

Notes on prml

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Contents

1	Introduction	1
1.6	Information Theory	1
3	Linear Models for Regression	2

Chapter 1

Introduction

1.6 Information Theory

We begin by considering a discrete random variable x and we ask how much information is received when we observe a specific value for this variable, which can be viewed as the ‘degree of surprise’ on learning the value of x . Our measure of information content will therefore depend on the probability distribution $p(x)$, and we therefore look for a quantity $h(x)$ that is a monotonic function of the probability $p(x)$ and that expresses the information content. The form of h can be found by noting that if we have two events x and y that are unrelated, then the information gain from observing both of them should be the sum of the information gained from each of them separately, so that $h(x, y) = h(x) + h(y)$. Two unrelated events will be statistically independent and so $p(x, y) = p(x)p(y)$. From these two relationships, it is easily shown that $h(x)$ must be given by the logarithm of $p(x)$ and so we have

$$h(x) = -\log_2 p(x)$$

where the choice of basis is arbitrary. Now suppose that a sender wishes to transmit the value of a random variable to a receiver. The average amount of information that they transmit in the process is obtained by taking expectation with respect to the distribution $p(x)$, given by

$$H[x] = -\sum_x p(x) \log_2 p(x),$$

which is called the *entropy* of x . When using 2 as the basis, $H[x]$ is indeed the lower bound on the number of *bits* needed to *encode* the state of x .

Chapter 3

Linear Models for Regression

A helpful insight is that when

$$Ax = b$$

is irresolvable (A being not invertible, etc), we turn to A^\dagger instead to achieve an optimal result in the sense that $\|Ax - b\|$ is minimized. This is a motivation for *Moore-Penrose pseudo-inverse* matrix.