Basics of Markov Chain Monte Carlo

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Motivation

► Bayesian Inference:

- ▶ Posterior Distribution: $p(\theta | \mathbf{y}) \propto \mathcal{L}(\theta | \mathbf{y}) \times \pi(\theta)$, with $\theta = (\theta_1, \dots, \theta_d)$.
- Quantity of Interest: $\tau = g(\theta)$.
- ► Point/Interval Estimate:

$$\hat{\tau} = E[\tau \,|\, \mathbf{y}] = \int g(\tau) p(\boldsymbol{\theta} \,|\, \mathbf{y}) \,\mathrm{d}\boldsymbol{\theta}$$

$$\mathsf{Cl}_{95}(\tau) = \left(F_{\tau \,|\, \mathbf{y}}^{-1}(2.5\% \,|\, \mathbf{y}), F_{\tau \,|\, \mathbf{y}}^{-1}(97.5\% \,|\, \mathbf{y})\right)$$

▶ **Deterministic Calculation:** Multidimensional integral and Inverse-CDF are typically very difficult for d > 2. (any grid method scales terribly with d)

Markov Chain Monte Carlo (MCMC)

Problem: Let

$$\tau = g(\mathbf{x}), \quad \mathbf{x} = (x_1, \dots, x_d) \sim p(\mathbf{x}).$$

Compute $E[\tau]$ and $F_{\tau}^{-1}(\alpha)$.

- ▶ **Deterministic calculation:** Typically very difficult for d > 2.
- ▶ Monte Carlo: If we can sample $\mathbf{x}^{(1)}, \dots, \mathbf{x}^{(M)} \stackrel{\text{iid}}{\sim} p(\mathbf{x})$, then
 - ► Point Estimate: $\bar{\tau} = \frac{1}{M} \sum_{i=1}^{M} g(\mathbf{x}^{(m)}) \to \tau$.
 - Interval Estimate: Let $au^{(m)}=g(\mathbf{x}^{(m)})$ and $au^{(1:M)}=(au^{(1)},\dots, au^{(M)}).$ Then

$$\hat{q}_{ au}(lpha) = ext{quantile}(\mathbf{x}^{(1:M)}, ext{prob} = lpha)
ightarrow \mathcal{F}_{ au}^{-1}(lpha).$$

Markov Chain Monte Carlo (MCMC)

- ▶ **Problem:** Let $\tau = g(\mathbf{x})$, $\mathbf{x} \sim p(\mathbf{x})$. Compute $E[\tau]$.
- ▶ Monte Carlo: If we can sample $\mathbf{x}^{(1)}, \dots, \mathbf{x}^{(M)} \stackrel{\text{iid}}{\sim} p(\mathbf{x})$, then

$$\bar{\tau} = \frac{1}{M} \sum_{m=1}^{M} \tau^{(m)} \to E[\tau].$$

▶ Markov Chain: Drawing $\mathbf{x}^{(m)} \stackrel{\text{iid}}{\sim} p(\mathbf{x})$ typically very difficult for d > 2. Instead, sample from a Markov chain $\mathbf{x}^{(m)} \sim \mathsf{T}(\mathbf{x} \,|\, \mathbf{x}^{(m-1)})$ for which the stationary distribution is $p(\mathbf{x})$.

Still have $\bar{\tau} \to E[\tau]$, but usually $var(\bar{\tau}_{iid}) < var(\bar{\tau}_{mcmc})$.

Markov Chain Monte Carlo

- ▶ **Problem:** Let $\tau = g(\mathbf{x})$, $\mathbf{x} \sim p(\mathbf{x})$. Compute $E[\tau]$.
- ► MCMC:
 - ► Sample from a Markov chain $\mathbf{x}^{(m)} \sim \mathsf{T}(\mathbf{x} \,|\, \mathbf{x}^{(m-1)})$ for which the stationary distribution is $p(\mathbf{x})$.
 - Calculate $ar{ au} = rac{1}{M} \sum_{m=1}^M g(\mathbf{x}^{(m)}) o E[au]$
- ▶ Transition density: How to pick T(x | x')?

Two fundamental concepts:

- 1. **REDUCE**: only sample parts of x at a time (Gibbs sampler)
- 2. APPROX: don't try to sample perfectly, as many approximate sampling schemes can be perfectly corrected (Metropolis-Hastings algorithm)

Gibbs Sampler

- ▶ **Problem:** sample $\mathbf{x} \sim p(\mathbf{x})$
- ▶ **Suppose** we know how to sample from $p(x_i | \mathbf{x}_{-i})$ for every $1 \le i \le d$.

input: $\mathbf{x}^{(0)}$ \triangleright Starting value

$$\begin{aligned} &\textbf{for } m=1,\ldots,M \textbf{ do} \\ &\tilde{\mathbf{x}} \leftarrow \mathbf{x}^{(m)} \\ &\textbf{for } i=1,\ldots,d \textbf{ do} \\ &\tilde{x}_i \sim p(x_i \,|\, \tilde{x}_{-i}) \\ &\textbf{end for} \\ &\mathbf{x}^{(m+1)} \leftarrow \tilde{\mathbf{x}} \end{aligned}$$

> Update each rv conditioned on all others

end for

output:

 $x^{(1)}, \dots, x^{(M)}$

Example: Bivariate Normal

▶ Model:

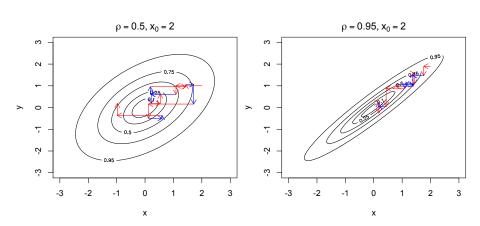
$$\begin{bmatrix} \mathbf{x} \\ \mathbf{y} \end{bmatrix} \sim \mathcal{N}_2 \left(\begin{bmatrix} \mu_{\mathbf{x}} \\ \mu_{\mathbf{y}} \end{bmatrix}, \begin{bmatrix} \sigma_{\mathbf{x}}^2 & \sigma_{\mathbf{x}} \sigma_{\mathbf{y}} \rho \\ \sigma_{\mathbf{x}} \sigma_{\mathbf{y}} \rho & \sigma_{\mathbf{y}}^2 \end{bmatrix} \right).$$

