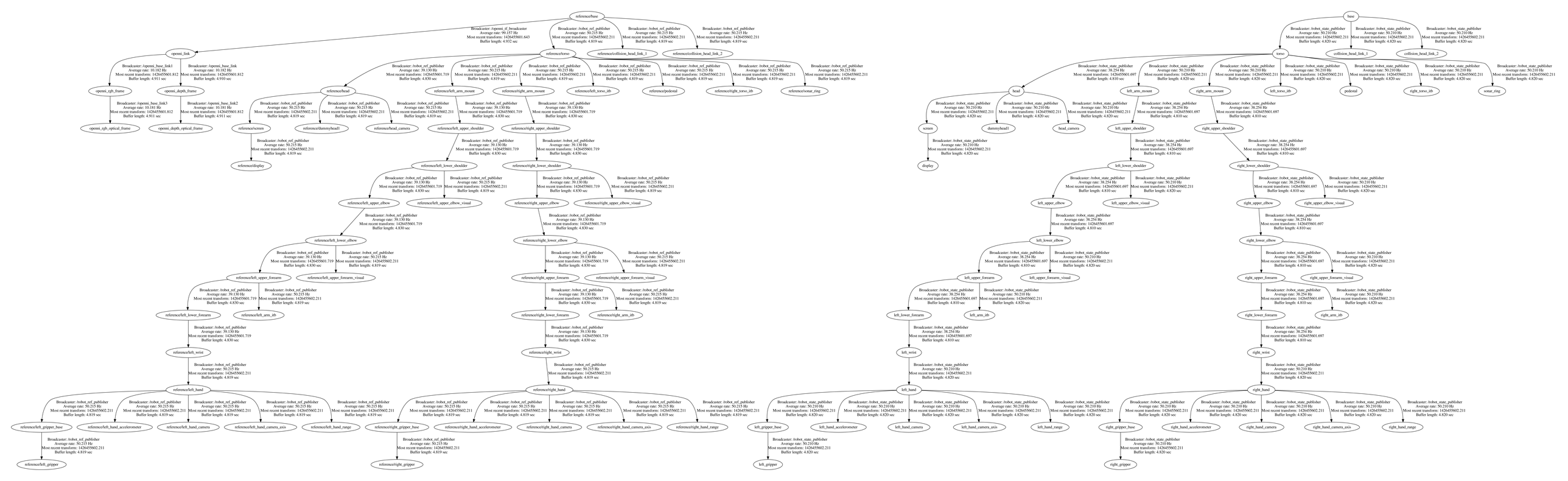
reference/base
Broadcaster: /openni_tf_broadcaster
Average rate: 99.157 Hz
Most recent transform: 1426455601.643
Buffer length: 4.932 sec
Broadcaster: /robot_ref_publisher
Average rate: 50.215 Hz
Most recent transform: 1426455602.211
Buffer length: 4.819 sec
Broadcaster: /robot_ref_publisher
Average rate: 50.215 Hz
Most recent transform: 1426455602.211
Buffer length: 4.819 sec
Broadcaster: /robot_ref_publisher
Average rate: 50.215 Hz
Most recent transform: 1426455602.211
Buffer length: 4.819 sec
openni_link
reference/torso
reference/collision_head_link_1
reference/collision_head_link_2
Broadcaster: /openni_base_link1
Average rate: 10.182 Hz
Most recent transform: 1426455601.812
Buffer length: 4.911 sec
Broadcaster: /openni_base_link
Average rate: 10.182 Hz
Most recent transform: 1426455601.812
Buffer length: 4.910 sec
Broadcaster: /robot_ref_publisher
Average rate: 39.130 Hz
Most recent transform: 1426455601.719
Buffer length: 4.830 sec
Broadcaster: /robot_ref_publisher
Average rate: 50.215 Hz
Most recent transform: 1426455602.211
Buffer length: 4.819 sec
Broadcaster: /robot_ref_publisher
Average rate: 50.215 Hz
Most recent transform: 1426455602.211
Buffer length: 4.819 sec
Broadcaster: /robot_ref_publisher
Average rate: 50.215 Hz
Most recent transform: 1426455602.211
Buffer length: 4.819 sec
Broadcaster: /robot_ref_publisher
Average rate: 50.215 Hz
Most recent transform: 1426455602.211
Buffer length: 4.819 sec
Broadcaster: /robot_ref_publisher
Average rate: 50.215 Hz
Most recent transform: 1426455602.211
Buffer length: 4.819 sec
Broadcaster: /robot_ref_publisher
Average rate: 50.215 Hz
Most recent transform: 1426455602.211
Buffer length: 4.819 sec
Broadcaster: /robot_ref_publisher
Average rate: 50.215 Hz
Most recent transform: 1426455602.211
Buffer length: 4.819 sec
openni_rgb_frame
openni_depth_frame
reference/head
reference/left_arm_mount
reference/right_arm_mount
reference/left_torso_itb
reference/pedestal
reference/right_torso_itb
reference/sonar_ring
Broadcaster: /openni_base_link3
Average rate: 10.181 Hz
Most recent transform: 1426455601.812
Buffer length: 4.911 sec
Broadcaster: /openni_base_link2
Average rate: 10.181 Hz
Most recent transform: 1426455601.812
Buffer length: 4.911 sec
Broadcaster: /robot_ref_publisher
Average rate: 50.215 Hz
Most recent transform: 1426455602.211
Buffer length: 4.819 sec
Broadcaster: /robot_ref_publisher
Average rate: 50.215 Hz
Most recent transform: 1426455602.211
Buffer length: 4.819 sec
Broadcaster: /robot_ref_publisher
Average rate: 50.215 Hz
Most recent transform: 1426455602.211
Buffer length: 4.819 sec
Broadcaster: /robot_ref_publisher
Average rate: 39.130 Hz
Most recent transform: 1426455601.719
Buffer length: 4.830 sec
Broadcaster: /robot_ref_publisher
Average rate: 39.130 Hz
Most recent transform: 1426455601.719
Buffer length: 4.830 sec
openni_rgb_optical_frame
openni_depth_optical_frame
reference/screen
reference/dummyhead1
reference/head_camera
reference/left_upper_shoulder
reference/right_upper_shoulder
Broadcaster: /robot_ref_publisher
Average rate: 50.215 Hz
Most recent transform: 1426455602.211
Buffer length: 4.819 sec
Broadcaster: /robot_ref_publisher
Average rate: 39.130 Hz
Most recent transform: 1426455601.719
Buffer length: 4.830 sec
Broadcaster: /robot_ref_publisher
Average rate: 39.130 Hz
Most recent transform: 1426455601.719
