EEE 554: Random Signal Theory

Fall 2021

Final Project: Due on December 8

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Note: The project is **due by 11:59 pm** on the date indicated. Several of these ideas were put together by Prof. Kosut, who has graciously allowed us to use them.

This project concerns the simulation of random variables. This is an important task in a wide variety of applications such as verification of systems in uncertain environments, quantifying uncertainty in statistical inference, and performing Bayesian inference. In fact, there is a strong connection between sampling and optimization, which is crucial to several Bayesian techniques in computational science and engineering.

In this project, you will implement and analyze an algorithm for simulating a given distribution. That is, given a PDF, your goal would be to efficiently generate samples from this distribution. **First, read and understand this document explaining the simulation algorithm in its entirety**. Then, you may write code to implement and analyze. (Python or Matlab is recommended, but not required.) You should turn in a report which includes your well-documented code, as well as a write-up describing your implementation details, and the answers to specific questions asked below. Specific tasks that *must* be covered in your project report will be labeled by the bold word **Task**. You should make sure that your response to these tasks are *clearly presented* in your final report.

Your grade for the project will be 50% based on the correctness of your algorithm implementation, and 50% based on the clarity of your project report. You may discuss the project in broad terms with other students, but you must work independently. Any incident of academic dishonesty will result in a zero in the project.

1.1 Rejection Sampling and The Ziggurat Algorithm

The idea of rejection sampling is to define a two-dimensional region \mathcal{R} that contains the target PDF f_S . This idea can be generalized slightly by using a function g(x) which is proportional to the target PDF $f_S(x)$; that is, $f_S(x) = cg(x)$ for some constant c. Then the region \mathcal{R} should be such that it includes the function g(x). (See Figure 1.1.) A random pair X, Y is generated uniformly in the region \mathcal{R} . If Y < g(X), then the sample X is accepted. Otherwise the sample is rejected and another random pair is generated, repeating until a sample is accepted. This accepted sample will be returned as a random sample from the given distribution.

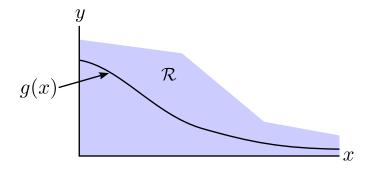


Figure 1.1: The basic rejection sampling concept.

Task 1: Theory

You will first establish why such a procedure could work. You may safely postpone this problem to until after you tackle the rest of the project.

Let us suppose that we want a sample from the distribution $f_S(x)$, and let us suppose that it much easier to sample from another distribution h(x) that is such that $Mh(x) > f_S(x)$ for all x, where $M \ge 1$ is some constant. Now, let us suppose you do the following procedure: (a) sample (X, Y) uniformly from the region \mathcal{R} that lies under Mh(x) (notice that this is equivalent to sampling X from h(x) and then sampling Y uniformly from (0, Mh(X))), and (b) return X if the sample drawn lies under the envelope of f_S . If (b) fails, continue until you get one sample.

Show that the sample X returned by the above procedure has the distribution $f_S(x)$ as desired.

Hint: Let A be the event that the step (b) succeeds. Now, notice that what you're required to show is that $f(X \mid A)$, the PDF of X conditioned on the event A happening, is equal to $f_S(x)$. For this, you can use the Bayes' rule as follows:

$$f(X \mid A) = \frac{\mathbb{P}(A \mid X)f(X)}{\mathbb{P}(A)},$$

where f(X) is the unconditional distribution of X. What is this equal to? Once this is clear, note that all that you need to do is to understand what $\mathbb{P}(A)$ and $\mathbb{P}(A \mid X)$ look like.

To make rejection sampling efficient, two objectives must be satisfied:

- 1. The region \mathcal{R} should be designed so that it is easy to generate random pairs X, Y uniformly from the region.
- 2. The probability of accepting a given pair should be as large as possible. This requires that the region \mathcal{R} does not include much area above g(x).

A particularly efficient way to do this is via the Ziggurat algorithm. This algorithm assumes that the function g(x) is monotonically decreasing; the cases where it is not may be handled quite easily. The region \mathcal{R} consists of n sub-regions stacked on top of each other: n-1 of these sub-regions are rectangles, and the nth is rectangle adjoined to the tail of the distribution. This idea is illustrated in Figure 1.2, where each of the n regions (in the figure n=4) is shaded in a different color.

