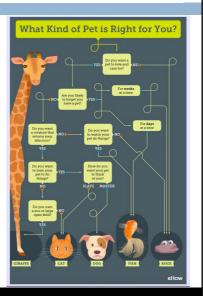
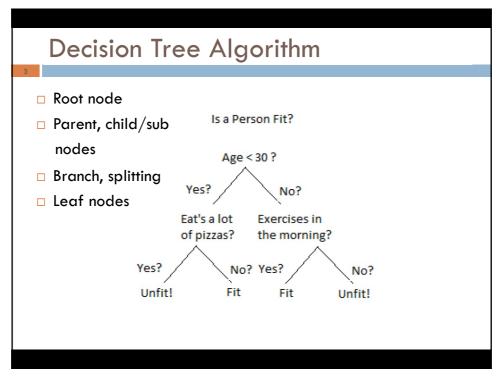
DECISION TREE AND RANDOM FOREST

1

Decision Tree Algorithm

- Similar to how humans make many different decisions
- Decision trees look at one feature/variable at a time





| Decision Tree Algorithm | | | | | | | | | | |
|-------------------------|-----|----------|------|----------|--------|---------|--|--|--|--|
| □ Training dataset | | | | | | | | | | |
| | Day | Outlook | Temp | Humidity | Wind | Tennis? | | | | |
| | 1 | Sunny | Hot | High | Weak | No | | | | |
| | 2 | Sunny | Hot | High | Strong | No | | | | |
| | 3 | Overcast | Hot | High | Weak | Yes | | | | |
| | 4 | Rain | Mild | High | Weak | Yes | | | | |
| | 5 | Rain | Cool | Normal | Weak | Yes | | | | |
| | 6 | Rain | Cool | Normal | Strong | No | | | | |
| | 7 | Overcast | Cool | Normal | Strong | Yes | | | | |
| | 8 | Sunny | Mild | High | Weak | No | | | | |
| | 9 | Sunny | Cool | Normal | Weak | Yes | | | | |
| | 10 | Rain | Mild | Normal | Weak | Yes | | | | |
| | 11 | Sunny | Mild | Normal | Strong | Yes | | | | |
| | 12 | Overcast | Mild | High | Strong | Yes | | | | |
| | 13 | Overcast | Hot | Normal | Weak | Yes | | | | |
| | 14 | Rain | Mild | High | Strong | No | | | | |

Decision Tree Algorithm

□ How can we build a decision tree given a data set?

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Decision Tree Algorithm

- □ We will make the best choice at each step
- □ Identify the best feature/attribute for the each node

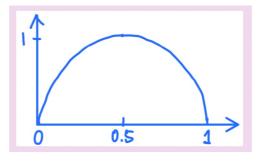
Decision Tree Algorithm

- □ Identify the best feature/attribute for root node
 - Best split: results of each branch should be as homogeneous (or pure) as possible
 - a feature that reduces impurity as much as possible
 - How do we measure the impurity in a set of examples
 - Entropy from information theory
 - Alternatively, use Gini Index

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Decision Tree Algorithm

 $\hfill\Box$ Entropy for a distribution over two outcomes



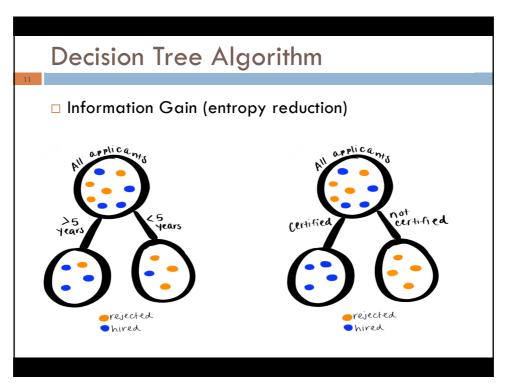
Decision Tree Algorithm

- □ Quantifying the information content of a feature
 - entropy of the examples before testing the feature minus the entropy of the examples after testing the feature - Information Gain