Buffer length: 4.830 sec
reference/display
reference/left_lower_shoulder
reference/right_lower_shoulder
Broadcaster: /robot_ref_publisher
Average rate: 39.130 Hz
Most recent transform: 1426455601.719
Buffer length: 4.830 sec
Broadcaster: /robot_ref_publisher
Average rate: 50.215 Hz
Most recent transform: 1426455602.211
Buffer length: 4.819 sec
Broadcaster: /robot_ref_publisher
Average rate: 39.130 Hz
Most recent transform: 1426455601.719
Buffer length: 4.830 sec
Broadcaster: /robot_ref_publisher
Average rate: 50.215 Hz
Most recent transform: 1426455602.211
Buffer length: 4.819 sec
reference/left_upper_elbow
reference/left_upper_elbow_visual
reference/right_upper_elbow
reference/right_upper_elbow_visual
Broadcaster: /robot_ref_publisher
Average rate: 39.130 Hz
Most recent transform: 1426455601.719
Buffer length: 4.830 sec
Broadcaster: /robot_ref_publisher
Average rate: 39.130 Hz
Most recent transform: 1426455601.719
Buffer length: 4.830 sec
reference/left_lower_elbow
reference/right_lower_elbow
Broadcaster: /robot_ref_publisher
Average rate: 39.130 Hz
Most recent transform: 1426455601.719
Buffer length: 4.830 sec
Broadcaster: /robot_ref_publisher
Average rate: 50.215 Hz
Most recent transform: 1426455602.211
Buffer length: 4.819 sec
Broadcaster: /robot_ref_publisher
Average rate: 39.130 Hz
Most recent transform: 1426455601.719
Buffer length: 4.830 sec
Broadcaster: /robot_ref_publisher
Average rate: 50.215 Hz
Most recent transform: 1426455602.211
Buffer length: 4.819 sec
reference/left_upper_forearm
reference/left_upper_forearm_visual
reference/right_upper_forearm
reference/right_upper_forearm_visual
Broadcaster: /robot_ref_publisher
Average rate: 39.130 Hz
Most recent transform: 1426455601.719
Buffer length: 4.830 sec
Broadcaster: /robot_ref_publisher
Average rate: 50.215 Hz
Most recent transform: 1426455602.211
Buffer length: 4.819 sec
Broadcaster: /robot_ref_publisher
Average rate: 39.130 Hz
Most recent transform: 1426455601.719
Buffer length: 4.830 sec
Broadcaster: /robot_ref_publisher
Average rate: 50.215 Hz
Most recent transform: 1426455602.211
Buffer length: 4.819 sec
reference/left_lower_forearm
reference/left_arm_itb
reference/right_lower_forearm
reference/right_arm_itb
Broadcaster: /robot_ref_publisher
Average rate: 39.130 Hz
Most recent transform: 1426455601.719
Buffer length: 4.830 sec
Broadcaster: /robot_ref_publisher
Average rate: 39.130 Hz
Most recent transform: 1426455601.719
Buffer length: 4.830 sec
reference/left_wrist
reference/right_wrist
Broadcaster: /robot_ref_publisher
Average rate: 50.215 Hz
Most recent transform: 1426455602.211
Buffer length: 4.819 sec
Broadcaster: /robot_ref_publisher
Average rate: 50.215 Hz
Most recent transform: 1426455602.211
Buffer length: 4.819 sec
reference/left_hand
reference/right_hand
Broadcaster: /robot_ref_publisher
Average rate: 50.215 Hz
Most recent transform: 1426455602.211
Buffer length: 4.819 sec
Broadcaster: /robot_ref_publisher
Average rate: 50.215 Hz
Most recent transform: 1426455602.211
Buffer length: 4.819 sec
Broadcaster: /robot_ref_publisher
Average rate: 50.215 Hz
Most recent transform: 1426455602.211
Buffer length: 4.819 sec
Broadcaster: /robot_ref_publisher
Average rate: 50.215 Hz
Most recent transform: 1426455602.211
Buffer length: 4.819 sec
Broadcaster: /robot_ref_publisher
Average rate: 50.215 Hz
Most recent transform: 1426455602.211
Buffer length: 4.819 sec
reference/left_gripper_base
