```
┌─────────────────────────────────┐
│        view_frames Result        │
│                                  │
│  Recorded at time: 1540582277.550│
└─────────────────────────────────┘

                world

         Broadcaster: /robot_state_publisher
         Average rate: 100.382 Hz
         Most recent transform: 1540582278.030 ( -0.480 sec old)
         Buffer length: 4.921 sec

             iiwa_link_0

         Broadcaster: /robot_state_publisher
         Average rate: 902.952 Hz
         Most recent transform: 1540582280.536 ( -2.986 sec old)
         Buffer length: 4.946 sec

             iiwa_link_1

         Broadcaster: /robot_state_publisher
         Average rate: 902.952 Hz
         Most recent transform: 1540582280.536 ( -2.986 sec old)
         Buffer length: 4.946 sec

             iiwa_link_2

         Broadcaster: /robot_state_publisher
         Average rate: 902.952 Hz
         Most recent transform: 1540582280.536 ( -2.986 sec old)
         Buffer length: 4.946 sec

             iiwa_link_3

         Broadcaster: /robot_state_publisher
         Average rate: 902.952 Hz
         Most recent transform: 1540582280.536 ( -2.986 sec old)
         Buffer length: 4.946 sec

             iiwa_link_4

         Broadcaster: /robot_state_publisher
         Average rate: 902.952 Hz
         Most recent transform: 1540582280.536 ( -2.986 sec old)
         Buffer length: 4.946 sec

             iiwa_link_5

         Broadcaster: /robot_state_publisher
         Average rate: 902.952 Hz
         Most recent transform: 1540582280.536 ( -2.986 sec old)
         Buffer length: 4.946 sec

             iiwa_link_6

         Broadcaster: /robot_state_publisher
         Average rate: 902.952 Hz
         Most recent transform: 1540582280.536 ( -2.986 sec old)
         Buffer length: 4.946 sec

             iiwa_link_7

         Broadcaster: /robot_state_publisher
         Average rate: 100.382 Hz
         Most recent transform: 1540582278.030 ( -0.480 sec old)
         Buffer length: 4.921 sec

             iiwa_link_ee

         Broadcaster: /robot_state_publisher
         Average rate: 100.382 Hz
         Most recent transform: 1540582278.030 ( -0.480 sec old)
         Buffer length: 4.921 sec

                palm
```

Broadcaster: /robot_state_publisher
Average rate: 100.382 Hz
Most recent transform: 1540582278.030 (-0.480 sec old)
Buffer length: 4.921 sec

Broadcaster: /robot_state_publisher
Average rate: 100.382 Hz
Most recent transform: 1540582278.030 (-0.480 sec old)
Buffer length: 4.921 sec

```
   finger_middle_link_0                tool0
```