► Conditional Distributions:

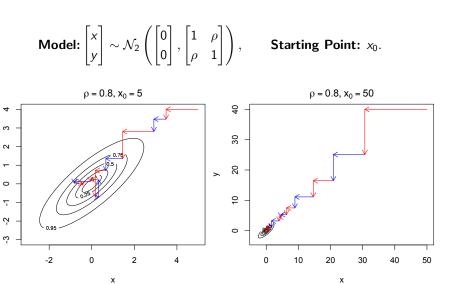
$$\begin{aligned} x \, | \, y &\sim \mathcal{N} \left(\mu_x + \rho \frac{\sigma_x}{\sigma_y} \times (y - \mu_y), (1 - \rho^2) \sigma_x^2 \right) \\ y \, | \, x &\sim \mathcal{N} \left(\mu_y + \rho \frac{\sigma_y}{\sigma_x} \times (x - \mu_x), (1 - \rho^2) \sigma_y^2 \right). \end{aligned}$$

Example: Bivariate Normal

$$\mathbf{Model:} \begin{bmatrix} x \\ y \end{bmatrix} \sim \mathcal{N}_2 \left(\begin{bmatrix} 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 & \rho \\ \rho & 1 \end{bmatrix} \right), \qquad \mathbf{Starting \ Point:} \ x_0.$$



Example: Bivariate Normal



Gibbs Sampler (Continued)

▶ **Summary:** Cycle through conditional updates $x_i \sim p(\mathbf{x}_{-i})$. Can do these in any order, even random.

▶ Limitations:

- ▶ Convergence is slow when $cor(x_i, \mathbf{x}_{-i}) \rightarrow 1$.
- ► Convergence is slow for poorly-chosen initial value $\mathbf{x}^{(0)}$
- ▶ Must be able to sample for each conditional $p(x_i | \mathbf{x}_{-i})$.

- ▶ Gibbs sampler requires you to be able to draw from each $p(x_i | \mathbf{x}_{-i})$.
- ▶ What if $p(x_i | \mathbf{x}_{-i})$ is not easy to draw from?
- ▶ M-H algorithm requires only a transition density $T(\mathbf{x} \mid \mathbf{x}')$ for which:
 - 1. You can draw $\mathbf{x} \sim \mathsf{T}(\mathbf{x} \,|\, \mathbf{x}')$
 - 2. You have a closed-form PDF (or PMF) for T(x | x')

 $x^{(0)}, T(x | x')$ input: Starting value, transition density for $m = 1, \ldots, M$ do $\mathbf{x}_{\text{curr}} \leftarrow \mathbf{x}^{(m)}$ $\mathbf{x}_{\text{prop}} \sim \mathsf{T}(\mathbf{x} \,|\, \mathbf{x}_{\text{curr}})$ ▶ Proposal $\alpha \leftarrow \min \left\{ 1, \frac{p(\mathbf{x}_{\mathsf{prop}}) / \mathsf{T}(\mathbf{x}_{\mathsf{prop}} | \mathbf{x}_{\mathsf{curr}})}{p(\mathbf{x}_{\mathsf{curr}}) / \mathsf{T}(\mathbf{x}_{\mathsf{curr}} | \mathbf{x}_{\mathsf{prop}})} \right\}$ $U \sim \text{Unif}(0,1)$ if $U < \alpha$ then $\mathbf{x}^{(m+1)} \leftarrow \mathbf{x}_{\text{prop}}$ \triangleright Keep proposal with probability α else $\mathbf{x}^{(m+1)} \leftarrow \mathbf{x}_{\text{curr}}$ \triangleright Reject proposal with probability $1-\alpha$ end if end for

output:

 $\mathbf{x}^{(1)}, \dots, \mathbf{x}^{(M)}$

► Algorithm Summary:

- 1. Draw $\mathbf{x}_{prop} \sim \mathsf{T}(\mathbf{x} \,|\, \mathbf{x}_{curr} = \mathbf{x}^{(m)})$
- 2. Let $\alpha = \min \left\{ 1, \frac{p(\mathbf{x}_{prop}) / T(\mathbf{x}_{prop} | \mathbf{x}_{curr})}{p(\mathbf{x}_{curr}) / T(\mathbf{x}_{curr} | \mathbf{x}_{prop})} \right\}$
- 3. Set $\mathbf{x}^{(m+1)}$ to \mathbf{x}_{prop} with probability α , to \mathbf{x}_{curr} with probability $1-\alpha$
- ▶ Requires only a transition density T(x | x') for which:
 - 1. You can draw $\mathbf{x} \sim \mathsf{T}(\mathbf{x} \,|\, \mathbf{x}')$
 - 2. You have a closed-form PDF (or PMF) for T(x | x')
- ► Only need $r(\mathbf{x}) = p(\mathbf{x})/Z$, where Z is unknown (since $p(\mathbf{x}_{prop})/p(\mathbf{x}_{curr}) = r(\mathbf{x}_{prop})/r(\mathbf{x}_{curr})$).

