# Project Guide

AI-DRIVEN RICE MONITORING USING EDGE COMPUTING ON ARM-M MICROCONTROLLERS

### **Prerequisites:**

- Google Colab (For training without local GPU)
- Python Version: 3.9.x or 3.10.x
- STM32Cube IDE Version 1.16
- Cuda Version 11.8 (If there is GPU on local device)
- STEdge AI Developer Cloud Account
- Knowledge on how to use STM32Cube IDE
- Review STM32 Model Zoo GitHub directory <u>here</u>

## **Training on Google Colab:**

- Upload the zip titled 'stm32-modelzoo-services-main\_untouched.zip, new\_5\_balanced.zip, new\_5\_test, and refreshed\_model\_zoo.ipynb to your Google Drive associated with your Google Colab account.
- In Google Colab, open the refreshed\_model\_zoo.ipynb notebook, connect to GPU, and run the cells starting from this cell:

until this cell:

```
import sys
import os

sys.path.append('/usr/local/lib/python3.10/site-packages')

sys.path.append('/usr/local/cuda-11.8/lib64')

sys.path.append('/usr/local/cuda-11.8/bin')

ss.environ("CUDA.PMET") = "/usr/local/cuda-11.8/lib64:/usr/lib/x86_64-linux-gnu"

os.environ("UD_LIBRARY_PATH"] = "/usr/local/cuda-11.8/lib64:/usr/lib/x86_64-linux-gnu"

os.environ("PATH") = "/usr/local/cuda-11.8/bin:" + os.environ("PATH")

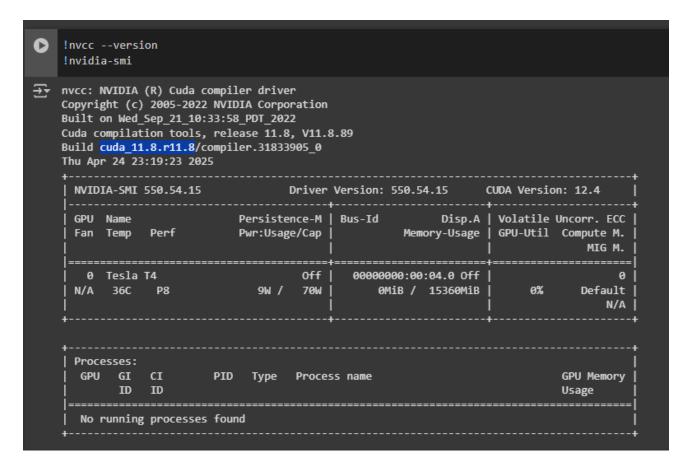
os.environ("CUDA.VISIBE_DEVICES") = "0"

Xcd /content/stm32al-modelzoo-services-main

|pip install -r requirements.txt
```

In which you will be prompted to restart the session after these cells have finished running.

 After the session has been restarted run this cell and ensure the output shows CUDA version 11.8 is used.



- Navigate to the /content/stm32ai-modelzoo-services-main/image\_classification/src and replace the contents of the user\_config.yaml file with the the contents from the new\_config.yaml. Note, to not change the name of user\_config.yaml file, just replace the contents.
- Run the last two cells to begin training, and subsequently download the training output

```
import sys
import os
sys.path.append('/usr/local/lib/python3.10/site-packages')
sys.path.append('/usr/local/cuda-11.8/lib64')
sys.path.append('/usr/local/cuda-11.8/lib64')
sys.path.append('/usr/local/cuda-11.8/bin')
os.environ['CUDA_HOME"] = "/usr/local/cuda-11.8"
os.environ['UDA_PATH'] = '/usr/local/cuda-11.8'
os.environ['UD_LIBRARY_PATH'] = '/usr/local/cuda-11.8/lib64' + os.environ.get('LD_LIBRARY_PATH', '')
os.environ['TF_CPP_MIN_LOG_LEVEL'] = '3' # Suppress TensorFlow warnings
%cd /content/stm32ai_modelzoo-services-main/image_classification/src
!python stm32ai_main.py

Show hidden output

[] import shutil
%cd /content/stm32ai-modelzoo-services-main/image_classification/src
shutil.make_archive('experiments_outputs', 'zip', 'experiments_outputs')
# If running on Colab, run this cell to automatically download the outputs.zip file, else download manually.
from google.colab import files
files.download('experiments_outputs.zip')
```

## **Deploying the Model:**

- Download and unzip the 'stm32-modelzoo-services-main.zip to your local device
- Within the unzipped folder, create a virtual environment using the following commands:

```
cd stm32-modelzoo-services-main
python -m venv st_zoo
```

Activate the virtual environment by navigating to the following directory:
 cd stm32-modelzoo-services-main\Scripts and use the 'activate.bat' command.

