

Given n vectors $(\vec{v}_1, \dots, \vec{v}_n)$ that form a basis of \mathbb{R}^n , this means

1) you can express any vector \vec{x} in \mathbb{R}^n as a linear combination $c_1\vec{v}_1 + \dots + c_n\vec{v}_n$

↳ this means the system $c_1\vec{v}_1 + \dots + c_n\vec{v}_n = \vec{b}$ is consistent for every vector \vec{b} in \mathbb{R}^n

↳ this means we can never row reduce to have a row of all zeros, so...

2) the matrix $\begin{bmatrix} \vec{v}_1 & \vec{v}_2 & \dots & \vec{v}_n \end{bmatrix}$ (this matrix has each vector as a column) row reduces to the Identity Matrix I_n

↳ this means there is only one way to express any vector \vec{x} as a linear combination $c_1\vec{v}_1 + \dots + c_n\vec{v}_n$

The Identity matrix I_n is a square matrix with n rows and n columns, with a leading one across the diagonal and zeros everywhere else.

To multiply two matrices, always check the dimensions align. If A is $p \times m$ and B is $m \times n$, then AB is a $p \times n$ matrix, but BA is not defined.

Example: $A = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$ $B = \begin{bmatrix} -3 & 4 \end{bmatrix}$ solve AB and BA if possible.

AB $\overbrace{(2 \times 1) \times (1 \times 2)}^{\text{must match}}$ = 2×2 matrix
resulting matrix B

$$A \begin{bmatrix} -3 & 4 \\ -3 & 4 \\ -6 & 8 \end{bmatrix} AB$$

BA $\overbrace{(1 \times 2) \times (2 \times 1)}^{\text{resulting matrix}}$ = 1×1 matrix
match

$$B \begin{bmatrix} 1 \\ 2 \end{bmatrix} A$$
$$B \begin{bmatrix} -3 & 4 \end{bmatrix} \begin{bmatrix} -3+8 \\ -3+8 \end{bmatrix} BA = \begin{bmatrix} 11 \end{bmatrix}$$