reference/left_hand_accelerometer
reference/left_hand_camera
reference/left_hand_camera_axis
reference/left_hand_range
reference/right_gripper_base
reference/right_hand_accelerometer
reference/right_hand_camera
reference/right_hand_camera_axis
reference/right_hand_range
Broadcaster: /robot_ref_publisher
Average rate: 50.215 Hz
Most recent transform: 1426455602.211
Buffer length: 4.819 sec
Broadcaster: /robot_ref_publisher
Average rate: 50.215 Hz
Most recent transform: 1426455602.211
Buffer length: 4.819 sec
reference/left_gripper
reference/right_gripper
base
Broadcaster: /robot_state_publisher
Average rate: 50.210 Hz
Most recent transform: 1426455602.211
Buffer length: 4.820 sec
Broadcaster: /robot_state_publisher
Average rate: 50.210 Hz
Most recent transform: 1426455602.211
Buffer length: 4.820 sec
Broadcaster: /robot_state_publisher
Average rate: 50.210 Hz
Most recent transform: 1426455602.211
Buffer length: 4.820 sec
torso
collision_head_link_1
collision_head_link_2
Broadcaster: /robot_state_publisher
Average rate: 38.254 Hz
Most recent transform: 1426455601.697
Buffer length: 4.810 sec
Broadcaster: /robot_state_publisher
Average rate: 50.210 Hz
Most recent transform: 1426455602.211
Buffer length: 4.820 sec
Broadcaster: /robot_state_publisher
Average rate: 50.210 Hz
Most recent transform: 1426455602.211
Buffer length: 4.820 sec
Broadcaster: /robot_state_publisher
Average rate: 50.210 Hz
Most recent transform: 1426455602.211
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Buffer length: 4.820 sec
Broadcaster: /robot_state_publisher
Average rate: 50.210 Hz
Most recent transform: 1426455602.211
Buffer length: 4.820 sec
Broadcaster: /robot_state_publisher
Average rate: 50.210 Hz
Most recent transform: 1426455602.211
Buffer length: 4.820 sec
head
left_arm_mount
right_arm_mount
left_torso_itb
pedestal
right_torso_itb
sonar_ring
Broadcaster: /robot_state_publisher
Average rate: 50.210 Hz
Most recent transform: 1426455602.211
Buffer length: 4.820 sec
Broadcaster: /robot_state_publisher
Average rate: 50.210 Hz
Most recent transform: 1426455602.211
Buffer length: 4.820 sec
Broadcaster: /robot_state_publisher
Average rate: 50.210 Hz
Most recent transform: 1426455602.211
Buffer length: 4.820 sec
Broadcaster: /robot_state_publisher
Average rate: 50.210 Hz
Most recent transform: 1426455602.211
Buffer length: 4.820 sec
screen
dummyhead1
head_camera
left_upper_shoulder
right_upper_shoulder
Broadcaster: /robot_state_publisher
Average rate: 50.210 Hz
Most recent transform: 1426455602.211
Buffer length: 4.820 sec
Broadcaster: /robot_state_publisher
Average rate: 38.254 Hz
Most recent transform: 1426455601.697
Buffer length: 4.810 sec
Broadcaster: /robot_state_publisher
Average rate: 38.254 Hz
Most recent transform: 1426455601.697
Buffer length: 4.810 sec
display
left_lower_shoulder
right_lower_shoulder
Broadcaster: /robot_state_publisher
Average rate: 38.254 Hz
Most recent transform: 1426455601.697
Buffer length: 4.810 sec
Broadcaster: /robot_state_publisher
Average rate: 50.210 Hz
Most recent transform: 1426455602.211
Buffer length: 4.820 sec
Broadcaster: /robot_state_publisher
Average rate: 38.254 Hz
Most recent transform: 1426455601.697
Buffer length: 4.810 sec
Broadcaster: /robot_state_publisher
Average rate: 50.210 Hz
Most recent transform: 1426455602.211
Buffer length: 4.820 sec
left_upper_elbow
left_upper_elbow_visual
right_upper_elbow
