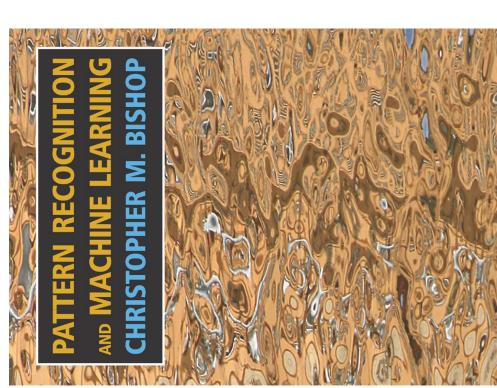
## Linear Classifiers

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#### Reference



Today's class *roughly* follows Chapter 4-4.2.

Pattern Recognition and Machine Learning Christopher Bishop, 2006

#### Outline

Geometry of decision function

Non probabilistic classifiers

Least square classifier

Fisher discriminant analysis

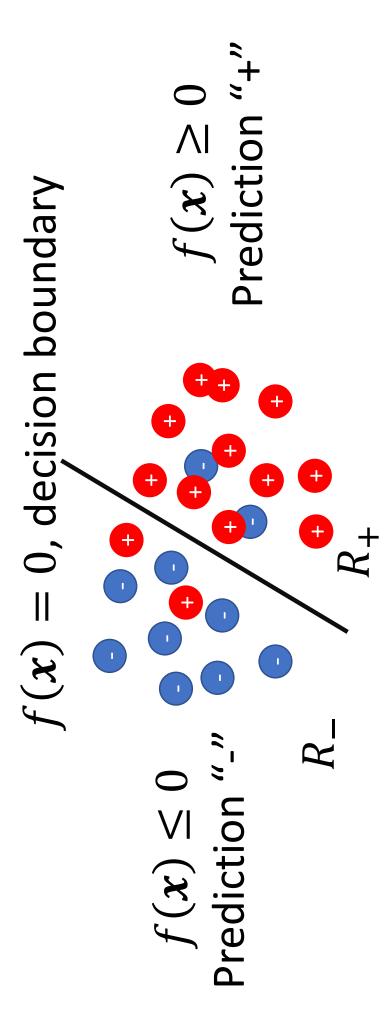
Probabilistic classifiers

Generative Classifiers

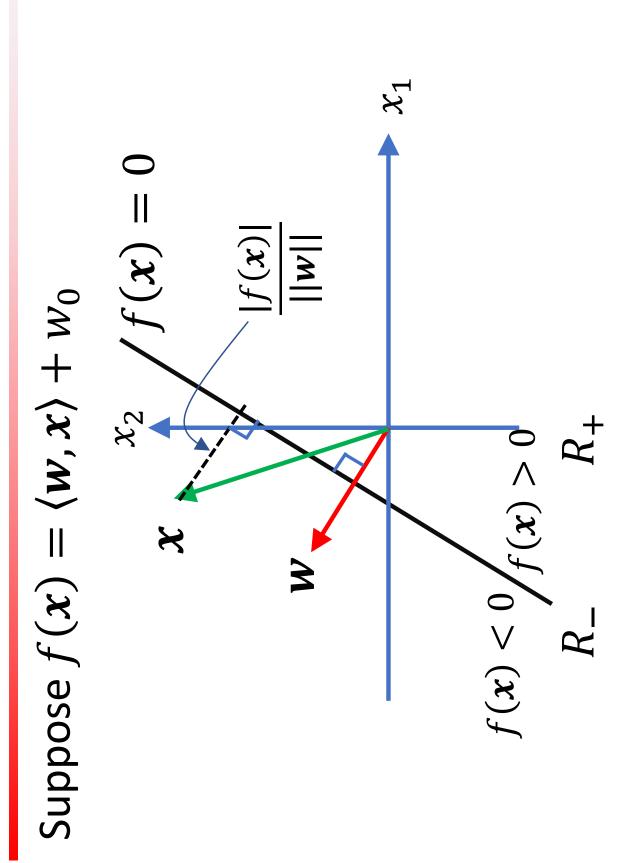
#### 4

### Binary Classification

- Input:  $x \in R^d$
- Output:  $y \in \{-1, +1\}$
- ullet A decision boundary is defined by a function f(x)



