2}} b_{n-1} \xrightarrow{\sigma_{n-1}} b_n \xrightarrow{\sigma_n} b_1$  is called an underlying faulty cycle of  $cl$  if  $b_i \in A_i$  and  $b_i \in B_F$ . Intuitively, if there is an  $F$ -indeterminate cycle, then the system has a cycle in the faulty mode  $F$  such that when it evolves on the cycle, it will generate the event sequence periodically. The cycle in the mode  $F$  and the corresponding event sequence keeps the diagnoser in the  $F$ -uncertain cycle indefinitely, and in this case, the system is not diagnosable.

**Lemma 1.** Let  $p = (A_1, -1) \xrightarrow{\sigma_1} \dots \xrightarrow{\sigma_{n-2}} (A_{n-1}, -1) \xrightarrow{\sigma_{n-1}} (A_n, -1)$  ( $n \geq 2$ ) be a path in the diagnoser  $\mathbf{G}_d$ . For any  $b_n \in A_n$ , there exist  $b_i \in A_i$  ( $1 \leq i \leq n-1$ ) such that  $b_i \xrightarrow{\sigma_i} b_{i+1}$ .

### A. Proof of Theorem 2 in Section III

**Proof:** (only if): Suppose that  $\mathbf{G}$  is diagnosable, but there exists an  $F$ -indeterminate cycle  $cl$  in the diagnoser  $\mathbf{G}_d = (\mathcal{A}_d, \Sigma_o, \Delta_d, A_{d0}, \hat{\kappa})$ . Since  $\mathbf{G}_d$  is reachable, there exists an event sequence that can take the diagnoser into a BSTA  $A_k$  belonging to  $cl$ . Let  $b_n \in A_n$  belong to an underlying faulty cycle of  $cl$ . By Lemma 1, there exist basic state-trees  $b_1, \dots, b_{n-1}$  such that  $b_i \xrightarrow{\sigma_i} b_{i+1}$  ( $1 \leq i \leq n-1$ ). After reaching  $b_n$ , the system may remain on the underlying faulty cycle causing the diagnoser to stay on the  $F$ -indeterminate cycle indefinitely. Therefore, there exists a trajectory for the system leading to basic state-trees in  $B_F$  such that the corresponding event

sequence throws the diagnoser into a cycle of  $F$ -uncertain BSTA and keeps it there indefinitely. Hence, the system is not diagnosable, which leads to a contradiction. So the necessity holds.

(if): Assume that no  $F$ -indeterminate cycle exists in the diagnoser  $\mathbf{G}_d$ . After the occurrence of  $F$  and the generation of a new observable event, the diagnoser reaches either  $F$ -certain or  $F$ -uncertain BSTA. If it is an  $F$ -certain BSTA, then it will remain  $F$ -certain (because fault is permanent) and the system is diagnosable. If it is an  $F$ -uncertain BSTA, then the number of  $F$ -uncertain BSTA is bounded. After the generation of a bounded number of observable events, the diagnoser will reach an  $F$ -certain BSTA (the diagnoser gets trapped indefinitely in a cycle of  $F$ -uncertain states only if the cycle is  $F$ -indeterminate).

Let  $n$  denote the number of events that it takes the diagnoser to detect and isolate. After the occurrence of  $F$ , the diagnoser can visit an  $F$ -uncertain BSTA  $(A, -1)$  at most  $|A \cap B_F|$  times. Then we have  $n \leq c \times m + m$ , where  $c = \sum_{(A, -1) \in \mathcal{A}_d} |A \cap B_F|$  and  $m$  is the length of the longest path of faulty basic state-trees. Since  $m \leq |B_F|$  and  $c \leq |B_F| \cdot |\mathcal{A}_d|$ ,  $n \leq c \times m + m \leq |B_F| \cdot |\mathcal{A}_d| \cdot |B_F| + |B_F| = |B_F|(|B_F| \cdot |\mathcal{A}_d| + 1)$ . Consequently, the system is diagnosable with a finite delay  $n = |B_F|(|B_F| \cdot |\mathcal{A}_d| + 1)$ . So the sufficiency holds.

### B. Proof of Proposition 1 in Section IV.B

**Proof:** Suppose no fault-free cycle exists in  $\mathbf{G}$ . Since faults are permanent, a cycle in  $\mathbf{G}$  composed of several faulty basic state-trees and normal basic state-trees can not exist. Hence, at least one faulty cycle exists in  $\mathbf{G}$ , which leads to the  $F$ -uncertain cycle  $cl$ . In this case, event  $\sigma_n$  is not eligible at normal basic state-trees satisfying  $M_n$ . Hence, after the occurrence of  $\sigma_n$  the successor predicate of  $M_n$  must be faulty, which leads to a contradiction.