Critical for Bayesian inference, in which case only know $p(\theta \mid \mathbf{y}) \propto \mathcal{L}(\theta \mid \mathbf{y}) \pi(\theta)$

► Algorithm Summary:

- 1. Draw $\mathbf{x}_{prop} \sim \mathsf{T}(\mathbf{x} \,|\, \mathbf{x}_{curr} = \mathbf{x}^{(m)})$
- $\mathbf{2. \ Let} \ \alpha = \min \left\{ 1, \frac{p(\mathbf{x}_{\mathsf{prop}}) / \mathsf{T}(\mathbf{x}_{\mathsf{prop}} \,|\, \mathbf{x}_{\mathsf{curr}})}{p(\mathbf{x}_{\mathsf{curr}}) / \mathsf{T}(\mathbf{x}_{\mathsf{curr}} \,|\, \mathbf{x}_{\mathsf{prop}})} \right\}$
- 3. Set $\mathbf{x}^{(m+1)}$ to \mathbf{x}_{prop} with probability α , to \mathbf{x}_{curr} with probability $1-\alpha$
- ► Transition Density: Most common choices:
 - 1. Random Walk Metropolis: $\mathbf{x}_{\text{prop}} \sim \mathcal{N}(\mathbf{x}_{\text{curr}}, \text{diag}(\sigma_{\text{tune}}^2))$. Let $f(\mathbf{x})$ denote the PDF of $\mathcal{N}(\mathbf{0}, \text{diag}(\sigma_{\text{tune}}^2))$. Then

$$\mathsf{T}(\mathbf{x}_{\mathsf{prop}} \,|\, \mathbf{x}_{\mathsf{curr}}) = f(\mathbf{x}_{\mathsf{prop}} - \mathbf{x}_{\mathsf{curr}}) = f(\mathbf{x}_{\mathsf{curr}} - \mathbf{x}_{\mathsf{prop}}) = \mathsf{T}(\mathbf{x}_{\mathsf{curr}} \,|\, \mathbf{x}_{\mathsf{prop}}).$$

Thus, the transition density is symmetric $\implies \alpha = \min\{1, p(\mathbf{x}_{prop})/p(\mathbf{x}_{curr})\}.$

► Algorithm Summary:

1. Draw
$$\mathbf{x}_{prop} \sim \mathsf{T}(\mathbf{x} \,|\, \mathbf{x}_{curr} = \mathbf{x}^{(m)})$$

2. Let
$$\alpha = \min \left\{ 1, \frac{\rho(\mathbf{x}_{\text{prop}}) / \mathsf{T}(\mathbf{x}_{\text{prop}} | \mathbf{x}_{\text{curr}})}{\rho(\mathbf{x}_{\text{curr}}) / \mathsf{T}(\mathbf{x}_{\text{curr}} | \mathbf{x}_{\text{prop}})} \right\}$$

- 3. Set $\mathbf{x}^{(m+1)}$ to \mathbf{x}_{prop} with probability α , to \mathbf{x}_{curr} with probability $1-\alpha$
- ► Transition Density: Most common choices:
 - $\mathbf{x}_{\text{prop}} \sim \mathcal{N}(\mathbf{x}_{\text{curr}}, \text{diag}(\boldsymbol{\sigma}_{\text{tupe}}^2)).$ 1. Random Walk Metropolis:
 - 2. Metropolis-Within-Gibbs:

```
for m = 1, \ldots, M do
        \mathbf{x}_{\text{curr}}, \mathbf{x}_{\text{prop}} \leftarrow \mathbf{x}^{(m)}
        for i = 1, \ldots, d do
                                                                                                                                                                                                                           x_{i,\text{prop}} \sim \mathcal{N}(x_{i,\text{curr}} \mid \sigma_{i,\text{tupe}}^2)
                                                                                                                                                              ▶ Metropolis step within conditional proposal
                \alpha \leftarrow \min\{1, p(\mathbf{x}_{\text{prop}})/p(\mathbf{x}_{\text{curr}})\}
                                                                                                                                        \triangleright Symmetric proposal, and note that \mathbf{x}_{-i,\text{prop}} = \mathbf{x}_{-i,\text{curr}}
                if runif(1) < \alpha then x_{j,\text{curr}} \leftarrow x_{j,\text{prop}}
                                                                                                                    \triangleright \implies p(\mathbf{x}_{\text{prop}})/p(\mathbf{x}_{\text{curr}}) = p(x_{i \text{ prop}} \mid \mathbf{x}_{-i \text{ prop}})/p(x_{i \text{ curr}} \mid \mathbf{x}_{-i \text{ curr}})
                else x_{i,prop} \leftarrow x_{icurr} end if
        end for
        \mathbf{x}^{(m+1)} \leftarrow \mathbf{x}_{curr}
```

end for

Storage at the end of update cycle

► Algorithm Summary:

- 1. Draw $\mathbf{x}_{prop} \sim \mathsf{T}(\mathbf{x} \,|\, \mathbf{x}_{curr} = \mathbf{x}^{(m)})$
- 2. Let $\alpha = \min \left\{ 1, \frac{p(\mathbf{x}_{prop}) / T(\mathbf{x}_{prop} | \mathbf{x}_{curr})}{p(\mathbf{x}_{curr}) / T(\mathbf{x}_{curr} | \mathbf{x}_{prop})} \right\}$
- 3. Set $\mathbf{x}^{(m+1)}$ to \mathbf{x}_{prop} with probability α , to \mathbf{x}_{curr} with probability $1-\alpha$
- ► Transition Density: Most common choices:
 - 1. Random Walk Metropolis: $\mathbf{x}_{prop} \sim \mathcal{N}(\mathbf{x}_{curr}, diag(\sigma_{tune}^2))$.
 - **2.** Metropolis-Within-Gibbs: $x_{j,\text{prop}} \sim \mathcal{N}(x_{j,\text{curr}}, \sigma_{j,\text{tune}}^2), \quad j = 1, \dots, d.$

Like a Gibbs sampler, but each update is RWM if $p(x_j | \mathbf{x}_{-j})$ can't be drawn from directly.

- ► Algorithm Summary:
 - 1. Draw $\mathbf{x}_{prop} \sim \mathsf{T}(\mathbf{x} \,|\, \mathbf{x}_{curr} = \mathbf{x}^{(m)})$
 - $\mathbf{2. \ Let} \ \alpha = \min \left\{ 1, \frac{\rho(\mathbf{x}_{\mathsf{prop}}) / \mathsf{T}(\mathbf{x}_{\mathsf{prop}} \,|\, \mathbf{x}_{\mathsf{curr}})}{\rho(\mathbf{x}_{\mathsf{curr}}) / \mathsf{T}(\mathbf{x}_{\mathsf{curr}} \,|\, \mathbf{x}_{\mathsf{prop}})} \right\}$
 - 3. Set $\mathbf{x}^{(m+1)}$ to \mathbf{x}_{prop} with probability α , to \mathbf{x}_{curr} with probability $1-\alpha$
- ► Transition Density: Most common choices:
 - 1. Random Walk Metropolis: $\mathbf{x}_{prop} \sim \mathcal{N}(\mathbf{x}_{curr}, \text{diag}(\sigma_{tune}^2))$.
 - **2.** Metropolis-Within-Gibbs: $x_{j,\text{prop}} \sim \mathcal{N}(x_{j,\text{curr}}, \sigma_{j,\text{tune}}^2), \quad j = 1, \dots, d.$
 - 3. Metropolized IID: $x_{prop} \stackrel{\text{iid}}{\sim} q(x)$.

