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Vectors (\vec{v_1},...,\vec{v_K}) are linearly independent if there exists a non-trivial linear relation among them.
A trivial linear relation is C, v, + ... + c, v, = 0 where all ci's are D. If any of the coefficients are non-zero, then we have a non-trivial linear relation.
Example: 2\vec{v_1} - 4\vec{v_3} + 5\vec{v_4} = \vec{o} is a non-trivial linear relation. 0\vec{v_1} + ... + 0\vec{v_k} = \vec{o} is a trivial linear relation
We can now update our definition of a basis to include this idea. A basis of Rn is a collection of linearly independent vectors (vi, ..., vii) that span Rn.
Note that with this definition, we don't specify that we have in vectors, since linear independence implies we will always only have in vectors
A subspace of \mathbb{R}^n is a set V in \mathbb{R}^n such that
       1) the sum of any two vectors in V is still in V. V is closed under addition
           If \vec{v_1}, \vec{v_2} are in V, then \vec{v_1} + \vec{v_2} is in V
       2) every scalar multiple of a vector in V is still in V. V is closed under scalar multiplication
            IF Vi is in V and K is a scalar, then KV is in V
           this property implies that ō is always in every subspace, and is always a good first thing to check
       To show a subset V of \mathbb{R}^n is a subspace of \mathbb{R}^n, you must show the subset is closed under addition and scalar multiplication
        1) check if 0 is in V. If it isn't, V isn't a subspace.
       2) 6how V is closed under addition.
               This usually involves taking the properties of Vi and Viz and adding the properties together
       3) show V is closed under scalar multiplication.
               This usually involves taking the properties of V and rewriting I distributing the scalar
       Example 2: V is a plane consisting of all vectors \begin{bmatrix} x \\ y \\ z \end{bmatrix} satisfying 2x - 4y + 3z = 0. Show V is a subspace and Find a basis of V.
              1) o is in V V
              2) let \overrightarrow{v_1} = \begin{bmatrix} x_1 \\ y_1 \\ z_1 \end{bmatrix}, \overrightarrow{v_2} = \begin{bmatrix} x_2 \\ y_2 \\ z_2 \end{bmatrix} e V
                                                        50 2x_1 - 4y_1 + 3z_1 = 0 and 2x_2 - 4y_2 + 3z_2 = 0
                  is \vec{V_1} + \vec{V_2} = \begin{bmatrix} x_1 + x_2 \\ y_1 + y_2 \\ z_1 + z_2 \end{bmatrix} in V^2
                                                        2x_1 - 4y_1 + 3z_1 + 2x_2 - 4y_2 + 3z_2 = 0 \rightarrow 2x_1 + 2x_2 - 4y_1 - 4y_2 + 3z_1 + 3z_2 = 0
                                                            2(x_1+x_2)-4(y_1-y_2)+3(z_1-z_2)=0 this is exactly the requirement to be in V; closed under addition
              3) let \vec{v} \in V = \begin{bmatrix} x \\ y \\ z \end{bmatrix}, and \vec{k} \in \mathbb{R}
                                                       so 2x-4y+3z=0
                  is K \vec{V} = \begin{bmatrix} kx \\ ky \\ kz \end{bmatrix} in V?
                                                             K(2x-4y+3z)=0 - 2Kx-4Ky+3kz=0
                                                            2(KX)-4(Ky)+3(K2)=0 this is exactly the requirement to be in V; closed under scalar multiplication
              Therefore V is a subspace. A basis of V is \begin{bmatrix} 5 \\ 3 \\ 4 \end{bmatrix}, \begin{bmatrix} 3 \\ 0 \\ -2 \end{bmatrix}. Since V is a plane, to find the basis just pick two non-parallel vectors in the plane.
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