#### **CIVIFORM**

# CODING E ROBOTICA PER L'INNOVAZIONE SOCIALE

# ROBOT

## ROBOT

Dal ceco robota, lavoro pesante.

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Dal ceco robota, lavoro pesante.

Usato dallo scrittore ceco Karel Čapek in un dramma teatrale del 1920 ad indicare degli umanoidi creati per svolgere i lavori più faticosi...

### **DEFINIZIONE**

Apparato meccanico ed elettronico programmabile, impiegato nell'industria, in sostituzione dell'uomo, per eseguire automaticamente e autonomamente lavorazioni e operazioni ripetitive, o complesse, pesanti e pericolose.



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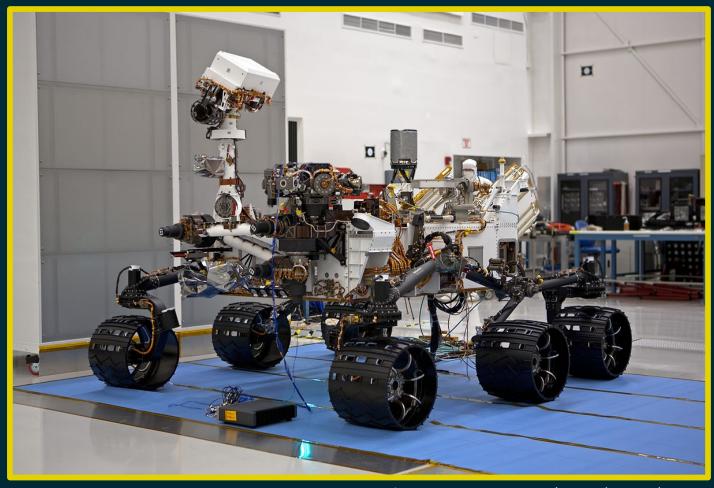
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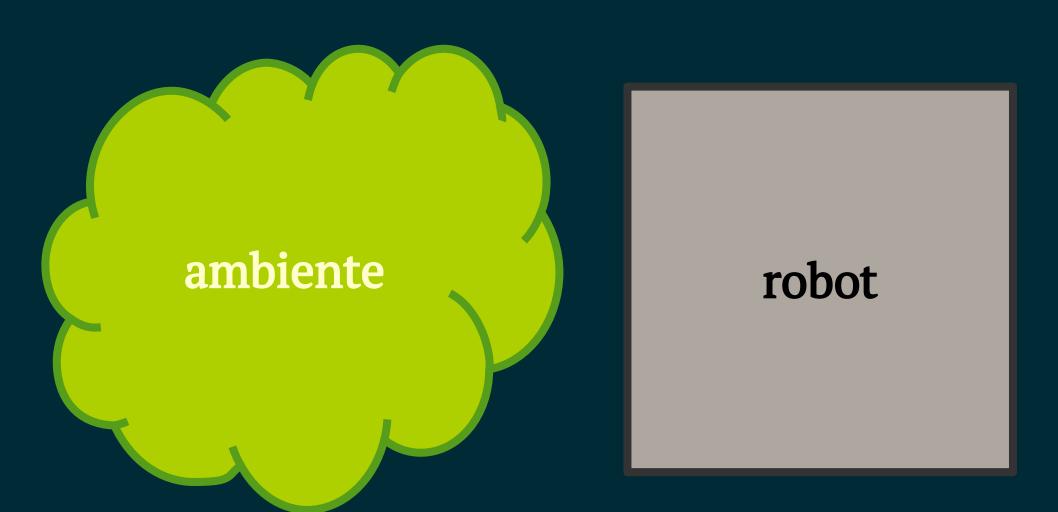
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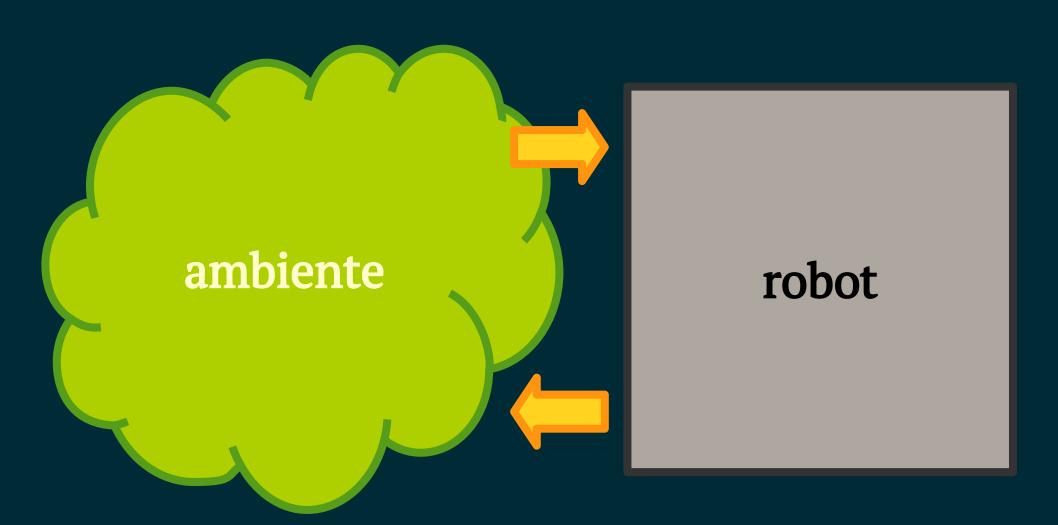