Typically this is "mode-quadrature" proposal $\mathcal{N}(\hat{\mathbf{x}}, -[\frac{\partial^2}{\partial \mathbf{x}^2}\log p(\hat{\mathbf{x}})]^{-1})$, where $\hat{\mathbf{x}} = \arg\max_{\mathbf{x}} p(\mathbf{x})$.

- ► Algorithm Summary:
 - 1. Draw $\mathbf{x}_{prop} \sim \mathsf{T}(\mathbf{x} \,|\, \mathbf{x}_{curr} = \mathbf{x}^{(m)})$
 - 2. Let $\alpha = \min \left\{ 1, \frac{p(\mathbf{x}_{prop})/T(\mathbf{x}_{prop} \mid \mathbf{x}_{curr})}{p(\mathbf{x}_{curr})/T(\mathbf{x}_{curr} \mid \mathbf{x}_{prop})} \right\}$
 - 3. Set $\mathbf{x}^{(m+1)}$ to \mathbf{x}_{prop} with probability α , to \mathbf{x}_{curr} with probability $1-\alpha$

Why does it work?

► **Theorem:** Suppose that $\mathbf{x}^{(m)}$ is drawn from $p(\mathbf{x})$, and $\mathbf{x}^{(m+1)}$ is an MH update, i.e.,

$$\mathbf{x}^{(m)} \sim p(\mathbf{x})$$

$$\mathbf{x}^{(m+1)} \mid \mathbf{x}^{(m)} \sim \mathsf{MH}\{\mathsf{T}, \mathbf{x}^{(m)}\}$$

$$= \alpha \cdot \mathsf{T}(\mathbf{x} \mid \mathbf{x}^{(m)}) + (1 - \alpha) \cdot \mathbb{I}\{\mathbf{x} = \mathbf{x}^{(m)}\}.$$

Then the marginal distribution of $\mathbf{x}^{(m+1)} \sim p(\mathbf{x})$. In other words, the MH algorithm generates a Markov chain with stationary distribution $p(\mathbf{x})$.

- ► Algorithm Summary:
 - 1. Draw $\mathbf{x}_{\text{prop}} \sim \mathsf{T}(\mathbf{x} \,|\, \mathbf{x}_{\text{curr}} = \mathbf{x}^{(m)})$
 - $\mathbf{2. \ Let} \ \alpha = \min \left\{ 1, \frac{\rho(\mathbf{x}_{\mathsf{prop}}) / \, \mathsf{T}(\mathbf{x}_{\mathsf{prop}} \, | \, \mathbf{x}_{\mathsf{curr}})}{\rho(\mathbf{x}_{\mathsf{curr}}) / \, \mathsf{T}(\mathbf{x}_{\mathsf{curr}} \, | \, \mathbf{x}_{\mathsf{prop}})} \right\}$
 - 3. Set $\mathbf{x}^{(m+1)}$ to \mathbf{x}_{prop} with probability α , to \mathbf{x}_{curr} with probability $1-\alpha$
- ► Theorem: $\mathbf{x}^{(m)} \sim \rho(\mathbf{x}) \implies \mathbf{x}^{(m+1)} \sim \rho(\mathbf{x}).$ $\mathbf{x}^{(m+1)} \mid \mathbf{x}^{(m)} \sim \mathsf{MH}\{\mathsf{T}, \mathbf{x}^{(m)}\}$
- ▶ **Proof:** Consider \mathbf{x}_a and \mathbf{x}_b such that $\alpha = \frac{p(\mathbf{x}_a)/\mathsf{T}(\mathbf{x}_a \mid \mathbf{x}_b)}{p(\mathbf{x}_b)/\mathsf{T}(\mathbf{x}_b \mid \mathbf{x}_a)} < 1$.
 - 1. Joint distribution of a then b: (proposal automatically accepted)

$$p(\mathbf{x}^{(m)} = \mathbf{x}_{a}, \mathbf{x}^{(m+1)} = \mathbf{x}_{b}) = p(\mathbf{x}_{a}) \cdot \mathsf{T}(\mathbf{x}_{b} \mid \mathbf{x}_{a}).$$

- ► Algorithm Summary:
 - 1. Draw $\mathbf{x}_{prop} \sim \mathsf{T}(\mathbf{x} \,|\, \mathbf{x}_{curr} = \mathbf{x}^{(m)})$
 - 2. Let $\alpha = \min \left\{ 1, \frac{p(\mathbf{x}_{prop}) / T(\mathbf{x}_{prop} | \mathbf{x}_{curr})}{p(\mathbf{x}_{curr}) / T(\mathbf{x}_{curr} | \mathbf{x}_{prop})} \right\}$
 - 3. Set $\mathbf{x}^{(m+1)}$ to \mathbf{x}_{prop} with probability α , to \mathbf{x}_{curr} with probability $1-\alpha$
- ▶ Theorem: $\mathbf{x}^{(m)} \sim \rho(\mathbf{x}) \implies \mathbf{x}^{(m+1)} \sim \rho(\mathbf{x}).$ $\mathbf{x}^{(m+1)} \mid \mathbf{x}^{(m)} \sim \mathsf{MH}\{\mathsf{T}, \mathbf{x}^{(m)}\}$
- ▶ **Proof:** Consider \mathbf{x}_a and \mathbf{x}_b such that $\alpha = \frac{p(\mathbf{x}_a)/\mathsf{T}(\mathbf{x}_a \mid \mathbf{x}_b)}{p(\mathbf{x}_b)/\mathsf{T}(\mathbf{x}_b \mid \mathbf{x}_a)} < 1$.
 - 1. Joint distribution of a then b: $p(\mathbf{x}^{(m)} = \mathbf{x}_a, \mathbf{x}^{(m+1)} = \mathbf{x}_b) = p(\mathbf{x}_a) \cdot \mathsf{T}(\mathbf{x}_b \mid \mathbf{x}_a)$.
 - **2.** Joint distribution of **b** then **a**: (proposal accepted with probability α)