# Geometry of Binary Classification



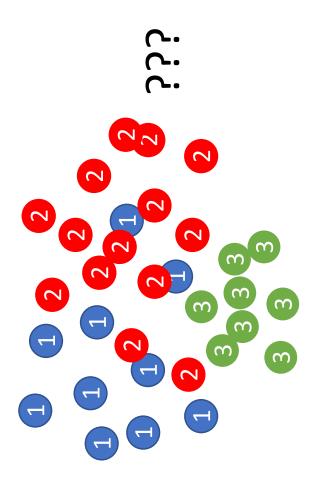
# Multi-class Classification

• Input:  $x \in R^d$ 

• Output:  $y \in \{1 ... K\}$ 

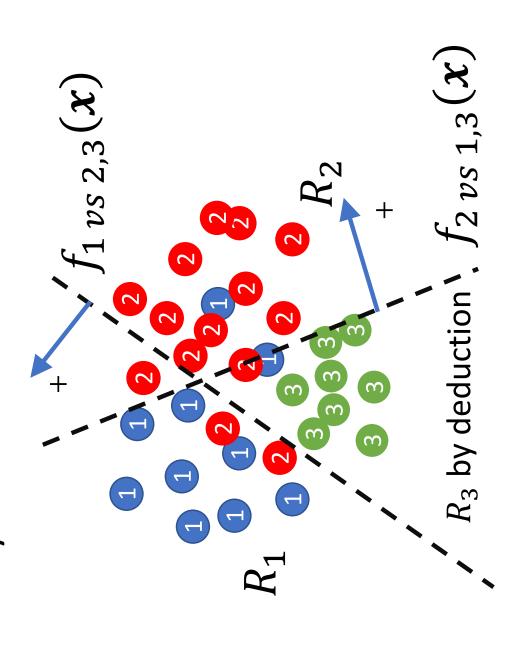
The geometry gets a lot more complicated...

• Cannot simply check the sign of a single f(x).



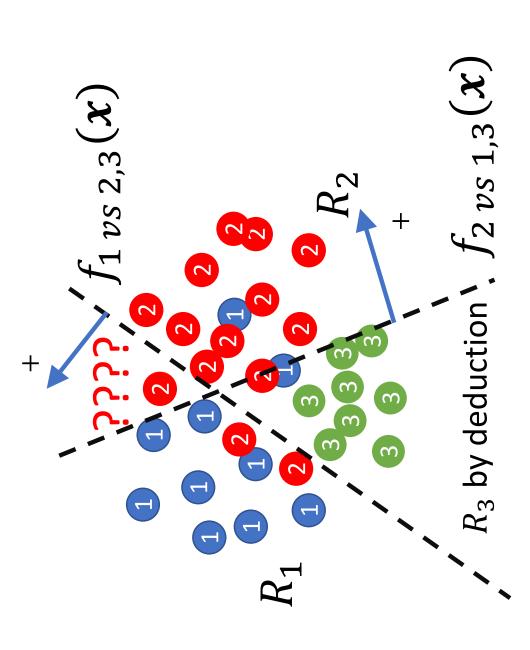
### One versus The Other

- ullet Construct K-1 binary classifiers
- Classify Class k vs. the rest of classes



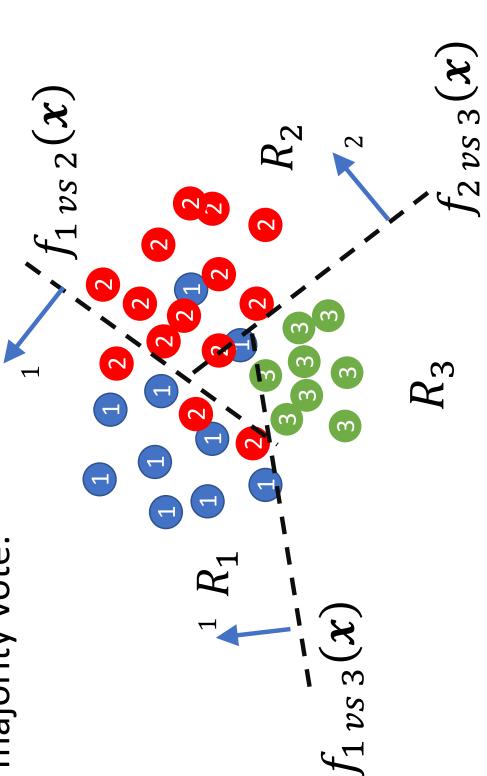
### One versus The Other

One versus the other also creates confusion!