The rectangles are set up so that each of the n sub-regions (including the nth region, which is not a rectangle) have exactly the same area. Thus, a point X,Y can be uniformly chosen from the full region as follows: First, choose a sub-region from a discrete uniform distribution—i.e., each with probability 1/n—in Matlab this can be done with the function randi. Then, for the rectangular regions, X can be chosen from a uniform distribution along the length of the rectangle, and Y can be chosen from a uniform distribution along the height of the rectangle. The nth region requires a more complicated algorithm, but since this is only needed with probability 1/n, this more complicated algorithm only needs to be run rarely. Thus, choosing a candidate X,Y is easy, which satisfies objective 1. If the number of regions n is large enough, then the stack of regions closely matches the function g(x), which satisfies objective 2.

If we focus on a single one of the rectangular regions, we can see another feature that makes the Ziggurat algorithm so fast. Figure 1.3 shows the kth region, for some k < n. The kth region consists of a rectangle extending horizontally from x_1 to x_{k+1} , and vertically from y_{k+1} to y_k . As shown in Figure 1.2, $y_k = g(x_k)$ for each k. Since g(x) is decreasing, $y_{k+1} < y_k$. We can easily choose a point uniformly from this rectangle by generating $X \sim \mathcal{U}(x_1, x_{k+1})$ and $Y \sim \mathcal{U}(y_{k+1}, y_k)$. After generating this point, we need to check whether Y < g(X). However, if $X < x_k$, then Y < g(X) no matter what Y is! This means that we do not even need to generate Y, nor evaluate the function g(X), unless $X > x_k$. If n is chosen to be large enough, each

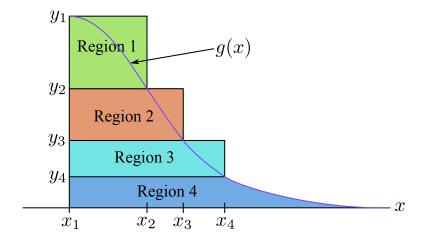


Figure 1.2: Diagram of the Ziggurat algorithm with n = 4. The name "Ziggurat algorithm" comes from the fact that this picture looks a little bit like a Ziggurat.

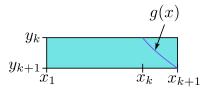


Figure 1.3: Diagram of the kth region of the Ziggurat algorithm.

rectangle will be much wider than it is tall, so the case where $X > x_k$ occurs only rarely.

To implement the Ziggurat algorithm, first the values x_1, x_2, \ldots, x_n and y_1, y_2, \ldots, y_n must be pre-computed. This pre-computation requires some effort, but it only needs to be done once. After these values are computed, the algorithm to generate one sample from the target distribution is summarized by the following pseudo-code.

```
Result: Returns one sample from distribution f_S while true do

Generate K uniformly from \{1, 2, ..., n\} if K < n then

Generate X \sim \mathcal{U}(x_1, x_{K+1}) if X < x_K then

return X

else

Generate Y \sim \mathcal{U}(y_{K+1}, y_K) if Y < g(X) then

return X

end

end

else

Generate a point from the nth region

end

end
```

The above pseudo-code does not give details about how do deal with the *n*th region. We'll get back to that! Note that, most of the time, to generate a sample of the target distribution, all we need to do is generate one uniform discrete variable K, generate one continuous uniform random variable X, and do one comparison $X < x_k$. Even though the alternative paths—when k = n, or $X > x_k$, or Y > g(X)—are more complicated, these alternative paths are rare, so most of the time we do not need to execute them.

1.2 Implement a baseline sampling algorithm

The baseline sampling algorithm uses a well known trick to generate samples from a given distribution. One can simply draw a sample U from the uniform random variable on [0,1] (i.e., $U \sim \text{Unf}(0,1)$), and return $F_S^{-1}(U)$, where F_S is the CDF of the desired distribution.

Task 2: Theory

Suppose that $U \sim \text{Unf}(0,1)$. Show that the random variable $Z = F_S^{-1}(U)$ has the desired distribution. **Hint:** Consider the CDF of Z.

Each of you is assigned a continuous distribution with a PDF of the form

$$f_S(x) = \begin{cases} cg(x), & x > x_1 \\ 0, & x < x_1 \end{cases}$$

where g(x) is a monotonically decreasing function in the range $x > x_1$. This assignment is randomized and will appear on your Canvas page.