$$p(\mathbf{x}^{(m)} = \mathbf{x}_b, \mathbf{x}^{(m+1)} = \mathbf{x}_a) = p(\mathbf{x}_b) \cdot \mathsf{T}(\mathbf{x}_a \mid \mathbf{x}_b) \cdot \frac{p(\mathbf{x}_a) / \mathsf{T}(\mathbf{x}_a \mid \mathbf{x}_b)}{p(\mathbf{x}_b) / \mathsf{T}(\mathbf{x}_b \mid \mathbf{x}_a)}$$
$$= p(\mathbf{x}_a) \cdot \mathsf{T}(\mathbf{x}_b \mid \mathbf{x}_a).$$

► Algorithm Summary:

- 1. Draw $\mathbf{x}_{prop} \sim \mathsf{T}(\mathbf{x} \,|\, \mathbf{x}_{curr} = \mathbf{x}^{(m)})$
- 2. Let $\alpha = \min \left\{ 1, \frac{p(\mathbf{x}_{prop}) / T(\mathbf{x}_{prop} | \mathbf{x}_{curr})}{p(\mathbf{x}_{curr}) / T(\mathbf{x}_{curr} | \mathbf{x}_{prop})} \right\}$
- 3. Set $\mathbf{x}^{(m+1)}$ to \mathbf{x}_{prop} with probability α , to \mathbf{x}_{curr} with probability $1-\alpha$
- ► Theorem: $\mathbf{x}^{(m)} \sim p(\mathbf{x})$ \Longrightarrow $\mathbf{x}^{(m+1)} \sim p(\mathbf{x})$. $\mathbf{x}^{(m+1)} \mid \mathbf{x}^{(m)} \sim \mathsf{MH}\{\mathsf{T}, \mathbf{x}^{(m)}\}$
- ▶ **Proof:** Consider \mathbf{x}_a and \mathbf{x}_b such that $\alpha = \frac{p(\mathbf{x}_a)/\mathsf{T}(\mathbf{x}_a \mid \mathbf{x}_b)}{p(\mathbf{x}_b)/\mathsf{T}(\mathbf{x}_b \mid \mathbf{x}_a)} < 1$.
 - 1. Joint distribution of a then b: $p(\mathbf{x}^{(m)} = \mathbf{x}_a, \mathbf{x}^{(m+1)} = \mathbf{x}_b) = p(\mathbf{x}_a) \cdot \mathsf{T}(\mathbf{x}_b \mid \mathbf{x}_a)$.
 - 2. Joint distribution of b then a: $p(\mathbf{x}^{(m)} = \mathbf{x}_b, \mathbf{x}^{(m+1)} = \mathbf{x}_a) = p(\mathbf{x}_a) \cdot \mathsf{T}(\mathbf{x}_b \mid \mathbf{x}_a)$.

$$\implies p(\mathbf{x}^{(m)} = \mathbf{x}_{a}, \mathbf{x}^{(m+1)} = \mathbf{x}_{b}) = p(\mathbf{x}^{(m)} = \mathbf{x}_{b}, \mathbf{x}^{(m+1)} = \mathbf{x}_{a}).$$

Since joint distribution is symmetric, each marginal must be identical

$$\implies p(\mathbf{x}^{(m+1)}) = p(\mathbf{x}^{(m)}) = p(\mathbf{x}).$$

Example: Weibull Distribution

Definition: If $X \sim \mathsf{Expo}(1)$, then

$$Y = \lambda X^{\gamma} \sim \text{Weibull}(\gamma, \lambda).$$

The PDF of Y is

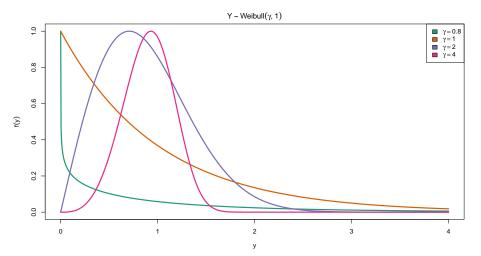
$$f(y) = \frac{\gamma}{\lambda} \left(\frac{y}{\lambda}\right)^{\gamma-1} e^{-(y/\lambda)^{\gamma}}, \quad y > 0.$$

- ▶ **Model:** $Y \sim \text{Weibull}(\gamma, \lambda)$ \iff $Y = \lambda X^{\gamma}, \ X \sim \text{Expo}(1).$
- ▶ Utility: Survival analysis
 - ► Hazard function: ≈ probability of failing in next instant:

$$h(y) = \lim_{\Delta y \to 0} \frac{\Pr(Y < y + \Delta y \mid Y > y)}{\Delta y} = \frac{f(y)}{1 - F(y)}$$

- ▶ h(y) characterizes distribution, just like f(y) or F(y)
- ▶ Weibull Hazard: $h(y) = (\frac{\gamma}{\lambda \gamma}) \cdot y^{\gamma 1}$
 - $\gamma = 1 \implies h(y) = \text{const} \implies Y \sim \lambda \cdot \text{Expo}(1)$ memoriless property (chance of failing constant through time)
 - ho $\gamma > 1 \implies h(y)$ increasing Ex: elderly patients more and more likely to die soon as they get older
 - $g < 1 \implies h(y)$ decreasing Ex: infants more and more likely to survive longer as they get older

- ▶ Model: $Y \sim \text{Weibull}(\gamma, \lambda)$ \iff $Y = \lambda X^{\gamma}, \ X \sim \text{Expo}(1).$
- ▶ Hazard Function: $h(y) \propto y^{\gamma-1}$