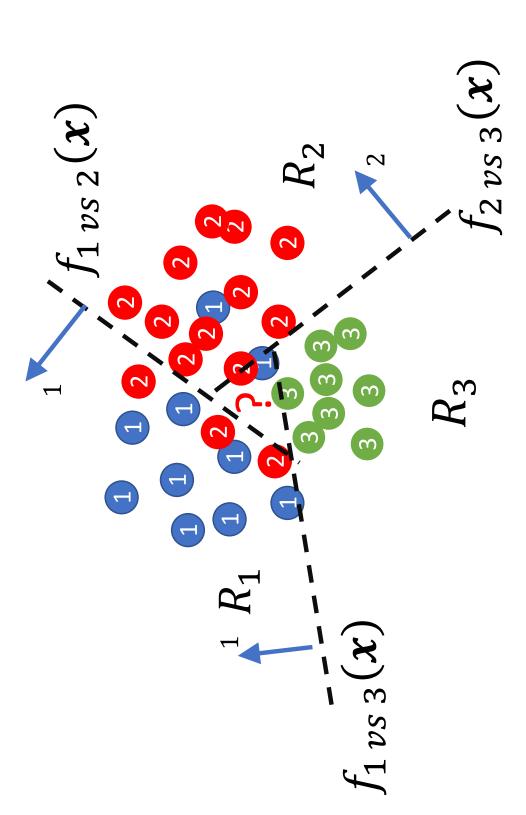
### One versus One

 We can create pairwise binary classifiers and check majority vote.



### One versus One

One versus one creates confusion as well...



# Multi-class Classification

- Or...
- rather than relying on sign of f to make predictions, we can fit a vector valued function  $f\colon R^d \to R^K$ :
- Given an x, prediction is  $\hat{k} = \underset{k}{\operatorname{argmax}} f^{(k)}(x)$ ,
- The classification does not have a simple geometry interpretation anymore.
- We will see an example soon.

# Least Squares Classifier

For binary classification, perform LS on D.

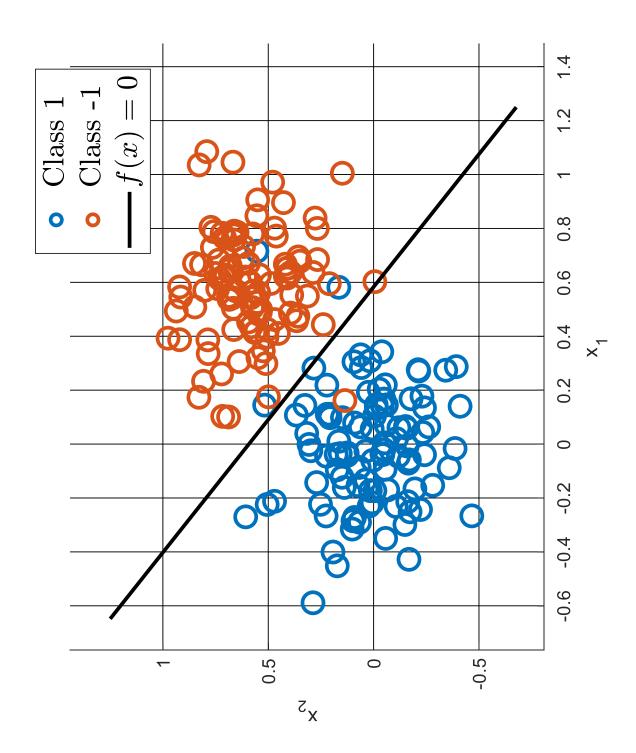
• 
$$\boldsymbol{w}_{\text{LS}} \coloneqq \underset{\boldsymbol{w}}{\operatorname{argmin}} \sum_{i \in D} [y_i - f(\boldsymbol{x}_i; \boldsymbol{w})]^2$$

ullet Now  $y_i$  takes binary value 1 or -1

• Prediction function  $f(x_i; w_{LS})$ .

• The predicted label  $\hat{y}\coloneqq \mathrm{sign}(f(\pmb{x}_i;\pmb{w}_{\mathrm{LS}}))$ 

## east Square Classifier

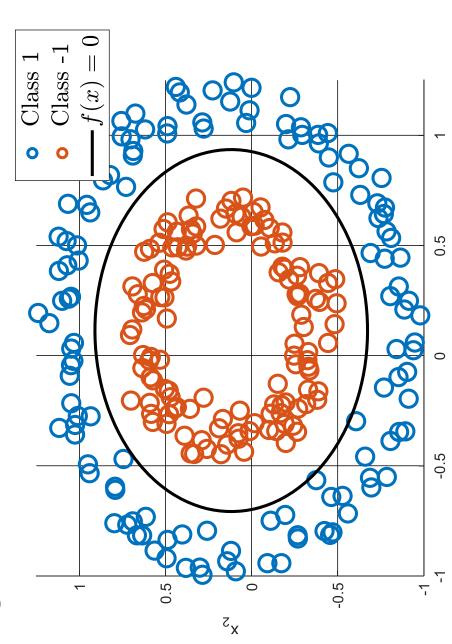


### east Square Classifier

ullet You can use feature transform  $oldsymbol{\phi}$  for f as well.