### C. Proof of Proposition 2 in Section IV.B

**Proof:** From Proposition 1, there exists at least one fault-free cycle formed by basic state-trees in  $\mathbf{G}$  that has the same observation  $(\sigma_1 \sigma_2 \dots \sigma_n)^*$ . Then, we only need to show that a corresponding faulty cycle formed by basic state-trees in  $\mathbf{G}$  also shares the same observation as  $cl$ . Suppose  $(\forall i \in [1, n], \forall \sigma_f \in \Sigma_f) \Delta(M_i \wedge P_N, \sigma_f) \equiv \text{false}$ . Then, we have  $M_{(i+1) \bmod n} \wedge P_F = \langle \Delta(M_i \wedge P_F, \sigma_i) \rangle$ . Based on Lemma 1, for any  $b_{n+1} \models M_1 \wedge P_F$ , there exist  $b_i \models M_i \wedge P_F$  ( $1 \leq i \leq n$ ) such that  $b_i \xrightarrow{\sigma_i} b_{i+1}$ . Let  $b_{n+1} = b_1$ . Then  $b_1, \dots, b_n$  forms an underlying faulty cycle, we can infer that a corresponding faulty cycle formed by basic state-trees in  $\mathbf{G}$  with the same observation as  $cl$  exists. Hence, the cycle  $cl$  is an  $F$ -indeterminate one as well.

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#### D. Proof of Proposition 3 in Section IV.B

**Proof:** It can be proved using mathematical induction.

**BASIS STEP:** For  $k = 1$ ,  $S_{n+1}^{cl} \preceq S_1^{cl}$  is true because  $S_1^{cl} = M_1 \wedge P_F$  and  $S_2^{cl} = \langle \Delta(S_1^{cl}, \sigma_1) \rangle \preceq M_2 \wedge P_F = \langle \Delta(M_2 \wedge P_N, \Sigma_f) \cup \Delta(M_1 \wedge P_F, \sigma_1) \rangle$ , with the same reasoning along the event sequence  $\sigma_1, \dots, \sigma_n$ , we have  $S_n^{cl} = \langle \Delta(S_{n-1}^{cl}, \sigma_{n-1}) \rangle \preceq M_n \wedge P_F = \langle \Delta(M_n \wedge P_N, \Sigma_f) \cup \Delta(M_{n-1} \wedge P_F, \sigma_{n-1}) \rangle$ . Hence,  $S_{n+1}^{cl} = \langle \Delta(S_n^{cl}, \sigma_n) \rangle \preceq M_1 \wedge P_F = \langle \Delta(M_1 \wedge P_N, \Sigma_f) \cup \Delta(M_n \wedge P_F, \sigma_n) \rangle = S_1^{cl}$ .

**INDUCTIVE STEP:** Suppose  $S_{1+kn}^{cl} \preceq S_{1+(k-1)n}^{cl}$ . We need to show  $S_{1+(k+1)n}^{cl} \preceq S_{1+kn}^{cl}$ . Since  $S_{1+kn}^{cl} = \langle \Delta(S_{kn}^{cl}, \sigma_n) \rangle$  and  $S_{(k+1)n}^{cl} \preceq S_{kn}^{cl}$ ,  $S_{(k+1)n}^{cl} = \langle \Delta(S_{(k+1)n}^{cl}) \rangle \preceq \langle \Delta(S_{kn}^{cl}, \sigma_n) \rangle = S_{1+kn}^{cl}$ .

#### E. Proof of Theorem 2 in Section IV.B

**Proof:** (only if): Suppose that  $cl$  is an  $F$ -indeterminate cycle. Then we need to show that the fixed point reached by sequence  $S'^{cl}$  associated with  $cl$  is non-empty.

Since  $cl$  is an  $F$ -indeterminate cycle, at least one faulty cycle formed by basic state-trees in  $\mathbf{G}$  exists. Assume there exist exactly  $m$  faulty cycles ( $m \geq 1$ ). There exist a string  $s_i^j$  in  $\Sigma_{uo}^*$  and a basic state-tree  $b_i^j$  satisfying  $M_i \wedge P_F$  such that  $b_{(i+1) \bmod n}^j = \Delta(b_i^j, s_i^j \sigma_i)$  and  $b_1^j = \Delta(b_n^j, s_n^j \sigma_n)$  ( $1 \leq i \leq n$ ,  $1 \leq j \leq m$ ). Thus,  $(\forall k \in \mathbb{N}^*) b_i^j \models S_{i+kn}^{cl}$ , indicating that all the terms of  $S'^{cl}$  are non-empty. Clearly, the reached fixed point is also non-empty.

(if): Suppose that sequence  $S'^{cl}$  associated with  $cl$  has a non-empty fixed point. Now, we need to show that  $cl$  is an  $F$ -indeterminate cycle. From Proposition 1, the existence of a faulty cycle sharing the same observation with  $cl$  is sufficient.

We know that there exists an integer  $k \in \mathbb{N}^*$  such that  $S_{1+kn}^{cl} = S_{1+(k-1)n}^{cl}$ . Due to  $S_{1+kn}^{cl} \neq false$ , we assume that the predicate  $S_{1+kn}^{cl}$  holds exactly on the basic state-tree subset  $B_{S_{1+kn}^{cl}} = \{b_1, \dots, b_m\}$ . According to the definition of sequence  $S^{cl}$ , there exist  $b_i, b_j \in B_{S_{1+kn}^{cl}}$ , and  $t = s_1 \sigma_1 s_2 \sigma_2 \dots s_{n-1} \sigma_{n-1} s_n \sigma_n$  with  $s_l \in \Sigma_{uo}^*$  such that  $b_i = \Delta(b_j, t)$  ( $1 \leq l \leq n, 1 \leq i, j \leq m$ ). By repeating this procedure to  $b_i$  at least  $m$  times, we can infer that  $b_i$  is certainly visited twice, which indicates the existence of at least one faulty cycle. Therefore, the cycle  $cl$  is  $F$ -indeterminate.