- ▶ **Model:** $Y \sim \text{Weibull}(\gamma, \lambda)$ \iff $Y = \lambda X^{\gamma}, X \sim \text{Expo}(1).$
- ▶ **Likelihood:** $\mathbf{y} = (y_1, \dots, y_n) \stackrel{\text{iid}}{\sim} \text{Weibull}(\gamma, \lambda)$

$$\ell(\gamma, \lambda \mid \mathbf{y}) = n \big[\log(\gamma) - \gamma \log(\lambda) \big] + \sum_{i=1}^{n} \gamma \log(y_i) - \lambda^{-\gamma} \sum_{i=1}^{n} y_i^{\gamma}.$$

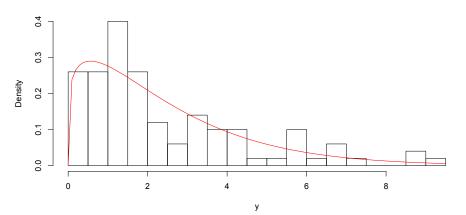
Not an Exponential Family (because of y_i^{γ}).

- ▶ **Model:** $Y \sim \text{Weibull}(\gamma, \lambda)$ \iff $Y = \lambda X^{\gamma}, X \sim \text{Expo}(1).$
- ▶ **Likelihood:** $\mathbf{y} = (y_1, \dots, y_n) \stackrel{\text{iid}}{\sim} \text{Weibull}(\gamma, \lambda)$

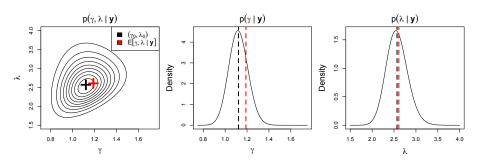
$$\ell(\gamma, \lambda \mid \mathbf{y}) = n \big[\log(\gamma) - \gamma \log(\lambda) \big] + \gamma \sum_{i=1}^{n} \log(y_i) - \lambda^{-\gamma} \sum_{i=1}^{n} y_i^{\gamma}.$$

Not an Exponential Family (because of y_i^{γ}).

- ▶ **Model:** $Y \sim \text{Weibull}(\gamma, \lambda)$ \iff $Y = \lambda X^{\gamma}, \ X \sim \text{Expo}(1).$
- ▶ Likelihood: $\ell(\gamma, \lambda \mid \mathbf{y}) = n \left[\log(\gamma) \gamma \log(\lambda) \right] + \sum_{i=1}^{n} \left[\gamma \log(y_i) \lambda^{-\gamma} y_i^{\gamma} \right].$
- **▶ Simulated Data:** $\gamma = 1.19, \lambda = 2.61, n = 100$



- ▶ **Model:** $Y \sim \text{Weibull}(\gamma, \lambda)$ \iff $Y = \lambda X^{\gamma}, \ X \sim \text{Expo}(1).$
- ▶ Likelihood: $\ell(\gamma, \lambda \mid \mathbf{y}) = n \left[\log(\gamma) \gamma \log(\lambda) \right] + \sum_{i=1}^{n} \left[\gamma \log(y_i) \lambda^{-\gamma} y_i^{\gamma} \right].$
- ullet **Prior:** $\pi(\gamma,\lambda)\propto 1$ (hopefully won't make much difference)
- ▶ **Posterior:** For 2-d problem can compute $p(\gamma, \lambda \mid \mathbf{y})$ on a grid



- ▶ **Model:** $Y \sim \text{Weibull}(\gamma, \lambda)$ \iff $Y = \lambda X^{\gamma}, \ X \sim \text{Expo}(1).$
- ▶ Likelihood: $\ell(\gamma, \lambda \mid \mathbf{y}) = n \left[\log(\gamma) \gamma \log(\lambda) \right] + \sum_{i=1}^{n} \left[\gamma \log(y_i) \lambda^{-\gamma} y_i^{\gamma} \right].$
- ▶ Prior: $\pi(\gamma, \lambda) \propto 1$
- ▶ **Posterior:** For 2-d problem can compute $p(\gamma, \lambda \mid \mathbf{y})$ on a grid,

OR MCMC on
$$\theta = (\gamma, \lambda)$$
:

- 1. Random-Walk Metropolis: $\theta_{\text{prop}} \sim \mathcal{N}(\theta_{\text{curr}}, \text{diag}(\sigma_{\text{RW}}^2))$.
- **2.** Metropolis-Within-Gibbs: $\theta_{j,\text{prop}} \sim \mathcal{N}(\theta_{j,\text{curr}}, \sigma_{j,\text{RW}}^2), \quad j = 1, 2.$
- 3. Metropolized IID: $\theta_{\text{prop}} \stackrel{\text{iid}}{\sim} \mathcal{N}(\hat{\theta}, \hat{\Sigma}), \qquad \hat{\theta} = \arg \max_{\theta} \log p(\theta \mid \mathbf{y})$

$$\hat{oldsymbol{\Sigma}} = -\left[rac{\partial^2}{\partial oldsymbol{ heta}^2}\log p(\hat{oldsymbol{ heta}}\,|\,\mathbf{y})
ight]^{-1}$$

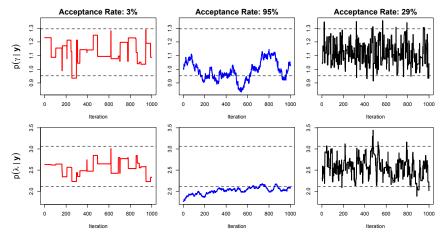
Random-Walk Metropolis (RWM)

- ullet Transition Density: $m{ heta}_{ extsf{prop}} \sim \mathcal{N}ig(m{ heta}_{ extsf{curr}}, extsf{diag}(m{\sigma}_{ extsf{RW}}^2)ig)$
- ▶ Tuning Parameters: coordinate-wise "jump size" σ_{RW} .
- ▶ **Question:** How to pick σ_{RW} ?