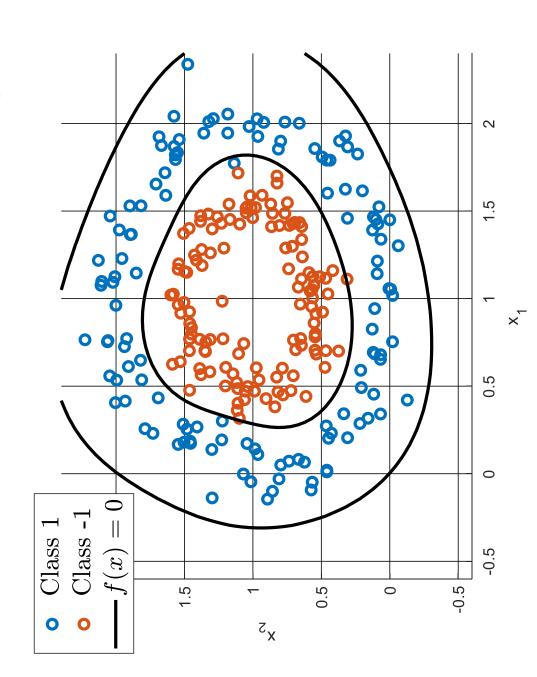
• 
$$f(x; w) := \langle w, \phi(x) \rangle$$
,

e.g. poly., trigonometric, RBF, kernel



### east Square Classifier

Data may not be separable in the original space but can be separable in the **feature space** created by  $oldsymbol{\phi}$ !



# Multi-class LS classification

- LS can be adapted to multi-class classification.
- Suppose output  $y \in \{1 ... K\}$
- Replace  $y_i = k$  in D with  $oldsymbol{t}_i \in \{0,1\}^K$  .
  - $t_i^{(k)} = 1$ .
- $t_i^{(j)} = 0, \forall j \neq k$
- "One-hot encoding"

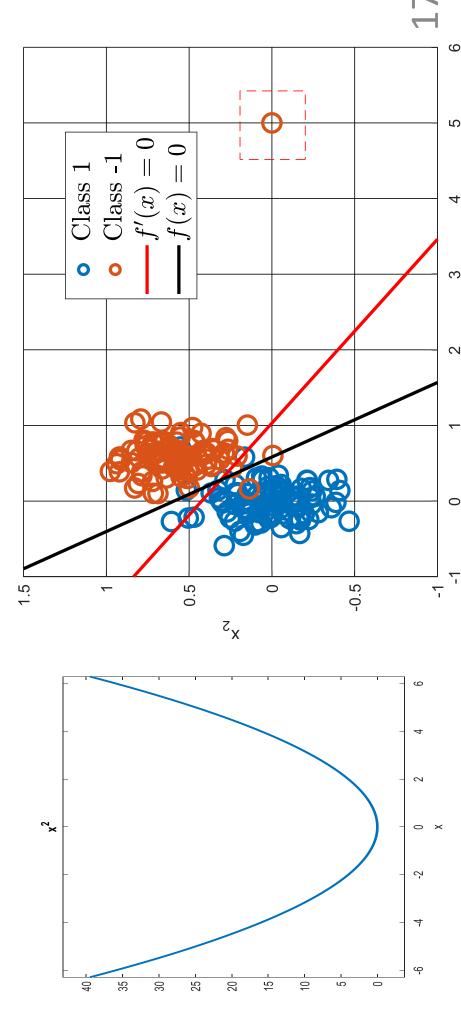
• 
$$W_{LS} \coloneqq \operatorname{argmin}_{W} \sum_{i \in D} || \boldsymbol{t}_i - \boldsymbol{f}(\boldsymbol{x}_i; \boldsymbol{W}) ||^2$$

• 
$$W_{LS} \coloneqq \operatorname{argmin}_{W} \sum_{i \in D} ||\boldsymbol{t}_{i} - f(\boldsymbol{x}_{i}; W)||^{2}$$
  
