

OpenCV4 图像处理与视频分析数程



全局阈值

- 全局阈值概述
- OTSU阈值
- 三角阈值
- 代码演示

全局阈值概述

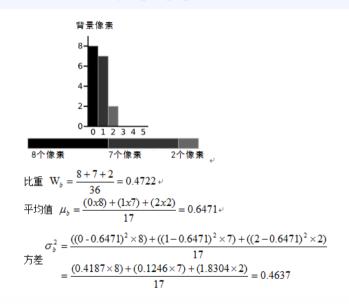
- 图像二值化分割, 最重要的就是计算阈值
- 阈值计算算法很多,基本分为两类,全局阈值与自适应阈值
- OTSU
- Triangle

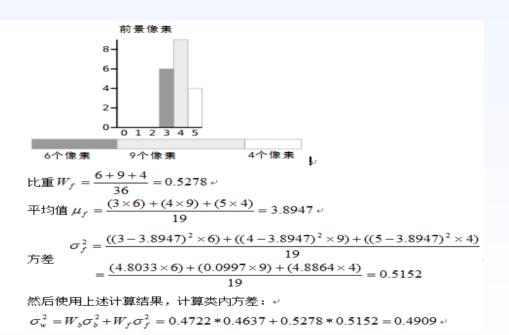
全局分割方法

- 均值法
- OTSU
- 三角法(Triangle)

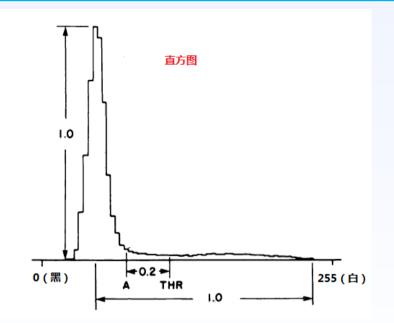
$$m = \frac{\sum_{i=0}^{h} \sum_{j=0}^{w} p(i,j)}{w * h} \quad p(i,j) = \begin{cases} >= m & 255 \\ < m & 0 \end{cases}$$

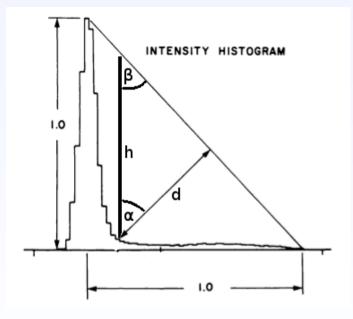
OTSU解释





三角法





$$h^2 = d^2 + d^2 \iff d = sqrt(\frac{h^2}{2})$$

$$d = \sin(0.7854) * h$$

API层面知识点与演示

```
THRESH_OTSU
THRESH_TRIANGLE
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> ret, binary = cv.threshold(gray,0, 255, cv.THRESH_BINARY | cv.THRESH_TRIANGLE)



Thank You!