Task 3

Find the constant c so that your PDF is normalized correctly.

Calculating c requires evaluating the integral

$$\int_{x_1}^{\infty} g(x)dx.$$

For some distributions, this integral is solvable in closed form. If it is not, you may use numerical integration software to calculate c numerically. In Matlab, you could use the <code>integral</code> function. In Python, you could use SciPy's numerical integration function <code>scipy.integrate</code>. You are also welcome to use Wolfram Alpha to do this, if possible. If you take the last route, please include a screenshot of the computation you performed on Wolfram Alpha in the report.

Task 4

Write a function that computes the CDF of your distribution.

As above, for some distributions the CDF will have a closed form expression, but for others it will require numerical integration.

Task 5

Implement a baseline sampling algorithm via the transformation $S = F_S^{-1}(U)$ where $U \sim \mathcal{U}(0,1)$.

This baseline algorithm will be used to compare against the more efficient Ziggurat algorithm. To implement this baseline algorithm requires inverting the CDF. If you cannot find a closed-form expression for this inverse function, you may need to implement the bisection algorithm, which is summarized below. This algorithm can be used for any monotonic function h(x). The idea is, in order to find a value x where h(x) = u, maintain values x_{\min} and x_{\max} where $h(x_{\min}) < u$ and $h(x_{\max}) > u$. A point x is chosen at the midpoint between x_{\min} and x_{\max} . Based on the value of h(x), either x_{\min} or x_{\max} is updated to halve the difference between them. (This pseudo-code assumes that h is increasing; the same algorithm can be used for monotonically decreasing functions with a slight variation.)

```
'Input: u, x_{\min}, x_{\max} where h(x_{\min}) < u and h(x_{\max}) > u

Output: x where h(x) = u

while x_{\max} - x_{\min} > tol do

\begin{vmatrix} x \leftarrow \frac{x_{\min} + x_{\max}}{2} & \text{if } h(x) > u \text{ then} \\ | x_{\max} & \leftarrow x; \\ | else & | x_{\min} \leftarrow x; \\ | end & \text{end} \end{vmatrix}
```

The tolerance parameter tol determines exactly how precise the result is. Setting tol = 10^{-12} or smaller is often a good choice.

Task 6

Generate at least 1000 samples from your baseline sampling algorithm. Keep track of the time it takes to run on your computer. In Python, you can use the package time to do this as follows:

```
import time

t0 = time.time()

code\_block

t1 = time.time()

time\_elapsed = t1 - t0
```

In Matlab, this can be done with the commands tic and toc. Plot an estimated PDF from these samples, and make sure it matches the true PDF.

1.3 Set up the Ziggurat

Before generating samples with the Ziggurat algorithm, the values x_1, x_2, \ldots, x_n must be pre-computed, as well as the corresponding values y_1, y_2, \ldots, y_n , where $y_k = g(x_k)$ for each k. These numbers should be selected so that each of the n regions have exactly the same area. For k < n, the kth region is a rectangle, so its area is

$$(x_{k+1}-x_1)(y_k-y_{k+1}).$$

For the nth region, the area is

$$(x_n - x_1)y_n + \int_{x_n}^{\infty} g(x)dx.$$

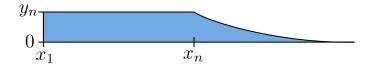


Figure 1.4: Diagram of the *n*th region of the Ziggurat algorithm.

To set up the Ziggurat, first choose a guess A for the area of each region. Based on this A, find x_2 so that the 1st region has area A. This can be done using the bisection algorithm. Then find x_3 so that the 2nd region has area A. Continue computing x_4, \ldots, x_n . Given the value that you get for x_n , compute the resulting area of the nth region. If this area is less than A, then the original guess for A must have been too large; if greater than A, then the original choice of A must have been too small. Again, the bisection algorithm can be used to find the exact value of A.

Task 7

Calculate x_1, x_2, \ldots, x_n and y_1, y_2, \ldots, y_n for three values of n: 4, 32, and 256. Check to make sure $x_1 < x_2 < \cdots < x_n$. Be sure to include the code that you used. Also list the x_k and y_k numbers for the n = 4 case. (Your report does not need to list the numbers for n = 32,256.)