•  $W \in R^{(d+1) \times K}$ ,  $\widetilde{\boldsymbol{x}}_{i} \coloneqq \left[\boldsymbol{x}_{i}^{\mathsf{T}}, 1\right]^{\mathsf{T}} \in R^{d}$ ,  $f(\boldsymbol{x}; W) = W^{\mathsf{T}}$ 

• Prediction: 
$$\hat{k} = argmaxf^{(k)}(\boldsymbol{x}; \boldsymbol{W}) = argmax \left(\boldsymbol{w}_{LS}^{(k)}\right)^{\top} \tilde{\boldsymbol{x}}$$

# Why not to use LS Classifier?

- Square loss does not make sense in classification tasks.
- Data point far away from decision boundary can influence the decision boundary by a lot.



# Why not to use LS Classifier?

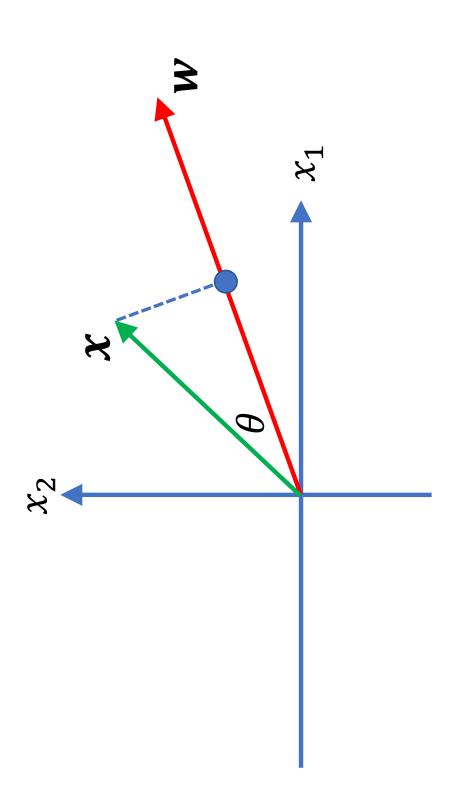
- Unlike LS regression,
- LS classification lacks a probabilistic interpretation.
- Likelihood of some probabilistic model It cannot be interpreted as Maximum

# Fisher Discriminant Analysis (FDA)



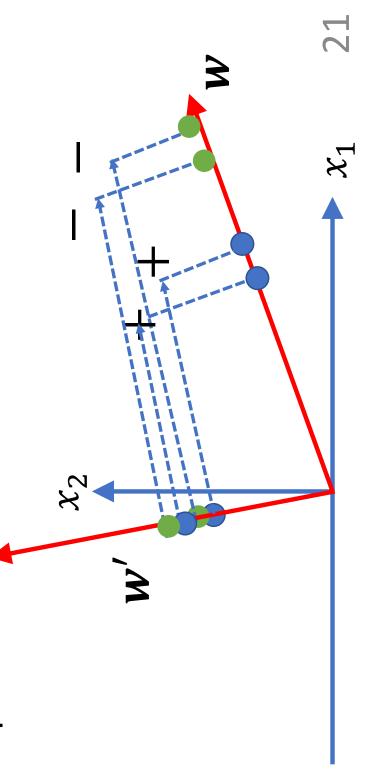
# **Embedding by Inner Product**

• The inner product  $\langle w, x \rangle$  "embeds" x, onto a onedimensional line along w direction.