Random-Walk Metropolis (RWM)

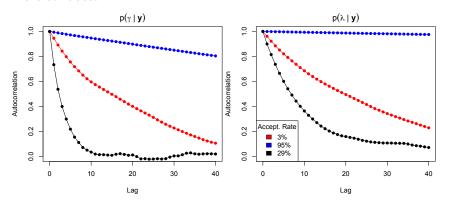
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- ▶ Tuning Parameters: coordinate-wise "jump size" σ_{RW} .

"Optimal" acceptance rate: $\approx 25\%$.



MCMC Diagnostics

- **1. Trace Plot:** Time series of MCMC output $\theta^{(1)}, \dots, \theta^{(M)}$
- **2. Autocorrelation Plot:** Ideally would have $\theta^{(m)} \stackrel{\text{iid}}{\sim} p(\theta \mid \mathbf{y})$, but instead draws are correlated.



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- **3. Effective Sample Size:** For given $\tau = g(\theta)$, M draws from MCMC are roughly equivalent to ESS (τ) iid draws, where

$$\mathsf{ESS}(\tau) = \frac{M}{1 + 2 \times \sum_{t=1}^{\infty} \gamma_t}, \qquad \gamma_t = \mathsf{cor}(\tau^{(m)}, \tau^{(m+t)}).$$

That is, if $\hat{\tau}_{\rm MCMC}$ and $\hat{\tau}_{\rm IID}$ are sample means of M draws from MCMC and IID sampler, then

$$\frac{\mathsf{var}(\hat{\tau}_{\mathsf{IID}})}{\mathsf{var}(\hat{\tau}_{\mathsf{MCMC}})} \approx \frac{1}{1 + 2 \times \sum_{t=1}^{\infty} \gamma_t}.$$

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Weibull example for M = 10,000:

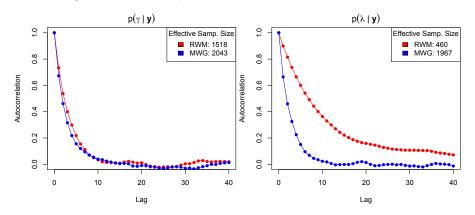
	Accept. Rate			
	3%	95%	29%	
γ	286	137	1518	
λ	235	125	460	

Metropolis-Within-Gibbs (MWG)

- ► Transition Density: $\theta_{\mathsf{prop},j} \sim \mathcal{N}(\theta_{\mathsf{curr},j}, \sigma^2_{\mathsf{RW},j})$ Contrast with RWM, which proposes all of θ at once.
- ▶ Tuning Parameters: "Optimal" coordinate-wise acceptance rate $\approx 45\%$. Contrast with RMW, for which optimal acceptance rate $\approx 25\%$.

Metropolis-Within-Gibbs (MWG)

- ▶ Transition Density: $\theta_{\mathsf{prop},j} \sim \mathcal{N}(\theta_{\mathsf{curr},j}, \sigma^2_{\mathsf{RW},j})$
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► Transition Density:

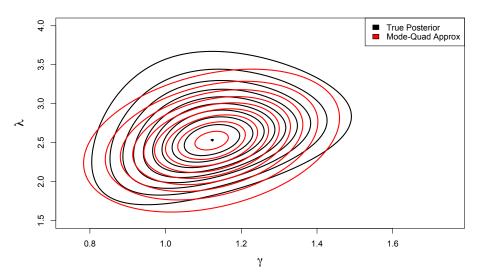
$$oldsymbol{ heta}_{\mathsf{prop}} \overset{\mathsf{iid}}{\sim} \mathcal{N}\left(\hat{oldsymbol{ heta}}, -\left[rac{\partial^2}{\partial oldsymbol{ heta}^2} \log p(\hat{oldsymbol{ heta}} \, | \, \mathbf{y})
ight]^{-1}
ight), \qquad \hat{oldsymbol{ heta}} = rg \max_{oldsymbol{ heta}} \log p(oldsymbol{ heta} \, | \, \mathbf{y}).$$

► Optimal acceptance rate:

► Transition Density:

$$m{ heta_{\mathsf{prop}}} \overset{\mathsf{iid}}{\sim} \mathcal{N}\left(\hat{m{ heta}}, -\left[rac{\partial^2}{\partial m{ heta}^2} \log p(\hat{m{ heta}} \,|\, \mathbf{y})
ight]^{-1}
ight), \qquad \hat{m{ heta}} = rg \max_{m{ heta}} \log p(m{ heta} \,|\, \mathbf{y}).$$

- ► Optimal acceptance rate: 100%!
 - ► MIID has no tuning parameters: no need to tune (good), but also stuck with whatever acceptance rate the proposals have (bad).
 - ▶ Since proposals are IID, all of $p(\theta_{\text{prop}} \mid \mathbf{y})$ and $q(\theta_{\text{prop}})$ can be precomputed before entering the MCMC \implies can parallelize these calculations, and write a generic and lightweight MIID sampler directly in \mathbf{R} (see miid.sampler in mcmc-functions.R on LEARN).
 - ▶ Works extremely well when number of parameters is $d \sim 10-20$. But for large d acceptance rate typically goes to 0.
 - ► I usually resort to MWG if MIID acceptance rate is < 10 25%, or if mode-finding algorithm is unreliable, etc.



Effective sample size for M = 10,000:

Algorithm (acc. rate)

	RMW (25%)	MWG (45%)	MIID (90%)
$\overline{\gamma}$	1518	2043	8892
λ	460	1967	4195

Summary

- ► RWM vs MWG:
 - ► Transition Density: $\theta_{\text{prop}}^{(RWM)} \sim \mathcal{N}(\theta_{\text{curr}}, \text{diag}(\sigma_{\text{RWM}}^2)), \quad \theta_{\text{prop},j}^{(MWG)} \sim \mathcal{N}(\theta_{\text{curr},j}, \sigma_{\text{MWG},j}^2).$
 - ► Almost always use MWG instead of RWM.
 - ► MWG almost always converges faster.
 - Price to pay is more log-posterior evaluations.
 - ▶ Optimal Acceptance Rates: $\alpha_{\rm RWM} \approx 25\%$ and $\alpha_{\rm MWG} \approx 45\%$.
- ► MIID:
 - ▶ Transition Density: $\theta_{\text{prop}} \stackrel{\text{iid}}{\sim} q(\theta)$ (typically a normal with mode-quadrature matching log $p(\theta \mid y)$).
 - ▶ Optimal Acceptance Rate: α_{MIID} as high as possible.
 - ▶ **Efficiency:** Calculation of $q(\theta_{prop})$ and $p(\theta_{prop} | \mathbf{y})$ can be easily vectorized (unlike RWM and MWG).
 - Can be combined with MWG, but recalculating mode-quadrature within each Gibbs step can be very expensive.