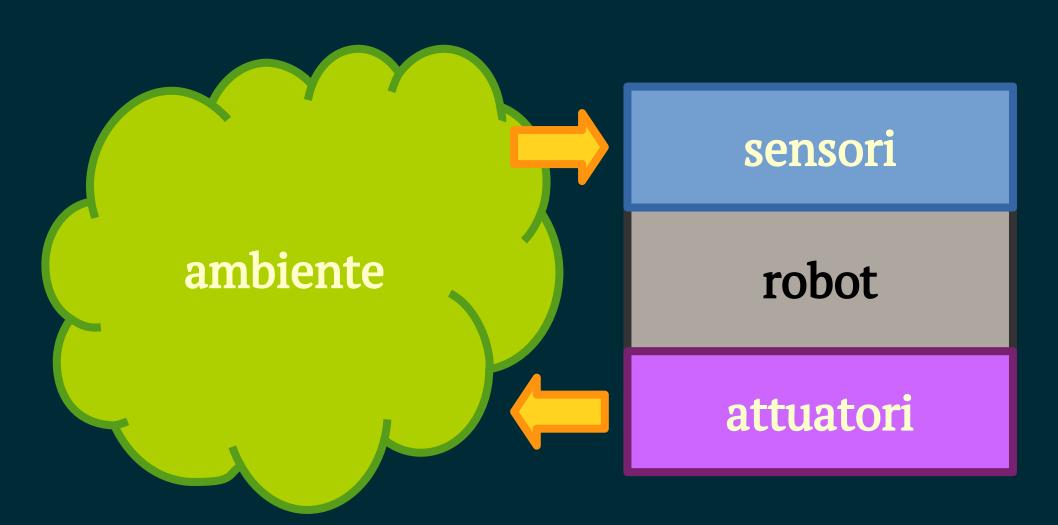
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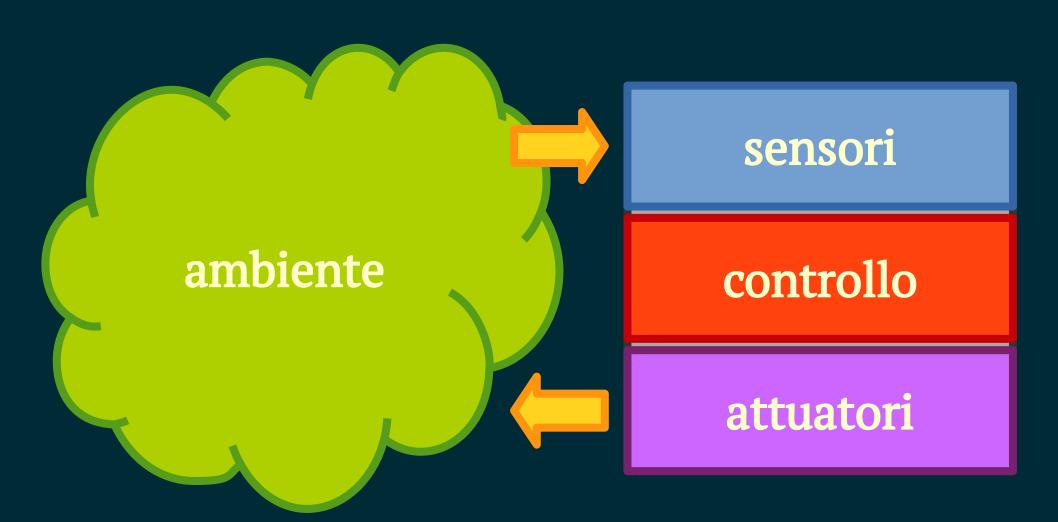