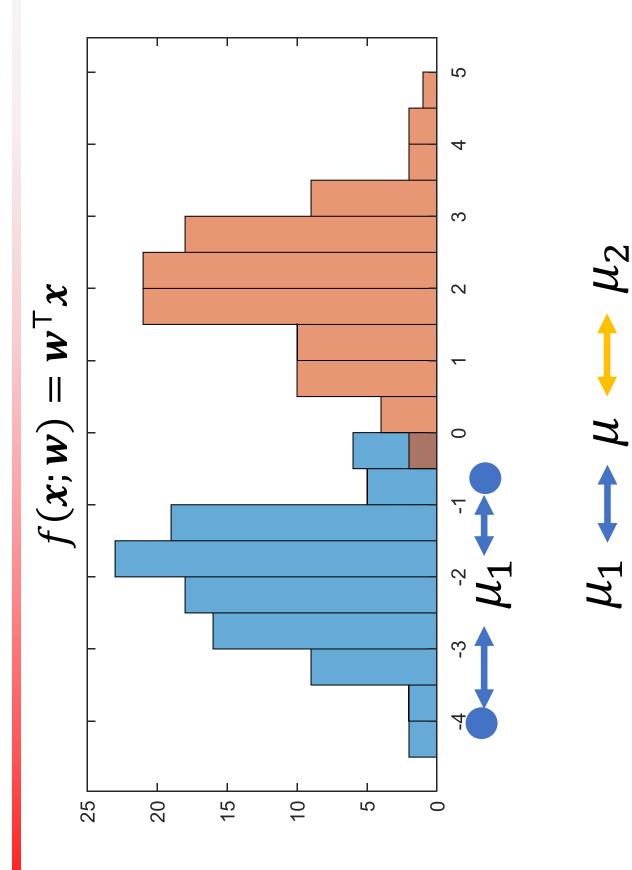


# **Embedding by Inner Product**

- What would be a good embedding?
- Clearly, we prefer  $\boldsymbol{w}$  to  $\boldsymbol{w}'$ , as the embedding is more separated between + and -
- We want points within the class close, but points between two classes far apart.



#### Within Class and Between Class Scatterness



# Within-class Scatterness

- Embedding is  $w^{\mathsf{T}}x$ .
- ullet Embedded center for class k:

$$oldsymbol{\hat{\mu}}_k = rac{1}{n_k} \sum_{i,y_i=k} oldsymbol{w}^{ op} oldsymbol{x}_i$$

Within class scatterness of class k:

$$\bullet s_{\mathrm{W},k} = \sum_{i,y_i=k} (\mathbf{W}^{\mathsf{T}} \mathbf{x}_i - \hat{\mu}_k)^2$$

Sum over points in individual classes.

# Between-class Scatterness

Embedded dataset center:

$$oldsymbol{\cdot} \hat{\mu} = rac{1}{n} \sum_{i=1}^n oldsymbol{w}^{\mathsf{T}} oldsymbol{x}_i$$

Between-class scatterness

$$\bullet s_{b,k} = n_k (\hat{\mu}_k - \hat{\mu})^2$$

 $ullet n_k$  is needed to make  $s_{\mathrm{b},k}$  at the same scale with  $S_{\mathrm{W},k}$ .

# Fisher Discriminant Analysis

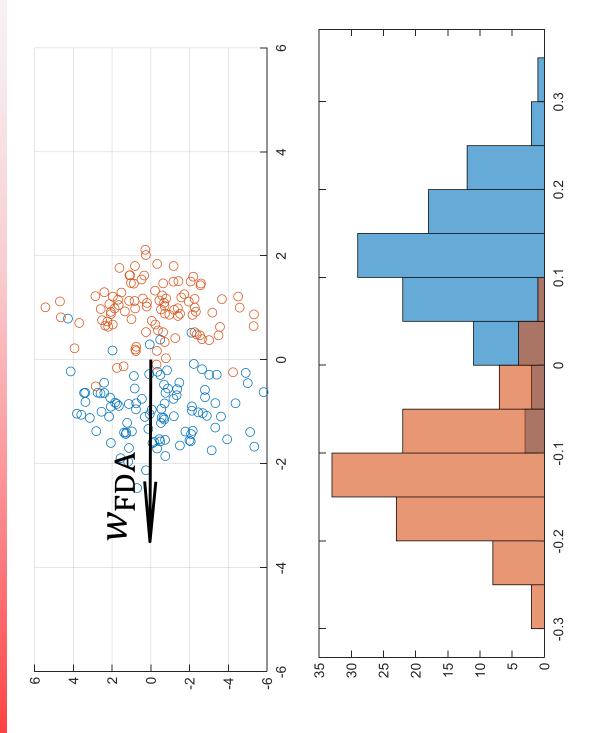
- **Maximizing** between class scatterness  $\forall_k$ .
- Minimize within class scatterness  $\forall_k$  •
- $\max_{\mathbf{w}} \sum_{k} S_{\mathbf{b},k} / \sum_{k} S_{\mathbf{w},k}$

• If K=2, this has a simple solution that

$$ullet W \coloneqq S_w^{-1}(\mu_+ - \mu_-), S_w \coloneqq \sum_{k=1}^K S_k$$

- ullet  $S_k$  is sample covariance of class k times  $n_k$ .
- Read PRML 4.14 for its derivation

### Example of FDA



# Fisher Discriminant Analysis

- However, FDA does not learn a decision function f.
- $f(x; w_{\text{FDA}}) = \langle w_{\text{FDA}}, x \rangle$  obtained by FDA cannot be directly used for making a prediction:
- as positive or negative data point: FDA does not care about • In general,  $f(x; oldsymbol{w}_{ ext{FDA}}) > 0$  does not mean x is predicted classification accuracy, a.k.a., minimizing FP or FN.