Return to the main environment and install the required packages with the command

```
pip install -r requirements.txt
```

• Setup on the local device is completed, follow the steps <a href="here">here</a> to proceed with deployment on the STM32H747-i Disco Board.

# Applying HSV Modification through STMCube IDE:

- Within the \stm32ai-modelzoo-servicesmain\application\_code\image\_classification\STM32H7\Application\STM32H74 7I-DISCO\STM32CubeIDE open up the '.project' file.
- In the 'app\_camera.c' file, modify the values of Hue, Saturation, and Brightness according to the value obtained from the 'linear\_mapping.py' script according to the correction to be applied

```
void Camera_Set_HueDegree()
{
   if (BSP_CAMERA_SetHueDegree(0,4) != BSP_ERROR_NONE)
   {
     while(1);
   }
}

void Camera_Set_Saturation()
{
   if (BSP_CAMERA_SetSaturation(0,1) != BSP_ERROR_NONE)
   {
     while(1);
   }
}

void Camera_Set_Brightness()
{
   if (BSP_CAMERA_SetBrightness(0, -2) != BSP_ERROR_NONE)
   {
     while(1);
   }
}
```

 Once modifications have been made, save, build, and run the application from the STM32Cube IDE

# **Utilizing Grad-CAM:**

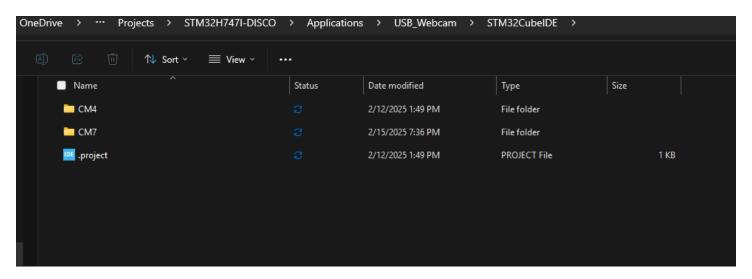
- Navigate to the stm32-modelzoo-services-main\image\_classification\src\prediction and open the 'predict.py' and go to the end of the *visualize\_gradcam* function.
- Modify this directory to the preferred directory where you want your images to be saved:

```
gradcam_result_dir = r'G:\My Drive\trained_quantized\thesis\better\grad-cam-copare\efficientnet'
os.makedirs(gradcam_result_dir, exist_ok=True)
grad_res_filename = f'{gradcam_result_dir}/{os.path.basename(img_path)}.png'
cv2.imwrite(grad_res_filename,output)
```

- To use the prediction script, refer to the Model Zoo guide to carry out prediction <a href="here">here</a> OR navigate to the <a href="mage\_classification\src\prediction\README.md">image\_classification\src\prediction\README.md</a> and follow the 'README.md' file.
- Make sure to use the '.h5' file and not the '.tflite' file as Grad-CAM will not work on quantized models

### **Camera Capture:**

Inside the Camera Capture STM Application, navigate to this folder:



- Open the .project file with STM32Cube IDE, build and run the project.
- Once the file is deployed on board, go to the camera app on your laptop to use that application for taking pictures.
- If you encounter any troubles, the STM32 FPVision AI package may be useful

### **Data Augmentation:**

Open the data\_augmentation.py python code, then input the folder for your dataset. It
will be better to use the same folder, so that the newly created images are kept in the
same folder. Else, you will need to copy the original images to the folder.

```
# Directory paths
original_data_dir = r'C:\Users\harth\datasets\new_6_balanced'
augmented_data_dir = r'C:\Users\harth\datasets\new_6_balanced'
```

• Adjust the augmentation parameters here.

• Run the program and you will get a balanced dataset