

Gokul H

Research Assistant

@Solarillion Foundation



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Education

B.E. Electrical and Electronics,
SSN College of Engineering (SSNCE),
Anna University | 2019 | GPA:
8.41/10.0

Class XII,
Doveton Matriculation Higher
Secondary School | 2015 | 98.0 %
Class X,
Doveton Matriculation Higher
Secondary School | 2013 | 96.8%

Skills

Languages: Python | C++ | C |
Matlab | Basics of Linux and C#.

Others: Pytorch | Keras | TensorFlow
| LaTeX | MS Office | Git | Adobe
Photoshop.

Extra-Curricular

Teaching Assistant @Solarillion
Foundation(SF)
- Teaching Machine Learning using
Python and Embedded C for juniors.
- Mentoring students in
undergraduate research and paper
writing..

Teaching Assistant @ S4S Project
Lab, SSNCE Electronics Department
- Taught PCB designing with Eagle
and Arduino Programming for juniors.

Stage Crew Head @ Lights Out
Please, SSN English Theatre art Club
- Managed Stage Setups and crew
teams for 8 English theatre plays.

Ongoing Research

- Since Dec'19 Practically implementable Adversarial attacks. SF
- Currently, we are investigating adversarial attack patches on optical flow based Video Action Recognition architectures in Surveillance datasets.
 - Our efforts to defend with adversarial training has given a good trade-off in classification results to improve robustness, and we are currently undertaking rigorous cross-testing procedures to validate our hypothesis in both black-box and white-box conditions.

Research Publications

- May'19-Sep'19 Gait Recovery System for Parkinson's Disease using Machine Learning on Embedded Platforms. SF
- Lead author of this paper.
 - Involves optimal designing of a signal feature extraction engine, pipelined to a 2KB Edge-ML model to deploy in microcontrollers.
 - Achieved a 1.3% efficiency trade-off with 400 times model size compression compared to state-of-the-art.
 - Accepted by 14th IEEE SYSCON 2019, Montreal, Canada.(<https://arxiv.org/abs/2004.05811>)
- Aug'18-Feb'19 Low-Cost Wearable Gesture Recognition System with Minimal User Calibration for ASL SF
- Proposes a rule-based decision system for a sensor-embedded, easy user-adaptable sign-language interpreting glove.
 - Published by 12th IEEE iThings 2019, Atlanta, US. (doi: 10.1109/iThings/GreenCom/CPSCom/SmartData.2019.00185)
- Jan'19-Mar'19 Design of Imitative Control Modalities for a 3-DoF Robotic Arm SSNCE
- Designed inertial sensor (IMU) based and mono-vision based motion-tracking systems to interface with a 3-DOF robotic arm.
 - Addresses 3D object-motion tracking, Inverse kinematics solutions, and Fitt's targeting experiments.
 - Accepted by 4th IEEE ICCSP 2020, Chennai, India.

Projects

- Apr'19-Jun'19 EMI-RNN - Faster Recurrent networks for sensor data patterns SF
- Study of Recurrent Neural Networks(RNN) incorporated with Early prediction & Multiple Instance Learning (EMI) concepts vs standard RNN counterparts.
 - On-device testing results with Raspberry Pi, showed several 100ms lower latency without compromising in efficiency, thus improving device scalability of RNN models.
- Feb'19-Apr'19 Solving Device Heterogeneity in Phone Activity recognition (AR) SF
- Accelerometer signal-preprocessing with decimation and wavelet transform techniques, trained in an LSTM- CNN stacked neural network architecture to tackle device heterogeneity problem in AR.
 - User adaptability was improved with transfer-learning techniques.
- Oct'17-Nov'18 Object Recognition Bot SSNCE
- Prototype real-time Object-Tracking Monocular Robot.
 - Was designed for further improvisation to a Mono-vision SLAM (Simultaneous Localization and Mapping) project with ORB-SLAM algorithm.

Awards

- Oct'18 Innovator of the Year 2017-2018 by IEEE ComSoc
- Proposed a study on feasibility and profitability for a futuristic non-invasive emotion sensing application for music industry.