#### Generative Classifiers Probabilistic

# Probabilistic Classification

 How to put classification problem under a prob. framework?

Minimize Expected Loss:

$$\hat{y} \coloneqq \operatorname{argmin}_{y_0} \mathbb{E}_{p(y|x)}[L(y, y_0) | x]$$

• We need: p(y|x),  $y \in \{1, ..., K\}$ 

- Discriminative: Infer p(y|x) directly.
- **Generative**: Infer  $p(y|x) \propto p(x|y)p(y)$ , infer p(x|y)!

# Continuous Input Variable

- To infer p(x|y), we need a model.
- If x is continuous, MVN is a natural choice for p(x|y).
- Model  $p(x|y=k;w) \coloneqq N_x(\mu_k,\Sigma_k)$
- Assuming IID, and all classes have shared covariance ∑
- Write down the likelihood over D:
- $\bullet \ p(D|\mathbf{w}) = \prod_{i \in D} p(\mathbf{x}_i, y_i|\mathbf{w}) = \prod_{i \in D} p(\mathbf{x}_i|y_i; \mathbf{w}) p(y_i)$  $= \left| \ \left| N_{x_i}(\boldsymbol{\mu}_{y_i}; \boldsymbol{\Sigma}) \, p(y_i) \right| \right.$

# Continuous Input Variable

• 
$$\widehat{\boldsymbol{\mu}}_{1...K}, \widehat{\boldsymbol{\Sigma}} := \underset{\boldsymbol{\mu}_{1...k,\Sigma}}{\text{arg max}} \sum_{i \in D} \log[N_{x_i}(\boldsymbol{\mu}_{y_i}; \boldsymbol{\Sigma}) p(y_i)]$$

- 1. Plug in estimates for  $p(y_i = k)$ , which is  $\frac{n_k}{n}$ .
- Now work out the MLE for  $\widehat{\pmb{\mu}}_k\coloneqq \frac{1}{n_k}\sum_{i\in D,y_i=k}\pmb{x}_i$
- $\sum (x_i \widehat{\boldsymbol{\mu}}_k)(x_i \widehat{\boldsymbol{\mu}}_k)^{\mathsf{T}}$ 3. Plug in  $\widehat{\boldsymbol{\mu}}_k$  to work out  $\widehat{\Sigma} := \sqrt{\frac{n_k}{1}}$

MLE of covariance of individual classes!

# Linear Decision Boundary

- Prediction:  $\hat{y} := \operatorname{argmax}_{y} p(y|\mathbf{x}; \hat{\mathbf{w}}) \propto p(\mathbf{x}|y; \hat{\mathbf{w}}) p(y)$
- Prove: when using shared covariance matrix MVN model,
  - $\{x|p(y=k|x; \widehat{\mathbf{w}}) = p(y=k'|x; \widehat{\mathbf{w}})\}$  $\forall k \neq k'$ the decision boundary is piecewise-linear. The decision boundary is