Marginal MCMC

- ▶ **Model:** $Y \sim \text{Weibull}(\gamma, \lambda)$ \iff $Y = \lambda X^{\gamma}, \ X \sim \text{Expo}(1).$
- ► Loglikelihood:

$$\ell(\gamma, \lambda \mid \mathbf{y}) = n \left[\log(\gamma) - \gamma \log(\lambda) \right] + \sum_{i=1}^{n} \left[\gamma \log(y_i) - \lambda^{-\gamma} y_i^{\gamma} \right]$$
$$= n \left[\log(\gamma) + \log(\eta) \right] + \gamma S - \eta T_{\gamma},$$

where $\eta = \lambda^{-\gamma}$, $S = \sum_{i=1}^n \log(y_i)$, and $T_{\gamma} = \sum_{i=1}^n y_i^{\gamma}$.

- ▶ Conditionally Conjugate Prior: For fixed γ :
 - ► Conditional Likelihood: $\ell(\eta \mid \gamma, \mathbf{y}) = n \log(\eta) \eta T_{\gamma}$.
 - ► Conjugate Prior: $\pi(\eta \mid \gamma) \sim \mathsf{Gamma}(\alpha, \beta)$

$$\iff \log \pi(\eta \,|\, \gamma) = (\alpha - 1) \log(\eta) - \eta \beta.$$

► Conditional Posterior: $\eta \mid \gamma, \mathbf{y} \sim \mathsf{Gamma}(\hat{\alpha}, \hat{\beta}_{\gamma}),$ $\hat{\alpha} = \alpha + n$

Marginal MCMC

- ▶ **Model:** $Y \sim \text{Weibull}(\gamma, \lambda)$ \iff $Y = \lambda X^{\gamma}, X \sim \text{Expo}(1).$
- ▶ Loglikelihood: $\ell(\gamma, \lambda \mid \mathbf{y}) = n[\log(\gamma) + \log(\eta)] + \gamma S \eta T_{\gamma}$, where $\eta = \lambda^{-\gamma}$, $S = \sum_{i=1}^{n} \log(y_i)$, and $T_{\gamma} = \sum_{i=1}^{n} y_i^{\gamma}$.
- ► Conditionally Conjugate Prior: $\pi(\gamma, \eta)$ such that $\gamma \sim \pi(\gamma)$ $\eta \mid \gamma \sim \mathsf{Gamma}(\alpha, \beta).$
- ► Conditional Posterior: $\eta \mid \gamma, \mathbf{y} \sim \mathsf{Gamma}(\hat{\alpha}, \hat{\beta}_{\gamma}), \qquad \hat{\alpha} = \alpha + n$
- ► Marginal Posterior:

$$\begin{split} p(\gamma \,|\, \mathbf{y}) &= \frac{p(\gamma, \eta \,|\, \mathbf{y})}{p(\eta \,|\, \gamma, \mathbf{y})} \propto \frac{\mathcal{L}(\gamma, \eta \,|\, \mathbf{y})\pi(\gamma, \eta)}{\operatorname{dgamma}(\eta \,|\, \hat{\alpha}, \hat{\beta}_{\gamma})} \\ &= \exp \left\{ \log \Gamma(\hat{\alpha}) - \hat{\alpha} \log(\hat{\beta}_{\gamma}) + n \log(\gamma) + \gamma S \right\} \times \pi(\gamma). \end{split}$$

 \implies can do 1-d MCMC to get $\gamma^{(m)} \sim p(\gamma \mid \mathbf{y})$, followed by $\eta^{(m)} \stackrel{\mathsf{ind}}{\sim} \mathsf{Gamma}(\hat{\alpha}, \hat{\beta}_{\gamma^{(m)}})$.

 $\hat{\beta}_{\sim} = \beta + T_{\sim}$

Efficiency of Gibbs Sampling Schemes

- ▶ **Theorem:** Consider three Gibbs sampling schemes on p(x, y, z):
 - 1. Single-Component Gibbs: x = y = z
 - 2. Block Gibbs: x = (y, z)
 - **3. Collapsed Gibbs:** first x = y, then $z \sim p(z \mid x, y)$.

Then we have: $ESS(Scheme 1) \leq ESS(Scheme 2) \leq ESS(Scheme 3)$.

- ► Practical Considerations:
 - ▶ Result only holds for exact Gibbs sampler, i.e., if all schemes above use Metropolis-within-Gibbs, then usually ESS(Scheme 1) ≥ ESS(Scheme 2), as the effectiveness of RW multivariate proposals decreases exponentially with number of dimensions.
 - ► If all schemes are MWG, then Scheme 3 (if available) is always better than the other two. However, if Scheme 1 is exact Gibbs and Scheme 3 is MWG, then often ESS(Scheme 1) ≥ ESS(Scheme 3) if number of parameters is large and few are being collapsed.

Resources

- ▶ Julia Programming Language: MCMC is for-loop intensive, and these are very slow in R. Julia is very similar to R and Matlab, but it can execute for-loops extremely fast (see here for technical details). Moreover, the R package JuliaCall allows you to interface Julia code directly from R.
- ▶ Adaptive MCMC: RWM and MWG algorithms work best when the acceptance rate is 25% or 45%. Instead of finding jump sizes σ_{RW} to achieve this by trial-and-error, it is possible to do so automatically (e.g., decrease jump size if fraction of accepted proposals so far is < 45%, increase otherwise).

However, doing this naively typically produces draws $\theta^{(1)}, \theta^{(2)}, \ldots$ which do not come from $p(\theta \mid \mathbf{y})$. For several examples of valid adaptive MCMC methods, see here.