right_upper_elbow_visual
Broadcaster: /robot_state_publisher
Average rate: 38.254 Hz
Most recent transform: 1426455601.697
Buffer length: 4.810 sec
Broadcaster: /robot_state_publisher
Average rate: 38.254 Hz
Most recent transform: 1426455601.697
Buffer length: 4.810 sec
left_lower_elbow
right_lower_elbow
Broadcaster: /robot_state_publisher
Average rate: 38.254 Hz
Most recent transform: 1426455601.697
Buffer length: 4.810 sec
Broadcaster: /robot_state_publisher
Average rate: 50.210 Hz
Most recent transform: 1426455602.211
Buffer length: 4.820 sec
Broadcaster: /robot_state_publisher
Average rate: 38.254 Hz
Most recent transform: 1426455601.697
Buffer length: 4.810 sec
Broadcaster: /robot_state_publisher
Average rate: 50.210 Hz
Most recent transform: 1426455602.211
Buffer length: 4.820 sec
left_upper_forearm
left_upper_forearm_visual
right_upper_forearm
right_upper_forearm_visual
Broadcaster: /robot_state_publisher
Average rate: 38.254 Hz
Most recent transform: 1426455601.697
Buffer length: 4.810 sec
Broadcaster: /robot_state_publisher
Average rate: 50.210 Hz
Most recent transform: 1426455602.211
Buffer length: 4.820 sec
Broadcaster: /robot_state_publisher
Average rate: 38.254 Hz
Most recent transform: 1426455601.697
Buffer length: 4.810 sec
Broadcaster: /robot_state_publisher
Average rate: 50.210 Hz
Most recent transform: 1426455602.211
Buffer length: 4.820 sec
left_lower_forearm
left_arm_itb
right_lower_forearm
right_arm_itb
Broadcaster: /robot_state_publisher
Average rate: 38.254 Hz
Most recent transform: 1426455601.697
Buffer length: 4.810 sec
Broadcaster: /robot_state_publisher
Average rate: 38.254 Hz
Most recent transform: 1426455601.697
Buffer length: 4.810 sec
left_wrist
right_wrist
Broadcaster: /robot_state_publisher
Average rate: 50.210 Hz
Most recent transform: 1426455602.211
Buffer length: 4.820 sec
Broadcaster: /robot_state_publisher
Average rate: 50.210 Hz
Most recent transform: 1426455602.211
Buffer length: 4.820 sec
left_hand
right_hand
Broadcaster: /robot_state_publisher
Average rate: 50.210 Hz
Most recent transform: 1426455602.211
Buffer length: 4.820 sec
Broadcaster: /robot_state_publisher
Average rate: 50.210 Hz
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Buffer length: 4.820 sec
Broadcaster: /robot_state_publisher
Average rate: 50.210 Hz
Most recent transform: 1426455602.211
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Average rate: 50.210 Hz
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Most recent transform: 1426455602.211
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Average rate: 50.210 Hz
Most recent transform: 1426455602.211
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Broadcaster: /robot_state_publisher
Average rate: 50.210 Hz
Most recent transform: 1426455602.211
Buffer length: 4.820 sec
Broadcaster: /robot_state_publisher
Average rate: 50.210 Hz
Most recent transform: 1426455602.211
Buffer length: 4.820 sec
left_gripper_base
left_hand_accelerometer
left_hand_camera
left_hand_camera_axis
left_hand_range
right_gripper_base
right_hand_accelerometer
right_hand_camera
right_hand_camera_axis
right_hand_range
Broadcaster: /robot_state_publisher
Average rate: 50.210 Hz
Most recent transform: 1426455602.211
Buffer length: 4.820 sec
Broadcaster: /robot_state_publisher
Average rate: 50.210 Hz
Most recent transform: 1426455602.211
Buffer length: 4.820 sec
left_gripper
right_gripper