1.4 Sampling from the *n*th region

Since the *n*th region of the Ziggurat is not a rectangle, it requires a different algorithm to sample from. However, since this region only comes up with probability 1/n, the algorithm does not need to be especially efficient. Figure 1.4 shows the *n*th region. It can be separated into two parts: (i) a rectangle extending horizontally from x_1 to x_n and vertically from 0 to y_n , and (ii) an infinitely long tail extending from x_n to ∞ , and upper bounded by g(x).

Task 8

If the point X, Y is chosen uniformly from this region, compute the probability p that it falls into the rectangular part of the nth region.

Remember that we do not really need Y, we only need X. When X, Y is in the rectangular part, then X is simply uniform from x_1 to x_n . Thus, we can do the following: with probability p, generate $X \sim \mathcal{U}(x_1, x_n)$. Otherwise, generate X from the tail distribution.

Generating X from the tail distribution is the last piece of the Ziggurat algorithm. This requires generating a random variable from the PDF

$$f_T(x) = \begin{cases} c'g(x), & x > x_n \\ 0, & x < x_n \end{cases}$$

where the constant c' is chosen appropriately.

Task 9

Find and implement a method to sample from the tail distribution f_T . One of two methods can be used, depending on your distribution:

- 1. If g(x) has a closed-form integral, then a version of the inverse-CDF transformation can be used, as in your baseline sampling algorithm.
- 2. If g(x) does not have a closed-form integral, you can use another rejection sampling algorithm. Here you can use the normal rejection sampling algorithm: choose a distribution f_R defined on $x > x_n$ that is easy to sample from, and a constant M such that $Mf_R(x) > g(x)$ for all $x > x_n$. For the distribution f_R , you may wish to use the exponential distribution restricted to $x > x_n$; another option is the Pareto distribution, given by PDF

$$f_R(x) = \begin{cases} \frac{\alpha x_n^{\alpha}}{x^{\alpha+1}}, & x > x_n \\ 0, & x < 0 \end{cases}$$

where $\alpha > 0$ is a parameter. The exact choice of distribution f_R is up to you, but be sure to explain your choice. To implement this rejection sampling algorithm, generate $X \sim f_R$, and $Y \sim \mathcal{U}(0, M f_R(X))$. Accept if Y < g(X), and repeat if not. Note that this rejection sampling loop should be done inside a single iteration of the outer rejection sampling loop.

1.5 Implement and analyze the Ziggurat algorithm

The final step is to complete the implementation of the Ziggurat for various values of n.

Task 10

Complete the implementation of the Ziggurat algorithm for n = 4, n = 32, and n = 256.

Congratulations! You now have your own shiny stochastic simulator! Let us analyze it to understand how well it does.

Task 11

For each of the three n values, run your Ziggurat algorithm to generate at least 1,000,000 samples. Make sure you compute the x_1, \ldots, x_n and y_1, \ldots, y_n constants only once. For each of the n values, use these samples to plot an estimated PDF, and compare against the true PDF. Carefully check that these match for your n = 4 algorithm, to make sure that your tail algorithm is working correctly.

The next is something you should be doing throughout your implementation. However, have an explicitly labeled part of your report that reports on the following statistics.

Task 12

As you generate samples from the three variants of your algorithm, keep track of the following data:

- 1. How long it takes to run. Compare the time per sample with your baseline algorithm. Make sure you run your code on the same computer, so that the comparison in meaningful.
- 2. How often each of the following possible outcomes occurs in the rejection loop:
 - (a) X is accepted because $X < x_k$,
 - (b) $X > x_k$ but X is accepted because Y < g(X),
 - (c) Y > g(X) so X is rejected,
 - (d) k = n and a sample is drawn from the rectangular part of the nth region,
 - (e) k = n and the tail algorithm is run.

^aSome of you may find that your baseline algorithm actually runs faster than the Ziggurat algorithm. If this is happens even for n=256, be sure to check your Ziggurat implementation to make sure it is working correctly. However, even if everything is working right, the baseline algorithm may still run faster. This could happen for two reasons. First, for some distributions with closed-form CDFs, computing the inverse CDF F_S^{-1} can be quite fast. Second, since Matlab is an interpreted language, it sometimes runs quite slowly compared to the same algorithm implemented in a language like C. For example, Matlab is notoriously slow when it comes to loops. Since the goal of this project is for you to understand the algorithm rather than to build a commercial product, this is nothing to worry about.

Task 13

Can you think of any ways to further improve the performance of your algorithm?