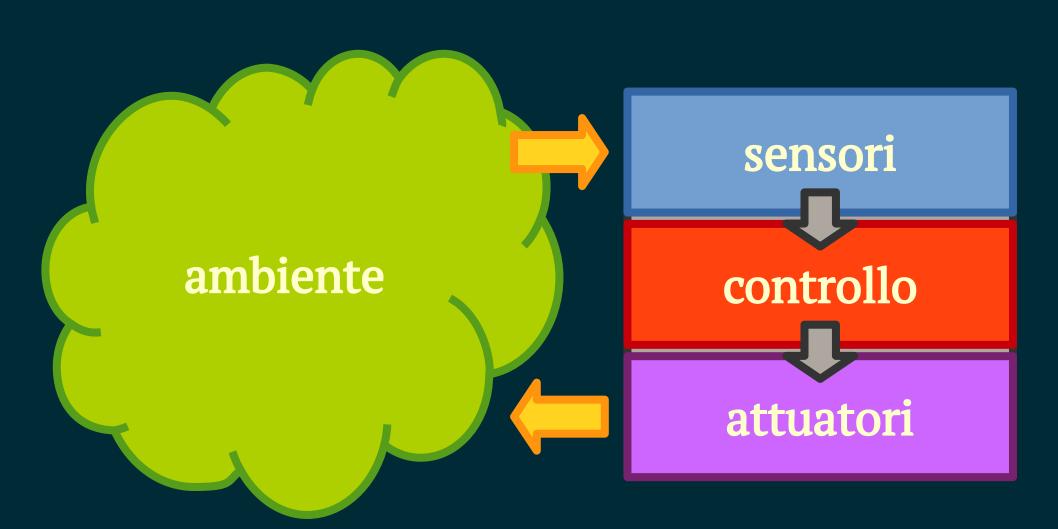
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# mBot2



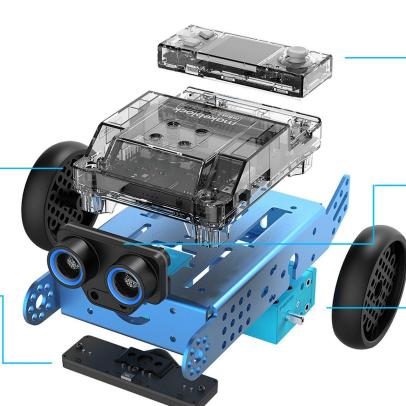
### mBot2

#### mBot2 shield

compatible with a variety of external components ,and includes a built-in lithium-ion battery.

#### Quad RGB sensor

Four sensor probes support color recognition ,as well as basic and advanced line detection programs.



#### CyberPi

ESP32 microprocessor for wireless communication ,and compatibility with block-based and Python coding.

#### **Ultrasonic Sensor 2**

Object detection is accompanied with 8 programmable LEDs for an enhanced interaction.

#### **Encoder Motors**

1 degree detection accuracy ,distance traveled, and up to 200 RPM can be precisely controlled.

### SENSORI

- joystick
- pulsanti
- microfono
- fotoricettore
- accelerometro/giroscopio
- sensore ultrasonico
- sensore di linea RGB