Decision Tree Algorithm

- □ Quantifying the information content of a feature
 - □ Information gain or entropy reduction

InfoGain =
$$I_{\text{before}} - I_{\text{after}}$$

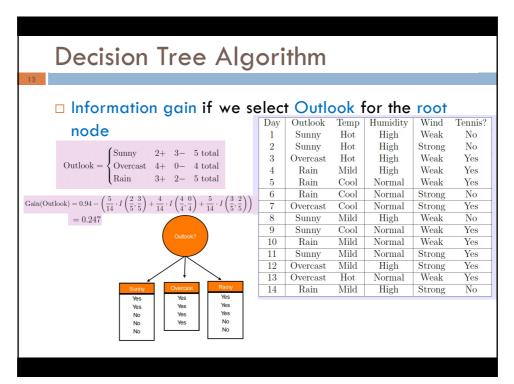


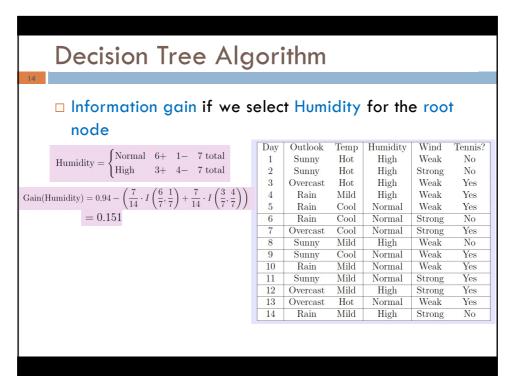
Decision Tree Algorithm

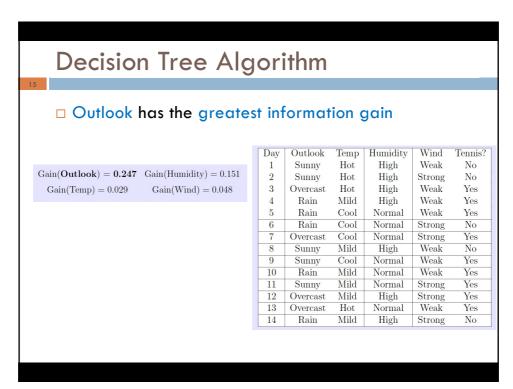
□ Entropy of the examples before we select a feature for the root node

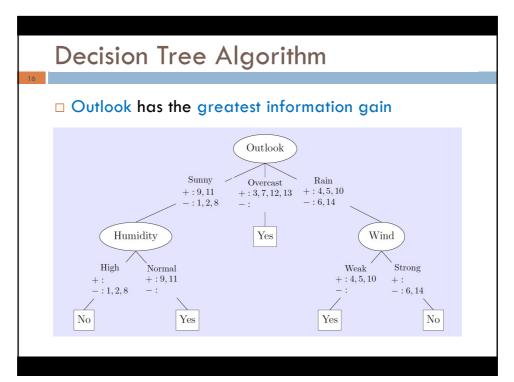
$$\begin{split} H_{\text{before}} &= -\left(\frac{9}{14}\log_2\left(\frac{9}{14}\right) + \frac{5}{14}\log_2\left(\frac{5}{14}\right)\right) \\ &\approx 0.94 \end{split}$$

