Hongyu Tu

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EDUCATION

University of Massachusetts Amherst

Master of Science in Computer Science

University of Maryland, College Park

Bachelor of Science in Computer Engineering

Amherst, MA

Aug. 2021 - May 2023

College Park, MD

Aug. 2017 - May 2021

TECHNICAL SKILLS

Languages: Python, C/C++, Java, Swift, MATLAB, SQL, Assembly, HTML, CSS

Tools & Libraries: Git, Docker, PyTorch, ROS, pandas, NumPy, Flask, Matplotlib, Seaborn, OpenCV, SciPy

Courses: Reinforcement Learning, Adv. Natural Language Processing, Deep Learning for Computer Vision/Graphics, Probabilistic Graphical Models, Data Science, ML Algorithms (Numerical Optimization, Statistical Estimation)

EXPERIENCE

Machine Learning Engineer

Feb. 2024 – Present

LCE Optics Philadelphia, PA

- Developing and optimizing deep learning-based feature extraction and matching pipelines to improve Visual SLAM performance for autonomous navigation, contributing to robust perception systems under real-world conditions.
- Enhancing perception accuracy through camera calibration and multi-sensor fusion.
- Applying RL in NVIDIA Isaac Sim/Lab with ROS 2 to train control policies in simulated environments.

ARVR System Research Assistant

June – Dec. 2023

Futurewei Technologies, IC Lab

Austin, TX

- Built real-time tracking and rendering systems using Azure Kinect DK, MediaPipe, and Unity.
- Created custom animation datasets and improved long-range finger/face tracking algorithms.
- Fine-tuned Transformers for motion prediction with temporal and spatial consistency.

Recommender System Research Assistant

Dec. 2019 - Jan. 2020

Tencent, News Feed Flatform Department, KanDian Team

Shenzhen, China

- Leveraged NLP techniques and internal data to improve recommender system performance.
- Analyzed real-time data streams to generate actionable insights for content personalization.

Projects

Bilimemenet | Python, Hugging face, ByT5, Chinese Roberta, GPT-2, bilibili-api

Jan. - May 2022

- Scraped over 1 million Danmu (live comments) from a Chinese video site Bilibili to form Danmu dataset.
- Proposed to extract in-jokes that are popular within different videos categories from the text-based comments using fine-tuned BERT, and generate Danmu that fits specified video categories.

Auto Crossy Road | Python, PyTorch

July - Dec. 2021

- Built an autonomous agent to play Crossy Road using deep learning, with modular design: object detection, state representation, and action generation.
- Developed a custom YOLO model with self-supervised labeling for real-time object detection, improving accuracy and reducing input complexity for downstream tasks.
- Trained a DQN using over 100 hours of gameplay data, outperforming supervised learning baselines and achieving faster convergence through efficient state-action modeling.

Robotic Arm Control with Reinforcement Learning | c#, Unity ML-Agents

Aug. – Dec. 2020

- Proposed to use the robot arm to interact with boxes on a table, maximizing the visibility by minimizing overlay while avoiding knocking anything to the ground.
- Used Unity library called ML_Agents to train for robotic arm's control policy in virtual environments.

Publication

H. Tu, S. Shorewala, T. Ma and V. Thost, Retrosynthesis Prediction Revisited, NeurIPS 2022 AI for Science: Progress and Promises, 2022.