As a recap, h is an eigenvalue of A if Av = hv for some vector v. As of now, however, we don't know how to find the eigenvectors or eigenvalues of A unless we are given them. Let's work through how to find both. If I is an eigenvalue of A, then AV = IV for some vector V. Then AV-2V= 0 ⇔ AV-2InV=0 ⇔ (A-2In)V=0 So the set of all vectors with eigenvalue 1, Ex = Ker (A-JIn). This is called the 1 eigenspace, where 1 is the specific eigenvalue Working from this, I is not an eigenvalue of A if and only if: E, = {0} Since of can't be the only thing in the eigenspace, since of is not an eigenv $Ker (A-\lambda I_n) = \{\vec{0}\}$ rref {A - \lambda In} = In $A - \lambda I_n$ is invertible det (A-JIn) # 0 So lis an eigenvalue of A if and only if det (A-LIn) = 0 det (A-JIn) is the characteristic polynomial of A. It is a degree n polynomial in J. Now we can find out our eigenvalues and their associated eigenvectors 1) Use the characteristic polynomial to find all eigenvalues. det (A-NIn)=0 E, = Ker (A- JIn) 2) Use each eigenvalue to Find each eigenspace. Some last definitions and Facts. IF I is an eigenvalue of A, the geometric multiplicity of λ is the dim (E_{λ}) , or the number of linearly independent eigenvectors with eigenvalue λ . the algebraic multiplicity of λ is the number of times it appears algebraically as a solution to the characteristic polynomial. 1 ≤ geometric multiplicity ≤ algebraic multiplicity If has an eigenbasis if and only if the algebraic multiplicity is equal to the geometric multiplicity for each eigenvalue This is the same as the geometric multiplicities summing to n (A is an n x n matrix). IF A has a distinct eigenvalues, it has an eigenbasis (without us even knowing the eigenvestors), since eigen vectors with different eigenvalues are always linearly independent. For a 2×2 matrix, the characteristic polynomial is λ^2 -(tr A) λ + (det A) tr A is the trace of A, which is the sum of the diagonal.