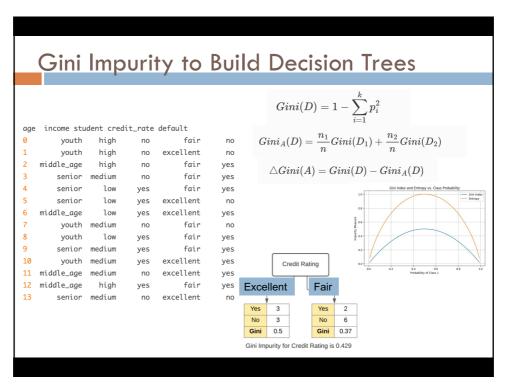
| I | Day | Outlook | Temp | Humidity | Wind | Tennis? |
|---|-----|----------|------|----------|--------|---------|
| | 1 | Sunny | Hot | High | Weak | No |
| | 2 | Sunny | Hot | High | Strong | No |
| | 3 | Overcast | Hot | High | Weak | Yes |
| | 4 | Rain | Mild | High | Weak | Yes |
| | 5 | Rain | Cool | Normal | Weak | Yes |
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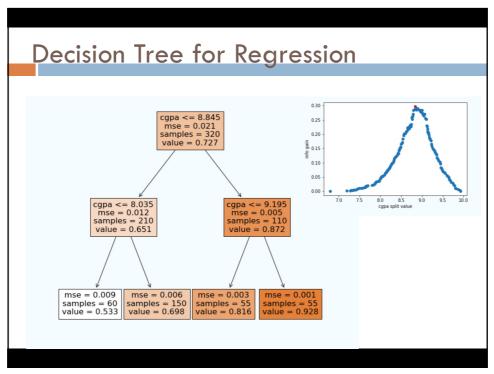


