IOT Final Project

Team: 跟不上我的速度吧 哈們!

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Outline

- Motivation
- Hardware architecture
- Software architecture
- Algorithm
- Experiment and result
- Future work

Motivation



Hardware

- Arduino Nano 33 IOT * 2
- Web Camera
- Speakers
- Servomotors
- DFplayer (Mini mp3)













Hardware architecture















Arduino Nano 33 IOT 6-axis IMUs WiFi module

Laptop as server to compute the Videos and IMUs information for movement detection

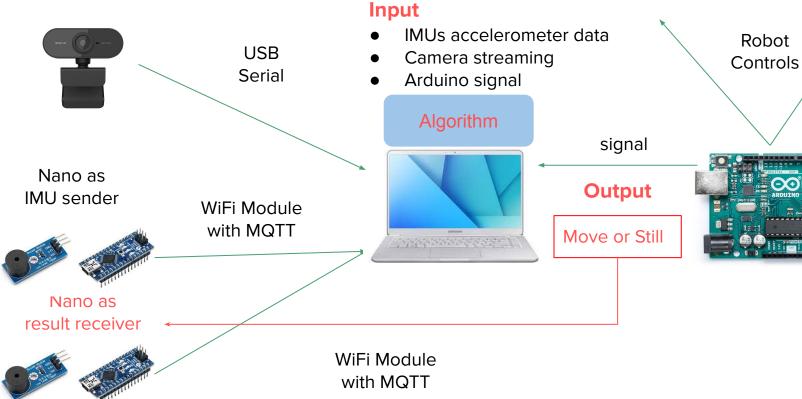
Player2

Player1

Software architecture

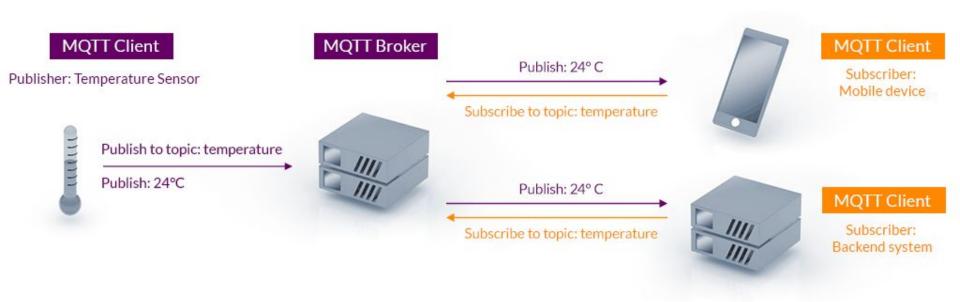






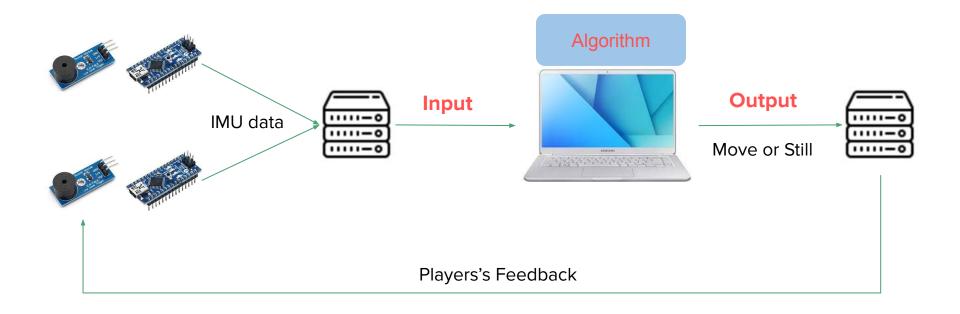
Intergration with MQTT

MQTT Publish / Subscribe Architecture



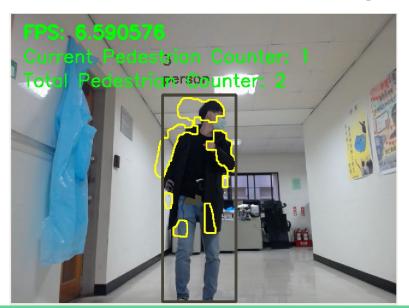
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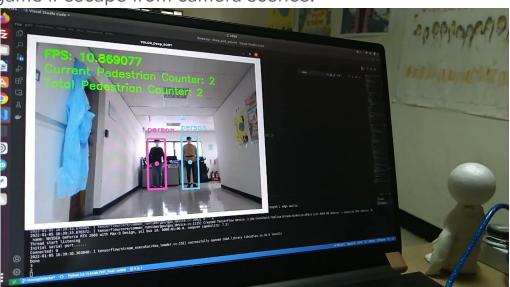


Algorithm

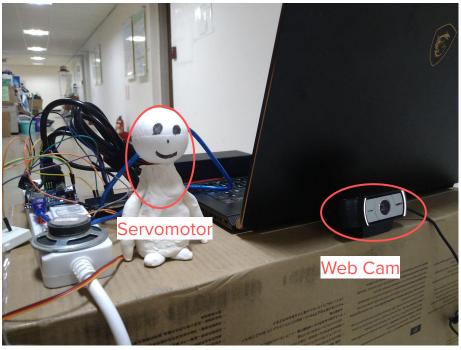
- Human bounding box detection and tracking with Yolov4
- Human movement detection with moving average (OpenCV) algorithm
- Calculate Intersection over Union between bounding box and moving contour



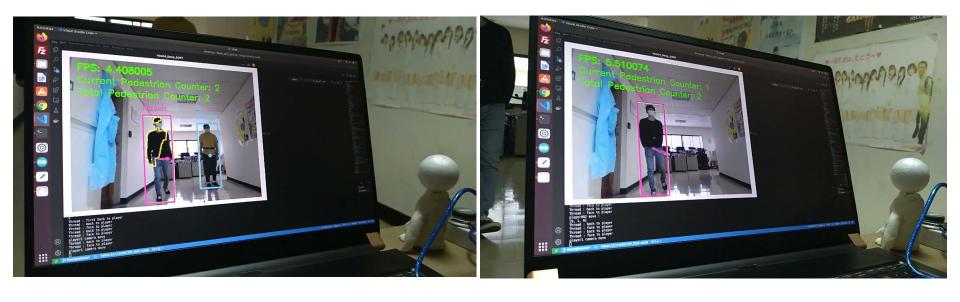
- Setup:
 - Random rotation frequency (1.5, 3, 6 second)
 - Movement either detected by sensing or viusal movement
 - Win the game if escape from camera scence!











Future work

- Improve the vision-based algorithm to increase and stablize the FPS
- Add human tracking for more complex scences e.g., occlusion, interaction
- Add more sensors to detect movement more accurately, but suffer from synchronization problem
- Use laser sensor and positioning IR camera sensor to add some atmosphere to the game

Thanks for your attention