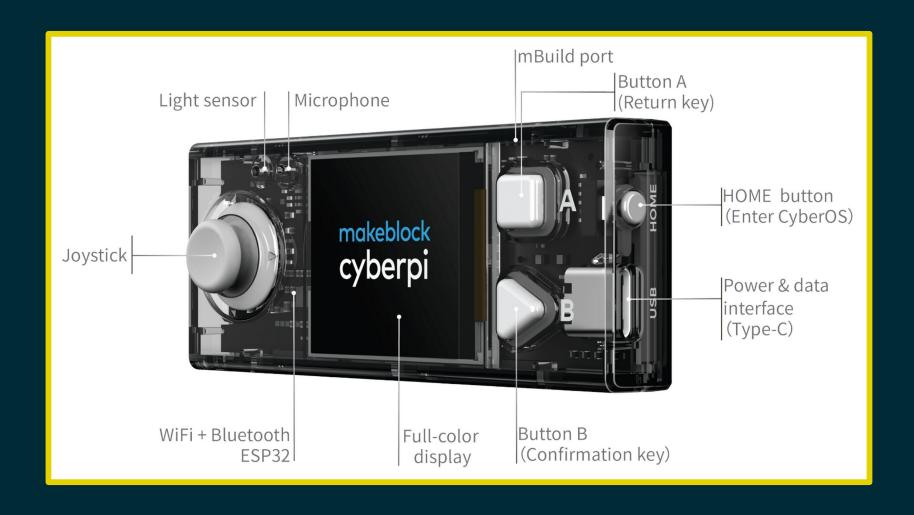
### **ATTUATORI**

- striscia LED
- altoparlante
- display grafico 128x128 a colori
- 2 motori con encoder
- 8 LED blu (montati sul sensore ultrasonico)

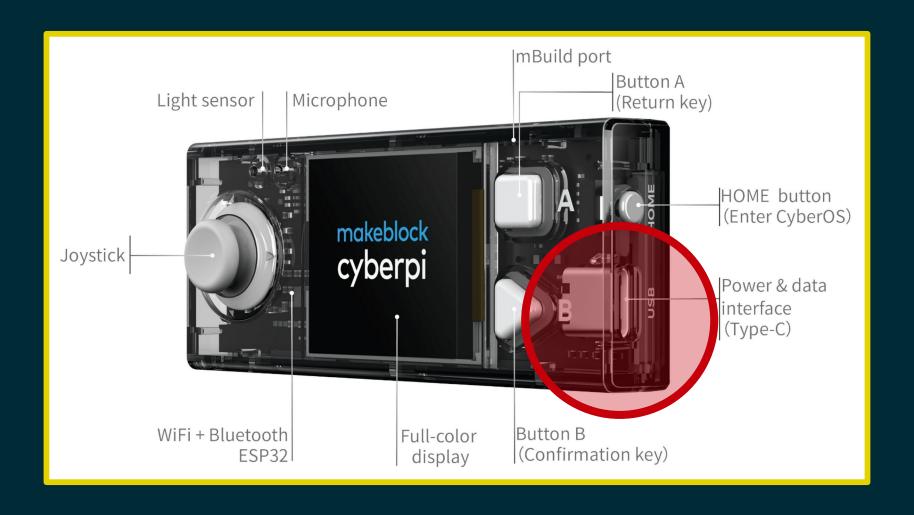
# CONTROLLO



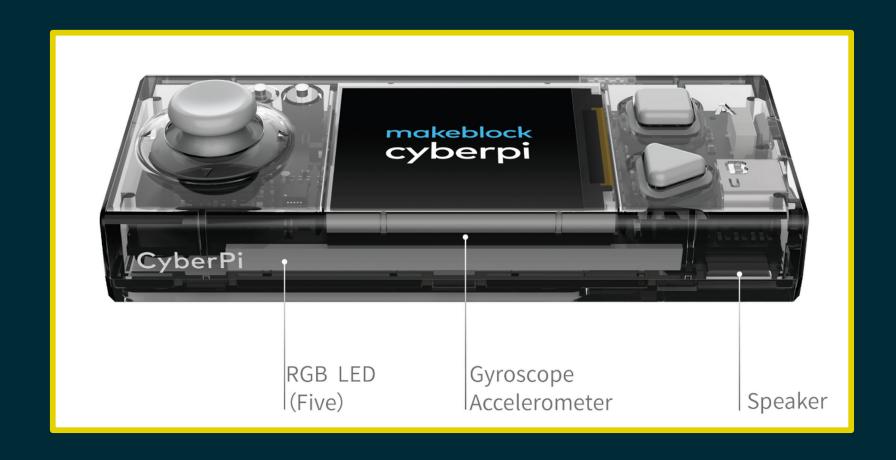
## **COMPONENTI**



# COMPONENTI



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### CARATTERISTICHE

Basata su SOC ESP-32

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#### Basata su SOC ESP-32

• CPU: Xtensa® 32-bit LX6 dual-core

• Clock: 240MHz

• **ROM**: 448KB

• **RAM**: 520KB

• Mem. di massa: 8MB SPI Flash + 8MB PSRAM