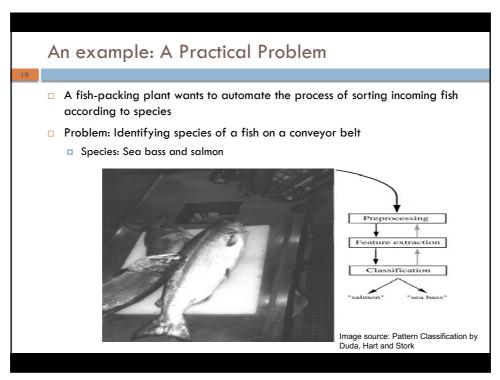


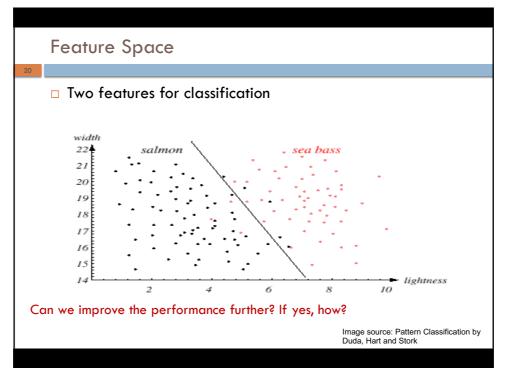


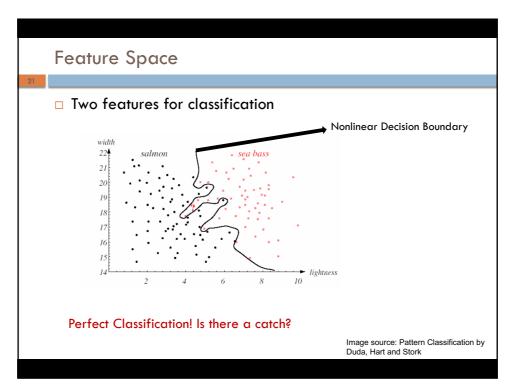








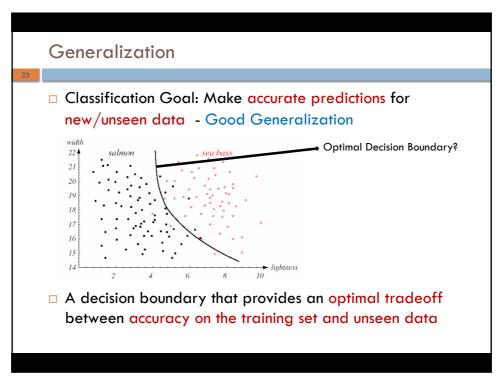


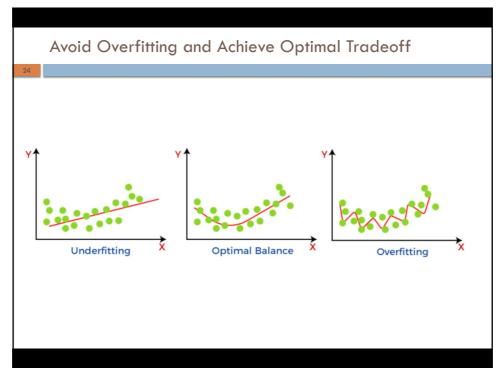


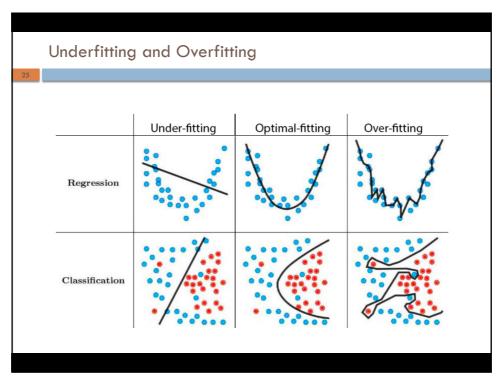
Generalization

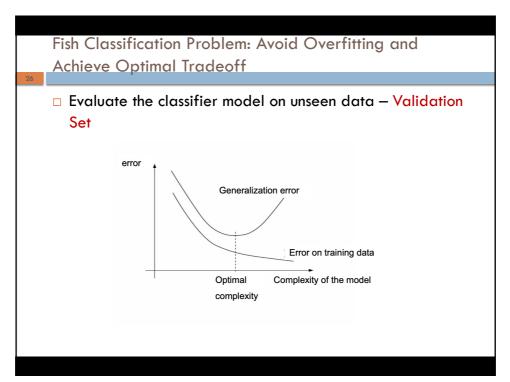
- Classification Goal: Make accurate predictions for new/unseen data - Good Generalization
- □ The model should NOT be tuned to the specific characteristics of the training data — Overfitting
- □ In practice, training data is likely to contain some noise

We are better off with a slightly poorer performance on the training examples if this means that our classifier will have better performance on unseen patterns.









Bias and Variance in Machine Learning

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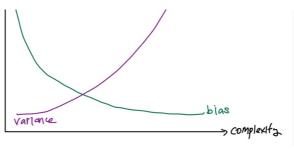
- ☐ Bias: The model makes strong assumptions about the training data to simplify the learning process
 - □ Examples: linear regression algorithms or shallow decision trees, which assume simple relationships even when the data patterns are more complex
- □ Variance: The model's sensitivity to fluctuations in the training data (the model's prediction changes as it is trained on different subsets of the training data)

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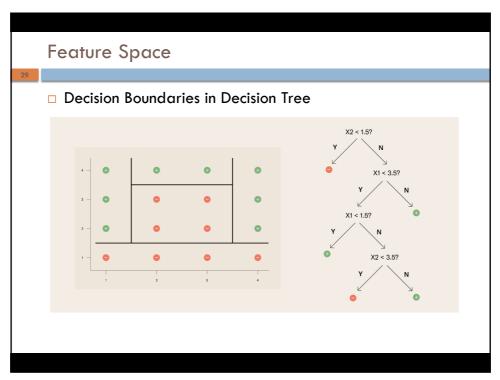
Bias and Variance in Machine Learning