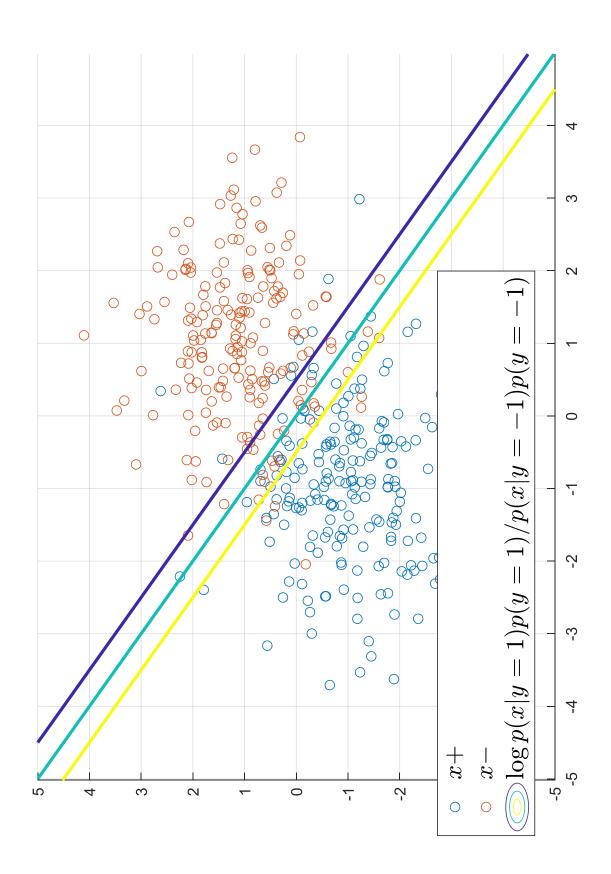
Which is the same as the set

$$\left\{ x \middle| \frac{p(\boldsymbol{x}|\boldsymbol{y} = k; \hat{\boldsymbol{w}}) p(\boldsymbol{y} = k)}{p(\boldsymbol{x}|\boldsymbol{y} = k'; \hat{\boldsymbol{w}}) p(\boldsymbol{y} = k')} = 1 \right\}$$

$$\forall k \neq k'$$

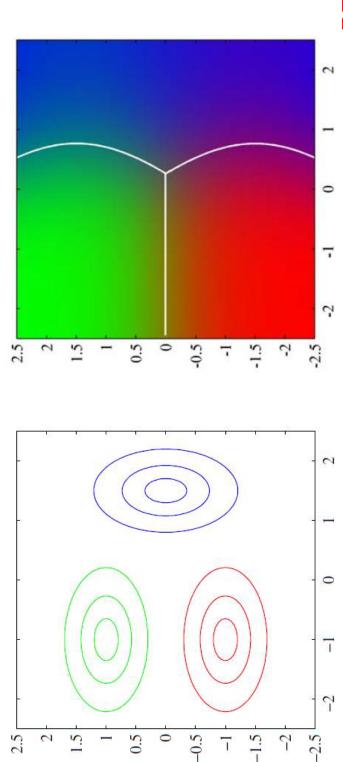
**Hint**: take log on both sides of the equality.

# Linear Decision Boundary



# Continuous Input Variable

- You can also assume for each class k, there are different covariance matrices  $\Sigma_k$ .
- The MLE reduces to estimating individual  $oldsymbol{\mu}_{k}$  and  $oldsymbol{\Sigma}_{k}$  .
- The decision boundary is no longer linear.



0.5

PRML, Figure 434

#### 35

# Discrete Input Variable x

- In many classification tasks, we are dealing with discrete variables as x. For example, in a spam filter,
- document. This is called "bag of words" representation.  $oldsymbol{x}\coloneqq \left[x^{(1)},...,x^{(d)}
  ight]^{ op}$  are frequencies of words in a
- $y \in \{\text{spam, ham}\}$ .
- For example, the document "to be or not to be"
- x := [to = 2, be = 2, or = 1, not = 1, question = 0]
- $x^{(i)} \in N_0$

#### Naïve Bayes

- Assume  $x^{(1)}$  ...  $x^{(d)}$  follows multinomial distribution
- $p(x=x_0|y) \propto \prod_{i=1\dots d} eta(i|y)^{x_0^{(i)}}$  up to constant does not depend on y.
- $\beta(i|y=k)$  is the probability of word i occurs in class k.
- It is easy to estimate:

$$\beta(i|y = k) \approx \frac{\sum_{j \in D, y_j = k} x_j^{(i)}}{\sum_{j \in D, y_j = k} \sum_{i=1}^d x_j^{(i)}}$$

•  $\beta(\text{to}|y=\text{spam})$  is occurrences of the word "to" in "spam" emails divided by total number of words in "spam" emails in our training dataset.

#### Naïve Bayes

• Prediction:  $\hat{y} := \operatorname{argmax}_{y} p(x = x_0 | y) p(y)$ 

• 
$$p(y=k)$$
:  $\frac{n_k}{n}$ 

$$ullet p(x=x_0|y) \propto \prod_{i=1...d} eta(i|y)^{x_0^{(i)}}$$

•  $\beta(i|y)$  has been obtained by previous counting.

• 
$$p(x = "to be or not to be" | y = spam) \propto \beta(to|spam)^2 \beta(be|spam)^2 \beta(or|spam)\beta(not|spam)$$

#### Conclusion

We have studied classification problem:

Geometry of decision function

Least square classifier

Fisher discriminant analysis

Within and between scatterness

Generative Classifiers:

MVN for continuous input variable

Naïve Bayes for discrete input variable

#### Homework

Prove the statement on page 33.

parameters in multinomial distribution. (2) Explain the Naïve Bayes classifier using a Maximum Likelihood (1) Derive the maximum likelihood estimation for framework.

### Computing Lab

Implement a version of Perception classifier: "Simplitron"

• Demo.