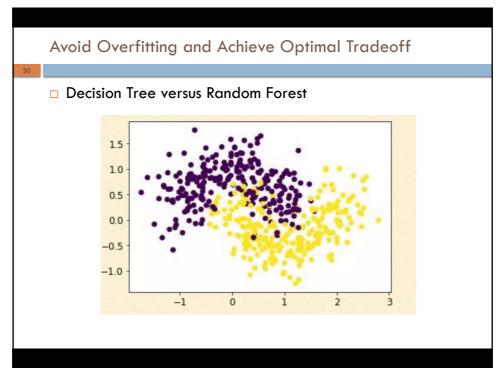
28

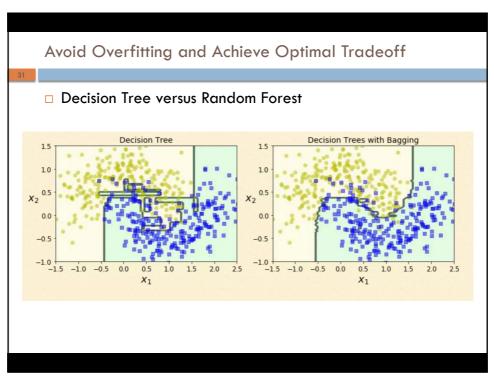
 Models with high bias have low variance, and models with low bias have high variance (inverse relationship)

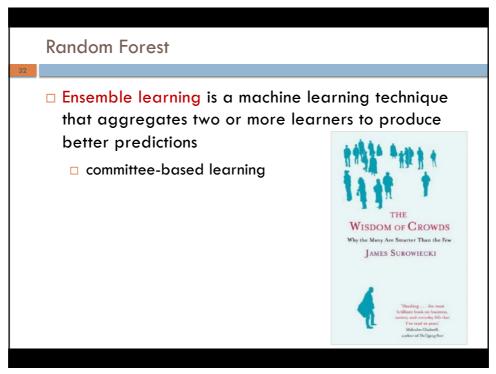


☐ Bias-variance trade-off: Minimizing errors caused by oversimplification and excessive complication









Random Forest

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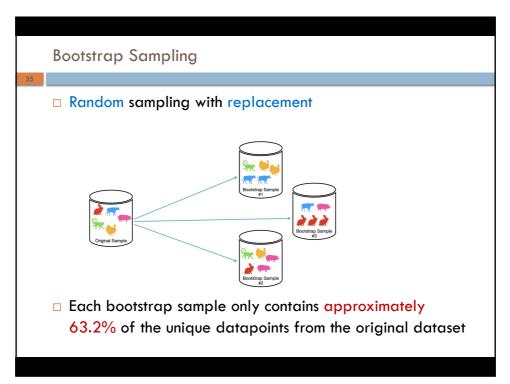
- □ Base learner, base model, base estimator refers to the individual models in ensemble algorithms
- □ consolidating base learner predictions
 - Majority Voting, Averaging

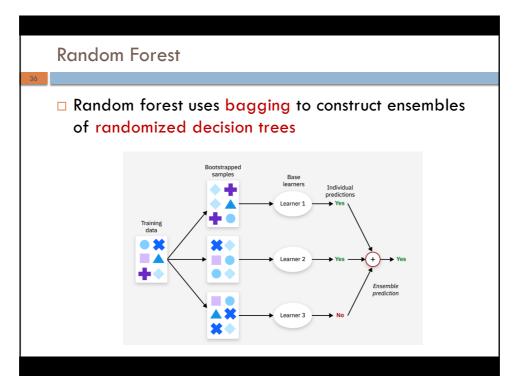
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Random Forest

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- □ Random forest uses bagging to construct ensembles of randomized decision trees
 - □ Bagging bootstrap sampling and aggregation
 - Bootstrap sampling to derive multiple new datasets from one initial training dataset to train multiple base learners





Random Forest

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- □ Random forest uses bagging to construct ensembles of randomized decision trees
 - considers random subsets of features when splitting a node
 - max_features parameter
- ☐ The greater diversity among combined models, the more accurate the resulting ensemble model

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Estimating generalization Performance:

Out-of-bag (OOB) error/score

- Out-of-bag samples as unseen data for evaluation
 - Out-of-bag samples are the unique sets of datapoints that are not used for model fitting

Original Dataset | X₁ | X₂ | X₃ | X₄ | X₅ | X₆ | X₇ | X₈ | X₉ | X₁₀

Bootstrap 1 $\begin{bmatrix} x_8 & x_6 & x_2 & x_9 & x_5 & x_8 & x_1 & x_4 & x_8 & x_2 \end{bmatrix}$

 Each bootstrap sample only contains approximately 63.2% of the unique data points from the original dataset

